## CSC718 Parallel Programming Midterm

Total: 100 points

Due by Midnight, Oct 16, 2022

(Midterm is a take-home exam. It includes four questions. The last one is a programming assignment. Please submit all your solutions and source code through D2L midterm Dropbox.)

- 1) (20 points) Binary semaphores only allow the integer to hold the values 0 and 1. However, binary semaphore are easier to implement than general semaphores. Here we demonstrate that a general semaphore can be implemented from a binary semaphore.
  - A structure of general semaphore is defined as below. It utilizes two binary semaphores. The binary semaphores support two functions.
  - b wait(s): decrements s if s>0. If not, the process executing is blocked.
  - b\_signal(s): increments s by 1 (does not change the value if s = 1). After the increment, a process waiting on s resumes its execution.

```
struct semaphore
{
        int value;
        int waiting = 0;
        b_semaphore queue = 0; // initialized to 0
        b semaphore mutex = 1; // initialized to 1
}
            void wait(struct semaphore *s)
                                                         void signal(struct semaphore *s)
                      b_wait(s->mutex);
                                                                   b_wait(s->mutex);
                      if (s->value == 0)
                                                                   if (s->waiting > 0)
                      {
                               s->waiting++;
                                                                            s->waiting--;
                               b_signal(s->mutex);
                               b_wait(s->queue);
                      }
                                                                   }
                                                                   else
                      else
                      {
                                                                   {
                               s->value--;
                                                                            s->value++;
                                                                            b_signal(s->mutex);
                      }
                                                                   }
            }
                                                         }
```

Figure 2

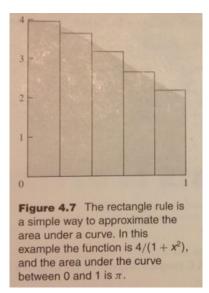
Two semaphore functions, wait(s) and signal(s) are given in Figure 2. However, there are three lines of code are missing. Fill the missing code in A, B, and C.

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- B. \_\_\_\_\_\_ C. \_\_\_\_\_
- (24 points) Assume n pieces of work forming into a one-dimensional array (0 to n-1), p
  processes, and block allocation (scatters larger blocks among processes) is used. Process rank i
  starts from 0.
  - a. What is the most pieces of work any process has?
  - b. What is the least pieces of work any process has?
  - c. How many processes have the most pieces of work?
  - d. What is the first element controlled by process i?
  - e. What is the last element controlled by process i?
  - f. Which process will have the control on element j?
- 3) (36 points) Programming Assignment: The value of the definite integral

$$\int_0^1 \frac{4}{1+x^2} dx$$

is  $\pi$ . We can use numerical integration to compute  $\pi$  by approximating the area under the curve. A simple way to do this is called the rectangle rule (Figure 4.7). We divide the interval [0,1] into k subintervals of equal size. We find the height of the curve at the midpoint of each of these subintervals. With these heights we can construct k rectangles. The area of the rectangles approximates the area under the curve. As k increases, the accuracy of the estimate also increases.



A C program that uses the rectangle rule to approximate  $\pi$  appears in Figure 4.8. The source code, pi.c, can be found in the class website. You can compile and run the program in Linux.

```
#include <stdio.h>
#define INTERVALS 1000000
int main(int argc, char* argv[])
{
    double area; /* The final answer */
    double ysum; /* Sum of rectangle heights */
    double xi; /* Midpoint of interval */
    int i;
    ysum= 0.0;
    for(i=0;i<INTERVALS;i++)
    {
        xi= ((1.0/INTERVALS)*(i+0.5)); /* Midpoint of interval */
        ysum += 4.0/(1.0 + xi*xi);
    }
        area=ysum*(1.0/INTERVALS);
    printf("Area is %13.11f\n",area);
    return 0;
}</pre>
```

Figure 4.8 A C program to compute the value of  $\pi$  using the rectangle rule.

- a. (10 points) Let INTERVALS=1000000, what is pi? Show your calculation result.
- b. (16 points) The program can be converted to a multithread program. A sample program, mthpi.c, has been provided as below. There are two lines, A and B, which are incomplete. Fill the blanks and complete the program.

c. (10 points) Fill the missing lines in mth-pi.c. Compile and run the program. Let INERVAL=1000000, what is pi? Is it the same value as your calculation result in a).

```
#include <pthread.h>
#include <stdio.h>
#define INTERVALS 1000000

#define THNUMS 3

// thread parametes
struct ThreadParams
{
    int id;  // id
    int low;  // start
```

```
int high;
                               // end
        double ysum;
                               // return partial sum
};
#define BLOCK_LOW(id, p, n)
                               ((id)*(n)/(p))
#define BLOCK_HIGH(id, p, n)
                              (BLOCK_LOW((id)+1,p,n)-1)
#define BLOCK_SIZE(id, p, n)
                               (BLOCK_HIGH(id, p, n)-BLOCK_LOW(id, p, n)+1)
// calculate pi partial sum
void *calcpi(void *arg)
        double ysum;
        double xi;
        int i;
       struct ThreadParams *pm = (struct ThreadParams*)arg;
       ysum = 0.0;
        for (i = pm->low; i <= pm->high; i++)
               xi=((1.0/INTERVALS)*(i+0.5));
               ysum=ysum+4.0/(1.0+xi*xi);
       }
        pm->ysum = ysum;
}
int main(int arc, char* argv[])
       struct ThreadParams ptharg[THNUMS];
        double area;
        double ysum;
        int i;
        pthread_t tid;
       void *status;
       // create multithreads to calculate partial sum
       ysum = 0.0;
        for (i = 0; i < THNUMS; i++)
        {
               ptharg[i].id = i;
               ptharg[i].low = _____
                                             Α
```

```
ptharg[i].high = ______;
               if (pthread_create(&tid, NULL, calcpi, (void*)&ptharg[i]) != 0)
               {
                       perror("error creating child");
                       return -1;
               }
               pthread_join(tid, &status);
       }
       // calculate total area
       area = 0;
       for (i = 0; i < THNUMS; i++)
       {
               area = area + ptharg[i].ysum;
       }
       area = area * (1.0/INTERVALS);
       printf("Area is %13.11f\n", area);
       return 0;
}
```

4) (20 points) Programming Assignment: Write a parallel program using MPI that computes the sum 1+2+...+p in the following manner: Each process i assigns the value i+1 to an integer, and then the processes perform a sum reduction of these values. Process 0 should print the result of the reduction. As a way of double checking the result, process 0 should also compute and print the value p(p+1)/2. Please benchmark the running time of the parallel program using the Rushmore cluster as discussed in the class.

	Np=1	Np=2	Np=3	Np=4
Execution time				