

Distance Between Point and Circle or Disk in 3D

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Contents

1	Point and Circle	2
2	Point and Disk	3

1 Point and Circle

A circle in 3D is represented by a center \mathbf{C} , a radius R , and a plane containing the circle, $\mathbf{N} \cdot (\mathbf{X} - \mathbf{C}) = 0$ where \mathbf{N} is a unit length normal to the plane. If \mathbf{U} and \mathbf{V} are also unit length vectors so that \mathbf{U} , \mathbf{V} , and \mathbf{N} form a right-handed orthonormal coordinate system (the matrix with these vectors as columns is orthonormal with determinant 1), then the circle is parameterized as

$$\mathbf{X} = \mathbf{C} + R(\cos(\theta)\mathbf{U} + \sin(\theta)\mathbf{V}) =: \mathbf{C} + R\mathbf{W}(\theta)$$

for angles $\theta \in [0, 2\pi)$. Note that $|\mathbf{X} - \mathbf{C}| = R$, so the \mathbf{X} values are all equidistant from \mathbf{C} . Moreover, $\mathbf{N} \cdot (\mathbf{X} - \mathbf{C}) = 0$ since \mathbf{U} and \mathbf{V} are perpendicular to \mathbf{N} , so the \mathbf{X} lie in the plane.

For each angle $\theta \in [0, 2\pi)$, the squared distance from a specified point \mathbf{P} to the corresponding circle point is

$$F(\theta) = |\mathbf{C} + R\mathbf{W}(\theta) - \mathbf{P}|^2 = R^2 + |\mathbf{C} - \mathbf{P}|^2 + 2R(\mathbf{C} - \mathbf{P}) \cdot \mathbf{W}.$$

The problem is to minimize $F(\theta)$ by finding θ_0 such that $F(\theta_0) \leq F(\theta)$ for all $\theta \in [0, 2\pi)$. Since F is a periodic and differentiable function, the minimum must occur when $F'(\theta) = 0$. Also, note that $(\mathbf{C} - \mathbf{P}) \cdot \mathbf{W}$ should be negative and as large in magnitude as possible to reduce the right-hand side in the definition of F . The derivative is

$$F'(\theta) = 2R(\mathbf{C} - \mathbf{P}) \cdot \mathbf{W}'(\theta)$$

where $\mathbf{W} \cdot \mathbf{W}' = 0$ since $\mathbf{W} \cdot \mathbf{W} = 1$ for all θ . The vector \mathbf{W}' is unit length vector since $\mathbf{W}'' = -\mathbf{W}$ and $0 = \mathbf{W} \cdot \mathbf{W}'$ implies $0 = \mathbf{W} \cdot \mathbf{W}'' + \mathbf{W}' \cdot \mathbf{W}' = -1 + \mathbf{W}' \cdot \mathbf{W}'$. Finally, \mathbf{W}' is perpendicular to \mathbf{N} since $\mathbf{N} \cdot \mathbf{W} = 0$ implies $0 = \mathbf{N} \cdot \mathbf{W}'$. All conditions imply that \mathbf{W} is parallel to the projection of $\mathbf{P} - \mathbf{C}$ onto the plane and points in the same direction.

Let \mathbf{Q} be the projection of \mathbf{P} onto the plane. Then

$$\mathbf{Q} - \mathbf{C} = \mathbf{P} - \mathbf{C} - (\mathbf{N} \cdot (\mathbf{P} - \mathbf{C}))\mathbf{N}.$$

The vector $\mathbf{W}(\theta)$ must be the unitized projection $(\mathbf{Q} - \mathbf{C})/|\mathbf{Q} - \mathbf{C}|$. The closest point on the circle to \mathbf{P} is

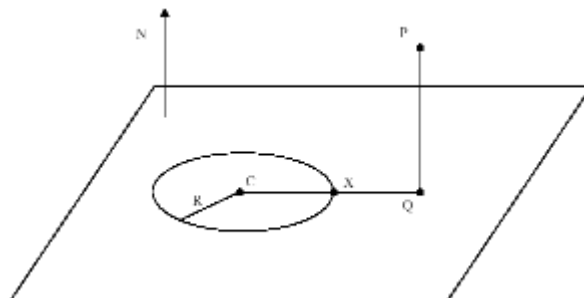
$$\mathbf{X} = \mathbf{C} + R \frac{\mathbf{Q} - \mathbf{C}}{|\mathbf{Q} - \mathbf{C}|}$$

assuming that $\mathbf{Q} \neq \mathbf{C}$. The distance from point to circle is then $|\mathbf{P} - \mathbf{X}|$.

If the projection of \mathbf{P} is exactly the circle center \mathbf{C} , then all points on the circle are equidistant from \mathbf{C} . The distance from point to circle is the length of the hypotenuse of any triangle whose vertices are \mathbf{C} , \mathbf{P} , and any circle point. The lengths of the adjacent and opposite triangle sides are R and $|\mathbf{P} - \mathbf{C}|$, so the distance from point to circle is $\sqrt{R^2 + |\mathbf{P} - \mathbf{C}|^2}$.

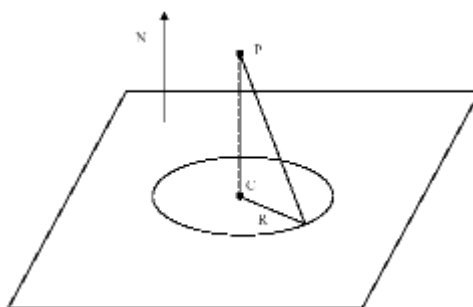
The typical case where \mathbf{P} does not project to circle center is shown in Figure 1.1.

Figure 1.1 Typical case, closest point to circle.



The case when \mathbf{P} does project to circle center is shown in Figure 1.2.

Figure 1.2 Typical case, closest point to circle.



2 Point and Disk

This requires a minor modification of the point and circle algorithm. The disk is the set of all points $\mathbf{X} = \mathbf{C} + \rho \mathbf{W}(\theta)$ where $0 \leq \rho \leq R$. If the projection of \mathbf{P} is contained in the disk, then the projection is already the closest point to \mathbf{P} . If the projection is outside the disk, then the closest point to \mathbf{P} is the closest point on the disk boundary, a circle.

Figure 2.1 shows the case when \mathbf{P} projects inside the disk.

Figure 2.1 Closest point when \mathbf{P} projects inside the disk.

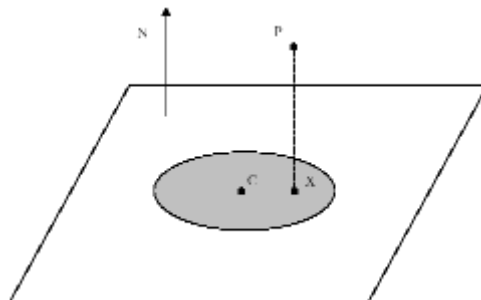


Figure 2.2 shows the case when \mathbf{P} projects outside the disk.

Figure 2.2 Closest point when \mathbf{P} projects outside the disk.

