NABILA ABRAHAM



647-825-2599



nabilaabraham



<u>nabsabraham</u>



nabila.abraham@ryerson.ca

EDUCATION

RYERSON UNIVERSITY

MASc. in Electrical & **Computer Engineering** 2017 - Present | Toronto, ON

- Research focus in medical image segmentation using deep learning
- Interested in probabilistic methods, VAEs, adversarial training, disentanglement

RYERSON UNIVERSITY

B.Eng in Biomedical Engineering

2012 – 2017 | Toronto, ON

Capstone thesis: Wireless intraoperative neuromonitoring system for spinal surgery

- Created 90V TENs machine to stimulate somatosensory evoked potential (SSEP)
- Assisted in design and fabrication of acquisition circuit
- Assisted in SSEP processing

TFACHING

Teaching Assistant (TA) for various courses where I supervise 20-30 students on lab material in both hardware and software courses:

- ELE532: Signals & Systems
- **ELE202: Electric Circuits**
- BME802: Human Computer Interaction
- DG8002: Digital Media **Environments**

SKILLS

- Python, MATLAB, C++, Azure
- PyTorch, Keras, Git, ROS
- **Technical Writing**

WORK EXPERIENCE

Ryerson Collaboratory | Research Technology Assistant Jan 2018 - Present

- Host beginner-level workshops on machine learning
- Provide tutorials on fabrication equipment such as 3D printers, laser cutters, digital embroidery machine and basic electronics

Toronto Hydro Electric Systems | Senior Technical Student Sept 2015 - Sept 2016

- Ran short circuit simulation studies using the CYME software
- Conducted protection and co-ordination studies on transformer stations to update existing relay settings

RESEARCH

Ryerson Multimedia Lab | Graduate Student Researcher Sept 2017 – Present

- Researching loss functions and generative models to improve semantic segmentation of medical data
- Working on an industry project with Shaftesbury VR to develop predictive cues on player stress using time series analysis on biomedical signal data

VOLUNTEER

Ryerson Rams Robotics Team | Vision System Developer Jan 2019 – Present

- Integrating recognition models into the vision pipeline using ROS
- Researching acoustic localization for navigation using deep learning

IEEE Ryerson Chapter | Graduate Student Representative Sept 2018 - Present

- Organize monthly journal clubs with graduate students to discuss literature in deep learning
- Assist in planning outreach/ networking events with AI companies

PUBLICATIONS

[1] N. Abraham and N. Khan, "A Novel Focal Tversky loss function with improved Attention U-Net for lesion segmentation", Accepted at IEEE International Symposium on Biomedical Imaging (ISBI), 2019.

[2] N. Khan, N. Abraham, M. Hon and L. Guan, "Machine Learning on Biomedical Images: Interactive Learning, Transfer Learning, Class Imbalance and Beyond", Accepted at IEEE International Conference on Multimedia Information and Processing (MIPR), 2019.