

# A Collinearity Test Independent of Input Point Order

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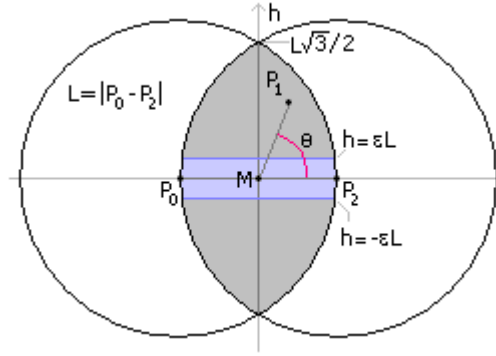
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# 1 Discussion

Given three points  $\mathbf{Q}_i$ ,  $0 \leq i \leq 2$ , construct an algorithm for determining collinearity that is order-independent when implemented in a floating point number system. Within that system the points can be labeled as collinear when they are “nearly” collinear with a suitable definition for what means “nearly”.

Let  $i_0$  and  $i_2$  be the indices of those points that are farthest apart. Let  $i_1$  be the other index. Define  $\mathbf{P}_j = \mathbf{Q}_{i_j}$ . Points  $\mathbf{P}_0$  and  $\mathbf{P}_2$  are farthest apart. Figure 1.1 shows the region that must contain  $\mathbf{P}_1$ . This region is the intersection of two circles centered at  $\mathbf{P}_0$  and  $\mathbf{P}_2$ , each of radius  $L = |\mathbf{P}_0 - \mathbf{P}_1|$ .

**Figure 1.1** The region that must contain  $\mathbf{P}_1$ .



The violet region in the figure contains those points within distance  $\varepsilon L$ ,  $\varepsilon \in [0, \sqrt{3}/2]$ , from the line segment connecting  $\mathbf{P}_0$  and  $\mathbf{P}_2$ . For a user-selected small  $\varepsilon$ , if  $\mathbf{P}_1$  is in the violet region we will say that the points are (nearly) collinear.

Mathematically it is sufficient to calculate the length of the projection of  $\mathbf{P}_1 - \mathbf{P}_0$  onto the orthogonal complement of the line through  $\mathbf{P}_0$  and  $\mathbf{P}_2$ , then compare that value to  $\varepsilon L$ . However, this has the potential to be order-dependent since swapping the roles  $\mathbf{P}_0$  and  $\mathbf{P}_2$  could lead to some numerical significance between the projections of  $\mathbf{P}_1 - \mathbf{P}_0$  and  $\mathbf{P}_1 - \mathbf{P}_2$ . Instead define  $\mathbf{M} = (\mathbf{P}_0 + \mathbf{P}_2)/2$  and project  $\mathbf{\Delta} = \mathbf{P}_1 - \mathbf{M}$  onto the orthogonal complement. That distance is  $|\mathbf{\Delta} - (\mathbf{U} \cdot \mathbf{\Delta})\mathbf{U}|$  where  $\mathbf{U} = (\mathbf{P}_2 - \mathbf{P}_0)/L$ . In squared terms,

$$|\mathbf{\Delta}|^2 - (\mathbf{U} \cdot \mathbf{\Delta})^2 \leq \varepsilon^2 L^2 \quad \text{or} \quad |\mathbf{\Delta}|^2 \leq (\mathbf{U} \cdot \mathbf{\Delta})^2 + (\varepsilon L)^2$$

Without vector normalization, the test is

$$L^2 |\mathbf{\Delta}|^2 \leq ((\mathbf{P}_2 - \mathbf{P}_0) \cdot \mathbf{\Delta})^2 + \varepsilon^2 L^4.$$

If  $\mathbf{V} = \mathbf{\Delta}/L$ , then the test is also equivalent to

$$|\mathbf{V}| \sin \theta \leq \varepsilon$$

where  $\theta$  is the angle between  $\mathbf{U}$  and  $\mathbf{V}$ . The left-hand side, when multiplied by  $L$ , is just the projection of  $\mathbf{P}_1 - \mathbf{M}$  onto the vertical axis. In geometric terms this requires either the length of  $\mathbf{P}_1 - \mathbf{M}$  to be small compared to that of  $\mathbf{P}_2 - \mathbf{P}_0$  or the angle between these two vectors to be small.