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I input: adjecency list of undirected graph 6-(VE) output: away of all budgers of all vertices. Hyprithm 1. Create an array of length IVI called degree 2. For each VEV store the length of adjecting row of v in the array. Vo gets array [0], this way array [0] contains the amount of neighbors Vo has. 3 to cally to Coeste a new away of length IVI initialized to O. the This armag is is called tendegræ. For each edge the endpoints of edge el one willest and to both endpoints and the tag Ux and Uy. Itel the degree of Ux to the two degree of u and the degree of Ux to the two degree of ux. The complexity of this algorithm is: 0(1) O(IVI) (Far each vEV) 0 (1) GO(IEI) (for each DeeF)
Total = O(IVI+IEI)

III These bottlement edges are in the all start in the min-cut of G. We want to their is and Go van Ford-Fulkeron to calculate the min cuti Run Ford-Fulkeson All edges from such a reachable edge to a non-reachable vetex are bottlenett edges IV We can extend the binary seach tree by keeping truck of how many keys are smaller than tor a key x, we trap truct of: X. Kea X. Smaller X. parent X\_ left X. right

To insertion there are two possibilities: Inseting x in tree: (X) (Z) (Z) Q X teg 2 y teg : = y smalle & t=1 X. Key > y. Key: - inset x in w. - X. smalle += 1 For finding an node x la which there are this algorithm; Algorithm: (using the same wales as above) 1. If y smalle == K, vetur y
2. If y smalle < K seach send vecursively use this algorithm to seach to y smalle ist smalle treas in w. (q. right) 3. It a smalle > to recursively use this algorithm to seach to smalle treys in 2 (y.left)

his algorithm works because to a male w, there are w. smalle smalle Keys in the tree plus the amount of smalle modes the part of a has because it going my the right the the abilitative node itself) This ratio will be used to adding items to the Knaprak. 1. For a botton-up appoach, we use a 2D array He with n H columns and W+1 rows (n = amount of products). Algorithm Knap Sack Algorithm Lint God, int Gester ] int well ] int n) { int K[n+1][W+1] or Ci=o; i <=n; itt) ? for (woo; wec= w; wetr)? if ( == 0 and we= 0) { ME: Jeur = 0; else it (weight Li-I to we) { TCi 3[we] = maximum (well ttCi-1, J[we], val[i-1]+ tr[i-, I we - weight Li-, J]); else K[i][w] = Ki-J[w]

either item on is in the trapsact or not. this way are can construct an algorithm: ( o if i == 0 0 if w ==0 Comx Chi-J[w], wli-1] + Ki-J[w]-weight[i-1]]) it weight [i-] <= remaining weight [t[i-,][w] if weight [i-1] less remaining weight We can keep truck of another bod array . This arrigg indicates whether an item at place is in the trapsact or not . his army will also tree track of the prese choice unde: Struct Choise & de perious = those hall choise previous;

Knap Salt Algorithm ( int w, int veight[], int oul[], int n) & int Klnt1 J Louti]; Choice ([n+1][w+1]; or (i=o; i(=n; itt)? la lue 6 aec=w; aett) { it ( == 0 0 Ne==0) } thistory = 0; Khaio [[:] [we] = null; else if (weight[i-i] (= we) ? Ke sfal if (val [i ] + tt[i-1] [ve-veight[i-1]] 6)= thi-Island) & H[i][ve] = val[i-1] + H[i-1][we-weighti-i] [[i] [ae] tin = true; [[i][we]. previous = ([i-,][we-weig(+[i-,]]) K[: ][we] = w tt[:-](we] Cliffued in = false; [Li] [we] previous = [Ci-i] [we] else } KliJ [we] = f[i-1] [we] ([i] [we] in = fulse ([i] [are] previous = ([i-])(are)

Choice c= CITIVI while (c= onall) { prote if (c.in) ?
print(toe);