

## AME 30358 – Score Sheet

### M6 – Stepper Motor and Linear Gantry

Name(s): \_\_\_\_\_

The following items will be *demonstrated* to the lab instructor during the allotted lab time. Credit will not be given for portions completed outside of lab.

Item and Description	Points Awarded	Possible Points
<b>Part I: Stepper Motor and Driver Board</b> The stepper motor spins smoothly, receiving pulses from the function generator.		5
<b>Part II: Microcontroller Implementation</b> The stepper motor repeatedly rotates one full revolution clockwise, then rotates another full revolution counter-clockwise.		5
<b>Part III: Mechanical Assembly</b> The linear belt drive system is properly assembled. The motor moves the gantry cart back and forth.		4
<b>Part IV: Actuator Calibration</b> The calibration constant looks correct.		2
<b>Part V: Limit Switches</b> The limit switches are properly mounted, and they disable the motor before the cart crashes.		4
<b>Part VI: Auto-calibration</b> The cart “finds” both limit switches, then comes to rest in the home position. The printed calibration constant looks correct.		3
<b>Part VII: Position Control</b> The serial monitor asks for a position (cm). The cart moves to the position entered by the user. A warning message is display to prevent crashing.		3
<b>Clean-up</b> The students returned the lab bench to its initial state.		2
<b>TOTAL</b>		28