$$P = |V| \qquad V = |R| \Rightarrow I = \frac{V}{R}$$
$$= \frac{V^{2}}{R}$$

$$V_{oc} = \frac{R_L V_{Th}}{R_L + R_{Th}}$$

$$P_{oc} = \frac{\begin{pmatrix} R_L V_{Th} \\ R_L + R_{Th} \end{pmatrix}}{R_L} = \frac{V_{Th}^2 R_L^2}{R_L^2 + 2R_L R_{Th} + R_{Th}^2}$$

$$= \frac{V_{Th}^2 R_L}{R_L^2 + 2R_L R_{Th} + R_{Th}^2}$$

$$\frac{dP_{oc}}{dR_L} = 0 = \frac{V_{Th}^2 (R_{Th} - R_L)}{(R_L + R_{Th})^3}$$

$$V_{th}^{2}(R_{Th}-R_{L})=0$$

$$P_{\text{max}} = \frac{V_{\text{th}}^2 R}{R^2 + 2R^2 + R^2} = \frac{V_{\text{th}}^2 R}{4R^2} = \frac{V_{\text{th}}^2}{4R}$$