

Face recognition

Face verification vs. face recognition

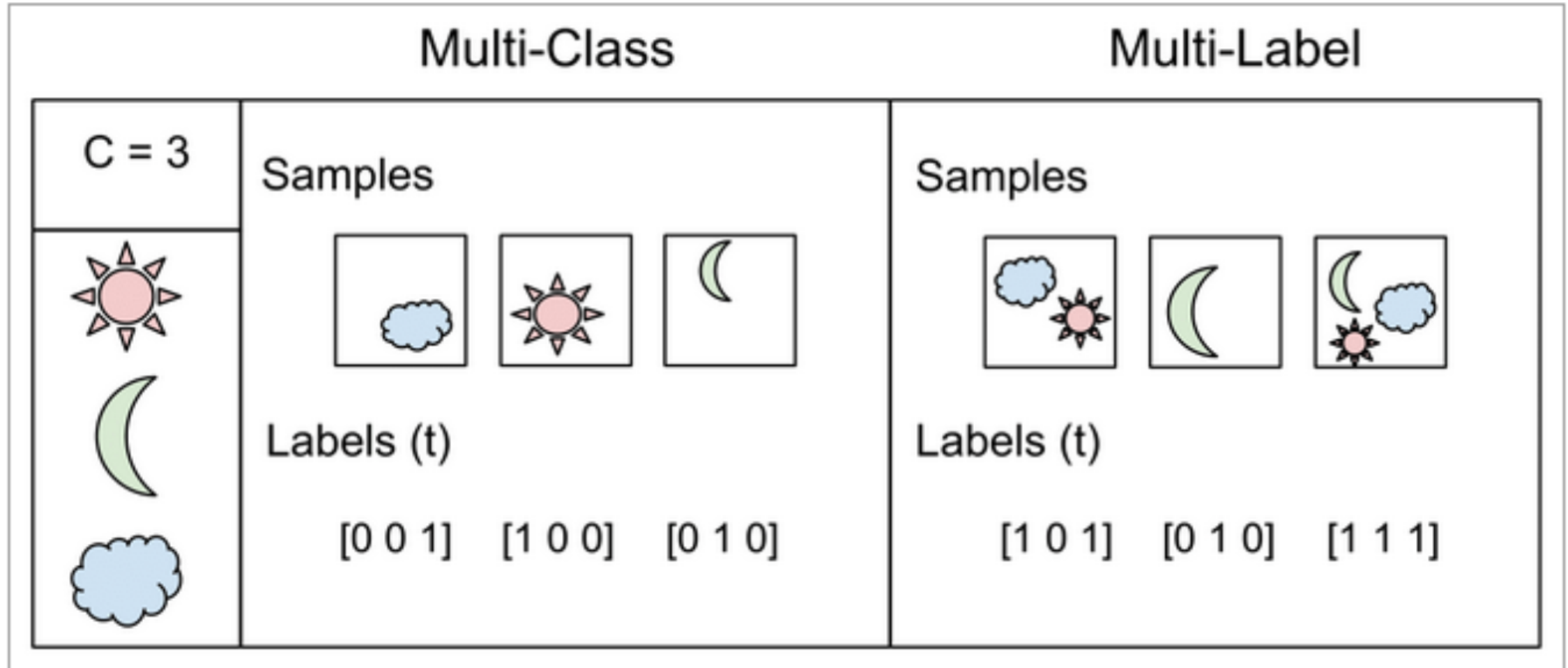
Verification (Binary Classification)

- Input image, name/ID
- Output whether the input image is that of the claimed person

Recognition (Multi Class Classification)

- Has a database of K persons
- Get an input image
- ID Output ID if the image is any of the K persons (or "not recognized")

Multi Class Classification vs Multi Label Classification



- ref: [scikit-learn](https://scikit-learn.org/)

One-shot learning: intro

하나의 example만으로 classifier를 학습하는 연구.

few-shot learning으로 추상되며,
보통 meta learning 방법론을 참조한다.

강의에서는 데이터들 간의 유사도 함수를 학습하는 형태의 방법론을 보였다.

One-shot learning: Meta Learning

Meta refers to a level above.

목표과제(labeled data)와는 간접적일 수 있는 목표함수(meta)를 학습하는 방법론 (한국웹에서는 보통 학습/해결 방법을 학습하는 방법 이라고 소개한다.)

일반적인 ML에서는 모델의 결과와, 데이터의 레이블에 기반한 loss(cost) function을 만들어 최소화 시키는 방법으로 학습하는데

$$f_{loss}(y, \hat{y})$$

Meta learning 에서는 보통 문제를 해결하기 위한 다른 함수(e.g. 유사도)를 정의하고 해당 **함수의 기능을 최대화**하는 방식으로 학습한 후 해당 함수를 이용하며 문제를 해결한다.

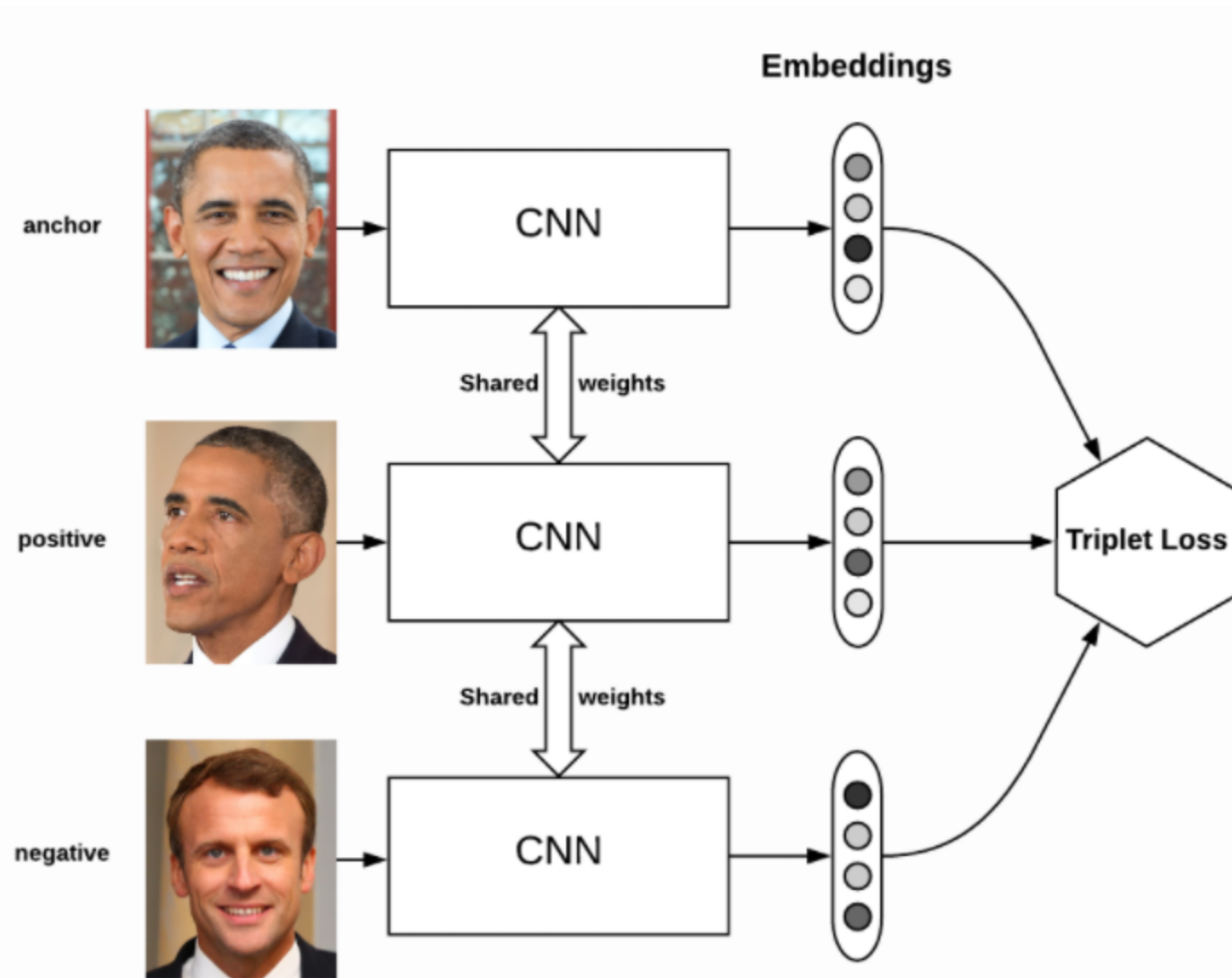
If $x^{(i)}, x^{(j)}$ are the same person, $\|f(x^{(i)}) - f(x^{(j)})\|^2$ is small.

If $x^{(i)}, x^{(j)}$ are different persons, $\|f(x^{(i)}) - f(x^{(j)})\|^2$ is large.

One-shot learning: refs

- refs
 - meta learning 영문 wiki
 - meta learning 영문 blog
 - Supervised vs one-shot 영문
 - few-shot 영문
 - few-shot 한글(카카오)

Triplets loss: intro



Triplet loss on two positive faces (Obama) and one negative face (Macron)

Triplets loss: code

```
def batch_all_triplet_loss(labels, embeddings, margin, squared=False):  
    """Build the triplet loss over a batch of embeddings.
```

We generate all the valid triplets and average the loss over the positive ones.

Args:

```
    labels: labels of the batch, of size (batch_size,)
    embeddings: tensor of shape (batch_size, embed_dim)
    margin: margin for triplet loss
    squared: Boolean. If true, output is the pairwise squared euclidean distance matrix.
             If false, output is the pairwise euclidean distance matrix.
```

Returns:

```
    triplet_loss: scalar tensor containing the triplet loss
```

```
    """
```

```
    # Get the pairwise distance matrix
```

```
    pairwise_dist = _pairwise_distances(embeddings, squared=squared)
```

```
    anchor_positive_dist = tf.expand_dims(pairwise_dist, 2)
```

```
    anchor_negative_dist = tf.expand_dims(pairwise_dist, 1)
```

```
    # Compute a 3D tensor of size (batch_size, batch_size, batch_size)
```

```
    # triplet_loss[i, j, k] will contain the triplet loss of anchor=i, positive=j, negative=k
```

```
    # Uses broadcasting where the 1st argument has shape (batch_size, batch_size, 1)
```

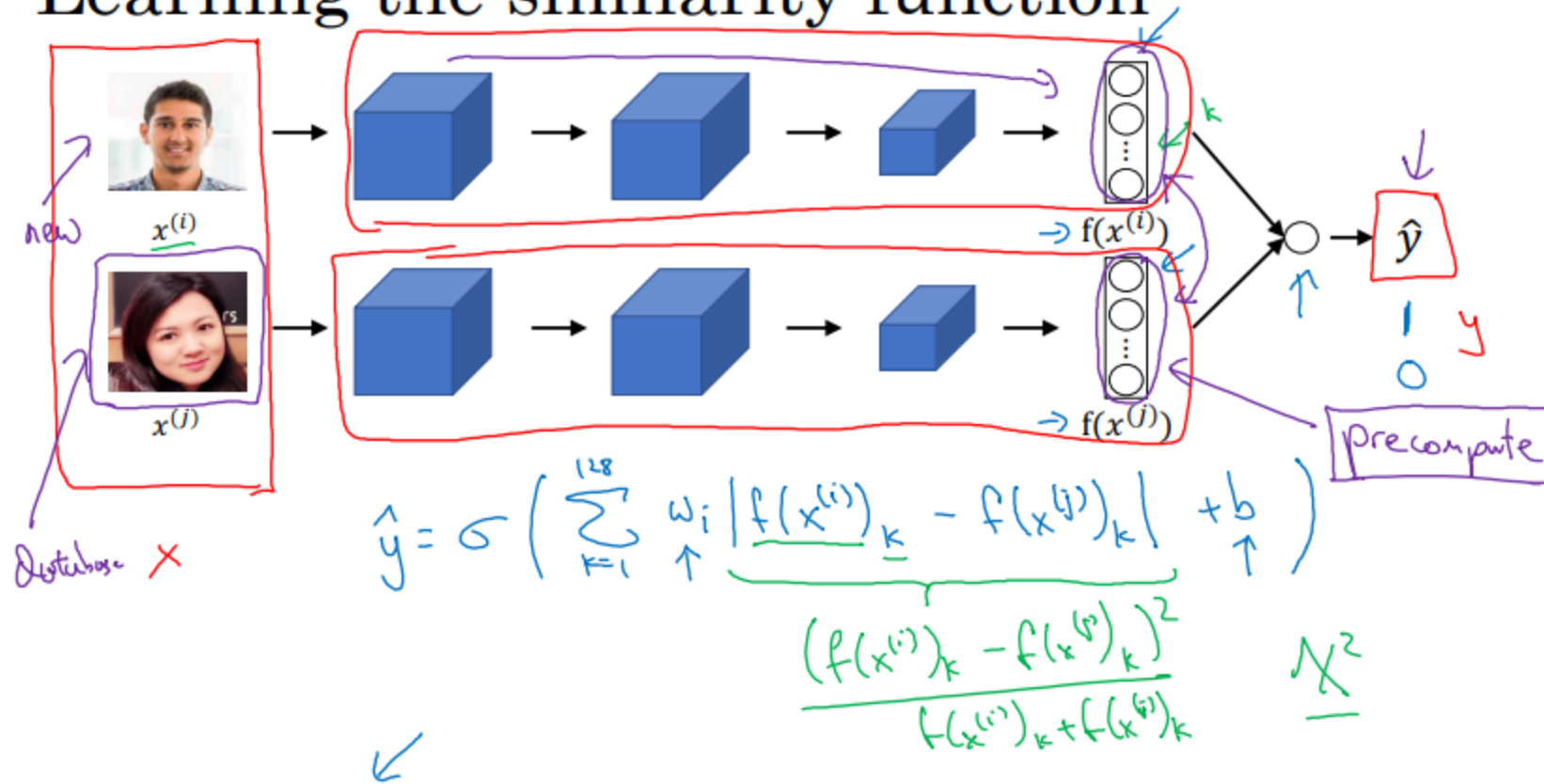
```
    # and the 2nd (batch_size, 1, batch_size)
```

```
    triplet_loss = anchor_positive_dist - anchor_negative_dist + margin
```

- ref: <https://omindrot.github.io/triplet-loss>

Face Verification in the lecture

Learning the similarity function







[Taigman et. al., 2014. DeepFace closing the gap to human level performance]

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Face Verification in the lecture

Face verification supervised learning

x		y	
		1	"Same"
		0	"Different"
		0	
		1	

[Taigman et. al., 2014. DeepFace closing the gap to human level performance]

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Neural Style Transfer

- Visualize CNN
- Neural Style Transfer

Visualize CNN

Visualize CNN: layer 1

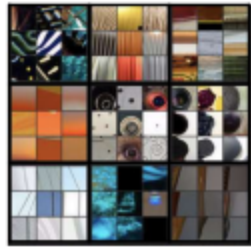
각 layer에서 unit의 최대로 activate 되게 하는 fetch를 보인 것 입니다.

- fetch는 dataset에서 찾습니다.

Visualizing deep layers: Layer 1



Layer 1



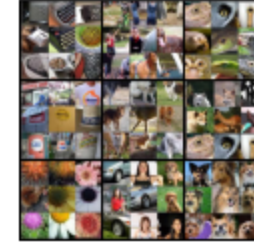
Layer 2



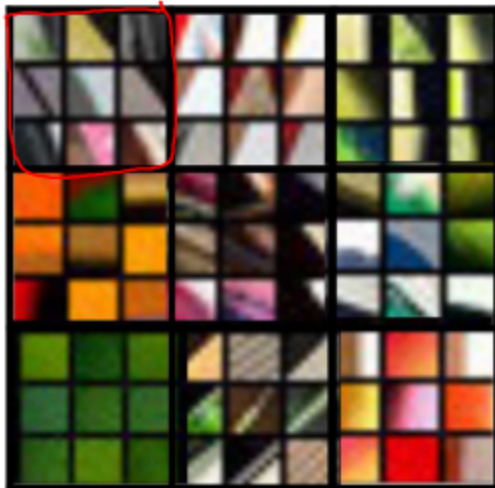
Layer 3



Layer 4

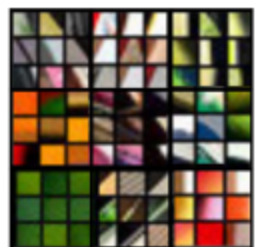


Layer 5

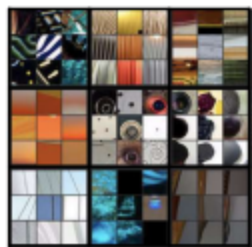


Visualize CNN: layer 2

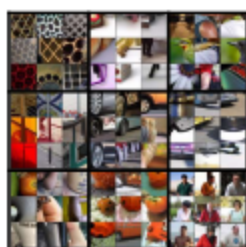
Visualizing deep layers: Layer 2



Layer 1



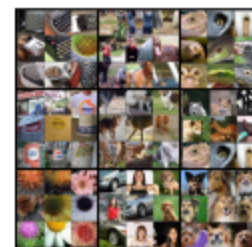
Layer 2



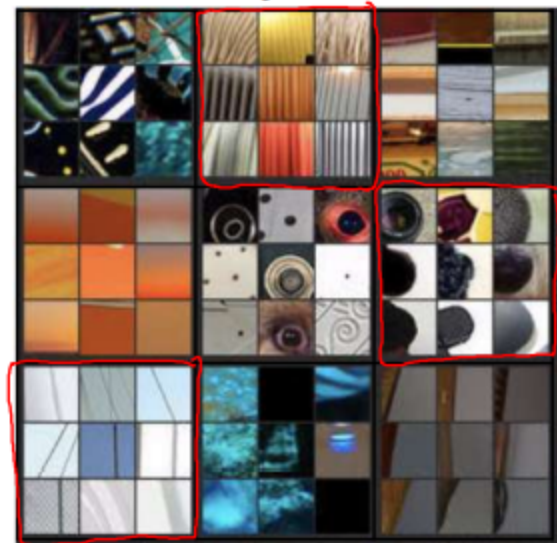
Layer 3



Layer 4



Layer 5



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Visualize CNN: layer 3

Visualizing deep layers: Layer 3



Layer 1



4



Layer 5

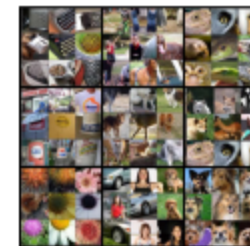
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Visualize CNN: layer 4

Visualizing deep layers: Layer 4



Layer 4



Layer 5

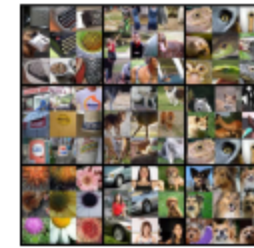
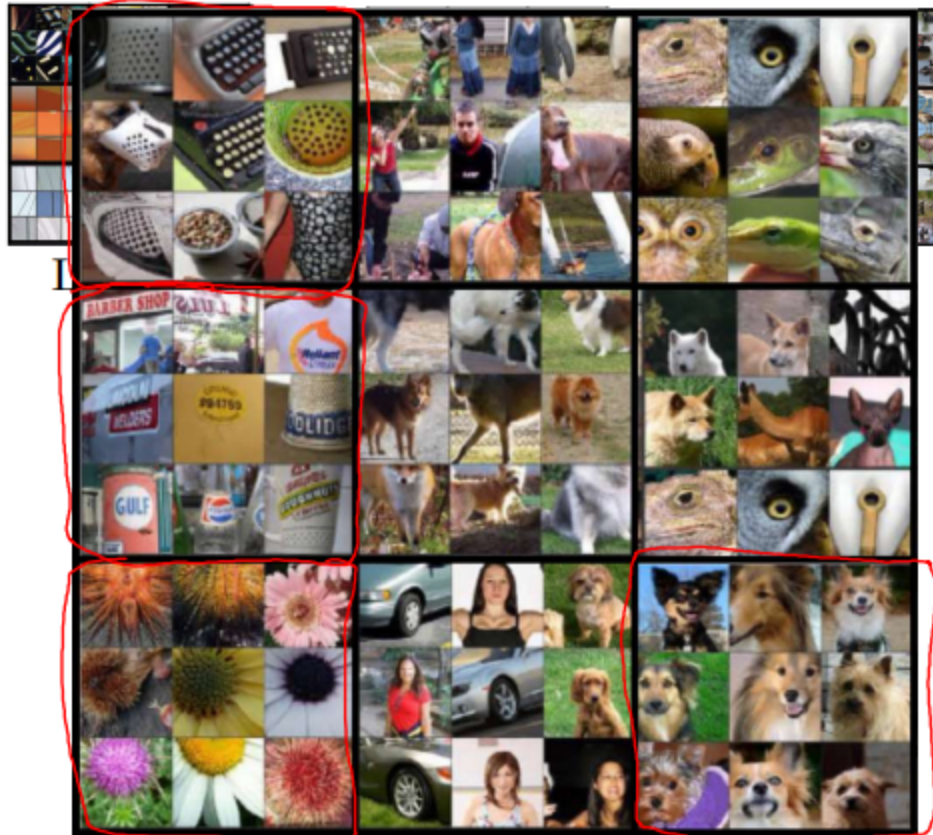
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Visualize CNN: layer 5

Visualizing deep layers: Layer 5



Layer 1



Layer 5

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Visualize CNN: other method

- Filters의 weight를 그대로 출력한다.
- Image를 the filters 에 그대로 적용하여 출력한다.



- <https://www.youtube.com/watch?v=ho6JXE3EbZ8>

Neural Style Transfer: cost function

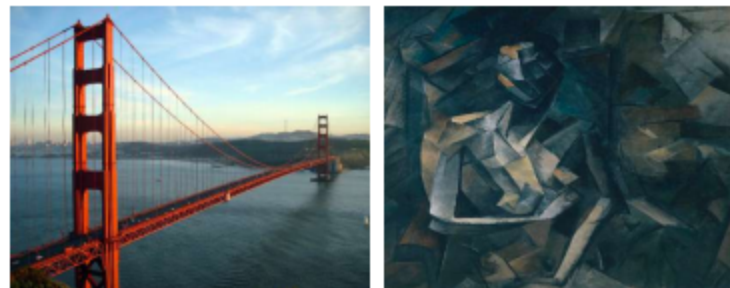
Neural style transfer



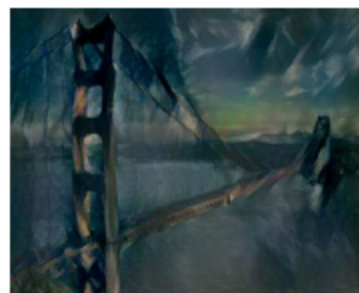
Content (C) Style (S)



Generated image (G)



Content (C) Style (S)



Generated image (G)

[Images generated by Justin Johnson]

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$$\underline{J(G)} = \alpha \underline{J_{content}(C, G)} + \beta J_{style}(S, G)$$

Arrows indicate the mapping: α points to the content image C , β points to the style image S , and $J_{content}$ points to the generated image G .

Neural Style Transfer: generate

Find the generated image G

1. Initiate G randomly

$G: 100 \times 100 \times 3$

↑
RGB

2. Use gradient descent to minimize $J(G)$

$$G := G - \frac{\partial}{\partial G} J(G)$$



[Gatys et al., 2015. A neural algorithm of artistic style]

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$$J(S, C, G)$$

에서 S, C 를 고정하고, gradient descent로 G 를 업데이트

Neural Style Transfer: content cost function

Content cost function

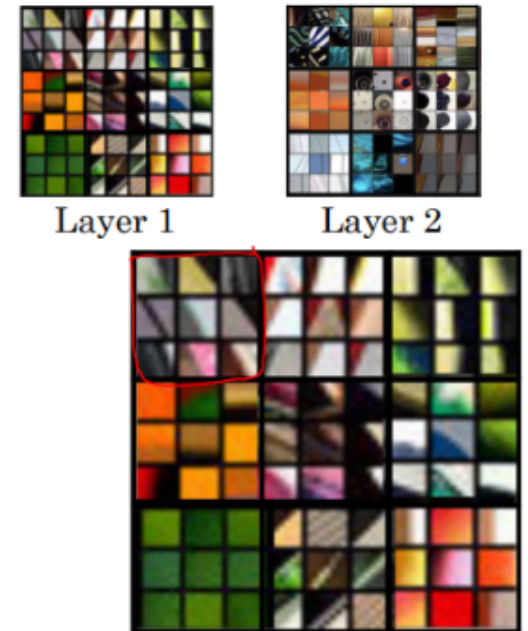
$$J(G) = \alpha J_{content}(C, G) + \beta J_{style}(S, G)$$

- Say you use hidden layer l to compute content cost.
- Use pre-trained ConvNet. (E.g., VGG network)
- Let $a^{[l](C)}$ and $a^{[l](G)}$ be the activation of layer l on the images
- If $a^{[l](C)}$ and $a^{[l](G)}$ are similar, both images have similar content

$$J_{content}(C, G) = \frac{1}{2} \left\| \underbrace{a^{[l](C)}}_{\substack{\downarrow \\ a^{[l](C)}}} - \underbrace{a^{[l](G)}}_{\substack{\downarrow \\ a^{[l](G)}}} \right\|^2$$

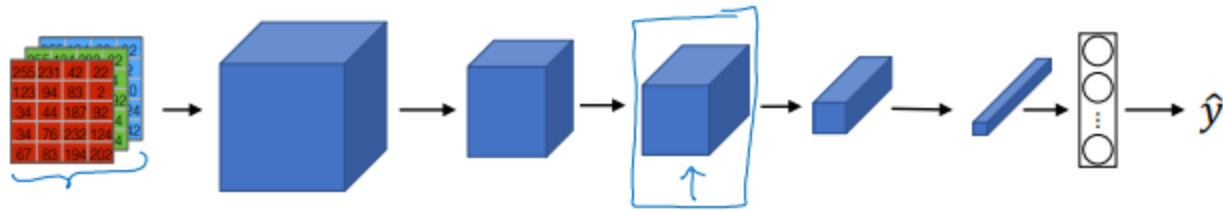
[Gatys et al., 2015. A neural algorithm of artistic style]

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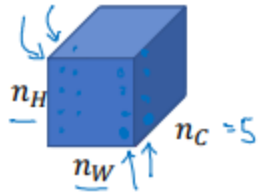


Neural Style Transfer: style cost function

Meaning of the “style” of an image



Say you are using layer l 's activation to measure “style.”
Define style as correlation between activations across channels.

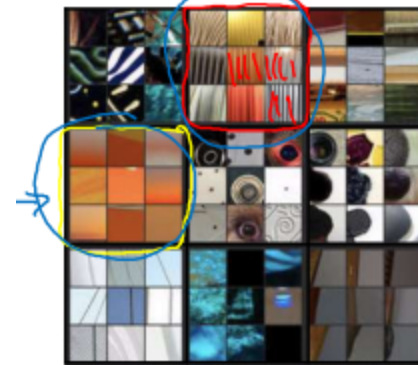
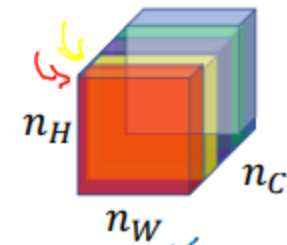


How correlated are the activations
across different channels?

[Gatys et al., 2015. A neural algorithm of artistic style]

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Style image



Activation들의 조합/곱은(k, k')

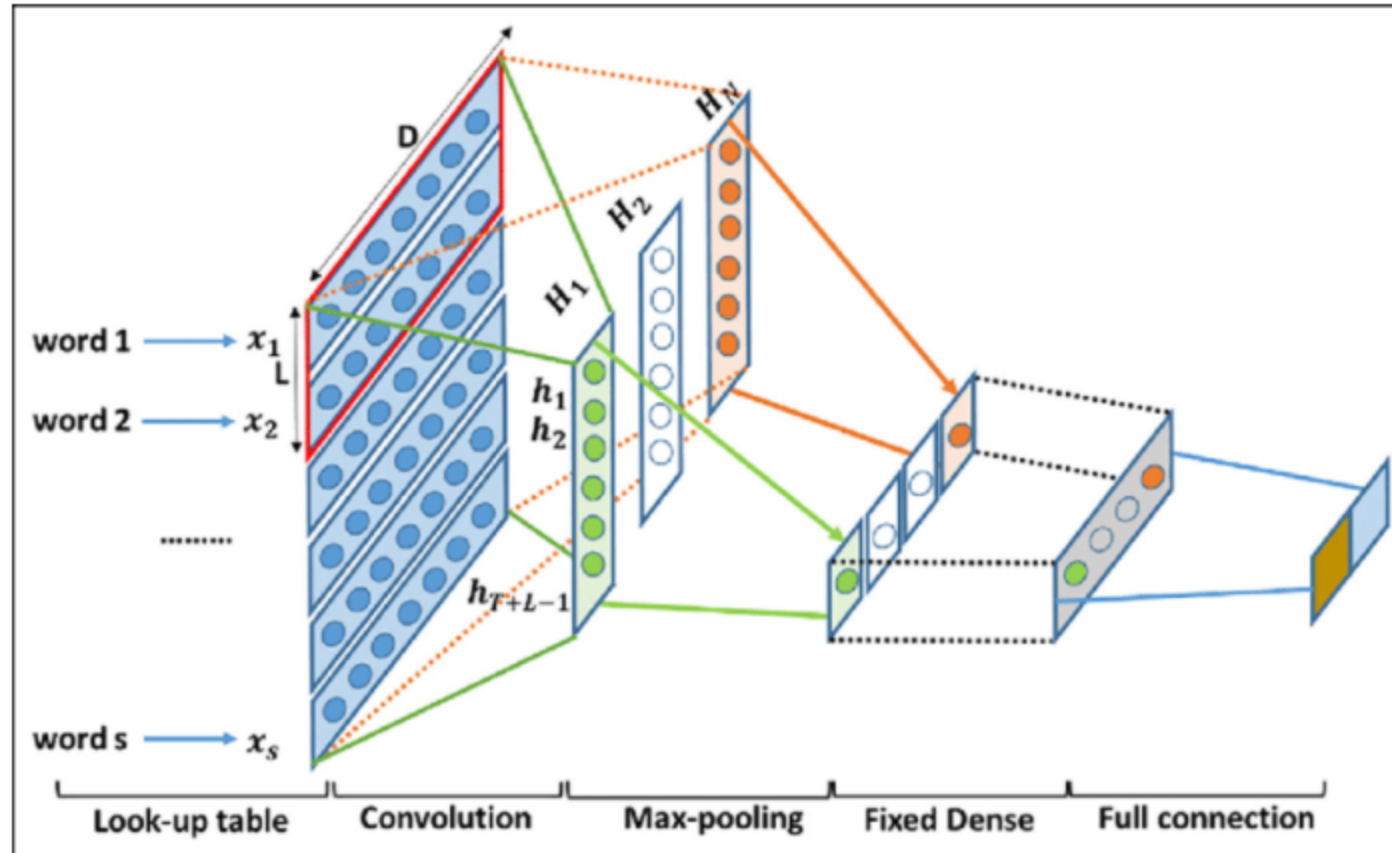
- 그림의 스트로크와 같은 특징(색상, 표현, 패턴 또는 이들의 조합)을 대표 할 것이다.
- Style cost는 generated image와 style image 간에 이 특징들의 차이를 나타낸다.
- Style cost를 최소화 하는 것은 generated image와 style image 간의 특징 차이를 최소화 하는 것!

The style cost function should be:

$$J_{style}^{[l]}(S, G) = \frac{1}{(2n_H^{[l]}n_W^{[l]}n_C^{[l]})^2} \sum_k \sum_{k'} \left(G_{kk'}^{[l](S)} - G_{kk'}^{[l](G)} \right)^2$$

1D and 3D Generalizations

Conv 1d



Standard CNN on text classification.

- ref <https://arxiv.org/abs/1408.5882>

Conv 3d

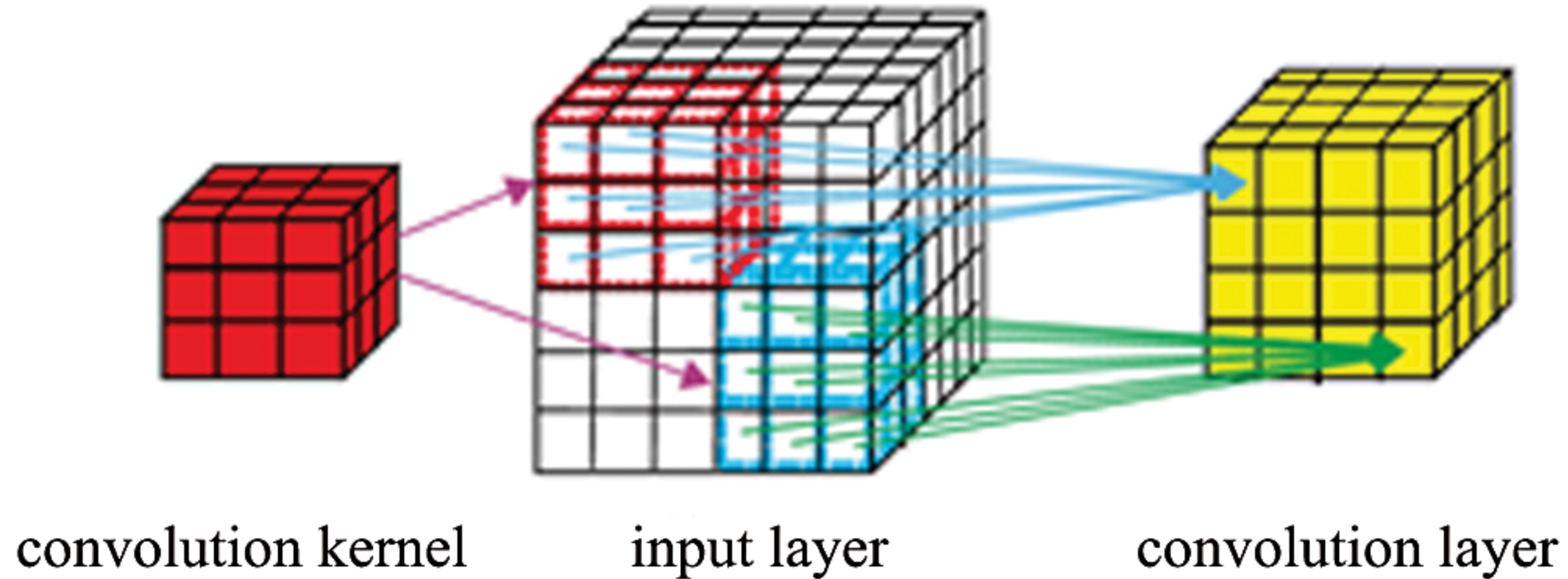


Figure 3: Illustration of the 3D convolutional operation

Conv 3d: rels

- Learning Spatiotemporal Features with 3D Convolutional Networks
- <https://github.com/karolzak/conv3d-video-action-recognition>
- conv3d for image classification