# **DoYoung Kim**

Graduate Student of Mechanical Design Engineering

 $Github: \underline{https://github.com/KimDoYoung1997}$ 

E-mail: <a href="mailto:ehdud4520@naver.com">ehdud4520@naver.com</a>

Phone: 010-5595-4520

# **RESEARCH INTEREST**

Deep Reinforcement Learning, Visual Navigation

### **EDUCATION**

Mar. 2016~Aug. 2022

- Bachelor of JeonBuk National University(JBNU), South Korea
- GPA: 4.09/4.5

## RESEARCH EXPERIENCES

Nov. 2022 ~ Present

- Intelligent Robotics Research Center, Korea Electronics Technology Institute, KETI
- ✓ Participating in projects related to autonomous mobile manipulators and industrial mobile robots
- $\checkmark$  Responsible for the comprehensive navigation process, including Simultaneous Localization and Mapping(SLAM) and management of middleware

Mar. 2021 ~ Aug. 2022

- Undergraduate Researcher, JBNU
- ✓ Supervised by Prof. Deok-Jin Lee
- ✓ Participated in projects related to autonomous driving motion control using Imitation learning

#### **PUBLICATIONS**

- The 23rd International Conference on Control, Automation and Systems (Oct 2023)
- ✓ "Development and Validation of Reconfigurable Autonomous Mobile Manipulator for Flexible Manufacturing Process," Accepted Regular Paper, The 23rd International Conference on Control, Automation and Systems, Oct. 2023

#### **HONARS & AWARDS**

- Minister's Award, Drone Navigation Challenge, Korea Ministry of Science and ICT, 2021
- ✓ Performed autonomous drone navigation tasks and won Ministry of Science and ICT's award
- Superior Academic Performance Scholarship (Mar 2016)
- ✓ Admitted as the top student of Mechanical Design Engineering department (full tuition)
- Presidential Award for Outstanding Graduates (Aug 2022)
- ✓ President's Award for the top graduate student, JBNU

## **SKILLS**

# ■ Robot Programming

- ✓ Programming language: C++ Python
- ✓ Frameworks: ROS, ROS2, Behavior Tree
- ✓ Tools: Isaac Sim, Gazebo, Docker, Linux, Git

# **EXTRACURRICULAR PROGRAMS**

## ■ Member, Robotics Club, AUTURBO, Jan. 2024 ~ Present

- ✓ Developing digital twin environment using Nvidia Isaac Lab for Reinforcement Learning(RL) and deployment of quadruped robots
- ✓ Contributed to and maintained open-source projects, <a href="StrideSim">StrideSim</a>, a quadruped robot simulation

## Running personal websites

- ✓ Notion
- ✓ Tech Blog

# **TEACHING EXPERIENCE**

### ■ Participated as an undergraduate mentor in JBNU Mar. 2022 ~ July. 2022

- ✓ Selected as an Excellent Mentor of Mentoring Program
- ✓ Presented "Artificial Intelligence" seminar for undergraduate student