

Learning with context feedback loop for robust medical image segmentation

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Presentation outline

1 Introduction

2 Previous Works

3 Proposed Method: LFB-Net

4 Materials and Experiments

5 Conclusions

Medical image segmentation

Clinical applications

- Medical image analysis
- Clinical interventions
- Extrapolate clinical information

Promising approach

- Deep learning methods
- Driving factors
 - Data
 - Processing power
 - Algorithm development

Deep learning methods for medical image segmentation

- FCN¹
- U-Net²
- Embedding shape models³

- Transfer learning⁴
- Attention based models⁵
- Post-processing or cascaded models^{6, 7}

¹ Noh, H., *et al.* (2015), CVPR.

² Ronneberger O., *et al.* (2015), MICCAI.

³ Oktay O., *et al.* (2017), IEEE Trans Med Imaging.

⁴ Gu Z., *et al.* (2019), IEEE Trans Med Imaging.

⁵ Schlemper J., *et al.* (2019), IEEE Trans Med Imaging.

⁶ Larrazabal A.J., *et al.* (2020), IEEE Trans Med Imaging.

⁷ Painchaud N., *et al.* (2020), IEEE Trans Med Imaging.

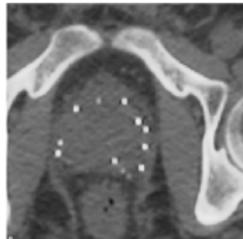
Deep learning methods for medical image segmentation

Success

- Automatically extract distinctive image features
- Achieved promising quantitative results

Challenges

- Strongly biased towards recognizing texture features ¹
- Produce unrealistic and incomplete segmentation



Input image



Reference



Predicted

¹Geirhos R., et al. (2018), ICLR.

Learning with context feedback loop for robust and accurate medical image segmentation (LFB-Net)

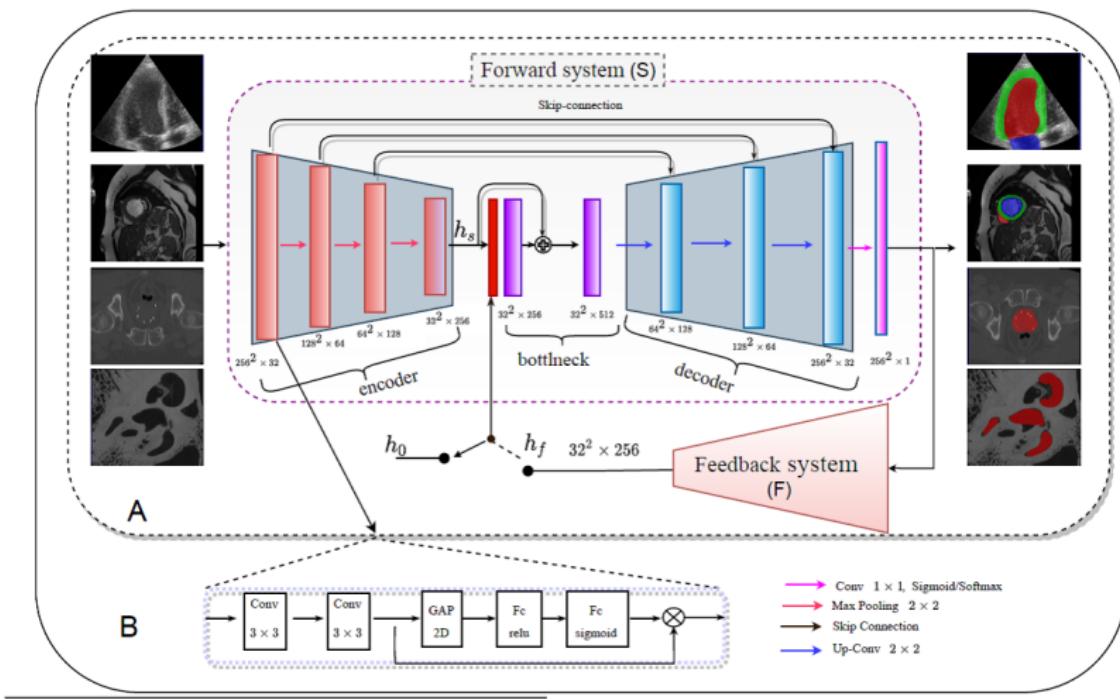
We formulate the segmentation process as a recurrent framework using two deep learning networks interconnected via feedback loop

Feedback loop: use output error signal to make adjustments on the input single¹

¹ Huh M., *et al.* (2019), CVPR.

Girum K.B., *et al.* (2020), IEEE Trans Med Imaging.

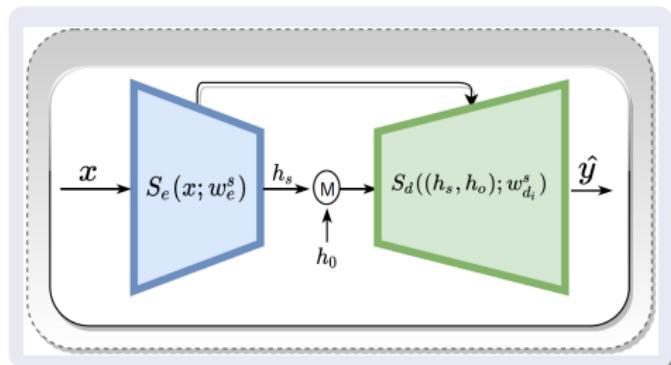
LFB-Net



Girum K.B., et al. (2020), IEEE Trans Med Imaging.

Forward system

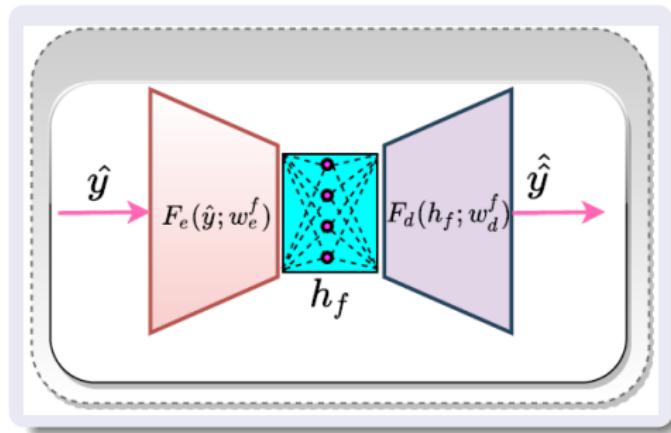
- Similar to U-net¹
- Encoder: $S_e : x \mapsto h$
- Decoder: $S_d : h \mapsto y$
- $\hat{y} = S(x) = S_d(S_e(x))$
- $L(y, \hat{y})$
- x is the input image
- h the latent space
- \hat{y} the predicted image



¹ Ronneberger O., et al. (2015), MICCAI.

Feedback system

- Similar to FCN¹
- Encoder: $F_e : \hat{y} \mapsto h_f$
- Decoder: $F_d : h_f \mapsto \hat{\hat{y}}$
- $\hat{\hat{y}} = F(\hat{y}) = F_d(F_e(\hat{y}))$
- $L(y, \hat{\hat{y}})$

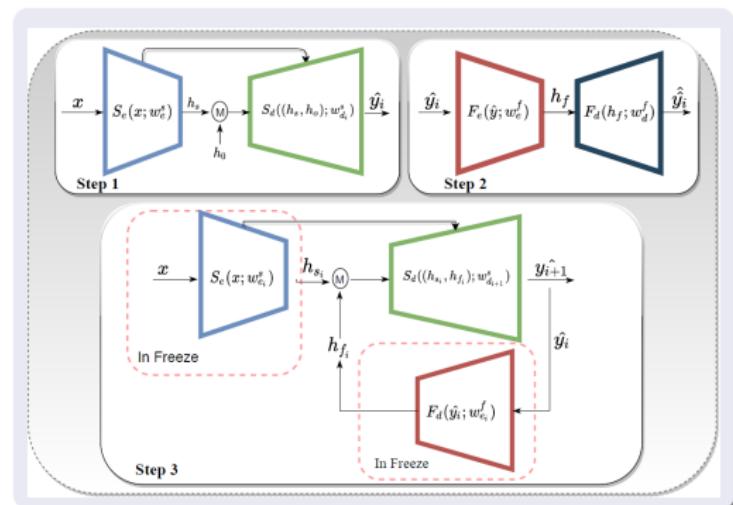


¹ Noh, H., et al. (2015), CVPR.

Integration: Segmentation with two systems

Recurrent process

- $\hat{y} = S(x) = S_d(S_e(x))$
- $\hat{\hat{y}} = F(\hat{y}) = F_d(F_e(\hat{y}))$
- $\hat{y}_{i+1} = S_{d_{i+1}}(h_{s_i}, F_{e_i}(\hat{y}_i))$



Experimental setup

Single label segmentation

① Prostate

- CT with seeds
- 78 CT exams

② Inner ear

- 17 μ CT exams¹

Multi-label segmentation

① Cardiac cine-MRI

- ACDC MICCAI 2017²
- 150 exams

② Echocardiography

- CAMUS data³
- 500 exams

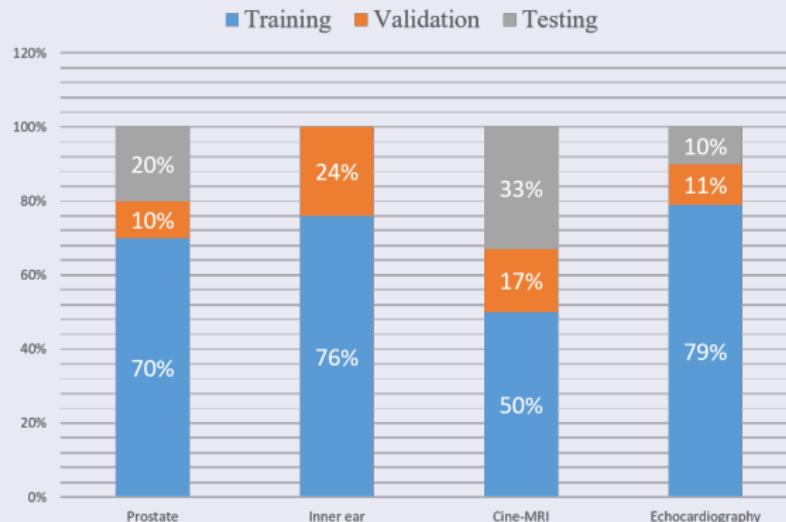
¹Gerber N., *et al.* (2017), Sci. Data.

²Bernard O., *et al.* (2018), IEEE Trans Med Imaging.

³Leclerc S., *et al.* (2019), IEEE Trans Med Imaging.

Girum K.B., *et al.* (2020), IEEE Trans Med Imaging.

Experimental setup



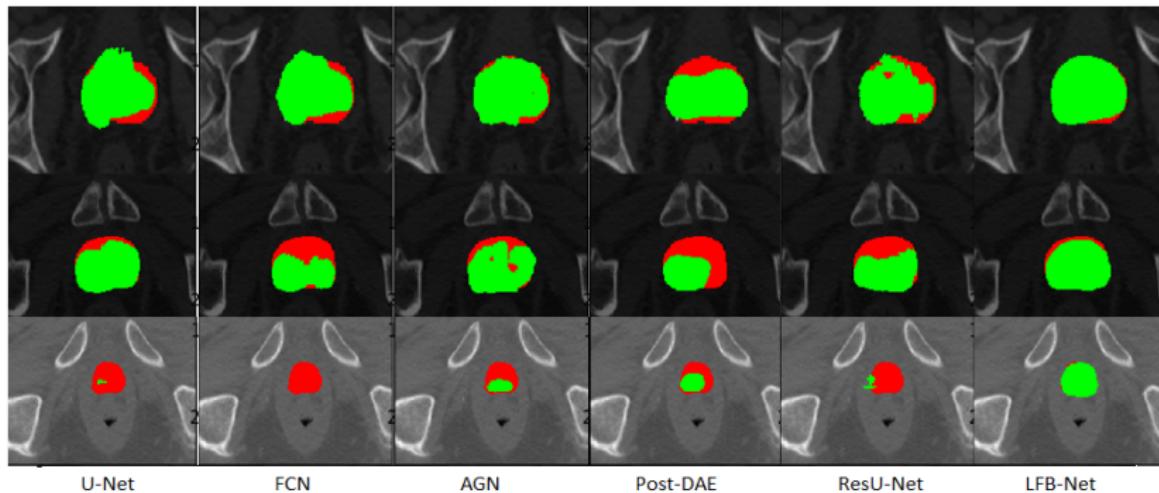
¹Gerber N., et al. (2017), Sci. Data. For the inner ear segmentation

²Bernard O., et al. (2018), IEEE Trans Med Imaging. For the cardiac cine-MRI segmentation

³Leclerc S., et al. (2019), IEEE Trans Med Imaging. For the echocardiographic image segmentation

Girum K.B., et al. (2020), IEEE Trans Med Imaging.

Prostate segmentation



¹Noh H., *et al.* (2015), CVPR.

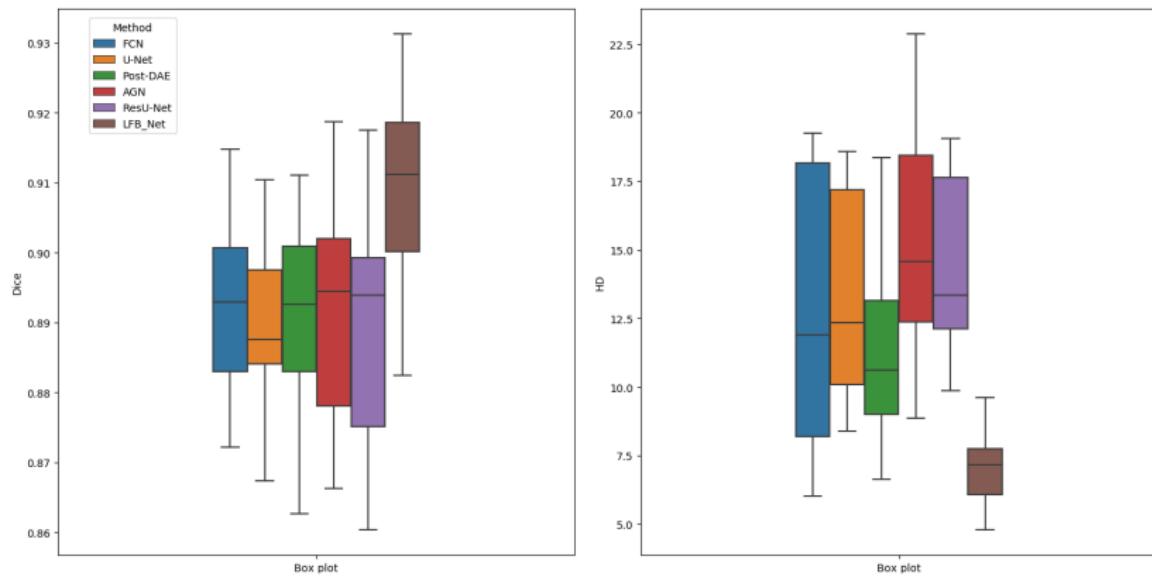
²Ronneberger O., *et al.* (2015), MICCAI.

³He K., *et al.* (2016), CVPR.

⁴Larrazabal A.J., *et al.* (2020), IEEE Trans Med Imaging.

⁵Schlempe J., *et al.* (2019), Med Image Anal.

Prostate segmentation

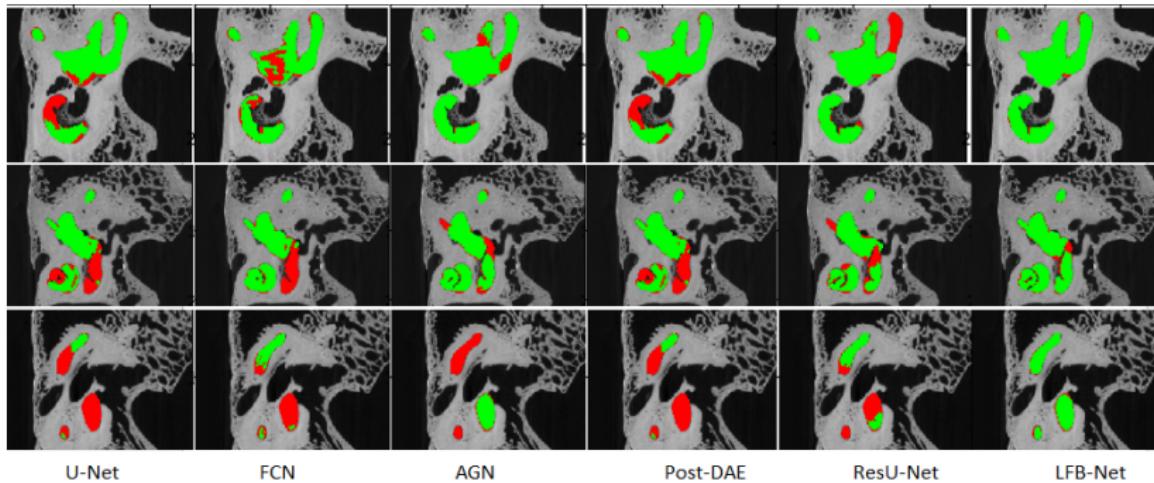


¹Noh H., et al. (2015), CVPR. ²Ronneberger O., et al. (2015), MICCAI.

³ He K. et al. (2016), CVPR. ⁴Larrazabal A.J. et al. (2020) IEEE Trans Med Imaging..

⁵Schlemper J. et al. 2019 Med Image Anal.

Inner ear segmentation



Ground truth in red, predicted in green

¹Noh H., et al. (2015), CVPR.

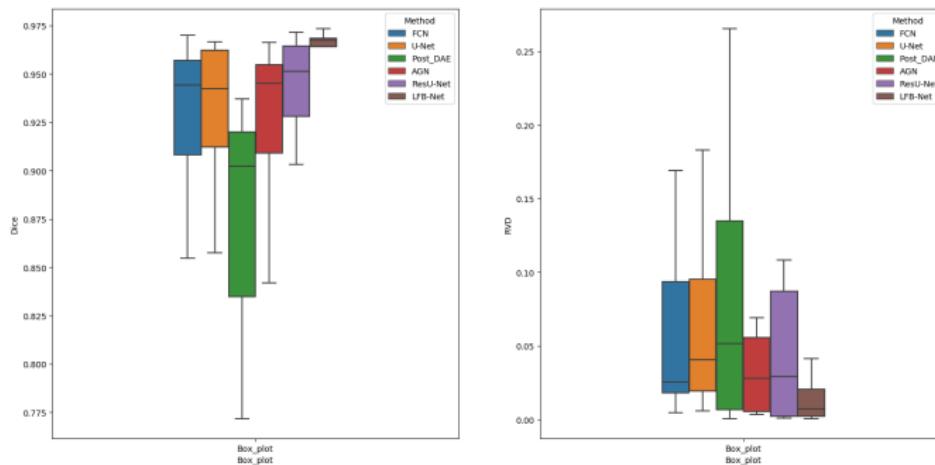
²Ronneberger O., et al. (2015), MICCAI.

³He K., et al. (2016), CVPR.

⁴Larrazabal A.J., et al. (2020), IEEE Trans Med Imaging.

⁵Schlempe J., et al. (2019), Med Image Anal.

Inner ear segmentation

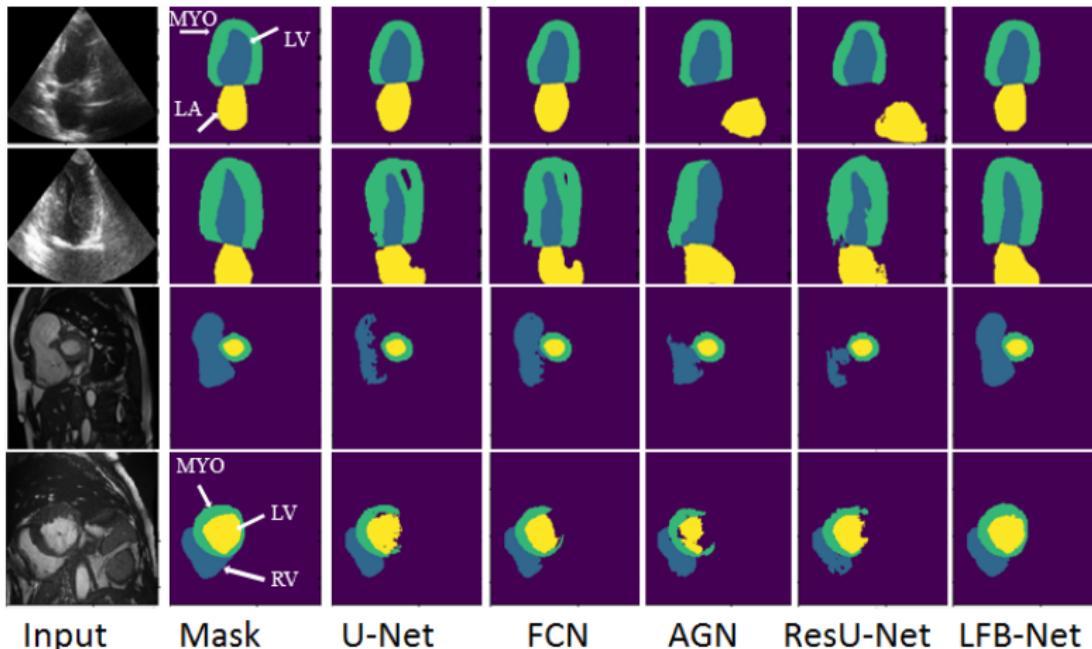


¹Noh H., et al. (2015), CVPR. ²Ronneberger O., et al. (2015), MICCAI.

³ He K. et al. (2016), CVPR. ⁴Larrazabal A.J. et al. (2020) IEEE Trans Med Imaging..

⁵Schlempe J. et al. 2019 Med Image Anal.

Multi-label segmentation



Echocardiographic image segmentation

Method	LV: Endocardium				LV: Epicardium				Left Atrium			
	Dice	ES	ED	HD	Dice	ES	ED	HD	Dice	ES	ED	HD
inter-observer	0.873 ±0.060	0.919 ±0.033	6.6 ±2.4	6.0 ±2.0	0.890 ±0.047	0.913 ±0.037	8.6 ±3.3	8.0 ±2.9	-	-	-	-
Intra-observer	0.930 ±0.031	0.945 ±0.019	4.5 ±1.8	4.6 ±1.8	0.951 ±0.021	0.957 ±0.019	5.0 ±2.1	5.0 ±2.3	-	-	-	-
Oktay O. <i>et al.</i> [1]	0.913	0.936	5.6	5.6	0.945	0.953	5.9	5.9	0.911	0.881	5.8	6.0
Leclerc S. <i>et al.</i> [2]	0.912	0.936	5.5	5.3	0.946	0.956	5.7	5.2	0.918	0.889	5.3	5.7
U-net-2 [2]	0.899	0.922	5.3	5.7	0.923	0.932	6.4	6.4	0.888	0.848	6.2	6.9
LFB-Net	0.926	0.946	4.8	4.8	0.952	0.959	5.2	5.2	0.924	0.902	5.0	5.2

¹Oktay O., *et al.*, *et al.* (2017), IEEE Trans Med Imaging.

² Leclerc S., *et al.* (2019), IEEE Trans Med Imaging.

Validation vs Testing

- Cardiac cine-MRI segmentation

Method	Metric			
	<u>Dice</u>		<u>HD (mm)</u>	
	Valid.	Test.	Valid.	Test.
AGN [1]	$0.910 \pm 0.07^*$	$0.894 \pm 0.09^*$	10.9 ± 7.13	$12.0 \pm 8.23^*$
FCN [2]	$0.903 \pm 0.07^*$	$0.890 \pm 0.08^*$	11.0 ± 7.22	$12.0 \pm 6.53^*$
U-Net [3]	$0.906 \pm 0.06^*$	$0.888 \pm 0.10^*$	11.5 ± 7.50	$12.3 \pm 7.79^*$
ResUnet [4]	0.903 ± 0.07	$0.893 \pm 0.09^*$	$11.9 \pm 8.39^*$	$11.9 \pm 7.32^*$
LFB-Net	0.921 ± 0.05	0.920 ± 0.06	9.9 ± 6.47	9.7 ± 6.18

¹Schlempe J. *et al.* (2019) Med Image Anal.

²Noh H., *et al.* (2015), CVPR.

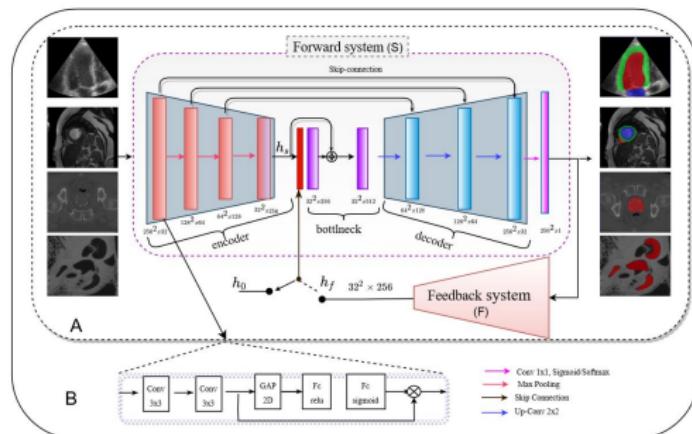
³Ronneberger O., *et al.* (2015), MICCAI.

⁴ He K. *et al.* (2016), CVPR.

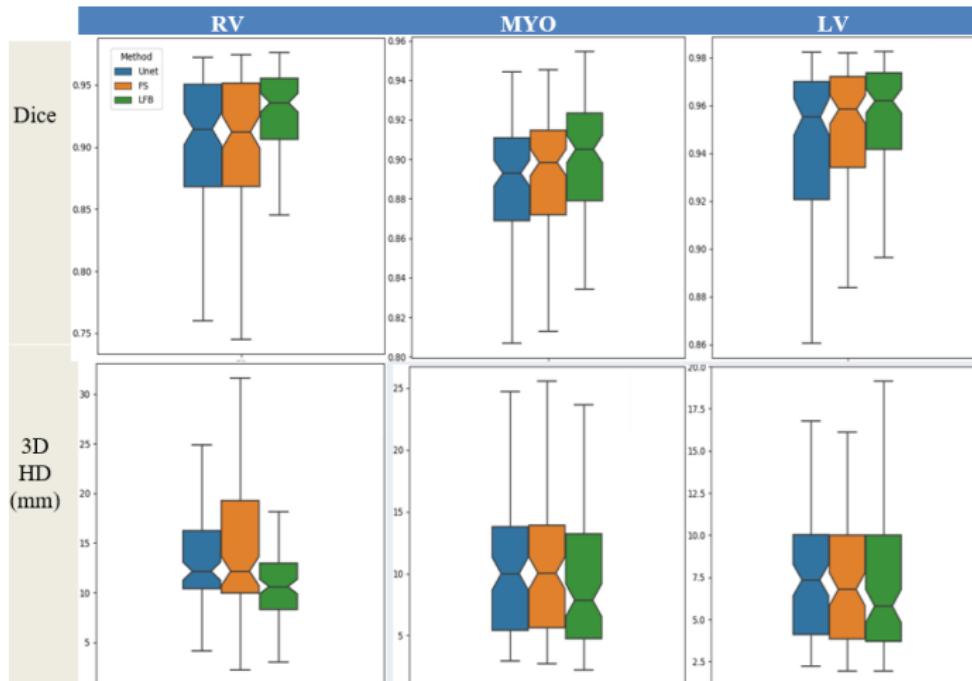
* corresponds to $p < 0.05$.

Ablation study

- ➊ System design
- ➋ Integration strategy
- ➌ Training scheme

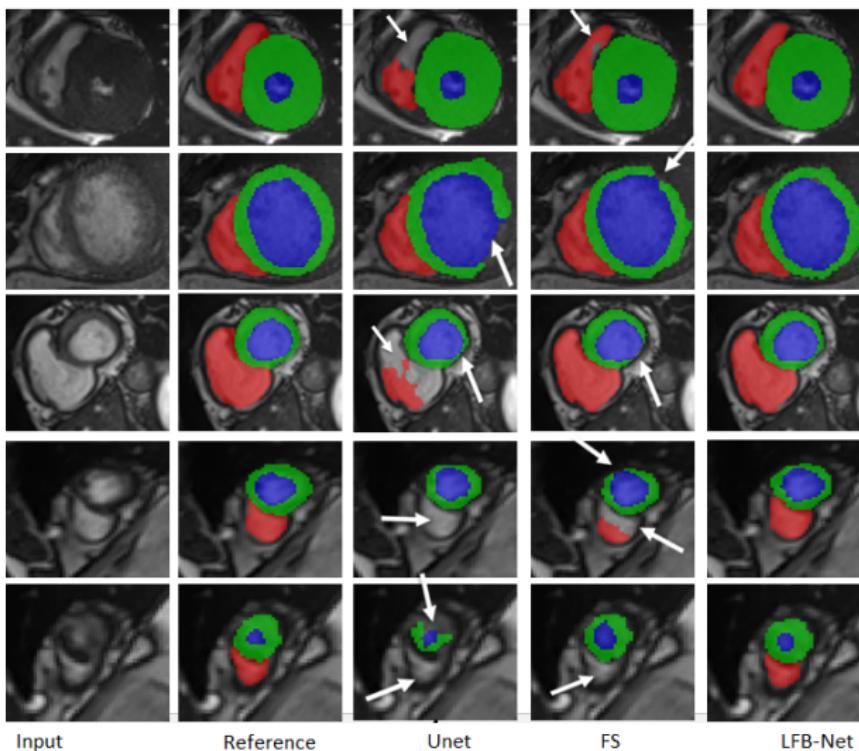


Ablation study of system design: cardiac cine-MRI



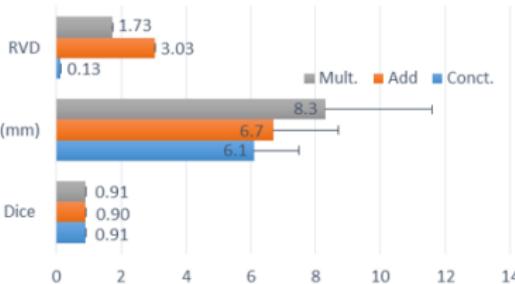
Unet: Forward system; FS: Forward system with squeeze-and-excitation network block; and
LFB: Our method.

Ablation study of system design



Ablation study of system integration and training strategy

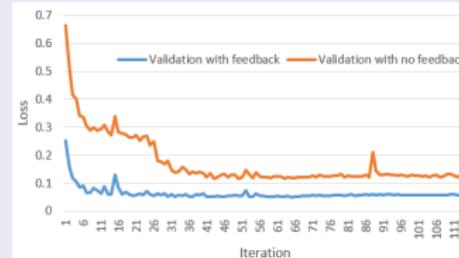
Integration strategy



Training loss



Validation loss



Conclusions

- Proposed and extensively evaluated a new fully automatic deep learning framework for medical image segmentation
- Experimental results revealed two important points:
 - ① A feedback loop-based segmentation produces both plausible and accurate segmentation results
 - ② It also produces results with reduced segmentation variability among the testing data, yielding state of the art results

Future perspectives

- Extend to other medical image analysis tasks
- Efficiently leverage the contextual feedback loop's latent space
- Efficiently leverage the merged contextual information
- 3D version of the proposed method could be applied in cases of available 3D datasets

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