

## AME 30358 – Score Sheet

### M3 – Servo Motors

Student Name(s): \_\_\_\_\_

The following items will be *demonstrated* to the lab instructor during the allotted lab time. Credit will not be given for portions completed outside of lab.

Item and Description	Points Awarded	Possible Points
<b>Part I: Testing the Servo</b> The servo spins to a location dictated by the pulse width generated by the function generator.		3
<b>Part II: Microcontroller Implementation</b> The student wrote down the mapping between pulse width and angle in lab notebook. The servo move correctly via the Arduino code.		3
<b>Part III: Design Challenge 1</b> Turning the potentiometer knob causes the servo to rotate.		4
<b>Part IV: Ultrasonic Rangefinder</b> The correct distances and angles are printed to the serial monitor.		3
<b>Part V: Pneumatic Missile Launcher</b> The Arduino prints the 10 sec countdown to the serial monitor, then fires the foam rocket.		4
<b>Part VI: Design Challenge 2</b> The turret locates the nearby target and strikes it with the foam rocket.		5
<b>Clean-up</b> The students returned the lab bench to its initial state.		2
<b>TOTAL</b>		24