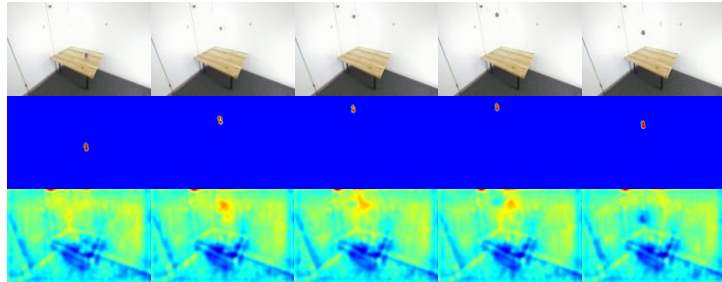
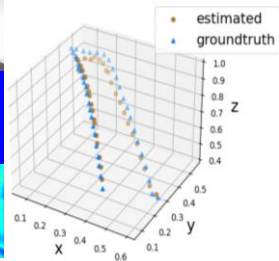


t_0 t_9 t_{18} t_{27} t_{36} 

world coordinates



camera coordinate depth

