

# Chapter 13. Introduction to numerical methods for Partial Differential Equations

**Finite-Difference Method for Equation of Heat Transfer along a beam/rod of constant cross section**

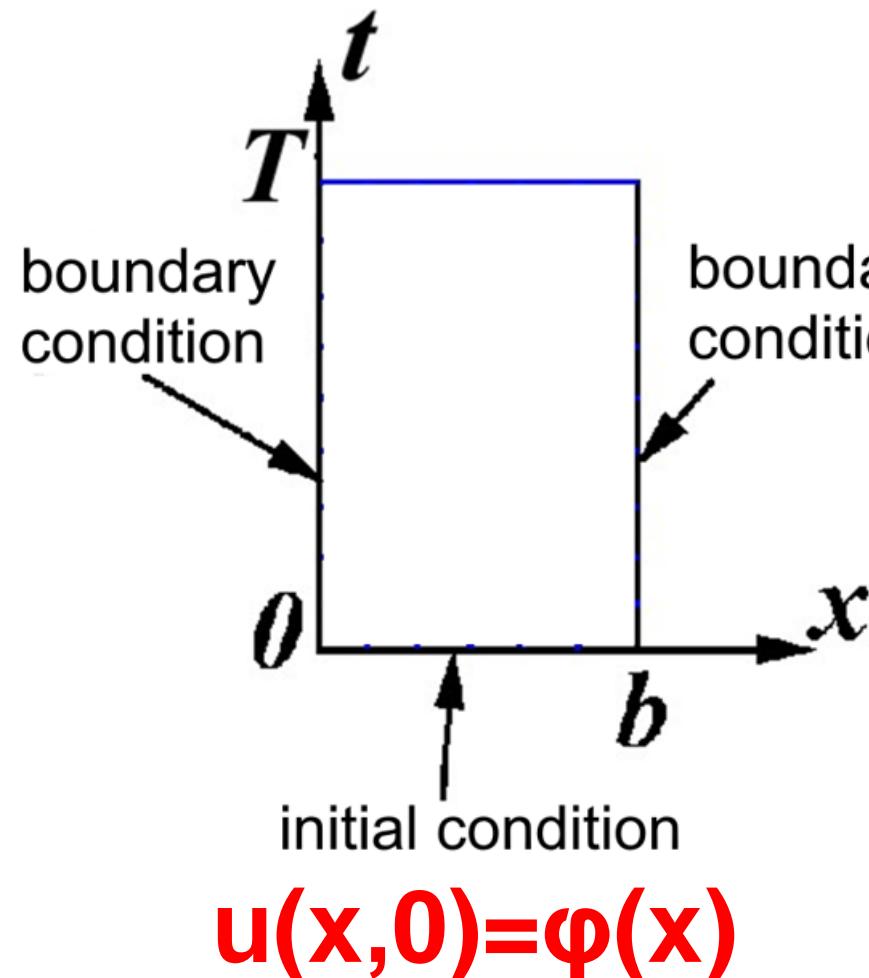
$$\frac{\partial u}{\partial t} - a^2 \frac{\partial^2 u}{\partial x^2} = f(x, t)$$

**$a=\text{const}$  ,  $f(x, t)$  is given in a rectangle**

$$0 < x < b, \quad 0 < t < T$$

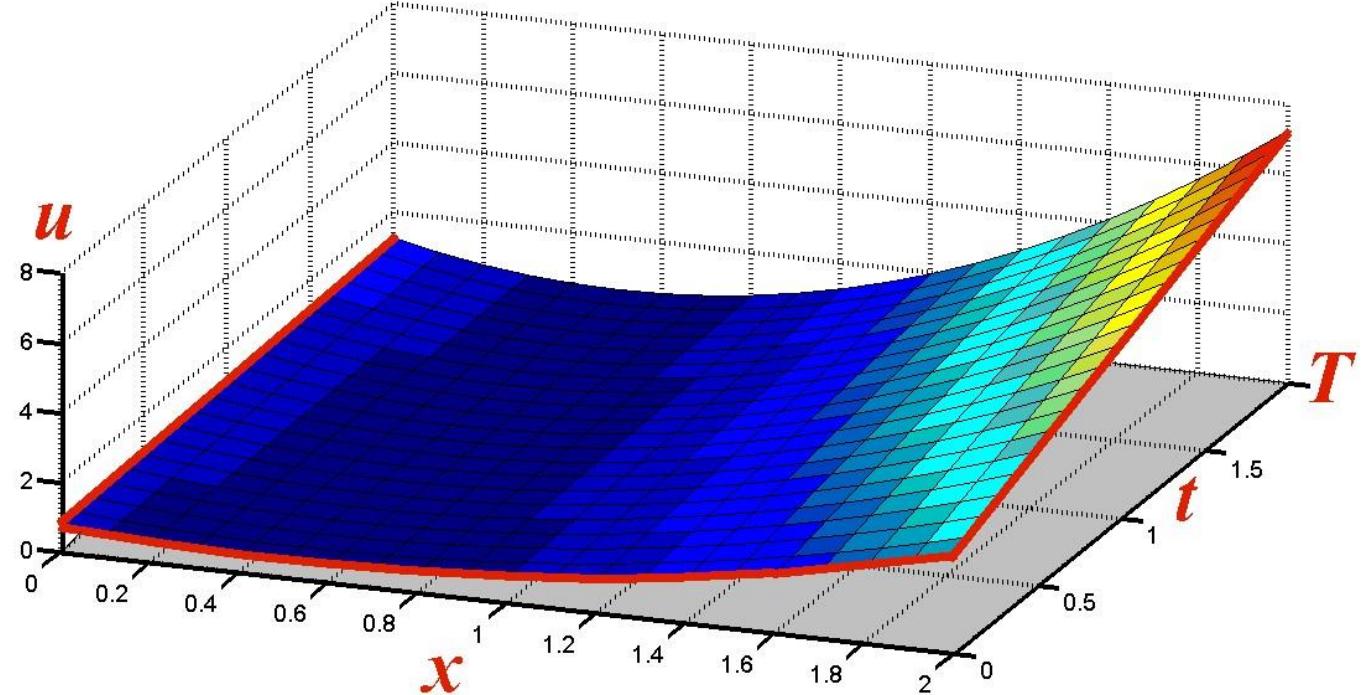
**The boundary and initial conditions are as follows:**

$$u(0,t) = \psi_1(t)$$



$$u(b,t) = \psi_2(t)$$

$$u(x,0) = \varphi(x)$$



If functions  $\varphi, \Psi_1, \Psi_2, f$  are continuous, and consistency conditions  $\varphi(0)=\Psi_1(t), \varphi(b)=\Psi_2(0)$  are satisfied, then there exists a unique solution  $u(x, t)$  of the problem (see a course of Mathematical Physics).

Let us split segment  $0 \leq x \leq b$  into  $n$  parts

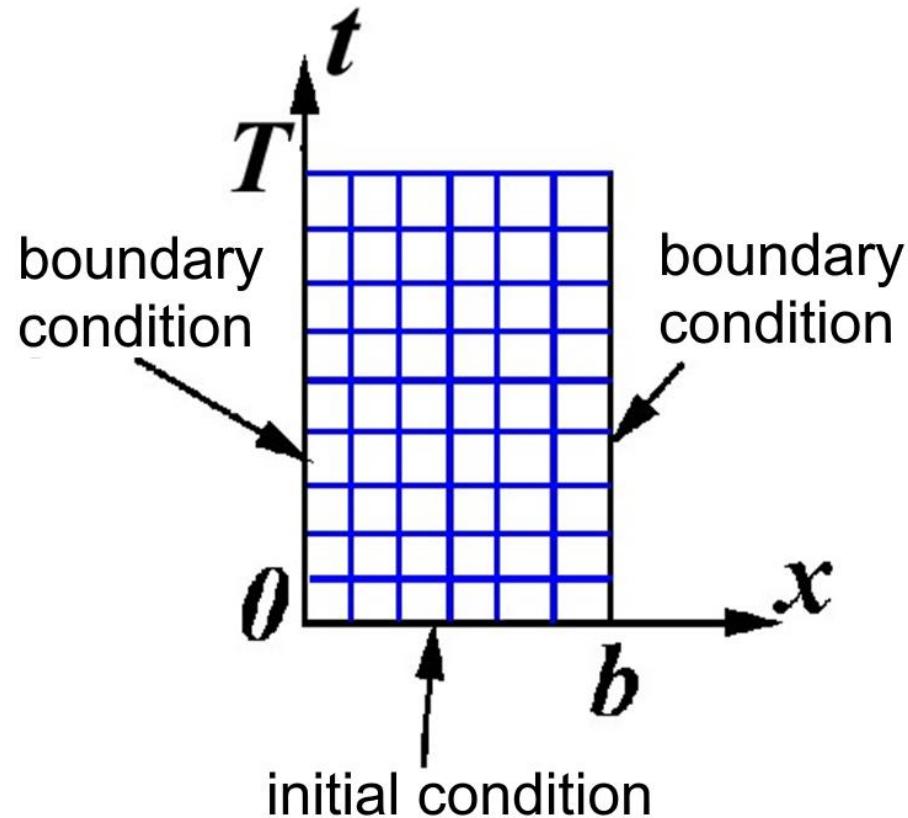
$$x_0 = 0, \quad x_1 = h, \quad x_2 = 2h, \dots, \quad x_n = b \quad h = (b-0)/n$$
$$i = 0, \quad 1, \quad 2, \dots, \quad n$$

and we split  $0 \leq t \leq T$  into  $m$  parts

$$t_0 = 0, \quad t_1 = \tau, \quad t_2 = 2\tau, \dots, \quad t_m = T \quad \tau = T/m$$
$$j = 0, \quad 1, \quad 2, \quad \dots, \quad m$$

By plotting horizontal and vertical lines, we obtain a mesh:

$$u(0,t) = \psi_1(t)$$



$$u(b,t) = \psi_2(t)$$

$$u(x,0) = \varphi(x)$$

**mesh nodes:**  $(x_i, t_j)$

Values of the exact solution at nodes:  $u(x_i, t_j)$   
For calculation of an approximate solution we  
use formulas from Chapter 11:

$$\frac{\partial u}{\partial t} \Big|_{i,j} = [u(x_i, t_{j+1}) - u(x_i, t_j)]/\tau + O(\tau)$$

$$\begin{aligned} \frac{\partial^2 u}{\partial x^2} \Big|_{i,j} = & [u(x_{i+1}, t_j) - 2u(x_i, t_j) + \\ & + u(x_{i-1}, t_j)]/h^2 + O(h^2) \end{aligned}$$

Inserting this into equation

$$\frac{\partial u}{\partial t} - a^2 \frac{\partial^2 u}{\partial x^2} = f(x, t)$$

we obtain at nodes

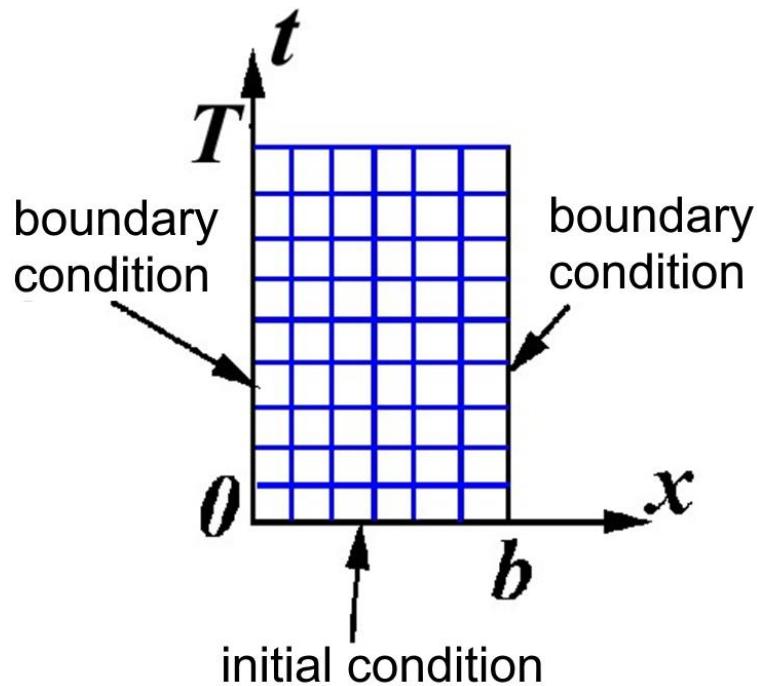
$$[u(x_i, t_{j+1}) - u(x_i, t_j)]/\tau + O(\tau) -$$

$$- a^2[u(x_{i+1}, t_j) - 2u(x_i, t_j) + u(x_{i-1}, t_j)]/h^2 + \\ + O(h^2) = f(x_i, t_j)$$

Omitting terms  $O()$ , we pass to the approximate equation

$$u_{i,j+1} - u_{i,j} - \tau a^2[u_{i+1,j} - 2u_{i,j} + u_{i-1,j}]/h^2 = \\ = \tau f(x_i, t_j)$$

$$u_{i,j+1} = u_{i,j} + [u_{i+1,j} - 2u_{i,j} + u_{i-1,j}] \tau a^2/h^2 + \\ + \tau f(x_i, t_j)$$



**At  $j=0$**  we know the initial distribution  $u_{i,0}$ , therefore it is possible to calculate  $u_{i,1}$  for  $i=1, 2, 3, \dots, n-1$  on the layer  $j=1$

$$u_{i,j+1} = u_{i,j} + [u_{i+1,j} - 2u_{i,j} + u_{i-1,j}] \tau a^2 / h^2 + \\ + \tau f(x_i, t_j)$$

Then we find  $u_{i,2}$  for  $i=1, 2, 3, \dots, n-1$  and so on up to  $u_{i,m}$

**Theorem** (On the stability and convergence of approximate solutions):

If  $\tau a^2/h^2 \leq 1/2$

then

$$\max_{i,j} |u(x_i, t_j) - u_{i,j}| = O(\tau + h^2)$$

*Example:*

```
tau=0.01
h=0.5
m=100
u= [50 60 35 5 15 40 60 40]
for i=1:8
    for j=1:m+1
        U(i,j)= u(i) ;
    end
end
for j= 1:m
    for i=2:7
        U(i,j+1)=U(i,j)+tau*(U(i+1,j)-2*U(i,j)+U(i-1,j))/(h*h)
+0.*tau*sin((i-1)*%pi/7)^2 ;
    end
end
[t,x]=meshgrid(1:m+1,1:8)
surf(x,t,U)
```

# Finite-Difference Method for Equation of Elastic String Oscillations

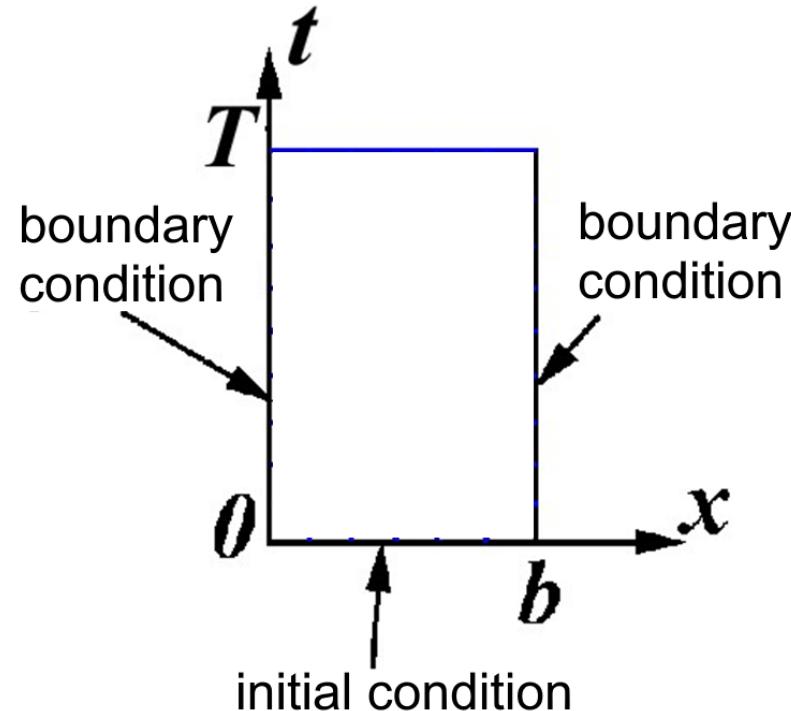
$$\frac{\partial^2 u}{\partial t^2} - a^2 \frac{\partial^2 u}{\partial x^2} = f(x, t)$$

where  $a=\text{const}$ , and  $f(x, t)$  is given in the rectangle  
 $0 < x < b, \quad 0 < t < T$



$$u(0,t) = \psi_1(t)$$

$$0 \leq t \leq T$$



$$u(b,t) = \psi_2(t)$$

$$u(x,0) = \varphi_1(x), \quad 0 \leq x \leq b$$

$$\frac{\partial u}{\partial t} \Big|_{t=0} = \varphi_2(x)$$

$$\begin{array}{lll}
 u(0,t) = \psi_1(t) & u(b,t) = \psi_2(t) & 0 \leq t \leq T \\
 \\ 
 u(x,0) = \varphi_1(x) & & 0 \leq x \leq b \\
 \\ 
 \partial u / \partial t \Big|_{t=0} = \varphi_2(x) & & 0 \leq x \leq b
 \end{array}$$

**Consistency at corner points:**

$$\varphi_1(0) = \psi_1(0), \quad \varphi_1(b) = \psi_2(0), \quad (*)$$

$$\varphi_2(0) = d\psi_1/dt \Big|_{t=0}, \quad \varphi_2(b) = d\psi_2/dt \Big|_{t=0}, \quad (**)$$

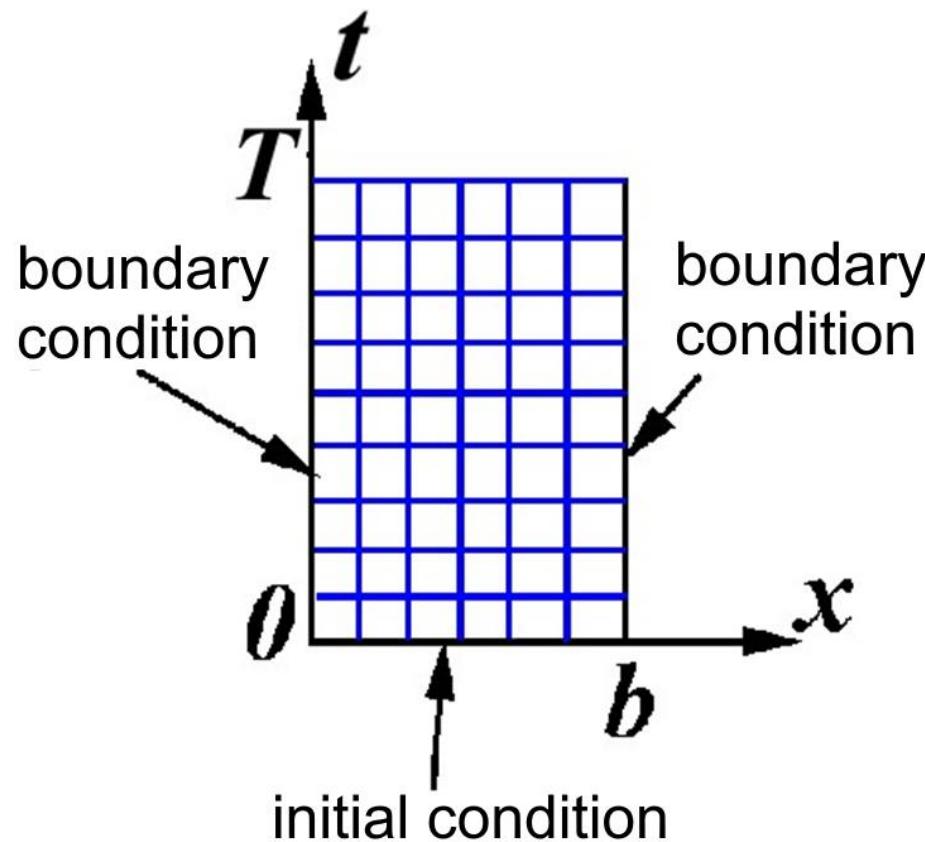
## Theorem:

If  $\varphi_1, \varphi_2, f$  are continuous functions;  $\Psi_1, \Psi_2$  have continuous derivative, and consistency conditions are true, there exists a unique solution of the problem (*see a course of Mathematical Physics*).

For calculation of an approximate solution we introduce a mesh

$$x_0 = 0, \quad x_1 = h, \quad x_2 = 2h, \dots, \quad x_n = b \quad h = (b - 0)/n$$
$$i = 0, \quad 1, \quad 2, \dots, \quad n$$

$$t_0 = 0, \quad t_1 = \tau, \quad t_2 = 2\tau, \dots, \quad t_m = T \quad \tau = T/m$$
$$j = 0, \quad 1, \quad 2, \quad \dots, \quad m$$



In order to calculate approximate solution at nodes  $(x_i, t_j)$ , we write differential equation at nodes and then pass to algebraic equations.

**True solution at nodes:  $u(x_i, t_j)$**

In order to obtain algebraic equations, we use formulas (see Chapter 11):

$$\frac{\partial^2 u}{\partial t^2} \Big|_{i,j} = [u(x_i, t_{j+1}) - 2u(x_i, t_j) + \\ + u(x_i, t_{j-1})]/\tau^2 + O(\tau^2)$$

$$\frac{\partial^2 u}{\partial x^2} \Big|_{i,j} = [u(x_{i+1}, t_j) - 2u(x_i, t_j) + \\ + u(x_{i-1}, t_j)]/h^2 + O(h^2)$$

**Substituting this into differential equation:**

$$\frac{\partial^2 u}{\partial t^2} - a^2 \frac{\partial^2 u}{\partial x^2} = f(x, t)$$

**we obtain**

$$[u(x_i, t_{j+1}) - 2u(x_i, t_j) + u(x_i, t_{j-1})]/\tau^2 + O(\tau^2) - \\ - a^2[u(x_{i+1}, t_j) - 2u(x_i, t_j) + u(x_{i-1}, t_j)]/h^2 + O(h^2) = f(x_i, t_j)$$

Omitting  $O(h^2)$ , we arrive at algebraic equation for the approximate solution

$$u_{i,j+1} = 2u_{i,j} - u_{i,j-1} + [u_{i+1,j} - 2u_{i,j} + \\ + u_{i-1,j}] \tau^2 a^2 / h^2 + \tau^2 f(x_i, t_j) \quad (***)$$

At  $j=0$  we know initial values

$$u_{i,0} = \Phi_1(x_i) \text{ and } \frac{\partial u}{\partial t} \Big|_{i=0} = \Phi_2(x_i), \text{ therefore}$$

$$(u_{i,1} - u_{i,0})/\tau \approx \Phi_2(x_i)$$

hence  $u_{i,1} = \varphi_1(x_i) + \tau\varphi_2(x_i)$

for all  $i=1, 2, 3, \dots, n-1$  *on the layer*  $j=1$

Now equation (\*\*\*) gives:

$u_{i,2}$  at  $i=1, 2, 3, \dots, n-1$

Then  $u_{i,3}$  at  $i=1, 2, 3, \dots, n-1$

and so on up to  $u_{i,m}$

Theorem on the stability and convergence: if

$$\tau^2 a^2 / h^2 \leq 1$$

then  $\max_{i,j} |u(x_i, t_j) - u_{i,j}| = O(\tau^2 + h^2)$

Example:  $f(x,t) \equiv 0$   $a \equiv 1$

Initial conditions:

$$u(x,0) = 50 \sin(3\pi x / b)$$

$$\partial u / \partial t = 0 \quad 0 \leq x \leq b, \quad b = 6$$

Boundary conditions:

$$u(b,t) = 0$$

$$u(0,t) = 40 \sin(1.5 t)$$

$$0 \leq t \leq T, \quad T = 15$$

```
clear // String oscillations
```

```
b=6
```

```
n=51
```

```
h= b/(n-1)
```

```
x=0:h:b
```

```
tau=0.1
```

```
for j=1:151
```

```
for i=1:n
```

```
U(i,j)= 50*sin(3*pi*x(i)/b)
```

```
// 1st initial condition and boundary condition on the right
```

```
end
```

```
end
```

```
for j= 2: 150
```

```
U(1,j)= 40*sin(1.5*tau*(j-1))
```

```
// boundary condition on the left
```

```
end
```

```

for i=1:n
fi2(i)= 0 // 2nd initial condition
end
for i=2:n-1 //
U(i,2)= U(i,1)+tau*fi2(i)
end
for j= 2: 150 //
for i=2: n-1 // all inner nodes
U(i,j+1) = 2*U(i,j)-U(i,j-1) +tau*tau*(U(i+1,j)-2*U(i,j)+U(i-1,j))/(h*h)
end
for i=1:n
u(i)=U(i,j+1) // for a graph
end
xgrid
plot(0,60,x',u,'r')

```

```
sleep(10)
plot(x',u,'b')
end // j
// [xx,tt]=meshgrid(1:151,1:n)
// surf(xx,tt,U)
```

# Finite-Difference Method for Solving Poisson's Equation

$$\frac{\partial^2 u}{\partial t^2} + a^2 \frac{\partial^2 u}{\partial x^2} = f(x, t)$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f(x, y)$$



Function  $f(x, y)$  is given in the rectangle

$$0 < x < b, \quad 0 < y < T$$

# Practical applications of the Poisson's equation: It governs

1) Potential of electrostatic field, where

$f(x,y)$  is density of distributed charges.

2) Velocity potential of fluid or gas stream (at low velocities, if viscosity is neglected), in this case  $f(x,y) \equiv 0$ .

3) Temperature of 2D-dimensional media in steady state, where

$f(x,y)$  is distribution of heat sources in the plane  $(x,y)$

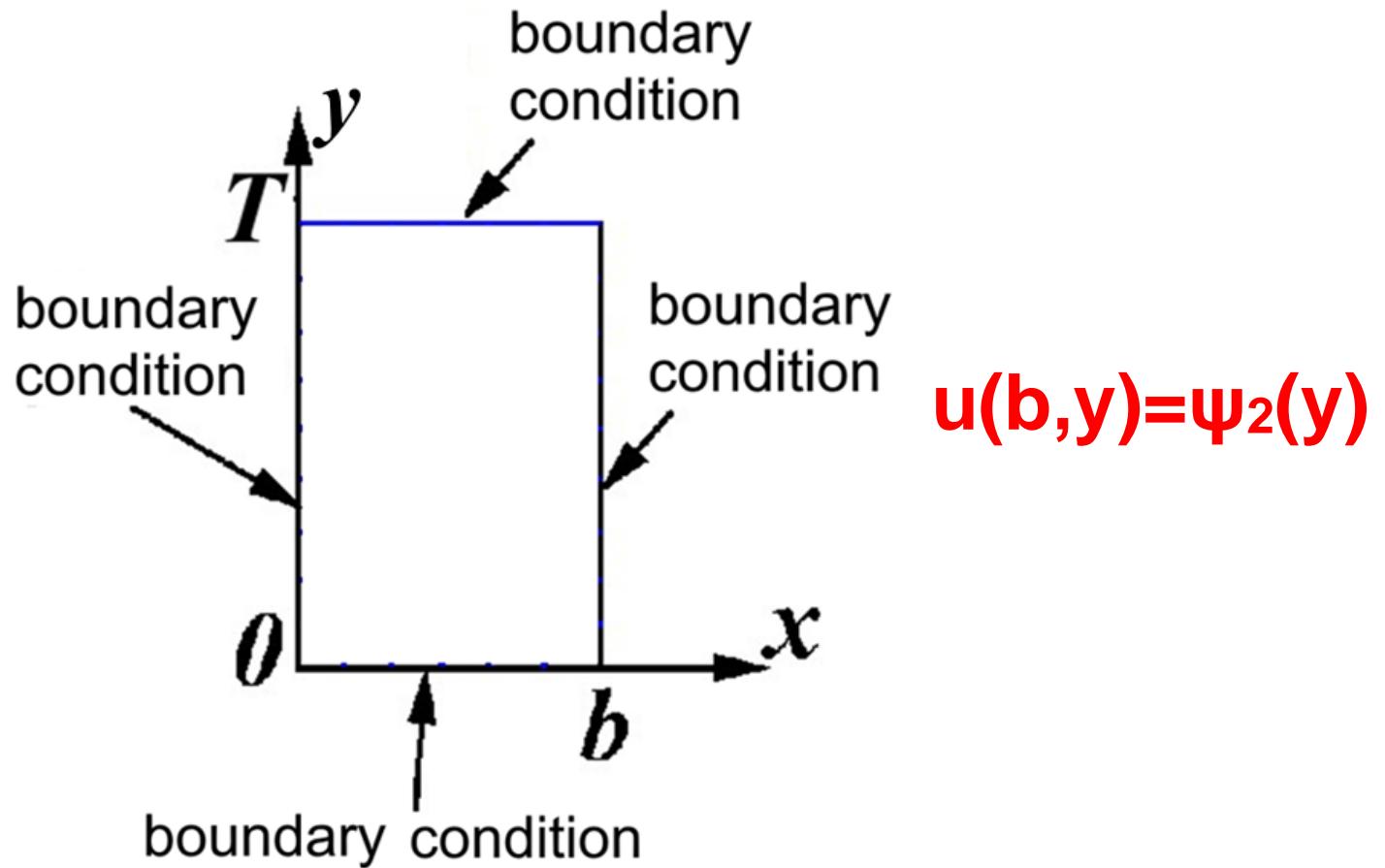


## Boundary conditions:

$$u(x, T) = \varphi_2(x) \quad 0 \leq x \leq b$$

$$u(0, y) = \psi_1(y)$$

$$0 \leq y \leq T$$



$$u(b, y) = \psi_2(y)$$

$$u(x, 0) = \varphi_1(x) \quad 0 \leq x \leq b$$

**Problem: find a solution of the equation**

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f(x, y)$$

**which equals to given boundary conditions on  
the sides of rectangle**

**Consistency conditions:**

$$\varphi_1(0) = \Psi_1(0), \quad \varphi_1(b) = \Psi_2(0), \quad (*)$$

$$\varphi_2(0) = \Psi_1(T), \quad \varphi_2(b) = \Psi_2(T), \quad (**)$$

## Theorem:

If functions  $\varphi_1, \varphi_2, \Psi_1, \Psi_2, f$  are continuous, and consistency conditions (\*), (\*\*) are satisfied, then there exists a unique solution of this problem (course of Math Physics).

For calculation of an approximate solution we introduce a mesh

$$x_0 = 0, \quad x_1 = h, \quad x_2 = 2h, \dots, \quad x_n = b \quad h = (b-0)/n$$

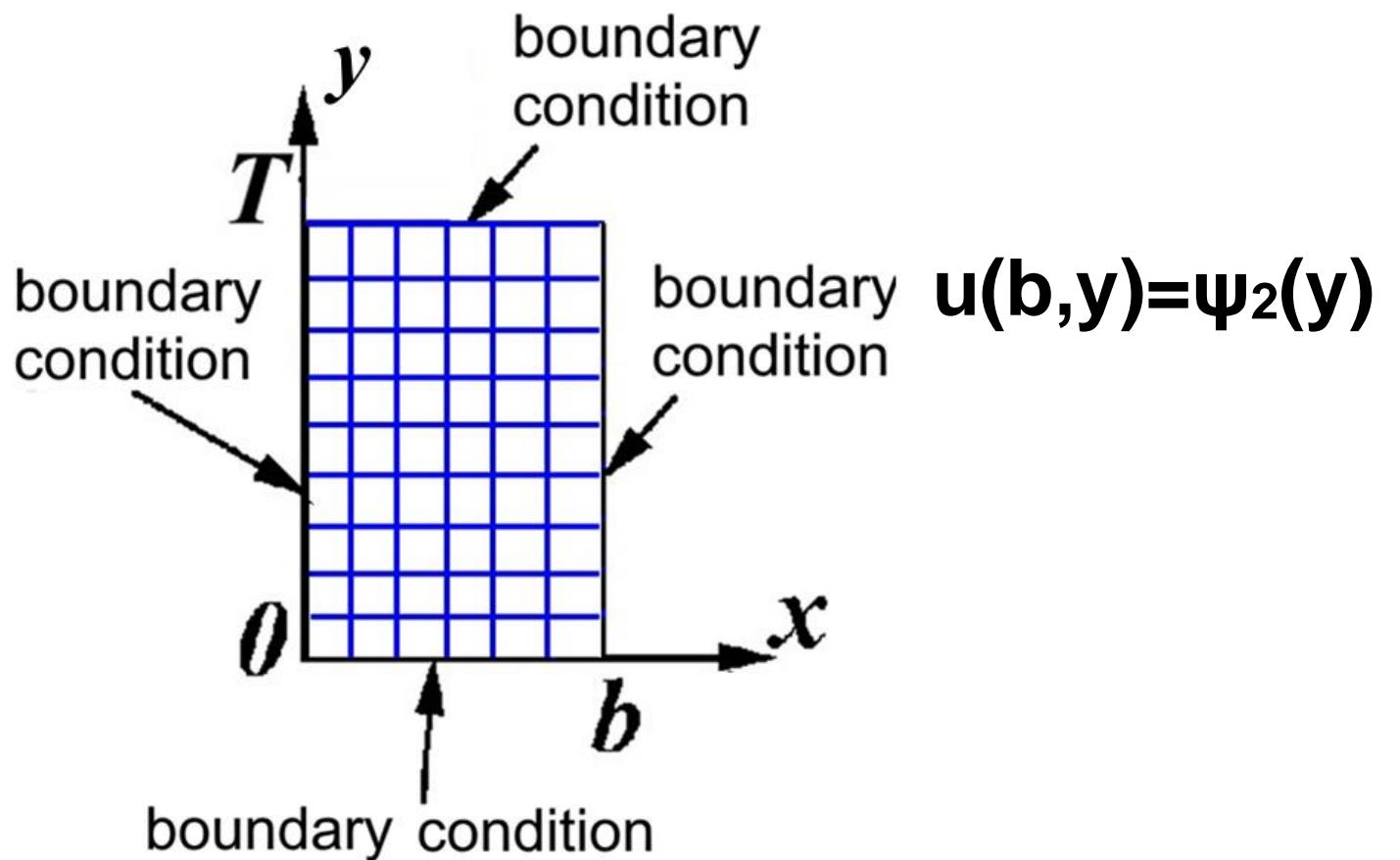
$$i = 0, \quad 1, \quad 2, \quad 3, \quad \dots, \quad n$$

$$y_0 = 0, \quad y_1 = \tau, \quad y_2 = 2\tau, \quad \dots, \quad y_m = T \quad \tau = (T-0)/m$$

$$j = 0, \quad 1, \quad 2, \quad \dots, \quad m$$

$$u(x, T) = \varphi_2(x) \quad 0 \leq x \leq b$$

$$u(0, y) = \psi_1(y) \quad 0 \leq y \leq T$$



$$u(x, 0) = \varphi_1(x) \quad 0 \leq x \leq b$$

Evidently,

$$\partial^2 u / \partial x^2 |_{i,j} \approx [u(x_{i+1}, x_j) - 2u(x_i, x_j) + u(x_{i-1}, x_j)] / h^2$$

$$\partial^2 u / \partial y^2 |_{i,j} \approx [u(x_i, y_{j+1}) - 2u(x_i, y_j) + u(x_i, y_{j-1})] / \tau^2$$

Let us insert this into equation

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f(x, y)$$

then we obtain at nodes  $(x_i, y_j)$

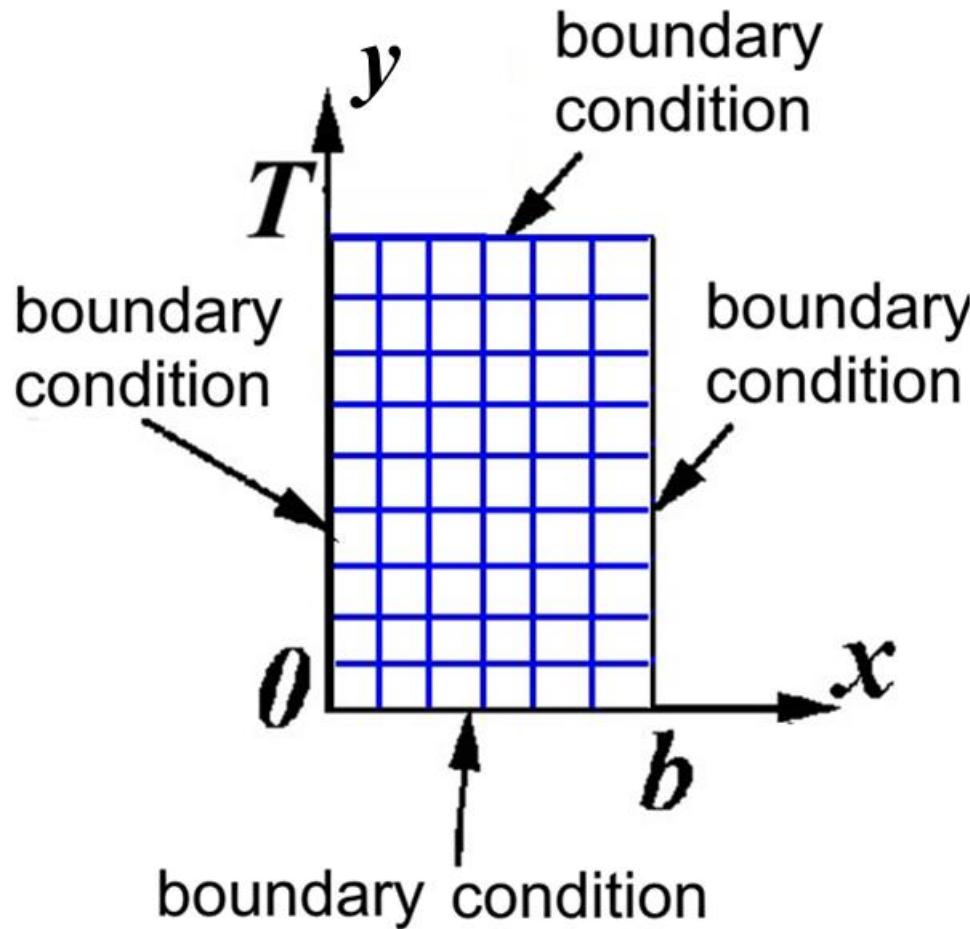
$$[u_{i+1, j} - 2u_{i, j} + u_{i-1, j}] / h^2 +$$

$$+[u_{i, j+1} - 2u_{i, j} + u_{i, j-1}] / \tau^2 = f(x_i, y_j)$$

For simplicity assume  $\tau=h$ , then

$$(u_{i+1,j} - 4u_{i,j} + u_{i-1,j}) + \\ + u_{i,j+1} + u_{i,j-1})/h^2 - f(x_i, y_j) = 0 \quad (***)$$

The number of unknowns is equal to number of inner nodes  $(n-1)*(m-1)$



**Gaussian's method of elimination of unknowns is inefficient if  $(n-1)*(m-1)$  is large.**

Therefore, it makes sense to use an iterative method:

$$\delta [(u_{i+1,j} - 4u_{i,j} + u_{i-1,j} + u_{i,j+1} + u_{i,j-1})/h^2 - f(x_i, y_j)] + u_{i,j} = u_{i,j}$$

$$\boxed{\delta [(u_{i+1,j} - 4u_{i,j} + u_{i-1,j} + u_{i,j+1} + u_{i,j-1})/h^2 - f(x_i, y_j)]^{(k)} + u_{i,j}^{(k)} = u_{i,j}^{(k+1)}}$$

[ This is analogous to the iteration method for systems of linear algebraic equations  $x^{(k+1)} = Cx^{(k)} + d$  ]

Clarification: Let us add derivative with respect to time into Poisson's equation

$$-\frac{\partial \textcolor{red}{u}}{\partial t} + \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f(x,y)$$

From Math Physics it is known that time-dependent solution tends to steady  $\hat{u}(x,y)$ :

$$u(x,y,t) \rightarrow \hat{u}(x,y) \quad \text{as} \quad t \rightarrow \infty.$$

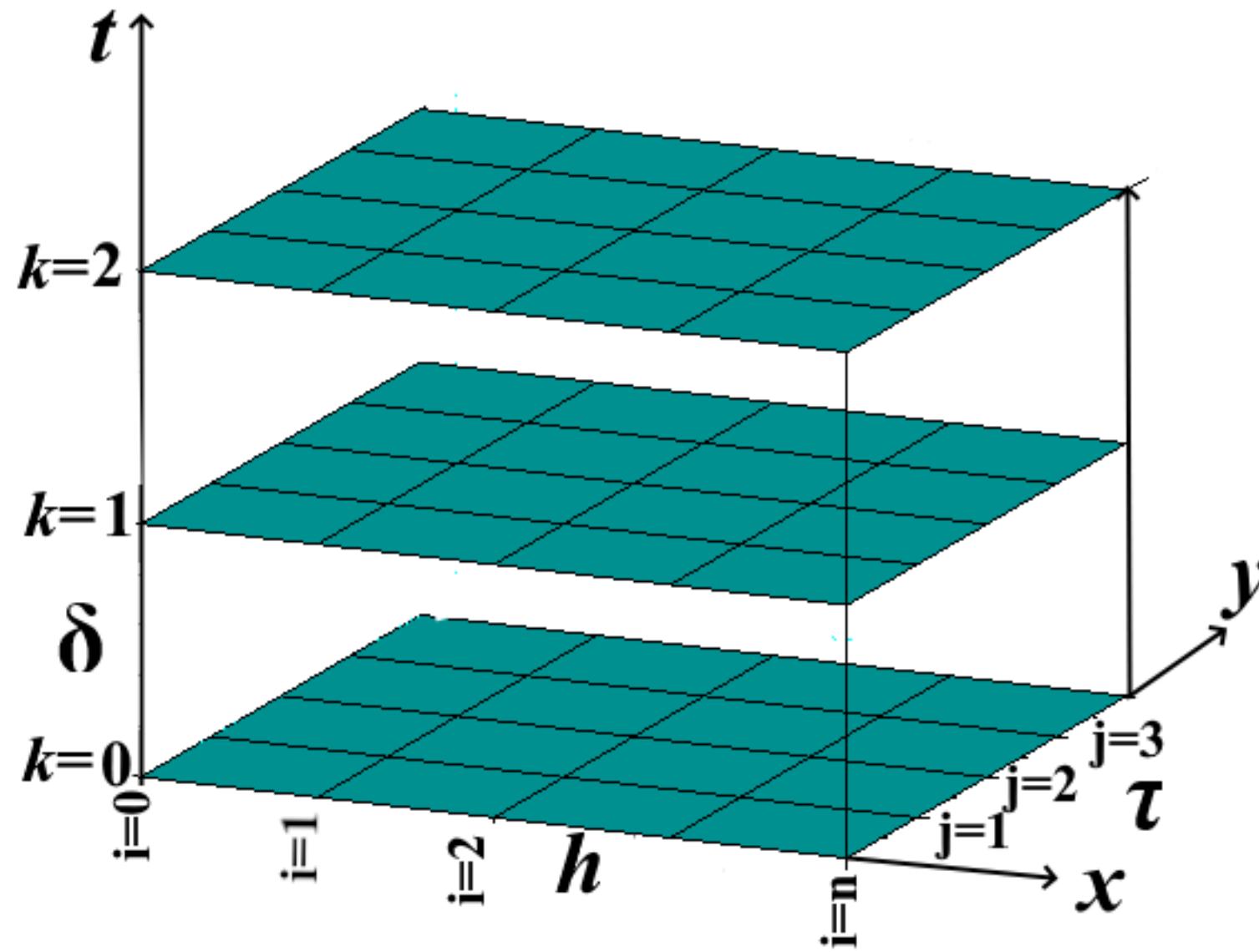
Due to  $\partial \hat{u}(x,y)/\partial t = 0$ , the function  $\hat{u}(x,y)$  is solution of the Poisson's equation.

Therefore the idea was to solve numerically the equation

$$-\frac{\partial \mathbf{u}}{\partial t} + \frac{\partial^2 \mathbf{u}}{\partial x^2} + \frac{\partial^2 \mathbf{u}}{\partial y^2} = f(x,y)$$

and find limit  $u(x,y,t) \rightarrow \hat{u}(x,y)$

# We introduce 3D mesh



and will seek  $u_{i,j,k}$

$$(u_{i+1,j,k} - 4u_{i,j,k} + u_{i-1,j,k} + u_{i,j+1,k} + \\ + u_{i,j-1,k})/h^2 - f(x_i, y_j) = \partial u(x, y)/\partial t \Big|_{i,j,k}$$

$$(u_{i+1,j,k} - 4u_{i,j,k} + u_{i-1,j,k} + u_{i,j+1,k} + \\ + u_{i,j-1,k})/h^2 - f(x_i, y_j) = (u_{i,j,k+1} - u_{i,j,k})/\delta$$

*$\delta$  is the time step, distance between layers*

$$\delta[(u_{i+1,j,k} - 4u_{i,j,k} + u_{i-1,j,k}) + u_{i,j+1,k} + \\ + u_{i,j-1,k})/h^2 - f(x_i, y_j)] + u_{i,j,k} = u_{i,j,k+1}$$

compare with the equation shown above:

$$\delta[(u_{i+1,j} - 4u_{i,j} + u_{i-1,j}) + u_{i,j+1} + \\ + u_{i,j-1})/h^2 - f(x_i, y_j)]^{(k)} + u_{i,j}^{(k)} = u_{i,j}^{(k+1)}$$

If  $\delta$  is chosen properly, then iterations  $u_{i,j}^{(k)}$  converge to a solution  $u_{i,j}$  of the algebraic system  $u_{i,j}^{(k)} \rightarrow u_{i,j}$

In its turn, solutions  $u_{i,j}$  of the algebraic system converge to a solution of the differential equation at  $\tau, h \rightarrow 0$ :

$$\max_{i,j} |u(x_i, y_j) - u_{i,j}| = O(\tau^2 + h^2) \rightarrow 0$$

# Notice on possible types of boundary conditions:

In practice, instead of the condition

$$u(0,y) = \psi_1(y) \quad \text{at} \quad 0 \leq y \leq T,$$

the condition of given derivative can be in need:

$$\frac{\partial u}{\partial x} \Big|_{x=0} = \Psi_1(y)$$

Then value  $u_{0,j}$  in the algebraic system (\*\*\*) is not known, i.e., value of solution on the left side of rectangle is not known.

In this case, at each  $k$ -step we must make an adjustment of  $u_{0,j}^{(k+1)}$  after calculation of  $u_{i,j}^{(k+1)}$  at inner nodes.

For the adjustment, we must use the condition of given derivative  $\frac{\partial u}{\partial x} \Big|_{x=0} = \Psi_1(y)$

The simplest formula:

$$u_{1,j} - u_{0,j} = h \psi_1(y_j) \rightarrow u_{0,j^{(k+1)}} = u_{1,j^{(k+1)}} - h \psi_1(y_j)$$

More accurate formula:

$$-3u_{0,j} + 4u_{1,j} - u_{2,j} = 2h \psi_1(y_j)$$

$$3u_{0,j} = 4u_{1,j} - u_{2,j} - 2h \psi_1(y_j)$$

$$u_{0,j^{(k+1)}} = [4u_{1,j^{(k+1)}} - u_{2,j^{(k+1)}} - 2h \psi_1(y_j)]/3$$

**Example:**  $f(x,y) = -5 * [\sin(x\pi/b) \sin(y\pi/b)]^4$ ,  
in the square  $0 < x < 6, 0 < y < 6$   
 $\partial u / \partial x = 2$  at  $x=0$  !

```
clear
delta=0.008
n=31
b=6
h= b/(n-1)
for j=1:n
for i=1:n
u(i,j)= 20 // zero approximation
end
end
// Boundary conditions on upper, lower and right sides
// we retain u=20
unew=u
```

```

for k= 1: 300 // simple iterations
for j= 2: n-1 //
for i=2: n-1
f = -5*(sin(h*(i-1)*%pi/b)*sin(h*(j-1)*%pi/b))^4 ;
unew(i,j)=u(i,j)+delta*((u(i,j+1)-4*u(i,j) +u(i,j-1) +
u(i+1,j) +u(i-1,j) ) /(h*h) -f ) ;
end // no i
// On the left boundary we prescribe heat flux
// du/dx=2 :
unew(1,j)=unew(2,j) - 2*h
end // j
u=unew
end // k
[xx,yy]=meshgrid(1:n,1:n)
surf(xx,yy,u)
xgrid

```

Shift of the heater to window:

$$f(x,y) = -35/[2+x^2+(y-3)^2]$$