

# Digital Signal Processing

## Lecture 12 – digital image processing 2

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# INTERPOLATION

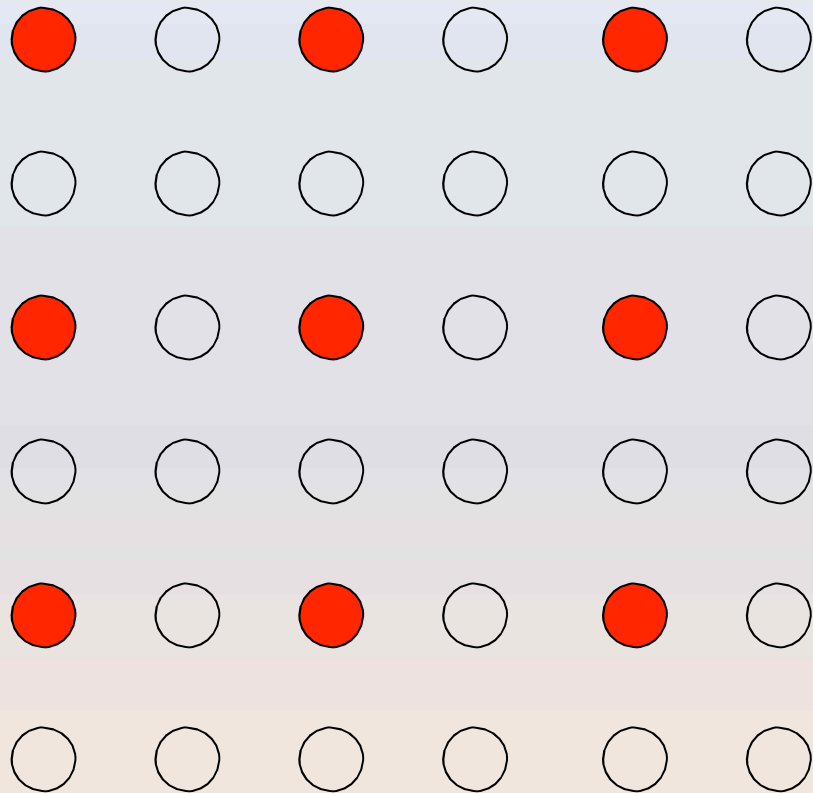
# What is image interpolation?

- An image  $f(x,y)$  tells us the intensity values when  $x$  and  $y$  are both integers.
- Image interpolation refers to the “guess” of intensity values at missing locations, i.e.,  $x$  and  $y$  can be arbitrary.
- Note that it is just a guess. (Note that all sensors have finite sampling distance)
- It is about Digital to Analog conversion.

# Why need image interpolation?

- We want big images
  - When we see a video clip on a PC, we like to see it in the full screen mode.
  - Sometime, we need a smaller image as well.
- We want good images
  - If some block of an image gets damaged during the transmission, we want to repair it.
- We want cool images
  - Image can be rotated, warped or screwed to make funny and cool images.

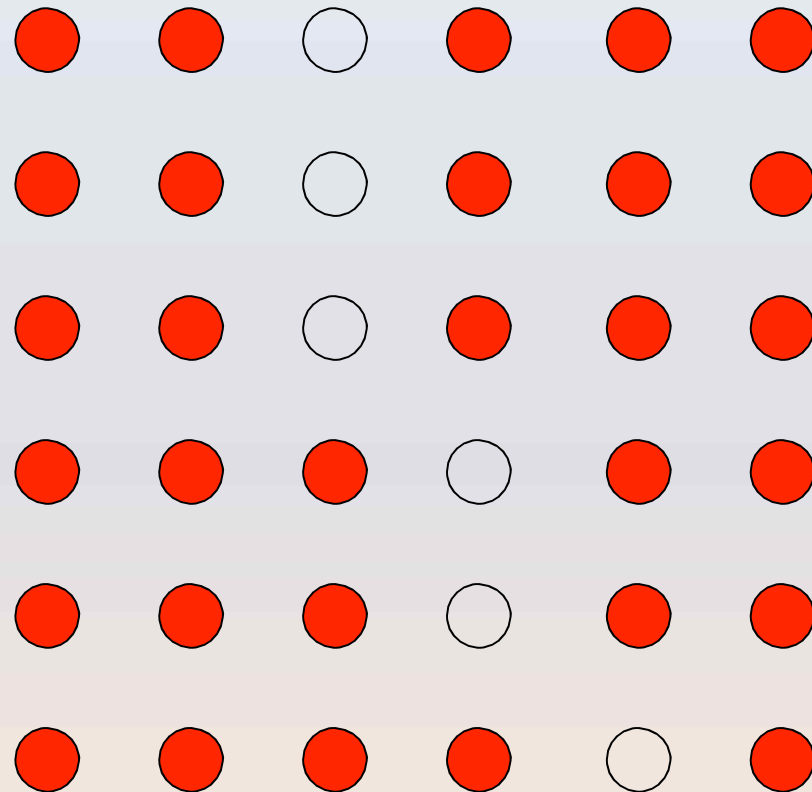
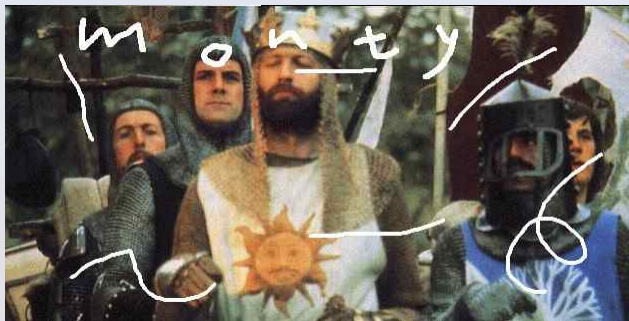
# Ex I – resolution enhancement



Low-Res.

High-Res.

## Ex 2 – Image inpainting

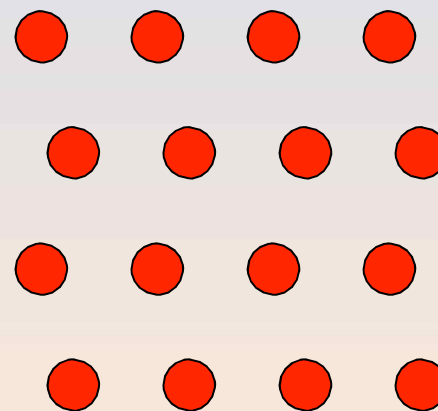
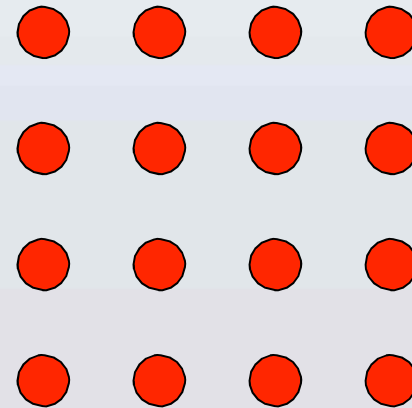


Non-damaged



Damaged

# Ex 3 – Image warping



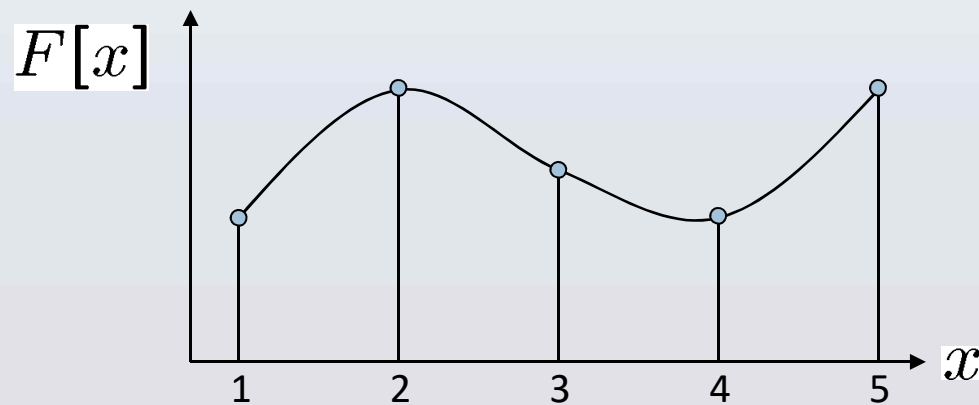
# Upsampling

- ▣ This image is too small for this screen:
- ▣ How can we make it 10 times as big?
- ▣ The simplest approach: repeat each row and column 10 times
- ▣ “Nearest neighbor interpolation”





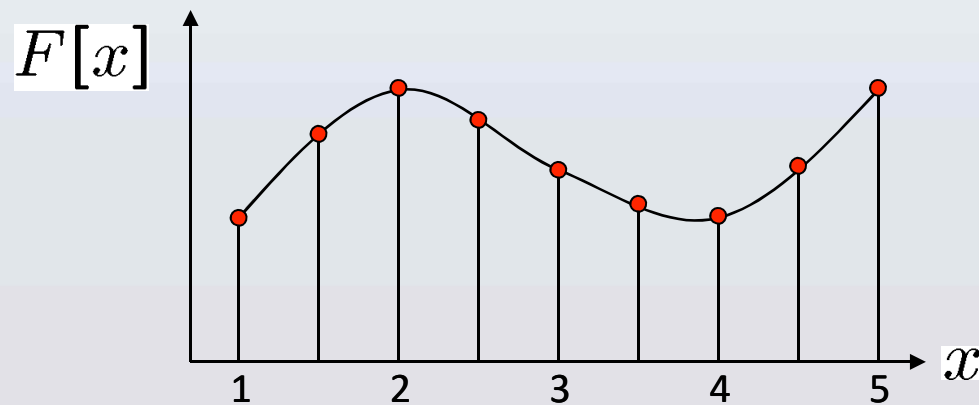
# Interpolation in 1-D



$d = 1$  in this example

- It is a discrete point--sampling of a continuous function
- If we could somehow reconstruct the original function, any new image could be generated, at any resolution and scale

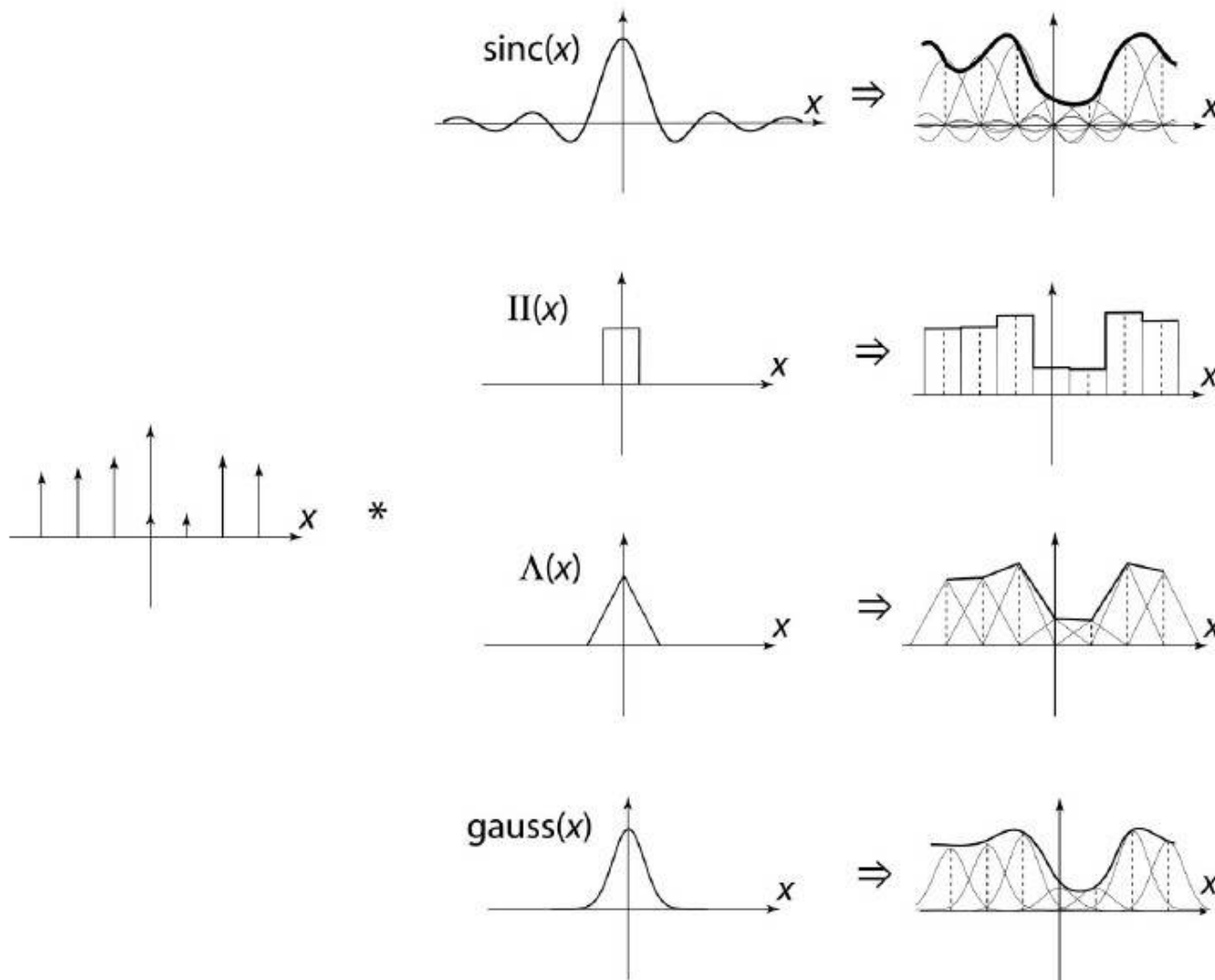
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# Interpolation in 1-D



“Ideal” reconstruction

Nearest-neighbor  
interpolation

Linear interpolation

Gaussian reconstruction

# Interpolation in I-D

Original image:  x 10



Nearest-neighbor interpolation

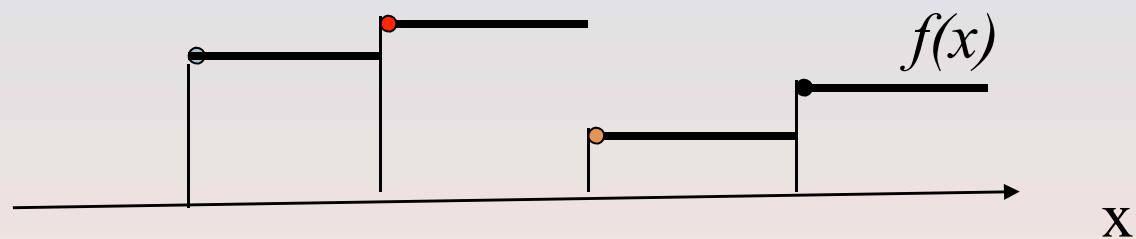
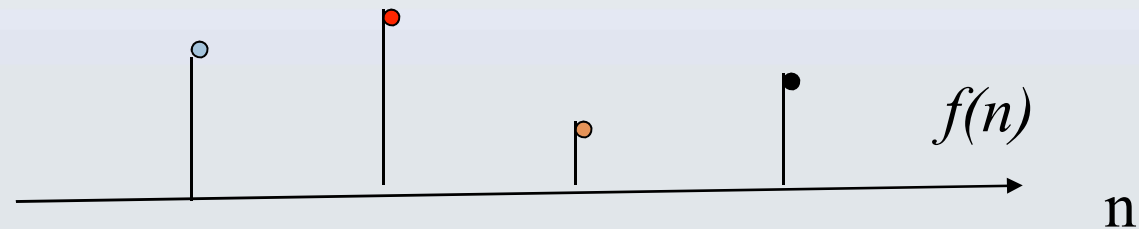


Bilinear interpolation

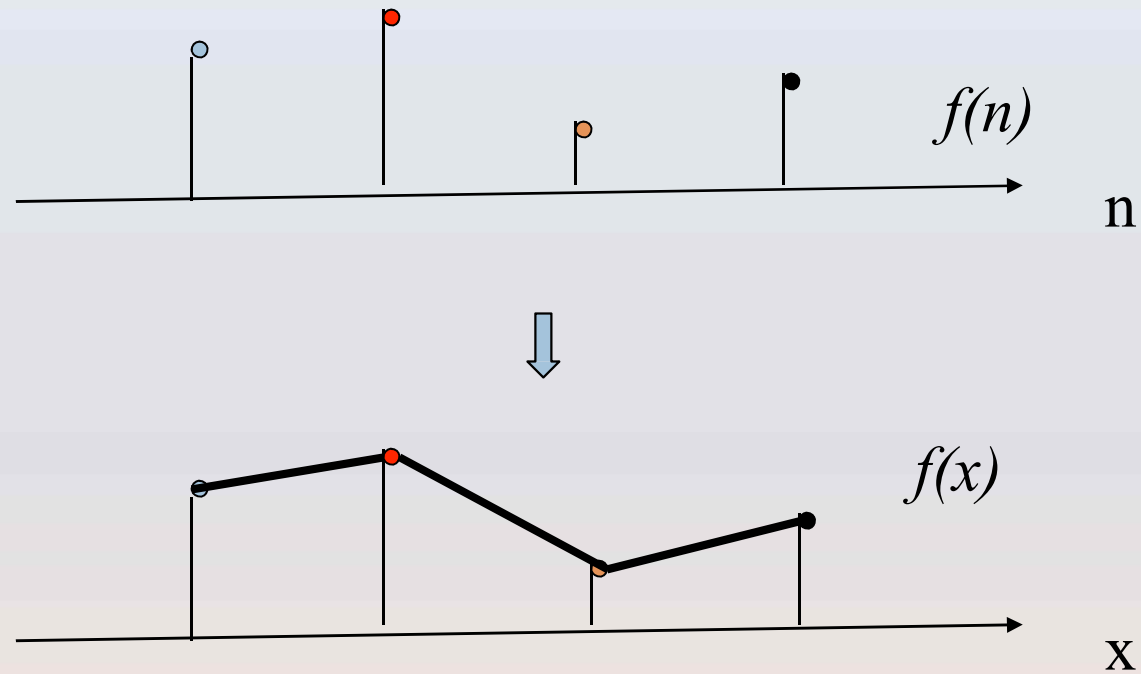


Bicubic interpolation

# I-D zero-order (replication)

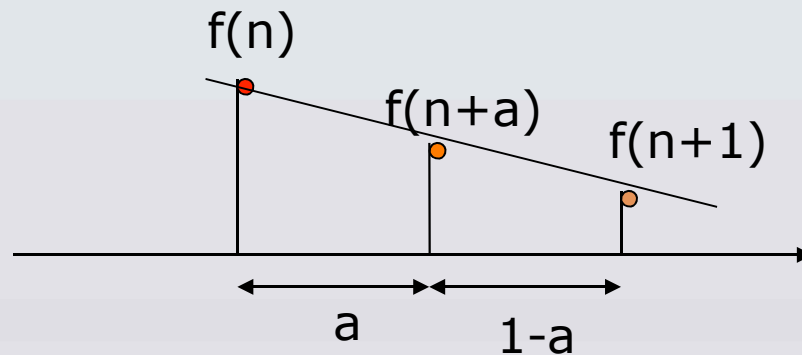


# I-D first-order (Linear)



# Linear interpolation example

Heuristic: the closer to a pixel, the higher weight is assigned  
Principle: line fitting to polynomial fitting (analytical formula)



$$f(n+a) = (1-a) \times f(n) + a \times f(n+1), \quad 0 < a < 1$$

Note: when  $a=0.5$ , we simply have the average of two

# Linear interpolation formula

$$f(n)=[0,120,180,120,0]$$

↓ Interpolate at 1/2-pixel

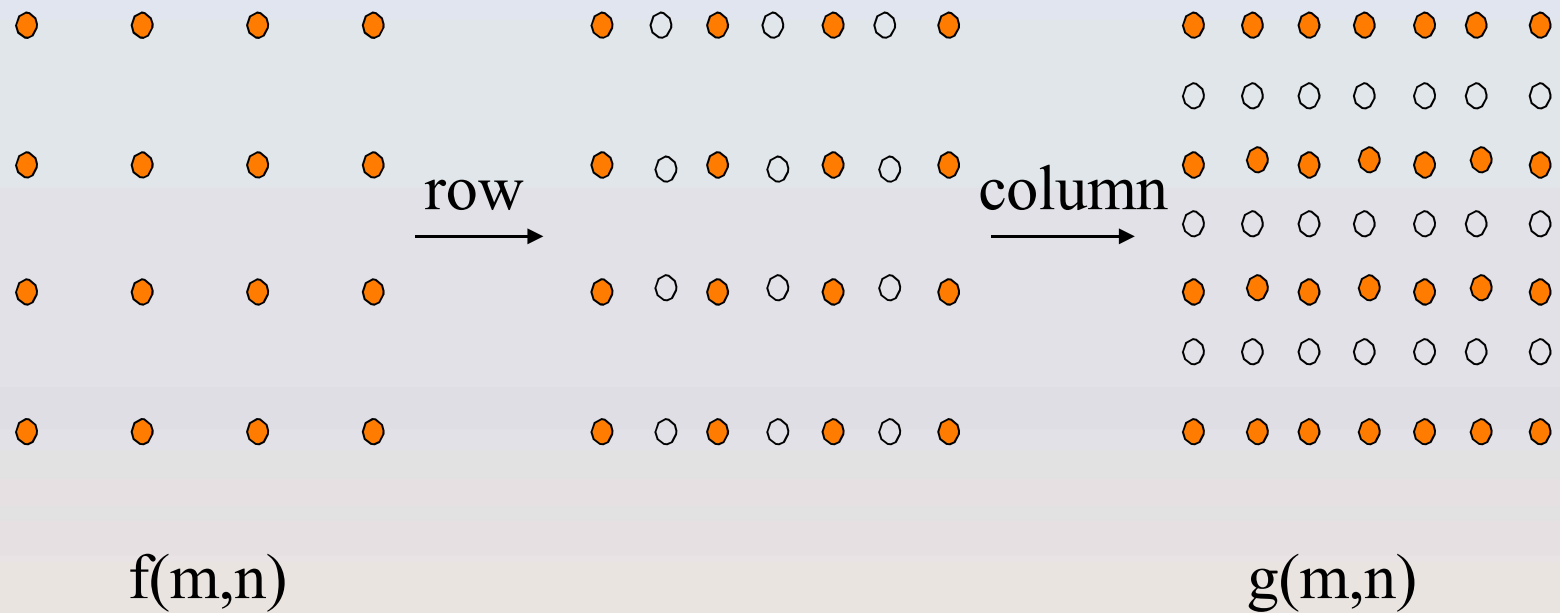
$$f(x)=[0,60,120,150,180,150,120,60,0], x=n/2$$

↓ Interpolate at 1/3-pixel

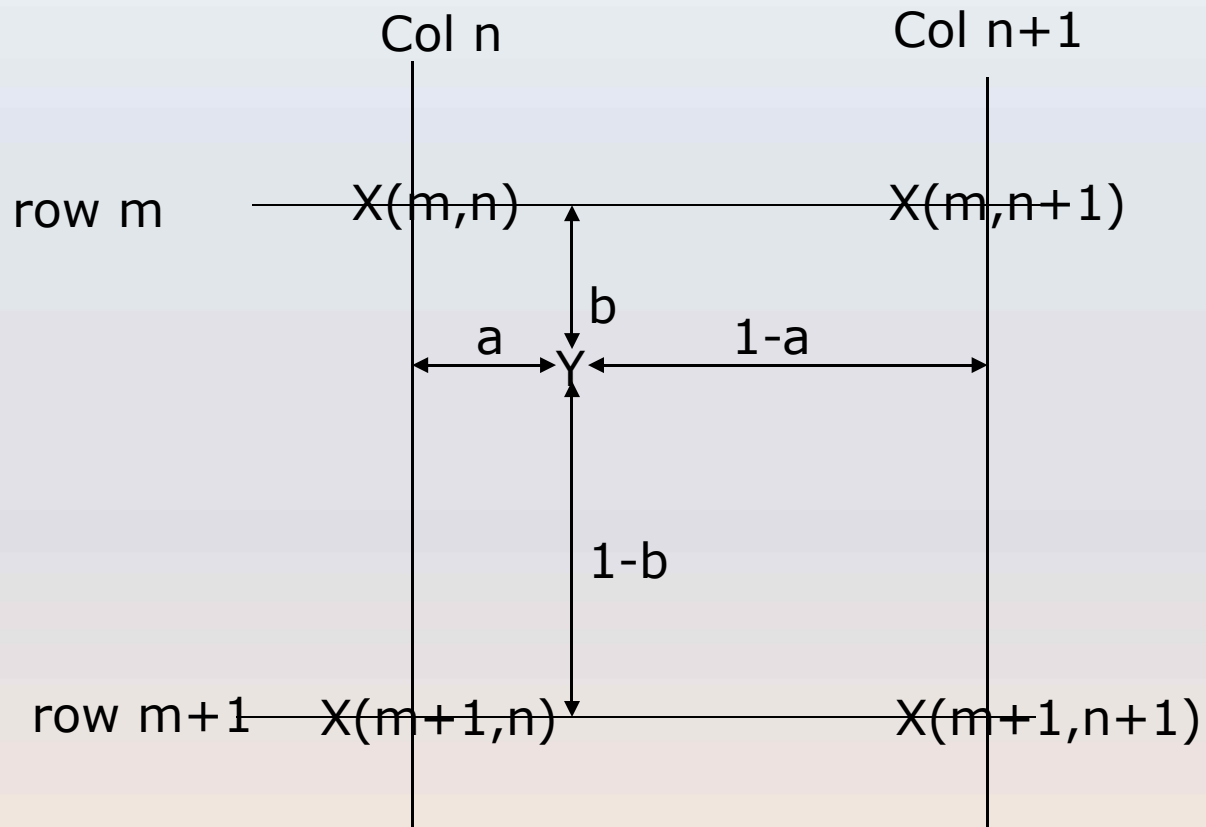
$$f(x)=[0,20,40,60,80,100,120,130,140,150,160,170,180,\dots], x=n/6$$



# From 1-D to 2-D



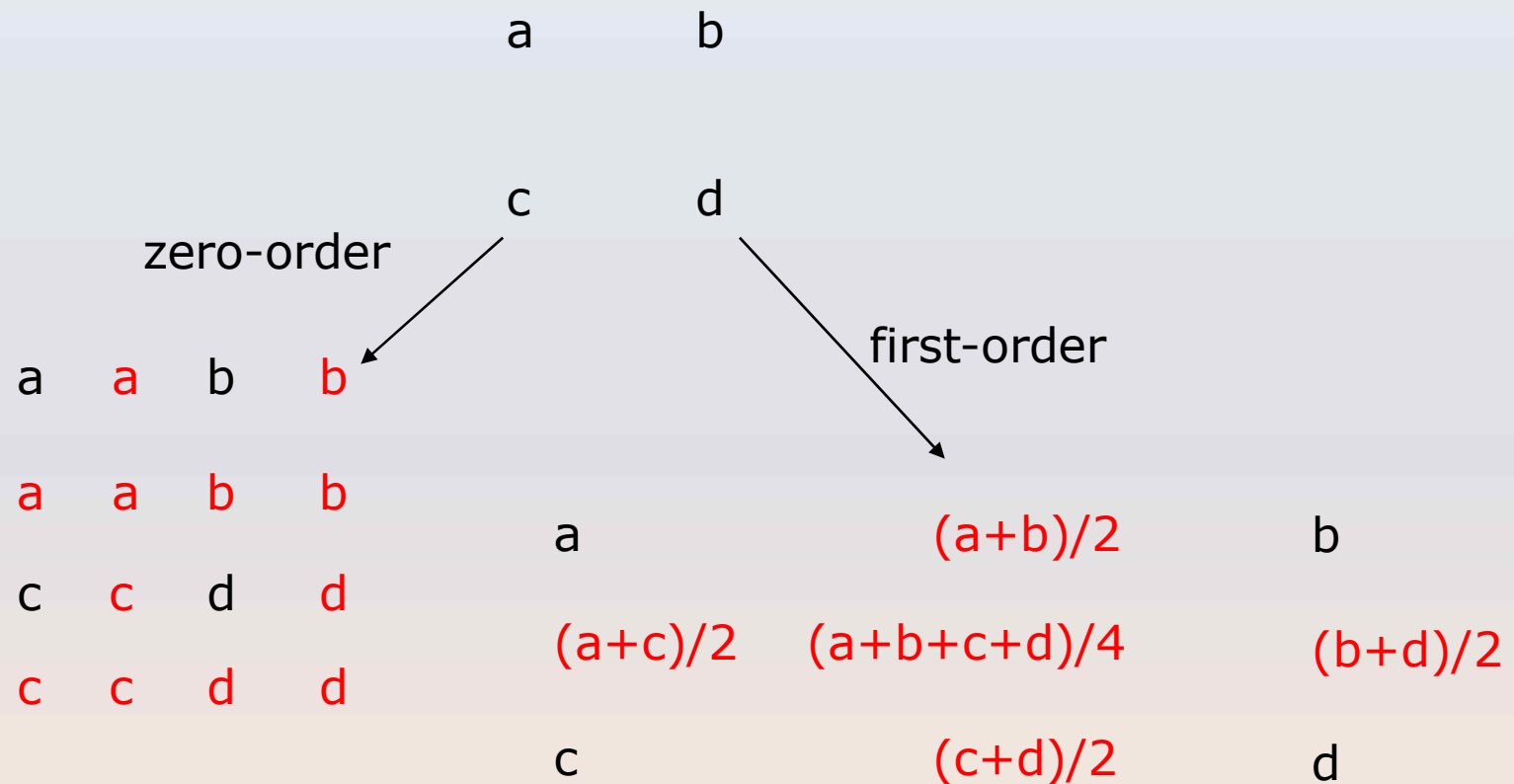
# From 1-D to 2-D example



Q: what is the interpolated value at Y?

Ans.:  $(1-a)(1-b)X(m,n) + (1-a)bX(m+1,n) + a(1-b)X(m,n+1) + abX(m+1,n+1)$

# From 1-D to 2-D example



# LAB

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- ▣ Scaling
  - ▣ magnification
  - ▣ reduction
- ▣ Rotation