

## Exercises (10 tasks, 5 points in total)

Each correctly solved task gives 0.5 points.

1. Let

$$f(x) = 10(x_2 - x_1^2)^2 + (1 - x_1)^2.$$

At  $x = (0, -1)$  draw the contour lines of the quadratic model

$$m_k(p) = f_k + g_k^T p + \frac{1}{2} p^T B_k p,$$

where  $B_k$  is the Hessian of  $f_k$ ,  $g_k = \nabla f(x_k)$  and  $f_k = f(x_k)$ . Draw the family of solutions of the trust-region subproblem

$$\min_{p \in \mathbb{R}^n} m_k(p) \quad \text{s.t. } \|p\| \leq \Delta_k,$$

as the trust region radius  $\Delta$  varies from 0 to 2. Repeat this at  $x = (0, 0.5)$ .

2. Write a program that implements the dogleg method. Choose  $B_k$  to be the exact Hessian. Apply it to solve Rosenbrock's function

$$f(x) = 100(x_2 - x_1^2)^2 + (1 - x_1)^2.$$

Experiment with the update rule for the trust region by changing the constants in the trust-region algorithm below, or by designing your own rules.

**Algorithm (Trust Region):**

- (a) Given  $\hat{\Delta} > 0$ ,  $\Delta_0 \in (0, \hat{\Delta})$ , and  $\eta \in [0, \frac{1}{4}]$ .
- (b) For  $k = 0, 1, 2, \dots$ :
  - i. Obtain  $p_k$  by (approximately) solving the subproblem above.
  - ii. Evaluate  $\rho_k$ .
  - iii. If  $\rho_k < \frac{1}{4}$ , set  $\Delta_{k+1} = \frac{1}{4}\Delta_k$ .
  - iv. Else if  $\rho_k > \frac{3}{4}$  and  $\|p_k\| = \Delta_k$ , set  $\Delta_{k+1} = \min(2\Delta_k, \hat{\Delta})$ .
  - v. Else set  $\Delta_{k+1} = \Delta_k$ .
  - vi. If  $\rho_k > \eta$ , set  $x_{k+1} = x_k + p_k$ , else  $x_{k+1} = x_k$ .

3. Theorem 14 (see Lecture Note 4) states that the sequence  $\{\|g_k\|\}$  has an accumulation point at zero. Show that if the iterates  $x_k$  stay in a bounded set  $B$ , then there is a limit point  $x_\infty$  of the sequence  $\{x_k\}$  such that

$$g(x_\infty) = 0.$$

4. Show that  $\tau_k$  defined by

$$\tau_k = \begin{cases} 1, & \text{if } g_k^T B_k g_k \leq 0, \\ \min\left(\frac{\|g_k\|^3}{\Delta_k g_k^T B_k g_k}, 1\right), & \text{otherwise,} \end{cases}$$

does indeed identify the minimizer of  $m_k$  along the direction  $-g_k$ .

5. The Cauchy–Schwarz inequality states that for any vectors  $u$  and  $v$ ,

$$|u^T v|^2 \leq (u^T u)(v^T v),$$

with equality only when  $u$  and  $v$  are parallel. When  $B$  is positive definite, use this inequality to show that

$$\gamma \stackrel{\text{def}}{=} \frac{\|g\|^4}{(g^T B g)(g^T B^{-1} g)} \leq 1,$$

with equality only if  $g$ ,  $Bg$ , and  $B^{-1}g$  are parallel.

6. Show that the following two root-finding updates are equivalent:

$$\lambda^{(\ell+1)} = \lambda^{(\ell)} - \frac{\phi_2(\lambda^{(\ell)})}{\phi'_2(\lambda^{(\ell)})}, \quad (\text{A})$$

and

$$\lambda^{(\ell+1)} = \lambda^{(\ell)} + \left( \frac{\|p_\ell\|}{\|q_\ell\|} \right)^2 (\|p_\ell\| - \Delta), \quad (\text{B})$$

using the identities

$$\frac{d}{d\lambda} \left( \|p(\lambda)\|^{-1} \right) = -\frac{1}{2} \|p(\lambda)\|^{-3} \frac{d}{d\lambda} \|p(\lambda)\|^2,$$

$$\frac{d}{d\lambda} \|p(\lambda)\|^2 = -2 \sum_{j=1}^n \frac{(q_j^T g)^2}{(\lambda_j + \lambda)^3},$$

and

$$\|q\|^2 = \sum_{j=1}^n \frac{(q_j^T g)^2}{(\lambda_j + \lambda)^3}.$$

7. Derive the solution of the two-dimensional subspace minimization problem in the case where  $B$  is positive definite.
8. Show that if  $B$  is any symmetric matrix, then there exists  $\lambda \geq 0$  such that  $B + \lambda I$  is positive definite.
9. Verify that the definitions

$$p_k^S = -\frac{\Delta_k}{\|D^{-1}g_k\|} D^{-2}g_k,$$

and

$$\tau_k = \begin{cases} 1, & \text{if } g_k^T D^{-2} B_k D^{-2} g_k \leq 0, \\ \min\left(\frac{\|D^{-1}g_k\|^3}{\Delta_k g_k^T D^{-2} B_k D^{-2} g_k}, 1\right), & \text{otherwise,} \end{cases}$$

are valid for the Cauchy point in the case of an elliptical trust region, where  $D$  is a diagonal scaling matrix with positive diagonal elements.

10. Consider the trust-region subproblem

$$\min_{p \in \mathbb{R}^n} m_k(p) = f_k + g_k^T p + \frac{1}{2} p^T B_k p \quad \text{s.t. } \|p\| \leq \Delta_k.$$

Suppose  $B_k$  is positive definite. Prove that if the unconstrained minimizer  $p_B = -B_k^{-1}g_k$  satisfies  $\|p_B\| \leq \Delta_k$ , then  $p_B$  is also the solution of the trust-region subproblem. Otherwise, the solution lies on the boundary  $\|p\| = \Delta_k$ .