Minimal counterexamples to Hendrickson's conjecture on globally rigid graphs

Georg Grasegger*

In this paper we consider the class of graphs which are redundantly d-rigid and (d+1)-connected but not globally d-rigid, where d is the dimension. This class arises from counterexamples to a conjecture by Bruce Hendrickson. It seems that there are relatively few graphs in this class for a given number of vertices. Using computations we show that $K_{5,5}$ is indeed the smallest counterexample to the conjecture.

In this paper we consider the class of graphs which are redundantly d-rigid and (d+1)-connected but not globally d-rigid, where d is the dimension. This class arises from counterexamples to a conjecture by Bruce Hendrickson. It seems that there are relatively few graphs in this class for a given number of vertices. Using computations we show that $K_{5,5}$ is indeed the smallest counterexample to the conjecture.

1 Introduction

The basis of the class of graph we consider is the following theorem from Hendrickson.

Theorem 1 (Hendrickson [9]). A globally d-rigid graph with at least d + 2 vertices is (d+1)-connected and redundantly d-rigid.

Hendrickson conjectured that the reverse direction of the theorem also holds. While this is true for $d \in \{1,2\}$ [10], it was shown to be false in any higher dimension [1] using some bipartite graphs. Since then further counterexamples were found [3, 12]. Still very little is known on the set of graphs which are (d+1)-connected and redundantly d-rigid

^{*}Johann Radon Institute for Computational and Applied Mathematics (RICAM), Austrian Academy of Sciences, Altenberger Straße 69, 4040 Linz, Austria

but not globally rigid. In this paper we computationally show that the well-known $K_{5,5}$ is indeed the smallest counterexample in dimension three.

Before starting the proof, we recall some definitions and results from rigidity theory. A framework (G, ρ) consisting of a graph G and a placement ρ of the vertices in d-dimensional space is d-rigid if edge-length preserving continuous motions can only arise from isometries in that space. A graph is d-rigid, if the framework with any generic placement is d-rigid. Redundant d-rigidity is obtained if the graph is d-rigid and remains so after removal of any of its edges. A graph is globally d-rigid, if all frameworks which yield the same edge-lengths, indeed also yield the same distances between all pairs of non-adjacent vertices. A graph that is redundantly d-rigid and (d+1)-connected but not globally d-rigid, i. e. a counterexample to Hendrickson's conjecture, we call an H_d -graph in this paper.

If the number of vertices is comparably low with respect to the dimension then Hendrickson's conjecture has been proven to hold.

Theorem 2 (Jordán [11, Thm. 3.2]). A graph G = (V, E) with $d + 2 \le |V| \le d + 4$ is globally d-rigid if and only if it is (d + 1)-connected and redundantly d-rigid.

In this paper we extend the theorem to $|V| \le d + 6$.

2 Computations

In this section we describe what computations we were able to do and what software we used for that.

Minimally rigid graphs with n vertices in dimension d do have $dn - \binom{d+1}{2}$ edges. We use GENG (a part of NAUTY [15, 14]) to generate such graphs. With a plugin by Martin Larsson [13] this process can be sped up using sparsity properties of rigid graphs, i. e. edge counts on subgraphs. However, not all of these graphs are indeed d-rigid. We then use RIGICOMP [7], a MATHEMATICA package, to check for rigidity. Hence, we obtain lists of all minimally rigid graphs with a certain number of vertices for dimension $d \leq 23$. We then can construct all d-rigid graphs by adding edges or we use GENG instead for getting graphs with at least $dn - \binom{d+1}{2}$ edges and check rigidity for all of them. From those we can select the (d+1)-connected and redundantly d-rigid ones (see Table 1). Since redundantly rigid graphs have at least $dn - \binom{d+1}{2} + 1$ edges, we can ignore all minimally rigid ones. The set of redundantly d-rigid graphs is made available at [6].

We then compute, again with RIGICOMP, the globally d-rigid ones from these lists (see Table 2). The list of globally rigid graphs is available at [5]. Since checking redundant rigidity seems to be the slowest computation we may also first compute rigid, then the non-globally rigid ones. From those we check connectivity and only in the end we compute redundancy.

	V	V $d=3$		d = 4		5	d = 6	d = 7	d =	8
	d+2	1	-	1		1	1	1		1
	d+3	3	3	3		3	3	3		3
	d+4	19)	22		23	24	24	2	4
	d+5	304	ŀ	531	75	56	900	984	102	1
	d+6	12055	4	7 777	12885	55 24	6302	362922	44858	37
	d+7	1079143	11 62	3 750 7	78 033 04	11				
V	d =	9 d=	10 d:	= 11	d = 12	d = 1	13 d	= 14	l = 15	d = 16
d+1	2	1	1	1	1		1	1	1	1
d + 3	3	3	3	3	3		3	3	3	3
d + d	4	24	24	24	24	2	24	24	24	24
d + d	5 10	40 10	47 1	l 051	1052	105	53	1053	1053	1053
$d + \epsilon$	6 4982	32 5225	17 533	3 0 9 2 5	37457	539 20	03 53	9 912 5	40194	540313
	V	d = 17	d = 18	d = 19	9 d=	= 20	d = 21	d = 22	d = d	: 23
_	d+2	1	1	-	1	1	1	1	1	1
	d+3	3	3	;	3	3	3	;	3	3
	d+4	24	24	24	1	24	24	24	1	24
	d+5	1053	1053	1053	3 1	053	1053	1053	3 1	053
_	d+6	540 360	540381	540 389	540	393	540 394	540 395	540	395

Table 1: Number of redundantly d-rigid and (d + 1)-connected graphs for different dimensions.

V	d = 3	d = 4	d = 5	d = 6	d = 7	d = 8
d+2	1	1	1	1	1	1
d+3	3	3	3	3	3	3
d+4	19	22	23	24	24	24
d+5	304	531	756	900	984	1021
d+6	12055	47777	128855	246302	362922	448587
d+7	1079142	11623749	78033040			

Table 2: Number of globally d-rigid graphs for different dimensions. For $|V| \le d+6$ this is the same as Table 1.

Note, that RIGICOMP provides both a probabilistic relatively fast computation which might give false negatives and a symbolic implementation (both based on [4]). For $|V| \leq d+5$ we can use the symbolic approach. For more vertices we used the probabilistic method. Nevertheless, for $|V| \leq d+6$ we get an exact answer due to the following.

Let us first assume we want to have all minimally rigid graphs. Every minimally rigid graph is tight which means it has $d|V| - {d+1 \choose 2}$ edges and every induced subgraph with $|V'| \geq d$ vertices has at most $d|V'| - {d+1 \choose 2}$ edges. These tight graphs are those that we get from initial computations from GENG with the plugin [13]. Not all of them, however, are rigid. The remaining ones are either flexible circuits or 0-extensions thereof or contain a non-tight circuit as a spanning subgraph. In [8] flexible circuits with at most d+6 vertices have been fully classified. Hence, we have a deterministic answer for minimal rigidity in that case. Computationally we may first use the probabilistic procedure and in case of a negative answer do check via flexible circuits. We can do similarly when checking d-rigidity (i. e. containing a spanning minimally rigid graph) and redundant

rigidity by tracing back to minimal rigidity. Hence, for $|V| \le d + 6$ the results are deterministic. For d = 3 also the computation for |V| = d + 7 was done symbolically.

The computations show that all redundantly d-rigid graphs that are also (d + 1)connected are indeed globally d-rigid if $|V| \leq d + 6$. For |V| = d + 7 we see that $K_{5,5}$ and successive cones give the only H_d -graphs at least until d = 5. The cone of a graph is obtained by adding a new vertex and edges from it to all the existing vertices (compare [16, 2]). This construction we also call coning.

3 Main Results

From the computations and some edge counting we can state the following main theorem.

Theorem 3. A graph G = (V, E) with $d+2 \le |V| \le d+6$ is globally d-rigid if and only if it is (d+1)-connected and redundantly d-rigid.

For the proof we use two basic statements.

Lemma 4. Let G = (V, E) be a redundantly d-rigid graph with $d \ge 23$, n = |V| = d + k and $k \le 6$. Then G has a vertex of degree n - 1.

Proof. Since G is redundantly d-rigid it has $dn - \binom{d+1}{2} + \ell$ edges for some $\ell \geq 1$. We assume for contradiction that all vertices have degree less than n-1. Then

$$0 = \sum_{v \in V} \deg(v) - 2|E|$$

$$\leq n(n-2) - 2(dn - \binom{d+1}{2} + \ell)$$

$$= (d+k)(d+k-2) - 2d(d+k) + d(d+1) - 2\ell$$

$$= (d+k)(k-d-2) + d(d+1) - 2\ell = k^2 - d^2 - 2d - 2k + d^2 + d - 2\ell$$

$$= k^2 - 2k - d - 2\ell < 24 - d - 2\ell$$

But this cannot be true for $d \geq 23$ and therefore G has a vertex of degree n-1.

Let G be a graph and let G' be constructed from G by coning. Coning preserves several properties in rigidity while increasing the dimension. Rigidity is proven to be preserved by [16]. This means that a graph is d-rigid if and only if the cone is (d+1)-rigid. The same is true for global rigidity due to [2]. If the cone G' is redundantly (d+1)-rigid, then it is easy to see that G is redundantly d-rigid. From this we get the following Lemma.

Lemma 5. Let $d \ge 23$ and let G = (V, E) be a redundantly d-rigid and (d+1)-connected graph with n = |V| = d + k and $k \le 6$. If G is not globally d-rigid then there exists an H_{d-1} -graph with n-1 vertices.

Proof. By Lemma 4 we know that G has a vertex of degree n-1. Hence, removing this vertex gives a graph G' that is redundantly (d-1)-rigid by and d-connected but not globally (d-1)-rigid on n-1 vertices.

Together with the computational results we can finally proof the main theorem.

Proof of Theorem 3. Let G be a redundantly d-rigid and (d+1)-connected graph with $|V| \leq d+6$. If $d \leq 22$, then we have seen from the computations that G is globally d-rigid. Assuming $d \geq 23$ we know from Lemma 5 that if G was not globally d-rigid then the removal of a vertex with degree n-1, which does exist, gives a non-globally (d-1)-rigid graph that is d-connected and redundantly (d-1)-rigid graph. If d-1=22 we know from the computations that such a graph does not exist. If $d-1\geq 23$ we continue inductively. This proves that G is globally d-rigid.

4 Examples

It is known from [1] that $K_{5,5}$ is an H_3 -graph. By successive coning we get H_d -graphs for all $d \geq 3$ by [2]. More generally, it is known from [1] that $K_{m,n}$ is an H_d -graph if $m+n=\binom{d+2}{2}$ and $m,n\geq d+2$. This means that there are two H_4 -graphs $K_{6,9}$ and $K_{7,8}$ with 15 vertices each, which is out of the computational scope of this paper.

For d = 3 a construction of six globally 3-rigid graphs, glued in a cycle (see for example Figure 1a) gives an H_3 -graph due to [12]. In Figure 1b we show an example of such a gluing with $K_{5,5}$, i.e., a non-globally 3-rigid base graph, which also gives an H_3 -graph as shown by computations. Both these graphs are not minimal in terms of edge counts with respect to the H_3 property. Indeed we can find five edges (indicated in red in the figures) that we can remove such that the result is still an H_3 -graph.

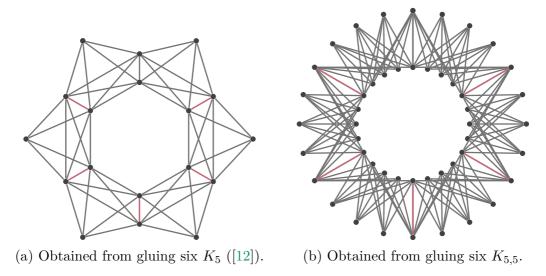


Figure 1: Two H_3 -graphs.

5 Conclusion

While the computations were handy to show that there are no other small counterexamples to Hendrickson's conjecture other than the known ones, they are insufficient for a full classification. Nevertheless, we think that computational experiments might reveal new counterexamples. For this, however either some more theory or improved software/hardware is needed.

6 Acknowledgments

This work was partially supported by the Austrian Science Fund (FWF): P31888.

References

- [1] Robert Connelly. On generic global rigidity. In Bernd Sturmfels and Peter Gritzmann, editors, Applied geometry and discrete mathematics: The Victor Klee Festschrift, volume 4 of DIMACS Series in Discrete Mathematics and Theoretical Computer Science, pages 147–155. 1991. doi:10.1090/dimacs/004.
- [2] Robert Connelly and Walter J. Whiteley. Global rigidity: The effect of coning. Discrete & Computational Geometry, 43(4):717–735, 2010. doi:10.1007/s00454-009-9220-0.
- [3] Samuel Frank and Jiayang Jiang. New classes of counterexamples to Hendrickson's global rigidity conjecture. *Discrete & Computational Geometry*, 45(3):574–591, 2011. doi:10.1007/s00454-010-9259-y.
- [4] Steven J. Gortler, Alexander D. Healy, and Dylan P. Thurston. Characterizing generic global rigidity. *American Journal of Mathematics*, 132(4):897–939, 2010. doi:10.1353/ajm.0.0132.
- [5] Georg Grasegger. Dataset of globally rigid graphs. Zenodo, 2022. doi:10.5281/zenodo.7473053.
- [6] Georg Grasegger. Dataset of redundantly rigid graphs. Zenodo, 2022. doi:10.5281/zenodo.7473079.
- [7] Georg Grasegger. RigiComp A Mathematica package for computational rigidity of graphs. Zenodo, 2022. doi:10.5281/zenodo.7457820.
- [8] Georg Grasegger, Hakan Guler, Bill Jackson, and Anthony Nixon. Flexible circuits in the d-dimensional rigidity matroid. *Journal of Graph Theory*, 100(2):315–330, 2022. doi:10.1002/jgt.22780.
- [9] Bruce Hendrickson. Conditions for unique graph realizations. SIAM Journal on Computing, 21(1):65–84, 1992. doi:10.1137/0221008.

- [10] Bill Jackson and Tibor Jordán. Connected rigidity matroids and unique realizations of graphs. *Journal of Combinatorial Theory*, *Series B*, 94(1):1–29, 2005. doi:10.1016/j.jctb.2004.11.002.
- [11] Tibor Jordán. A note on generic rigidity of graphs in higher dimension. *Discrete Applied Mathematics*, 297:97–101, 2021. doi:10.1016/j.dam.2021.03.003.
- [12] Tibor Jordán, Csaba Király, and Shin-ichi Tanigawa. Generic global rigidity of body-hinge frameworks. *Journal of Combinatorial Theory, Series B*, 117:59–76, 2016. doi:10.1016/j.jctb.2015.11.003.
- [13] Martin Larsson. Nauty Laman plugin, 2021. Downloaded February 2021. URL: https://github.com/martinkjlarsson/nauty-laman-plugin.
- [14] Brendan D. McKay and Adolfo Piperno. Practical graph isomorphism, II. *Journal of Symbolic Computation*, 60:94–112, 2014. doi:10.1016/j.jsc.2013.09.003.
- [15] Brendan D. McKay and Adolfo Piperno. Nauty & traces version 2.7, 2021. URL: http://pallini.di.uniroma1.it.
- [16] Walter Whiteley. Cones, infinity and one-story buildings. Structural Topology, 8:53-70, 1983. URL: https://hdl.handle.net/2099/1003.