#### Lecture 19:

# Solving directional dynamic games for all Markov perfect equilibria

Econometric Society Summer Schools in Dynamic Structural Econometrics

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#### **ROAD MAP**

- 1. Collusion of Australian corrugated fibre packaging (CFP) producers
  - Collusion between Amcor and Visy
  - Bertrand pricing and investment game
  - Solution concept: Markov perfect equilibrium (MPE)
- 2. Experiment with the model
- 3. State recursion algorithm
  - ► Theory of directional dynamic games (DDGs)
- 4. Recursive lexicographical search (RLS) algorithm
- 5. Full solution for the leapfrogging game
- Structural estimation of directional dynamic games with Nested RLS method

# Estimation of directional dynamic games: Full solution nested MLE estimation

Nested Recursive Lexicographic Search algorithm

## Markov Perfect Equilibria

- MPE is a pair of strategy profile and value functions
- In compact notation

$$V = \Psi^{V}(V, P, \theta)$$
  
 $P = \Psi^{P}(V, P, \theta)$ 

Set of all Markov Perfect Equilibria

$$SOL(\Psi, \theta) = \left\{ (P, V) \middle| \begin{array}{c} V = \Psi^{V}(V, P, \theta) \\ P = \Psi^{P}(V, P, \theta) \end{array} \right\}$$

- $\blacktriangleright \ \Psi^{V}: \ V,P \longrightarrow V \ Bellman \ operator$
- $\blacktriangleright$   $\Psi^{P}: V, P \longrightarrow P$  Choice probability formulas (logit)
- $ightharpoonup \Gamma: P \longrightarrow V$  Hotz-Miller inversion

## Estimation methods for dynamic stochastic games

- ► Two step (CCP) estimators
  - Fast, potentially large finite sample biases
  - Hotz, Miller (1993); Altug, Miller (1998); Pakes, Ostrovsky, and Berry (2007); Pesendorfer, Schmidt-Dengler (2008)
    - 1. Estimate  $CCP \rightarrow \hat{P}$
    - 2. Method of moments Minimal distance Pseudo likelihood

$$\begin{split} \min_{\boldsymbol{\theta}} \left[ \hat{P} - \boldsymbol{\Psi}^{P}(\boldsymbol{\Gamma}(\boldsymbol{\theta}, \hat{P}), \hat{P}, \boldsymbol{\theta}) \right]' \boldsymbol{W} \left[ \hat{P} - \boldsymbol{\Psi}^{P}(\boldsymbol{\Gamma}(\boldsymbol{\theta}, \hat{P}), \hat{P}, \boldsymbol{\theta}) \right] \\ \max_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{Z}, \boldsymbol{\Psi}^{P}(\boldsymbol{\Gamma}(\boldsymbol{\theta}, \hat{P}), \hat{P}, \boldsymbol{\theta})) \end{split}$$

- Nested pseudo-likelihood (NPL)
  - ► Recursive two step pseudo-likelihood
  - ▶ Bridges the gap between efficiency and tractability
  - Unstable under multiplicity
  - Aguirregabiria, Mira (2007); Pesendorfer, Schmidt-Dengler (2010); Kasahara and Shimotsu (2012); Aguirregabiria, Marcoux (2021)

## Estimation methods for dynamic stochastic games

- Equilibrium inequalities (BBL)
  - Minimize the one-sided discrepancies
  - Computationally feasible in large models
  - Bajari, Benkard, Levin (2007)
- Math programming with equilibrium constraints (MPEC)
  - MLE as constrained optimization
  - Does not rely on the structure of the problem
  - ► Much bigger computational problem
  - 闻 Su (2013); Egesdal, Lai and Su (2015)

$$\max_{(\theta,P,V)} \mathcal{L}(Z,P) \text{ subject to } V = \Psi^V(V,P,\theta), P = \Psi^P(V,P,\theta)$$

- All solution homotopy MLE
  - Borkovsky, Doraszelsky and Kryukov (2010)

#### Overview of NRLS

- ► Robust and *computationally feasible*<sup>(?)</sup> MLE estimator for directional dynamic games (DDG)
- Rely of full solution algorithm that provably computes all MPE under certain regularity conditions
- Employ smart discrete programming method to maximize likelihood function over the finite set of equilibria
- ► Fully robust to multiplicity of MPE
- ► Relax single-equilibrium-in-data assumption
- ▶ Path to estimation of equilibrium selection rules

## Nested Recursive Lexicographical Search (NRLS)

- ▶ Data from M independent markets from T periods  $Z = \{a^{jt}, x^{jt}\}_{j \in \{1,...,N\}, t \in \{1,...,T\}}$
- Let the set of all MPE equilibria be  $\mathcal{E} = \{1, \dots, K(\theta)\}$
- 1. Outer loop

Maximization of the likelihood function w.r.t. to structural parameters  $\boldsymbol{\theta}$ 

$$\theta^{ML} = \arg\max_{\theta \in \Theta} \mathcal{L}(Z, \theta)$$

2. Inner loop

Maximization of the likelihood function w.r.t. equilibrium selection

$$\mathcal{L}(Z, \theta) = \arg \max_{k \in \{1, \dots, K(\theta)\}} \mathcal{L}(Z, \theta, V_{\theta}^{k})$$

Max of a function on a discrete set organized into RLS tree

## Likelihood over the state space

• Given equilibrium k choice probabilities  $P_i^k(a|x)$ , likelihood is

$$\mathcal{L}(Z, \theta, V_{\theta}^k) = \sum_{j=1}^{N} \sum_{t=1}^{T} \sum_{i=1}^{J} \log P_i^k(a_i^{jt}|x^{jt}; \theta)$$

- Let  $\iota$  index points in the state space  $\iota = 1$  initial point,  $\iota = S$  the terminal state
- ▶ Denote  $n_{\iota}$  the number of observations in state  $x_{\iota}$  and  $n_{\iota}^{a_{i}}$  the number of observations of player i taking action  $a_{i}$  at  $x_{\iota}$

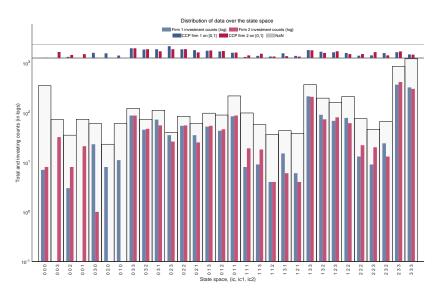
$$n_{\iota} = \sum_{j=1}^{N} \sum_{t=1}^{T} \mathbb{1}\{x^{jt} = x_{\iota}\} \qquad n_{\iota}^{a_{i}} = \sum_{j=1}^{N} \sum_{t=1}^{T} \mathbb{1}\{a_{i}^{jt} = a_{i}, x^{jt} = x_{\iota}\}$$

Then equilibrium-specific likelihood can be computed as

$$\mathcal{L}(Z, \theta, V_{\theta}^{k}) = \sum_{\iota=1}^{S} \sum_{i=1}^{J} \sum_{a} n_{\iota}^{a_{i}} \log P_{i}^{k}(a|x_{\iota}; \theta)$$

## Data distribution over the state space

1000 markets, 5 time periods, init at apex of the pyramid



## Branch and bound (BnB) method

# Land and Doig, 1960 Econometrica

- ▶ Old method for solving discrete programming problems
- ► Maximizing/minimizing a function over a discrete set
- 1. Form a tree of subdivisions of the set of admissible plans
- Specify a bounding function representing the best attainable objective on a given subset
  - Monotonicity: the bounding function has to be weakly decreasing in the cardinality of the set argument (for max problem)
  - ▶ Has to equal the criterion function when computed at singletons
- 3. Dismiss the subsets of the plans where the bound is below the current best attained value of the objective
- ► There are several flavors of BnB method, differences in implementation
- ▶ There are several extensions to the BnB method

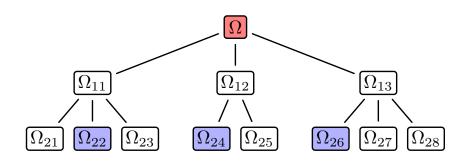
# Theory of BnB: branching

$$\max f(x)$$
 s.t.  $x \in \Omega$ 

$$f(x): \mathbb{R}^n \to \mathbb{R} \ \text{ objective function}$$
 
$$\Omega \ \text{ set of feasible } x$$
 
$$\mathcal{P}_j(\Omega) \ \text{ partition of } \Omega \ \text{ into } k_j+1 \ \text{ subsets, } k_0=0, \ \mathcal{P}_0(\Omega)=\Omega$$
 
$$\mathcal{P}_j(\Omega)=\{\Omega_{j1},\ldots,\Omega_{jk_j}: \ \Omega_{ji}\cap\Omega_{ji'}=\varnothing, i\neq i', \ \cup_{i=1}^{k_j}\Omega_{ji}=\Omega\}$$
 
$$\{\mathcal{P}_j(\Omega)\}_{j=1,\ldots,J} \ \text{ a sequence of } J \ \text{ gradually refined partitions}$$
 
$$0=k_0\leq k_1\leq \cdots \leq k_J$$
 
$$|\Omega|\geq \max_i |\Omega_{k_1i}|\geq \cdots \geq \max_i |\Omega_{k_ji}|\geq \cdots \geq \max_i |\Omega_{k_Ji}|$$
 
$$\forall j=1,\ldots,J, \forall i=1,\ldots,k_j, \forall j'< j: \ \exists i'\in\{1,\ldots,k_{j'}\} \ \text{ such that } \Omega_{ji}\subset\Omega_{j'i'}$$

# Theory of BnB: branching

$$\max f(x)$$
 s.t.  $x \in \Omega$ 



# Theory of BnB: bounding

$$\max f(x)$$
 s.t.  $x \in \Omega$ 

 $g(\Omega_{ij}): 2^{\Omega} \to \mathbb{R}$  bounding function: from subsets of  $\Omega$  to real line  $g(\{x\}) = f(x)$  for singletons, i.e. when  $\Omega_{ij} = \{x\}$ 

#### Monotonicity of bounding function

$$\forall \Omega_{j_1,i_1} \supset \Omega_{j_2,i_2} \supset \cdots \supset \Omega_{j_k,i_k}$$
 $g(\Omega_{j_1,i_1}) \ge g(\Omega_{j_2,i_2}) \ge \cdots \ge g(\Omega_{j_k,i_k})$ 

Inequalities should be reversed for the minimization problem

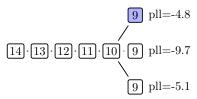
#### BnB with NRLS

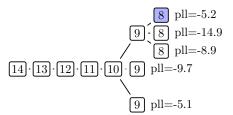
- **▶ Branching**: RLS tree
- Bounding: The bound function is partial likelihood calculated on the subset of states that

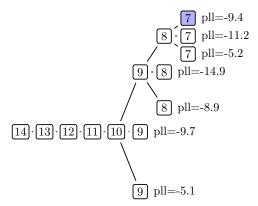
$$\mathcal{L}^{\mathsf{Part}}(Z, \theta, \mathcal{S}) = \frac{1}{M} \sum_{i=1}^{N} \sum_{m=1}^{M} \sum_{t=1}^{T} \log P_{i}^{\ell}(a_{i}^{jt}|x^{jt}; \theta)$$
s.t.  $(x^{jt}, a_{i}^{jt}) \in \mathcal{S}$ 

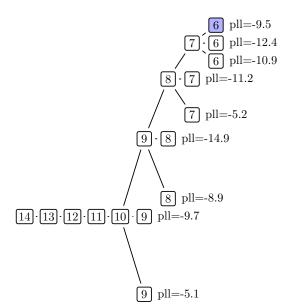
- ► Monotonically declines as more data is added
- Equals to the full log-likelihood at the leafs of RLS tree

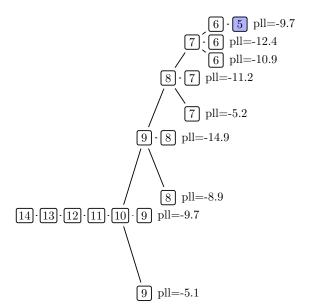
 $\fbox{14} \cdot \fbox{13} \cdot \fbox{12} \cdot \fbox{11} \cdot \fbox{10} \text{ Partial loglikelihood} = -3.2$ 

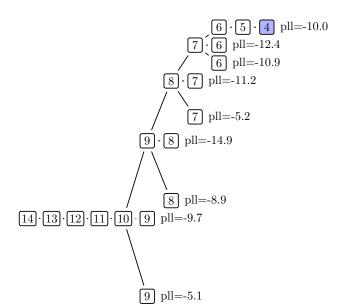


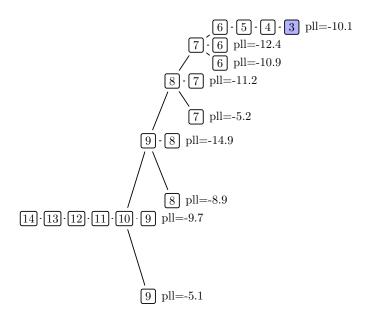


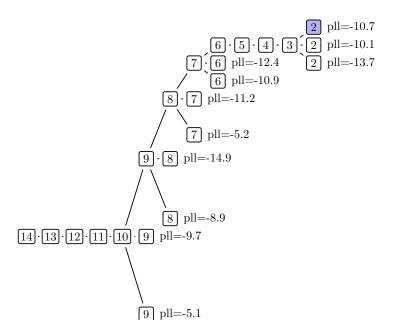


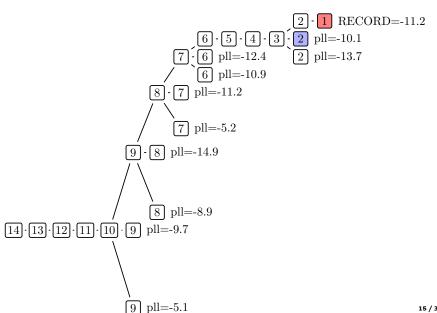


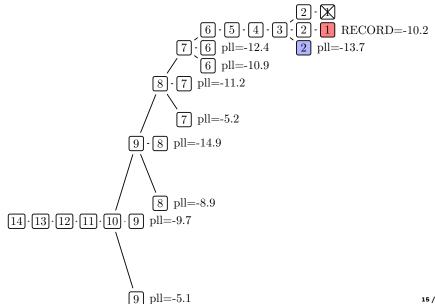


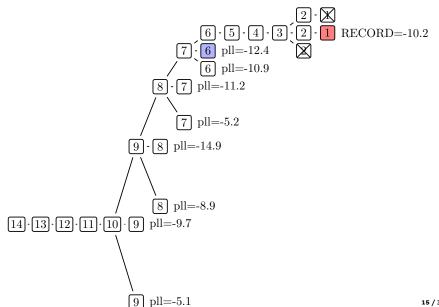


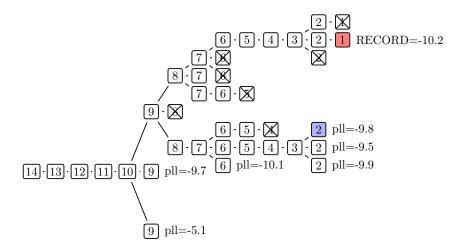


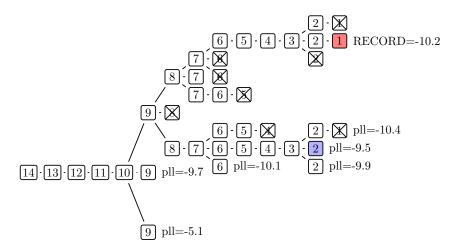


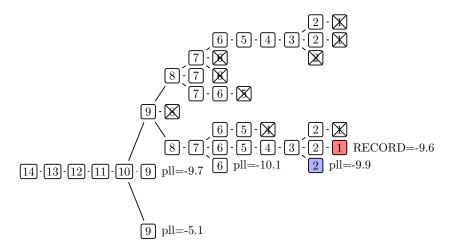


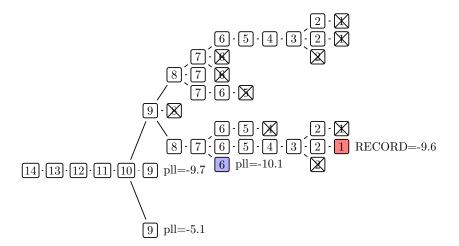


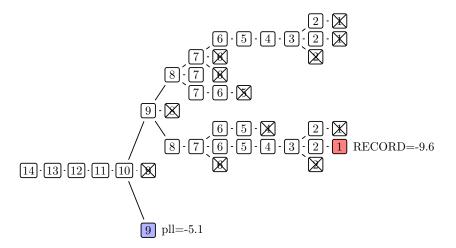


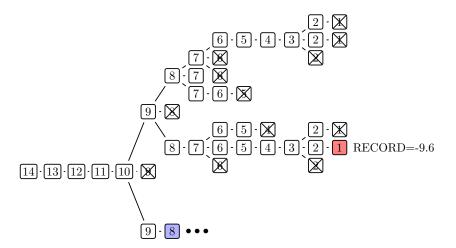












## Non-parametric likelihood bounding

▶ Replace choice probabilities  $P_i^k(a|x_\iota;\theta)$  with frequencies  $n_\iota^a/n_\iota$ 

$$\mathcal{L}^{\mathsf{non\text{-}par}}(Z^{\mathcal{S}}) = \sum_{\iota \in \mathcal{S}} \sum_{i=1}^J \sum_{\mathsf{a}} n_\iota^{\mathsf{a}_i} \log(n_\iota^{\mathsf{a}}/n_\iota)$$

- $ightharpoonup \mathcal{L}^{\text{non-par}}(Z^{\mathcal{S}})$  depends only on the counts from the data!
- ▶ Not hard to show algebraically that for any  $Z^S$  ( $\approx$ Gibbs inequality)

$$\mathcal{L}^{\mathsf{non\text{-}par}}(Z^{\mathcal{S}}) > L^{\mathsf{part}}(Z^{\mathcal{S}}, \theta, V_{\theta}^{k})$$

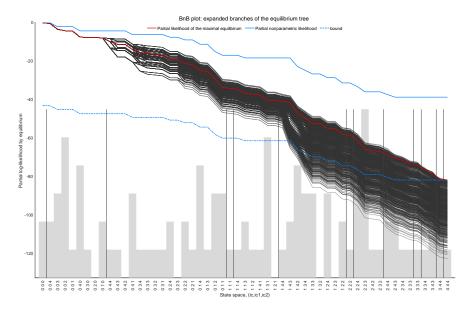
Therefore partial likelihood can be optimistically extrapolated by empirical likelihood at any step  $\iota$  of the RLS tree traversal

$$\mathcal{L}^{\mathsf{part}}(Z^{\{S,S-1,\ldots,\iota\}},\theta,V_{\theta}^k) + \mathcal{L}^{\mathsf{non-par}}(Z^{\{\iota-1,\ldots,1\}})$$

Augmented partial likelihood is much more powerful bound for BnB

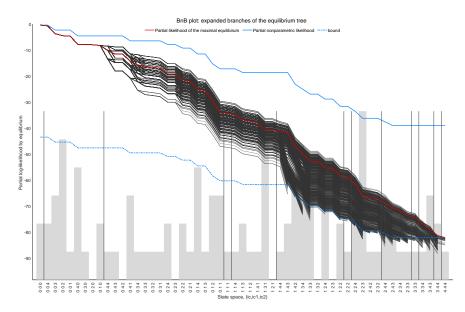
# Non-parameteric likelihood bounding

 $\iota = \mathit{S} = 14$  (terminal state) on the left,  $\iota = 1$  (initial state) on the right



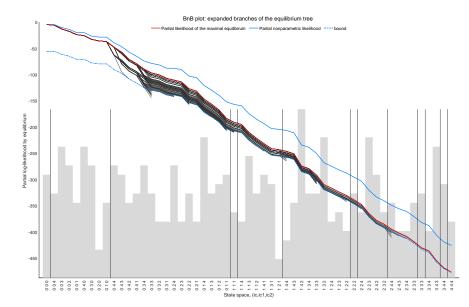
# BnB with non-parameteric likelihood bound

Greedy traversal + non-parameteric likelihood bound



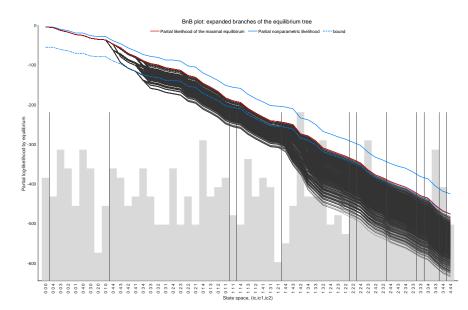
# BnB with non-parameteric likelihood bound, larger sample

Non-parametric o parametric likelihood as  $extit{N} o \infty$  at true  $heta \Rightarrow$  even less computation



## Full enumeration RLS in larger sample

Comparing with the previous slide most of the computation is avoided!



## BnB refinement with non-parametric likelihood

- For any amount of data the non-parametric likelihood is greater or equal to the parametric likelihood algebraically
- ▶ BnB augmented with non-parameteric likelihood bound gives sharper Bounding Rules → less computation
- ▶ Wih more data as  $M \to \infty$
- Non-parametric log-likelihood converge to the likelihood line
- ▶ The width of the band between the blue lines in the plots decreases
  - → Even sharper Bounding Rules
  - $\rightarrow$  Even less computation

MLE for any sample size, but easier to compute with more data!

### Monte Carlo simulations

Α

Single equilibrium in the model One equilibrium in the data

В

Multiple equilibria in the model Same equilibrium played the data

(

Multiple equilibria in the model Multiple equilibria in the data:

- Long panels, each market plays their own equilibrium
- Groups of markets play the same equilibrium

(not today)

## Implementation details

- ► Two-step estimator, NPL and EPL
  - Matlab unconstrained optimizer (with numerical derivatives)
  - CCPs from frequency estimators
  - Max 120 iterations (for NPL and EPL)
- ► MPEC
  - ► Matlab constraint optimizer (interior-point) with analytic derivatives
  - MPEC-VP: Constraints on both values and choice probabilities (as in Egesdal, Lai and Su, 2015)
  - MPEC-P: Constraints in terms of choice probabilities + Hotz-Miller inversion (twice less variables)
  - Starting values from two-step estimator
- Estimated parameter k<sub>1</sub>
- ► Sample size: 1000 markets in 5 time periods
- ▶ Parameters are chosen to ensure good coverage of the state space and non-degenerate CCPs in all states

## Monte Carlo A, run 1: no multiplicity

Number of equilibria at true parameter: 1

Number of equilibria in the data: 1

	2step	NPL	EPL	MPEC-VP	MPEC-P	NRLS
True $k_1 = 3.5$	3.52786	3.49714	3.49488	3.49488	3.49486	3.49488
Bias	0.02786	-0.00286	-0.00512	-0.00512	-0.00514	-0.00512
MCSD	0.10037	0.06522	0.07042	0.07042	0.07078	0.07042
ave log-like	-1.16661	-1.16144	-1.16143	-1.16143	-1.16139	-1.16143
log-likelihood	-5833.07	-5807.21	-5807.16	-5807.16	-5806.95	-5807.16
log-like short	-	-0.050	-0.000	-0.000	-0.000	-0.000
KL divergence	0.03254	0.00021	0.00024	0.00024	0.00024	0.00024
P - P0	0.11270	0.00469	0.00495	0.00495	0.00500	0.00495
$  \Psi(P) - P  $	0.16185	0.0000	0.0000	0.0000	0.0000	0.0000
$  \Gamma(v) - v  $	0.87095	0.00000	0.00000	0.00000	0.00000	0.00000
Convrged of 100	-	100	100	100	99	100

- ► Equilibrium conditions satisfied (except 2step)
- ▶ Nearly all MLE estimators identical to the last digit
- ▶ NPL and EPL estimators approach MLE

## Monte Carlo B, run 1: little multiplicity

Number of equilibria at true parameter: 3

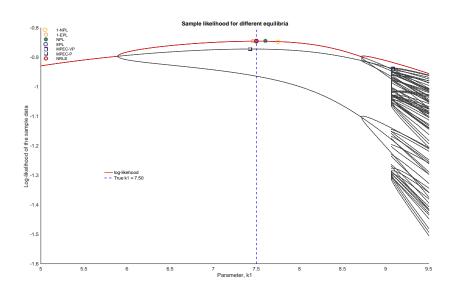
Number of equilibria in the data: 1 Data generating equilibrium: stable

	2step	NPL	EPL	MPEC-VP	MPEC-P	NRLS
True k1=7.5	7.55163	7.49844	7.49918	7.65318	7.35124	7.49919
Bias	0.05163	-0.00156	-0.00082	0.15318	-0.14876	-0.00081
MCSD	0.17875	0.06062	0.03413	0.99742	0.47136	0.03413
ave log-like	-0.84779	-0.84425	-0.84421	-0.88682	-0.87541	-0.84421
log-likelihood	-21194.86	-21106.33	-21105.13	-22170.40	-21885.37	-21105.13
log-like short	-	-1.206	-0.000	-1062.740	-776.809	-0.000
KL divergence	0.02557	0.00040	0.00013	0.23536	0.16051	0.00013
$  P - P_{0}  $	0.11085	0.00490	0.00280	0.17466	0.20957	0.00280
$  \Psi(P)-P  $	0.170940	0.000000	0.000000	0.000000	0.000000	0.000000
$  \Gamma(v) - v  $	1.189853	0.000000	0.000000	0.000000	0.000000	0.000001
N runs of 100	100	100	100	98	97	100

- ► MPEC convergence deteriorates
- Equilibrium conditions are satisfied, but estimators start to converge to wrong equilibria (as seen from KL divergence from the data generating equilibrium)

# Likelihood correspondence

Lines are costructed using symmetric KL-divergence



## Monte Carlo B, run 2: little multiplicity, unstable

Number of equilibria at true parameter: 3

Number of equilibria in the data: 1 Data generating equilibrium: unstable

	2step	NPL	EPL	MPEC-VP	MPEC-P	NRLS
True k1=7.5	7.54238	7.39276	7.48044	7.73133	7.63100	7.50176
Bias	0.04238	-0.10724	-0.01956	0.23133	0.13100	0.00176
MCSD	0.17145	0.05608	0.15801	0.72988	0.89874	0.03820
ave log-like	-0.86834	-0.89374	-0.86550	-0.88512	-0.90196	-0.86504
log-likelihood	-21708.60	-22343.58	-21637.54	-22127.91	-22549.06	-21626.12
log-like short	-	-765.242	-11.413	-502.121	-920.643	-0.000
KL divergence	0.02271	0.15996	0.00257	0.11452	0.20182	0.00012
$  P - P_{0}  $	0.09757	0.20709	0.00619	0.03860	0.02504	0.00307
$  \Psi(P) - P  $	0.160102	0.000000	0.000000	0.000000	0.000000	0.000000
$  \Gamma(v) - v  $	1.126738	0.000000	0.000000	0.000000	0.000000	0.000001
N runs of 100	100	18	100	99	98	100

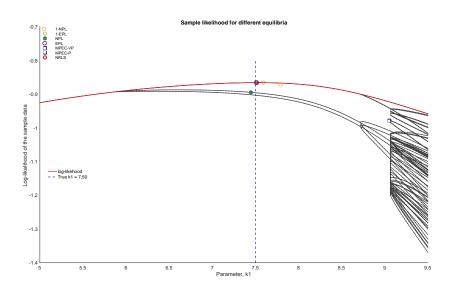
- ► NPL estimator fails to converge
- ► Similar convergence issues for MPEC
- ► EPL estimator performs well



Aguirregabiria, Marcoux (2021)

# Likelihood correspondence

Lines are costructed using symmetric KL-divergence



## Monte Carlo B, run 3: discontinuous likelihood

Number of equilibria at true parameter: 9

Number of equilibria in the data: 1

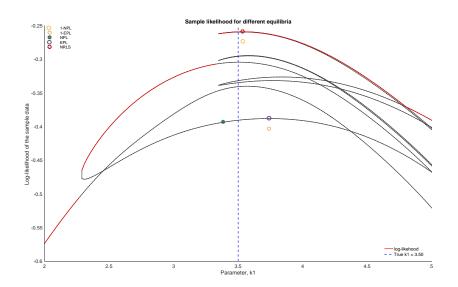
Data generating equilibrium: unstable, near "cliffs"

	2step	NPL	EPL	MPEC-VP	MPEC-P	NRLS
True k1=3.5	3.49739	3.55144	3.64772	3.65943	3.67027	3.50212
Bias	-0.00261	0.05144	0.14772	0.15943	0.17027	0.00212
MCSD	0.13999	0.07133	0.12900	0.12693	0.11583	0.03255
ave log-like	-0.27494	-0.29474	-0.29528	-0.30330	-0.30257	-0.25086
log-likelihood	-1374.721	-1473.695	-1476.425	-1516.503	-1512.847	-1254.320
log-like short	-	-219.375	-222.104	-270.999	-267.523	-0.000
KL divergence	0.01512	0.04889	0.04495	0.04102	0.04078	0.00016
$  P - P_{0}  $	0.62850	0.86124	0.83062	0.66562	0.65879	0.01610
$  \Psi(P) - P  $	0.763764	0.000000	0.000000	0.000000	0.000000	0.000002
$  \Gamma(v) - v  $	0.852850	0.000000	0.000000	0.000000	0.000000	0.000005
N runs of 100	100	100	100	28	27	100

- ► Similar convergence issues
- Poor estimates by EPL, NPL and MPEC (constraints are satisfied, yet low likelihood and high KL divergence)

## Likelihood correspondence

Lines are costructed using symmetric KL-divergence



## Monte Carlo B, run 4: massive multiplicity

Number of equilibria at true parameter: 2455

Number of equilibria in the data: 1

Time to enumerate all equilibria (RLS): 10m 39s

	1-NPL	NPL	EPL	NRLS
True k1=3.75	3.70959	3.71272	3.78905	3.74241
Bias	-0.04041	-0.03728	0.03905	-0.00759
MCSD	0.11089	0.06814	0.40716	0.03032
ave log-likelihood	-0.38681557	-0.37348793	-0.45256293	-0.35998461
log-likelihood	-1934.078	-1867.440	-2262.815	-1799.923
log-like shortfall	-	-66.529	-467.607	-0.000
KL divergence	Inf	14.07523	12231.59186	0.32429
$  P-P_{0}  $	0.82204	0.65580	0.79241	0.07454
$  \Psi(P) - P  $	0.963574	0.000000	0.000000	0.000006
$  \Gamma(v) - v  $	7.020899	0.000000	0.000000	0.000008
N runs of 100	100	18	68	100
CPU time	0.159s	11.262s	4.013s	4.731s

- Severe convergence problems for NPL and EPL
- ▶ Poor eqb identification (low likelihood and high KL divergence)
- ▶ NRLS has comparable CPU time (much faster than full enumeration)

## Monte Carlo C, multiple equilibria in the data

#### The path forward:

- Assume that the same equilibrium is played in each market over time
- Grouped fixed-effects, groups defined by the equilibria played
- 1. Joint grouped fixed-effects estimation
  - ightharpoonup Estimate the partition of the markets into groups playing different equilibria together with heta
  - ► For each market compute maximum likelihood over all equilibria and "assign" it to the relevant group (estimation+classification)
  - Computationally very demanding: BnB market-by-market, non-parametric refinement has no bite
- 2. Two-step grouped fixed-effects estimation
  - Step 1: partition the markets based on some observable characteristics (K-means clustering)
  - $\triangleright$  Step 2: estimate  $\theta$  allowing different equilibria in different groups
  - Small additional computational cost!
- Bonhomme, Manresa (2015); Bonhomme, Lamadon, Manresa (2022)

### Conclusions: Bertrand investments model

- ▶ Many types of endogenous coordination is possible in equilibrium
  - Leapfrogging (alternating investments)
  - Preemption (investment by cost leader)
  - Duplicative (simultaneous investments)
- ▶ Full rent dissipation and monopoly outcomes are supported as MPE.
- ▶ Numerous MPE equilibria and "Folk theorem"-like result
- ► The equilibria are generally inefficient due to over-investment
  - Duplicative or excessively frequent investments

## Conclusions: Solution of dynamic games

- ► When equilibrium is not unique the computation algorithm inadvertently acts as an equilibrium selection mechanism
- When directionality in the state space is present, state recursion algorithm is preferred to time iterations
- ▶ Plethora of Markov perfect equilibria poses new challenges:
  - ▶ How firms manage to coordinate on a particular equilibrium?
  - Increased difficulties for empirical applications.
  - Daunting perspectives for identification of equilibrium selection rule from the data.
- ► Estimation of dynamic games with multiple equilibria Nested Recursive Lexicographical Search (NRLS)

## Conclusions: NRLS estimator

- ► Full solution MLE estimator for dynamic games of a particular type, namely directional dynamic games (DDGs)
- Nested loop: outer likelihood max + inner model solver
- Need to maximize over the set of all equilibria ↔ daunting computational task
- Smart BnB algorithm not to waste time on unlikely MPE
- NRLS is MLE estimator for dynamic games of a particular type, directional dynamic games (DDGs)
  - Fully robust to multiplicity of equilibria
  - Able to identify multiple equilibria in the data