TreadMill

COA Lab Project (2016-17) The LNMIIT, Jaipur

Khushboo Baheti (15UCS168) Smriti Jha (15UCS142) Shreya Rajput (15UCS134) Sakshi Goyal (15UCS116)

Introduction

- We are designing a 16-bit Treadmill Machine.
- Includes functions that can measure and analyse procedures or the levels of an activity that can properly attribute performance factor.

Example:

- CaloriesBurnt: It will tell the amount of calories burnt during a particular run for a particular time.
- VO2Consumption: which will tell the amount of oxygen consumed in a run.

Functions

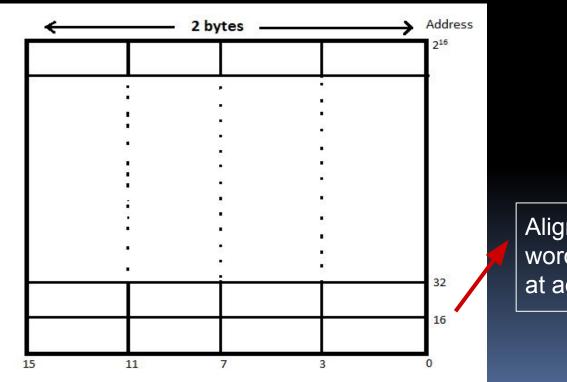
- VO2Consumption: Vo2 measurement represents the rate of oxygen consumption in that activity, which is, VO2(ml/(kg*min))=[(0.2*speed(m/min))+(0.9*speed*% grade)+3.5
- 2. setGrade: This function is used to initialise the inclination of the treadmill floor in terms of tan theta taken as input.
- 3. MET: Metabolic Equivalent of Task, 1 met is the energy equivalent expended by an individual while seated at rest.(1MET=3.5ml/(kg*min))

 MET(mets)=VO2/3.5
- 4. CaloriesBurnt: This can be derived from the relation Calories burnt: Time spent running(min)*[MET value*3.5*weight of body (in kg)/ 200]
- 5. CalculateDistance:Given the speed(m/min) and the time (min), Distance(m) = speed/time.

- 6. SetSpeed: This function is used to initialise the speed of machine (in m/min).
- 7. Start: This function starts the treadmill by taking time of running (in minutes) as an argument. It starts the timer accordingly.
- 8. SpeedInc: This will increment the current speed by 1.
- 9. SpeedDec:This will decrement the current speed by 1.
- 10. SetWeight: This function will initialise the weight as the weight given by the user(in kgs).

Memory Model

- We are using Little Endian model, where word is made up of 16 bits(2 bytes).
- Our memory is word addressable memory.
- We are using an Aligned memory model.



Aligned 2 byte word at address 16

Registers

 Ro-R10 are general purpose registers which will be used to store key local variables and immediate results of calculations.

Ro 0000

R1 0001

. .

R6 0101

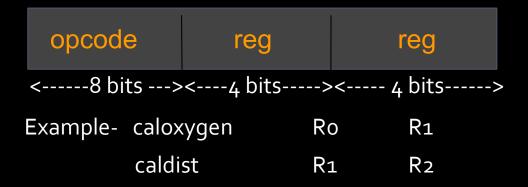
Special Registers:

GRD	0111
WGT	1000
TME	1001
SPD	1010
IN	1011
OUT	1100
PC	1101
IR	1110
FR	1111

- Special-purpose registers control various caches, memory, I/O devices and other hardware features.
- IN/OUT registers will be used to take input & display output.
- GRD(Grade), WGT(Weight), TME(Time), SPD(Speed), PC(Program Counter), IR(Instruction register), FR(Flag register) are special purpose registers.

Instruction Format

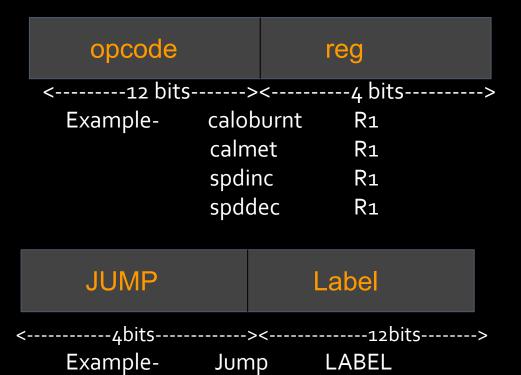
2 - Address Instructions:



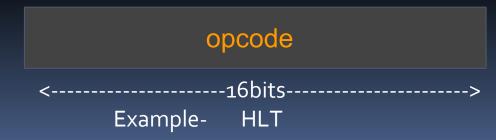
Immediate Address Instruction:

opcode	imm	1	reg	
Example- setspe	ed	imm	R1	
settim	e	imm	R1	
setwei	ght	imm	R1	
setgra	de	imm	R1	

1- Address Instructions:



o-Address Instructions:



In our instructions, second operand will be the destination register in which the result will be stored.

Instruction Design

4 bits: setspeed oooo

settime 0001

setweight 0010

setgrade 0011

Jump 0100

8 bits: caldist 01010000

caloxygen 01010001

12 bits: caloburnt 010100100000

calmet 010100100001

spdinc 010100100010

spddec 010100100011

16 bits: HLT 010100100100000

- RISC due to faster clock speeds.
- Fixed length instructions because of easy decoding.

Instruction Types

- Data Movement:
 Register to Register= caldist
 Immediate to Register=setspeed
- Dyadic Instructions:

```
caldistop1 op2settimeop1 op2caloxygenop1 op2setweightop1 op2setspeedop1 op2setgradeop1 op2
```

Monodic Instructions:

```
caloburnt op1 spdinc op1 calmet op1 Jump label
```

Branching:

```
Jump label
```

Data Types

We are using only Unsigned Integers.

Addressing Modes

Immediate Addressing Modes:

setspeed value R1
settime value R1
setweight value R1
setgrade value R1

Register Addressing Modes:

caloxygen Ro R1 caldist Ro R1

Flow of Control Handling

Sequential flow of control and Branching are checked in which LABEL provides the name for a particular address where jump statements are used to change or control the flow of program.

THANK YOU!!!!