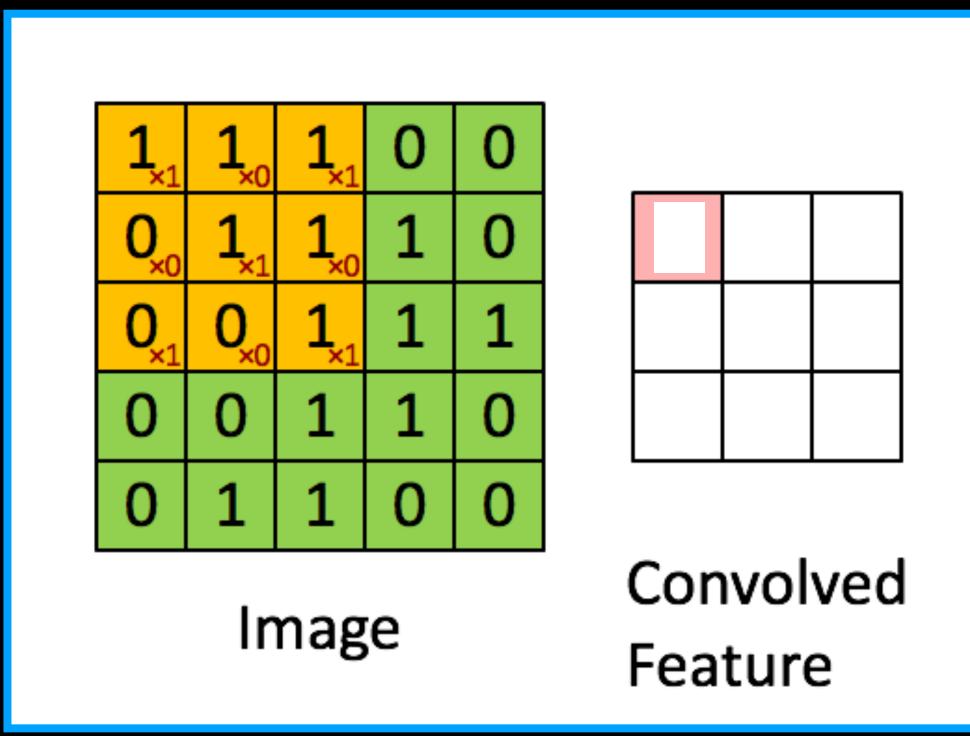
Convolution neural networks

Objectives

- Building blocks of convolution neural networks
- Training and evaluation pipeline



Why Convolution?

Add your answers here

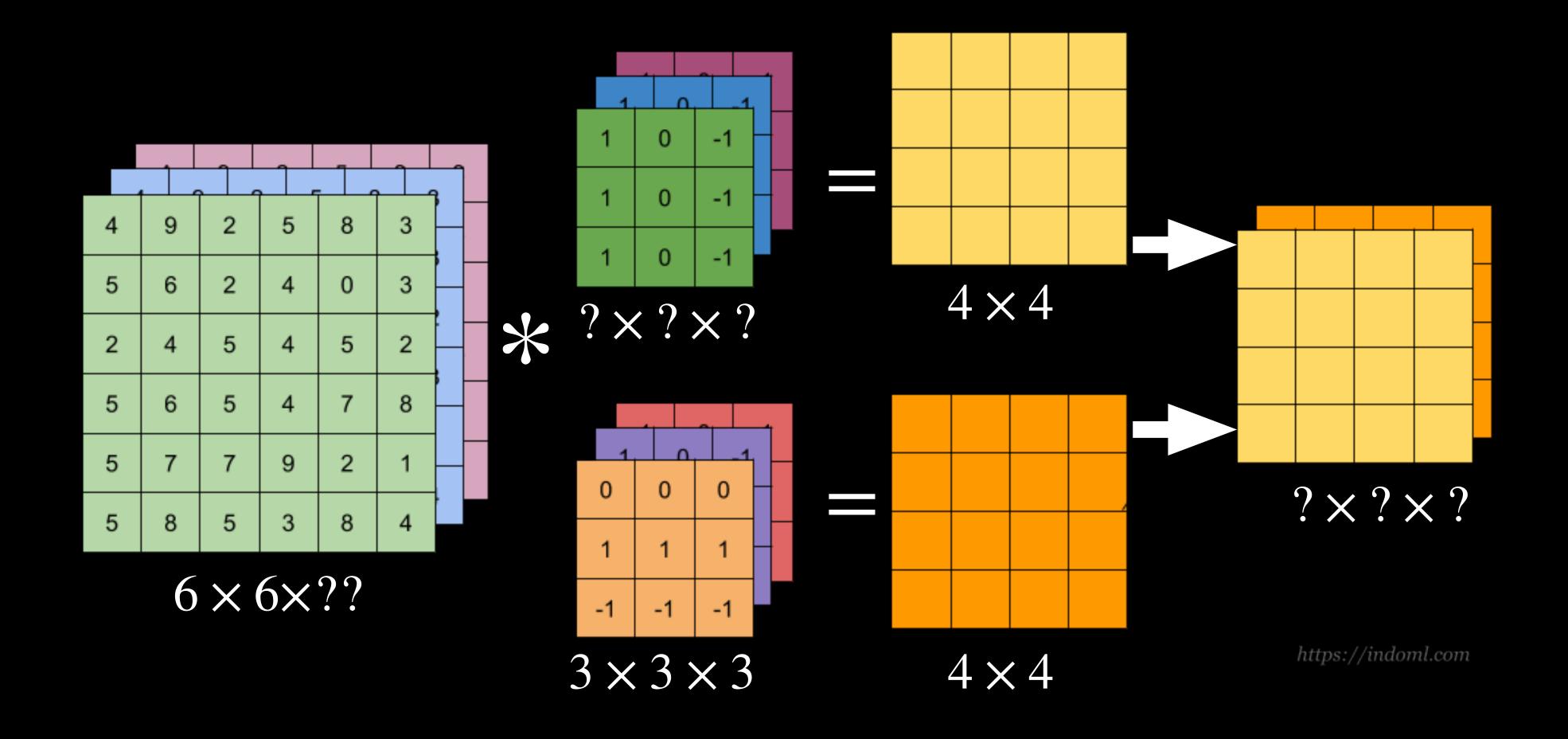
Convolution

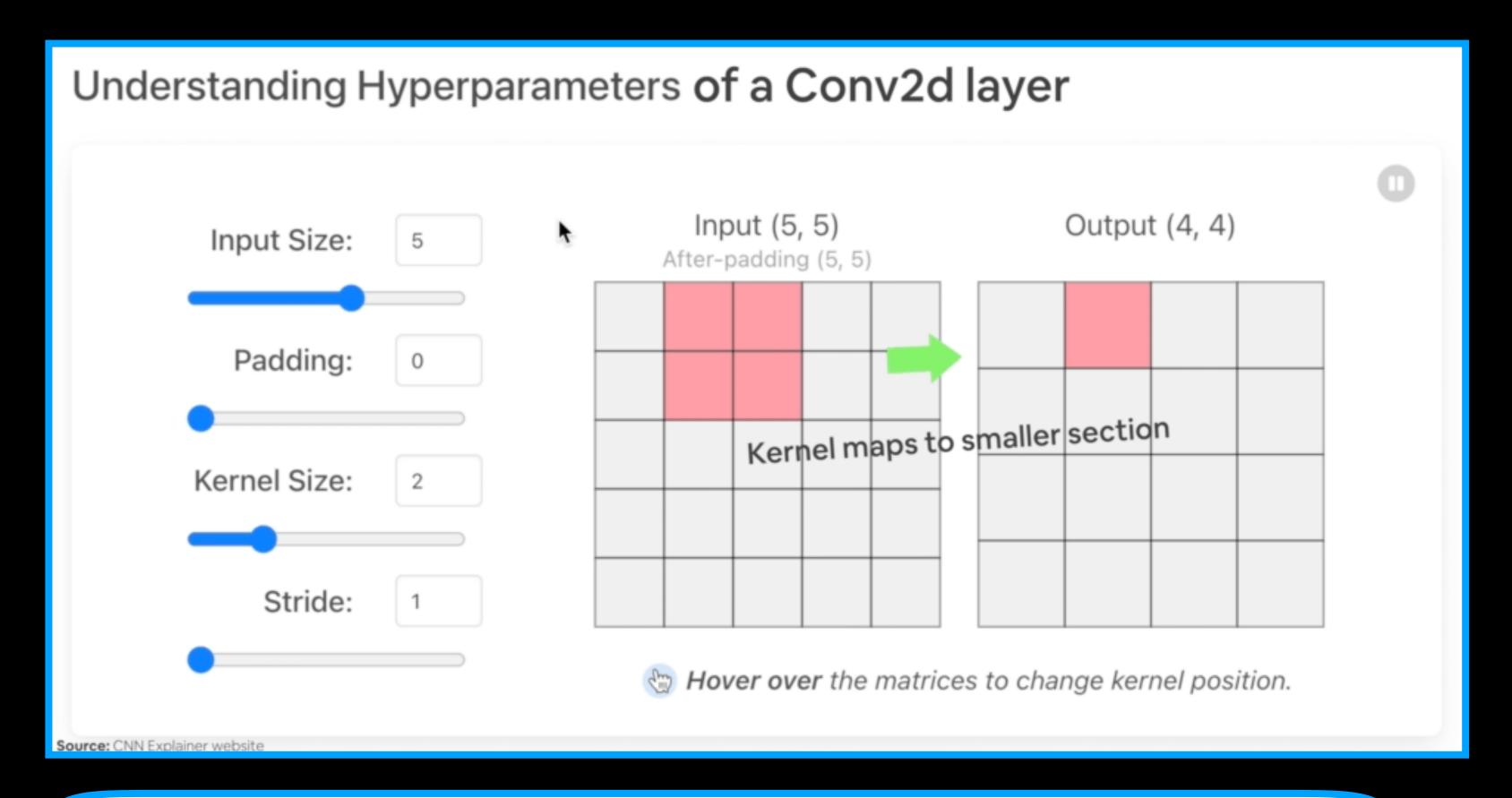
Definition

self.conv = nn.Conv2d(in_channels, out_channels, kernel_size, stride, padding)

Call

x = self.conv(input)



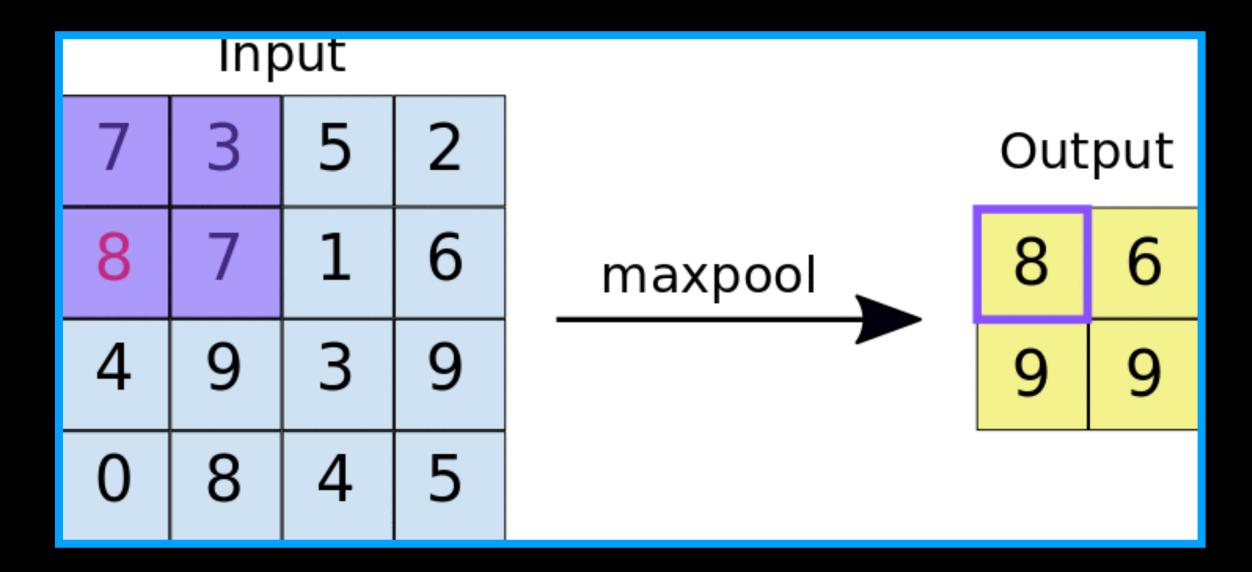


Definition

self.conv = nn.Conv2d(in_channels, out_channels, kernel_size, stride, padding)

Call

x = self.conv(input)



Invariance

MaxPooling

Definition

self.pool = nn.MaxPool2d(kernel_size, stride, padding)
Call

x = self.pool(F.relu(self.conv(input))

Convolution neural network

Feature Extraction

Convolution Neural Network (CNN) Input Output Pooling Pooling Pooling Horse Zebra Dog SoftMax Activation Convolution Convolution Convolution Function ReLU ReLU ReLU Kernel Flatten Layer Fully Connected Feature Maps Layer

Probabilistic

Distribution

Classification

Objectives

- Building blocks of convolution neural networks
- Training and evaluation pipeline

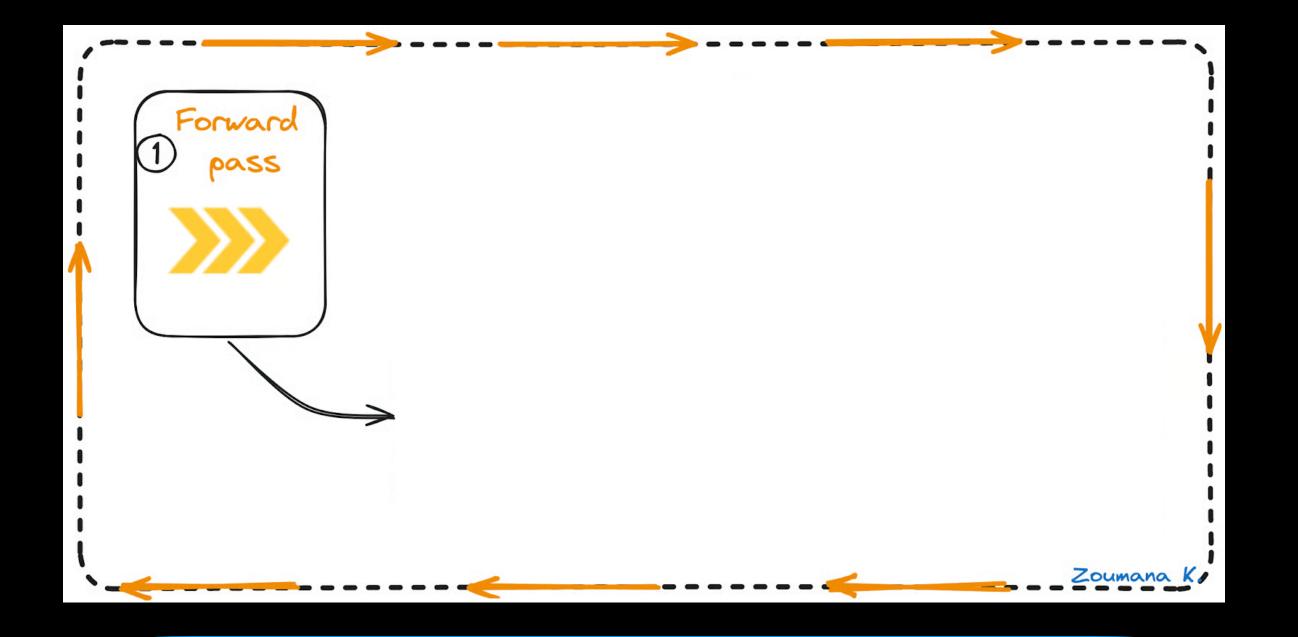






Step 1: Load your dataset

Step 2: Train your model



```
for epoch in range(epochs):
    for i, data in enumerate(train_loader):
        inputs, labels = data
        optimizer.zero_grad()
        outputs = model(inputs)
```

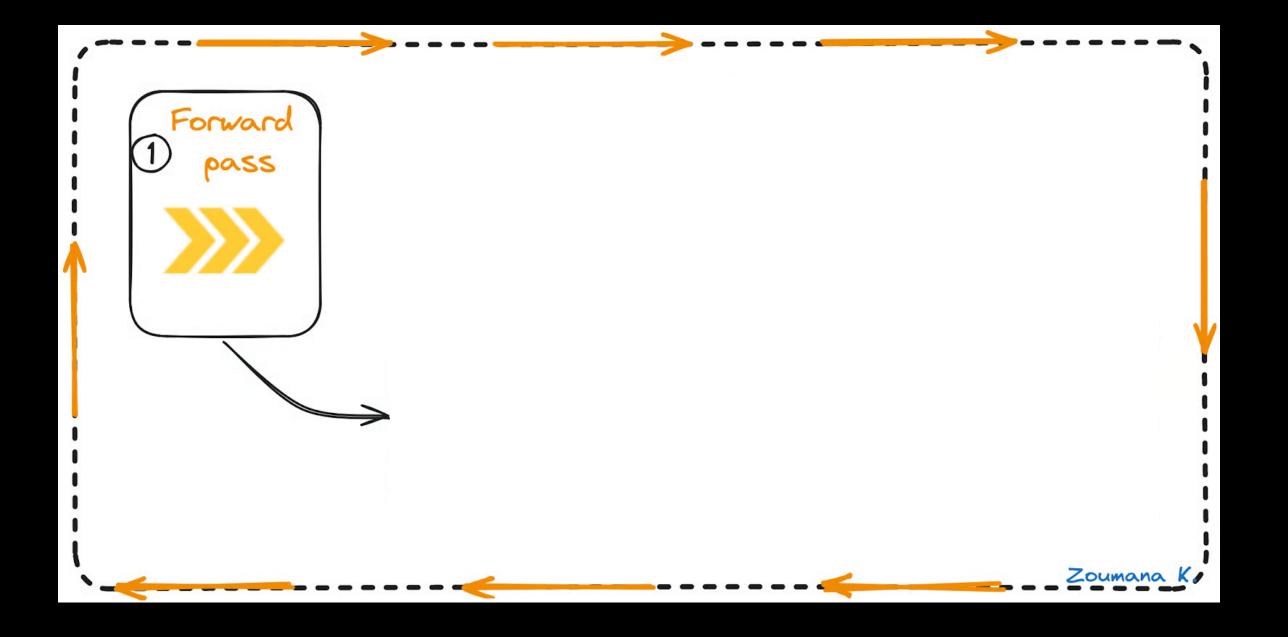






Step 1: Load your dataset

Step 2: Train your model



```
for epoch in range(epochs):
    for i, data in enumerate(train_loader):
        inputs, labels = data
        optimizer.zero_grad()
        outputs = model(inputs)
        loss = criterion(outputs, labels)
```

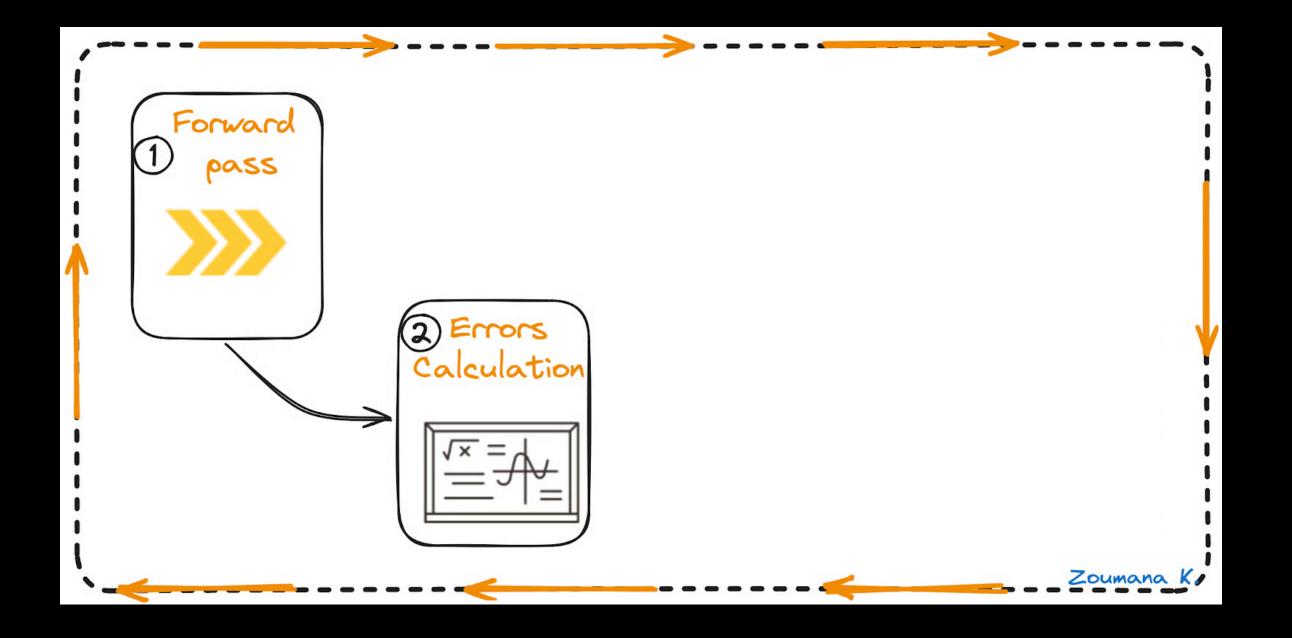






Step 1: Load your dataset

Step 2: Train your model



```
for epoch in range(epochs):
    for i, data in enumerate(train_loader):
        inputs, labels = data
        optimizer.zero_grad()
        outputs = model(inputs)
        loss = criterion(outputs, labels)
        loss.backward()
```



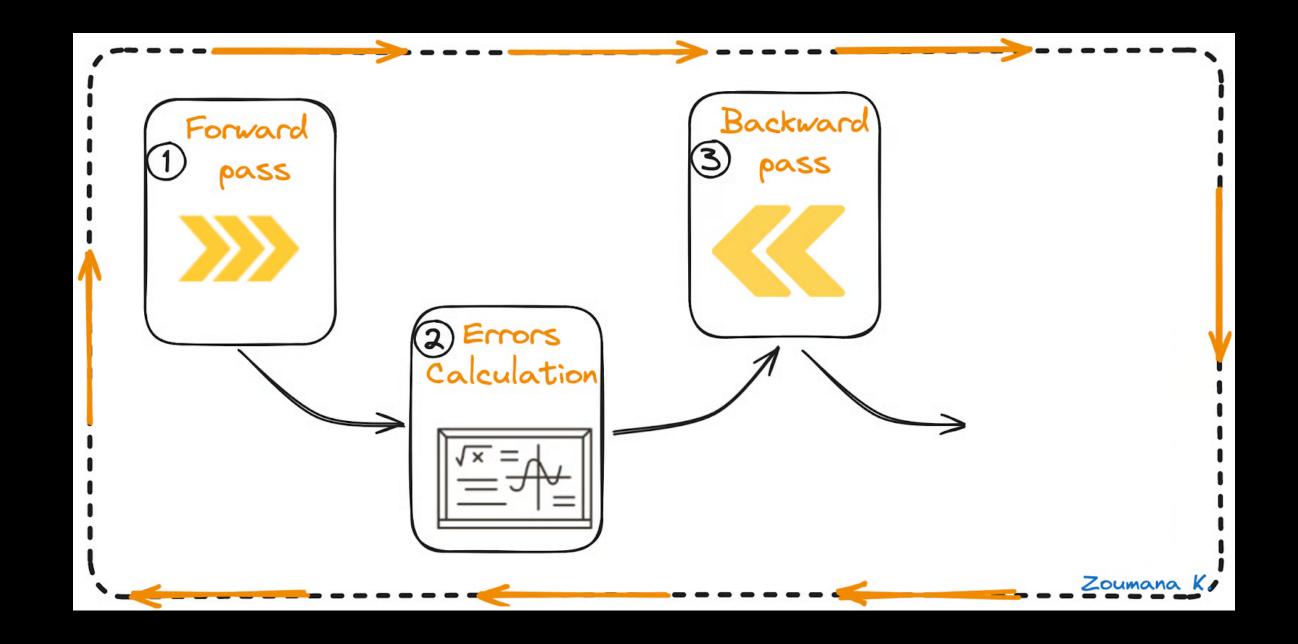




Step 1: Load your dataset

Step 2: Train your model

Step 3: Evaluate your model



```
for epoch in range(epochs):
    for i, data in enumerate(train_loader):
        inputs, labels = data
        optimizer.zero_grad()
        outputs = model(inputs)
        loss = criterion(outputs, labels)
        loss.backward()
        optimizer.step()
```