Example: Maximizing the Minimum Eigenvalue of a Matrix Using SDP

Given a symmetric matrix X, we want to **maximize its smallest eigenvalue** while ensuring it remains positive semidefinite (PSD). This is a classic **SDP problem** because eigenvalues define the PSD constraint.

Problem Formulation

Let's define a symmetric **matrix variable** X **of size** 2×2 :

$$X = \begin{bmatrix} x_{11} & x_{12} \\ x_{12} & x_{22} \end{bmatrix}$$

We seek to maximize the smallest eigenvalue of X, denoted as $\lambda_{\min}(X)$, subject to constraints.

SDP Formulation

- 1. Introduce a new scalar variable λ , representing the minimum eigenvalue.
- 2. Impose the LMI (Linear Matrix Inequality) constraint:

$$\setminus [X - \lambda I \succeq 0 \setminus]$$

This ensures that all eigenvalues of X are at least λ .

3. Solve for **maximum** λ .

Thus, the SDP problem becomes:

$$\max_{\lambda,X} \quad \lambda$$

Subject to:

$$[X - \lambda I \succeq 0] [X \succeq 0]$$

This ensures that the **minimum eigenvalue of** X **is maximized**, while X remains PSD.

Brief Explanation of the Code

This code solves a semidefinite programming (SDP) problem using the CVXPY library to maximize the smallest eigenvalue of a symmetric 2 x 2 matrix X.

Libraries Used:

- cvxpy (cp) \rightarrow Defines and solves convex optimization problems.
- numpy (np) → Used for numerical operations (e.g., creating the identity matrix).

How It Works:

- 1. Define Variables:
 - X → A symmetric 2 \times 2 matrix.
 - lambda_min → The smallest eigenvalue to maximize.

2. Define Constraints:

- X lambda_min * I >> 0 \rightarrow Ensures \lambda_{\min} is the smallest eigenvalue.
- $x \gg e$ \rightarrow Ensures X is **positive semidefinite (PSD)**.
- cp.trace(X) == 1 → Prevents unbounded solutions.

3. Define Objective:

• Maximize lambda_min.

4. Solve the Problem:

• Uses the **CVXOPT solver** (problem.solve(solver=cp.CVXOPT)).

CVXOPT → More reliable for SDP problems.

5. Print Results:

• Displays the solver status, optimal minimum eigenvalue, and optimal X matrix.

Results:

Solving SDP problem...

Solver status: optimal

Optimal minimum eigenvalue: 0.49999999999998

Optimal X matrix:

[[0.5 0.]

[0. 0.5]]