

Deep generative model-driven multimodal prostate segmentation in radiotherapy

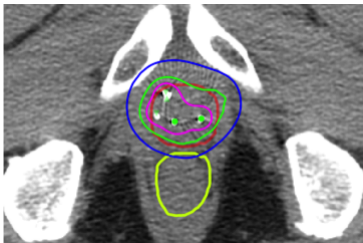
Kibrom B. Girum, Gilles Créhange, Raabid Hussain, Paul M. Walker, Alain Lalande

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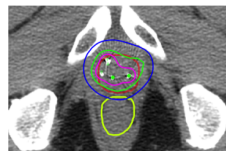
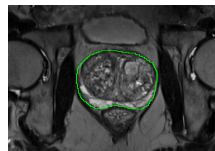
Prostate brachytherapy

- Planning
- Intra-operative procedures
- Post-procedural dose analysis

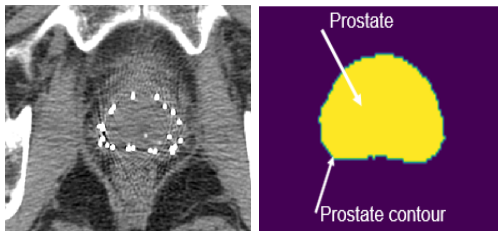


Prostate segmentation in brachytherapy

- **Magnetic resonance images (MRI):**
 - ✓ Relatively better contrast for the contour of the prostate and rectum
 - ✗ Difficulties in relating the tissue density with the voxel intensity value
 - ✗ Low signal for the radioactive seeds
- **Computed tomography images (CT):**
 - ✓ Relate the tissue density with the voxel intensity value
 - ✓ Good signal for radioactive seeds
 - ✗ Low-contrast for the contour of the prostate



Related works



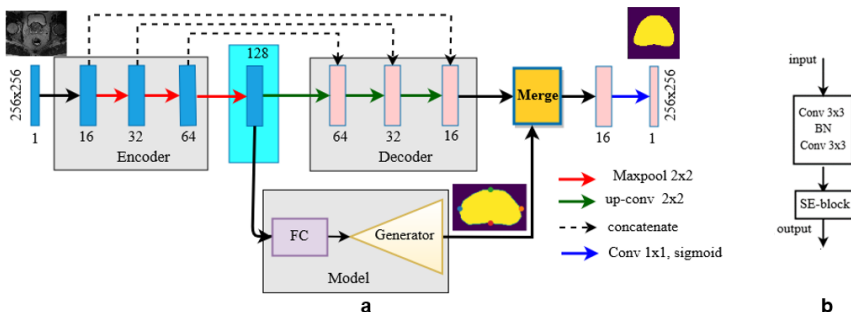
- Pixel classification with U-net¹
- Combination of information from contour and/or shape with pixel classification²
- Combination of convolutional neural network (CNN) based pixel classification with atlas of the prostate gland³

¹Kazemifar S. et al. 2018, Biomed Phys Eng Express

ImViA²Martínez F. et al. 2014, Phys. Med. Biol.

³Ma L. et al. 2017, SPIE

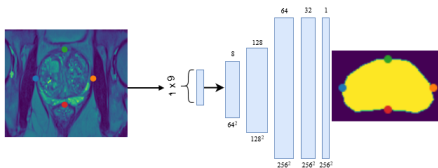
Proposed architecture



Proposed architecture: (a) The overall framework (DGMNet), and (b) The schema of a single block in the encoder and decoder

Proposed architecture

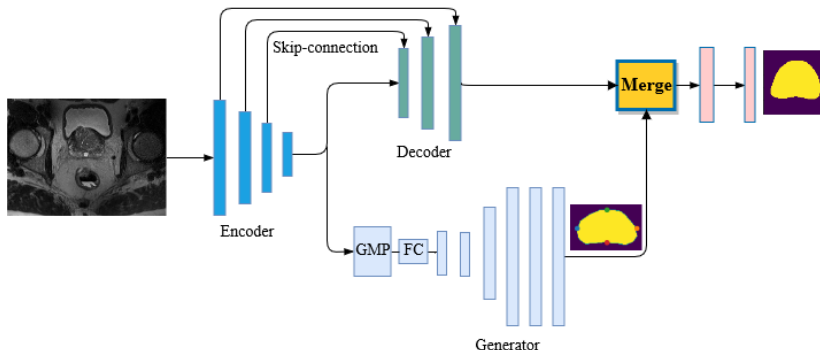
- Regression for surface coordinates x and y
- Image based classification z



Generator

- Binary cross entropy loss

Proposed architecture



The number of feature channels in the Encoder/Decoder is 16 in the first level, which is then doubled/halved after each pooling/upsampled with a maximum of 128 features channels at the bottleneck.

Cost function

$$L_{total} = L_{mask} + \lambda L_{clsLnd} , \quad (1)$$

where the segmentation loss is: $L_{mask} = L_{dice} + L_{CE}$

Given $I^u = (x^u, y^u, z^u)$, and $I^v = (x^v, y^v, z^v = p)$, the joint classification and regression loss can be calculated as:

$$L_{clsLnd}(I^u, I^v) = L_{cls}(p, z^u) + [z^u = 1]L_{lnd}(t^u, t^v) , \quad (2)$$

$$L_{lnd}(t^u, t^v) = \sum_{i \in \{x, y, z=1\}} smooth_{L1}(t_i^u - t_i^v) , \quad (3)$$

in which

$$smooth_{L1}(\Delta t) = \begin{cases} 0.5(\Delta t)^2 & \text{if } |\Delta t| < 1 \\ |\Delta t| - 0.5 & \text{otherwise ,} \end{cases} \quad (4)$$

Dataset

- T2-weighted magnetic resonance images (MRI)
 - 60 T2-weighted MR exams
 - In-plane resolution ranging from $0.312 \times 0.312 \text{ mm}^2$ to $0.676 \times 0.676 \text{ mm}^2$
 - Slice thickness between 1.250 mm and 2.722 mm
- Computed tomography (CT) images
 - 40 CT exams
 - Permanent prostate brachytherapy with ^{125}I
 - In-plane resolution ranging from $0.4 \times 0.4 \text{ mm}^2$ to $0.58 \times 0.58 \text{ mm}^2$
 - Slice thickness between 1.5 mm and 2.5 mm

Pre-processing

- Resolution of $0.5 \times 0.5 \times 1.25 \text{ mm}^3$ and $0.7 \times 0.7 \times 1.25 \text{ mm}^3$ for CT and MRI, respectively
- Resized and cropped to 256×256
- Zero-centered the intensity values and normalize by standard deviation

Training and testing

- 25% of the dataset were used for validation
- Experiments were performed using different metrics to investigate the effect of each layer in the proposed method

Quantitative results

Data	Method	DSC	Sen	ASD	PPV
CT	Unet	0.83 ± 0.04	0.76 ± 0.08	0.16 ± 0.08	0.93 ± 0.03
	ResUnet	0.82 ± 0.03	0.73 ± 0.03	0.16 ± 0.10	0.93 ± 0.03
	SE-ResUnet	0.84 ± 0.03	0.88 ± 0.05	0.84 ± 0.53	0.82 ± 0.06
	SE-Unet	0.85 ± 0.03	0.78 ± 0.07	0.17 ± 0.15	0.93 ± 0.04
	DGMNet	0.89 ± 0.02	0.92 ± 0.03	0.28 ± 0.09	0.87 ± 0.03
MRI	DGMNet	0.93 ± 0.12	0.92 ± 0.15	0.11 ± 0.22	0.96 ± 0.07

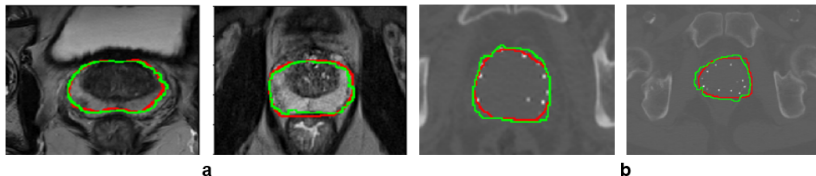
DSC: Dice Similarity Coefficient

Sen: Sensitivity

PPV: Positive Predicted Value

ASD: Average Surface distance (in mm)

Qualitative results



Qualitative evaluation of prostate segmentation on 2D: (a) T2-weighted MRI, and (b) CT images with seeds from low-dose-rate brachytherapy. The ground truth labels are shown in red and segmentation results in green.

Summary and remarks

Take home message

- We proposed a new method to segment the prostate in multimodal images using shape modeling and pixel classification
- Embedding prior organ knowledge via learning-based shape modeling and registration from better contrast images can improve segmentation on low-contrast images

Future work

- Evaluate on larger multi-center dataset
- Apply to intra-operative TRUS image segmentation
- Generalize the proposed method on other organs such as the heart and the lung

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