Digital Signal Processing

Lecture 10 - Filtering and Convolution

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Smoothing I

- Removing short-term variations from a signal in order to reveal long-term trends.
 - A common smoothing algorithm is a moving average.
 - It computes the mean of the previous n values.

The gray line is the raw data.
The darker line shows the
30-day moving average.

Smoothing removes the most extreme changes.

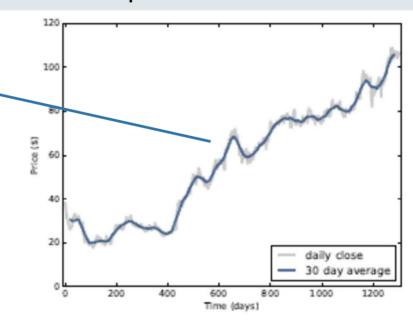


Figure 8.1: Daily closing price of Facebook stock and a 30-day moving average.

Smoothing 2

```
signal = thinkdsp.SquareSignal(freq=440)
wave = signal.make_wave(duration=1, framerate=44100)
segment = wave.segment(duration=0.01)
```

Create a window with II elements and normalize them so that the elements add up to I.

window = np.ones(11) window /= sum(window)

The window is added to the end (to N) with zero values.

ys = segment.ys N = len(ys) padded = thinkdsp.zero_pad(window, N)

The sum of the elementwise products is the average of the first 11 elements.

prod = padded * ys
sum(prod)

Here, elements are all -1 so the average is also -1.

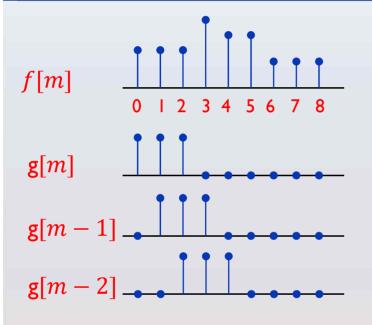
Smoothing the square waveform

The average of the NEXT II elements of the wave array.

```
rolled = np.roll(rolled, 1)
prod = rolled * ys
sum(prod)
```

```
Ex > r0 = [0, 1, 2, 3, 4, 5]
    rI = np.roll(r0, I)
    print(rl)
                            def smooth(ys, window):
                                 N = len(ys)
    rl = [5, 0, 1, 2, 3, 4]
                                 smoothed = np.zeros(N)
                                 padded = thinkdsp.zero_pad(window, N)
                                 rolled = padded
                                 for i in range(N):
                                     smoothed[i] = sum(rolled * ys)
                                     rolled = np.roll(rolled, 1)
                                 return smoothed
```

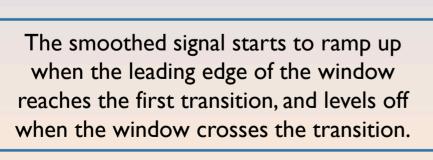
Smoothing the square waveform

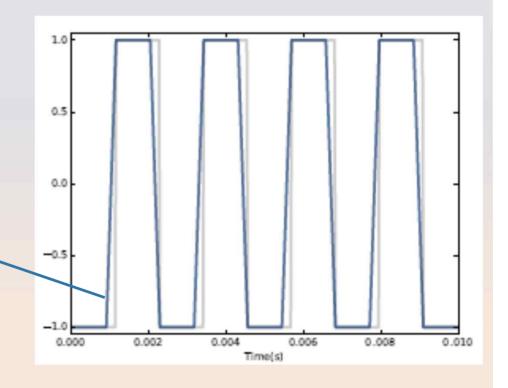


Cross correlation

$$(f \star g)[n] = \sum_{m=0}^{N-1} f[m]g[m-n]$$

, where f is a wave, g is the window.





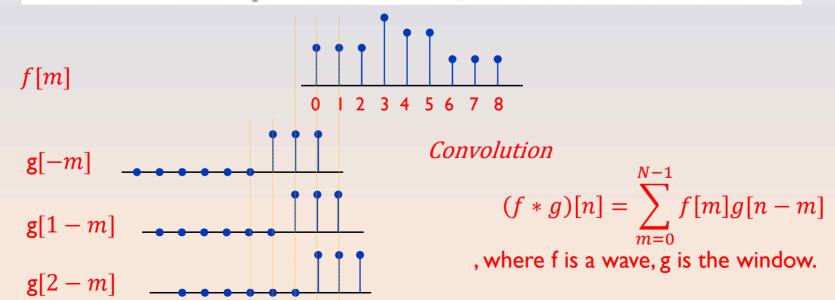
Convolution

Definition

- Applying a window function to each overlapping segment of a wave.
- NumPy provides a simpler and faster version.

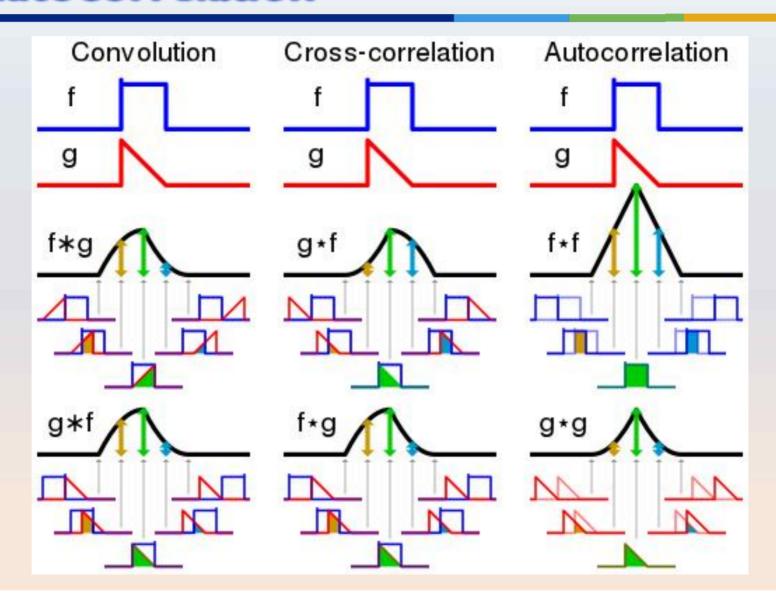
Mode 'valid': only computes values when the window and the wave array overlap completely, so it stops when the right edge of the window reaches the end of the wave array.

convolved = np.convolve(ys, window, mode='valid')
smooth2 = thinkdsp.Wave(convolved, framerate=wave.framerate)

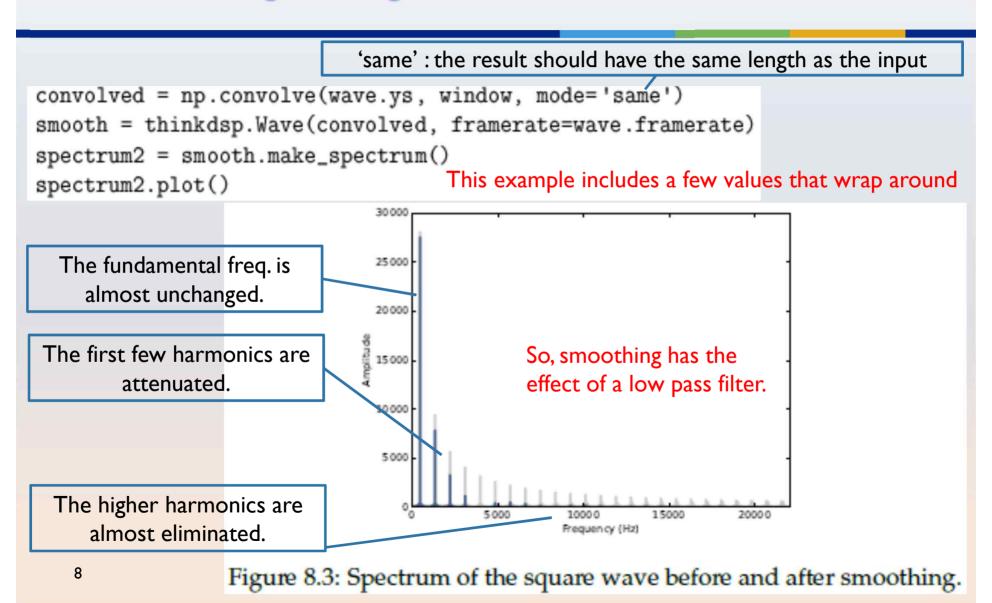


Convolution, Crosscorelation, Autocorrelation

7



The frequency domain 1



The frequency domain 2

To see how much each component has been attenuated.

The ratio is high for low frequencies and drops off at a cutoff freq. near 4400Hz.

amps = spectrum.amps
amps2 = spectrum2.amps
ratio = amps2 / amps
ratio[amps<560] = 0
thinkplot.plot(ratio)</pre>

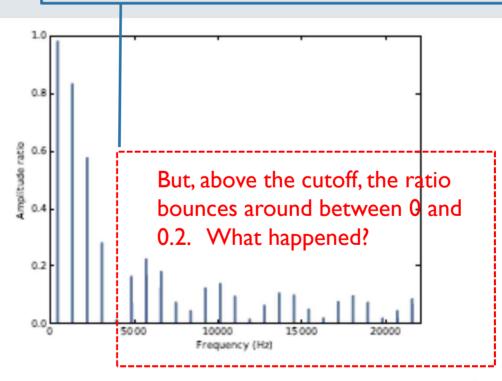


Figure 8.4: Ratio of spectrums for the square wave, before and after smoothing.

The convolution theorem 1

- The answer of the question raised up in the previous slide.
 - Convolution theorem
 - $DFT(f * g) = DFT(f) \cdot DFT(g)$
- Convolution in the time domain corresponds to multiplication in the frequency domain.

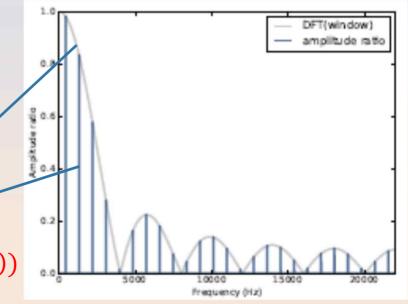
This explains Figure 8.4 because when we convolve a wave and a window, we multiply the spectrum of the wave with the spectrum of the window.

```
padded = zero_pad(window, N)
dft_window = np.fft.rfft(padded)
thinkplot.plot(abs(dft_window))
```

The DFT of the smoothing window

The ratio from the previous slide

abs (DFT(f * g))/abs (DFT(f)) = abs (DFT(g))



Gaussian filter I

- The DFT of a window is called filter.
 - For any convolution window in the time domain, there is a corresponding filter in the frequency domain.
- The moving average window is a low-pass filter, but it is not a very good one.
 - The DFT drops off steeply at first, then it bounces around.
 - The bounces are called sidelobes.
 - The spectrum contains high freq. harmonics that drops off relatively slow.
- Better low freq. filter : Gaussian filter

```
gaussian = scipy.signal.gaussian(M=11, std=2)
gaussian /= sum(gaussian)
```

M: the number of elements in the window std: the standard deviation of the Gaussian distribution

Gaussian filter 2

The ratio of the spectrums before and after smoothing.

As a low-pass filter, Gaussian smoothing is better than a simple moving average.

After the ration drops off, it stays low

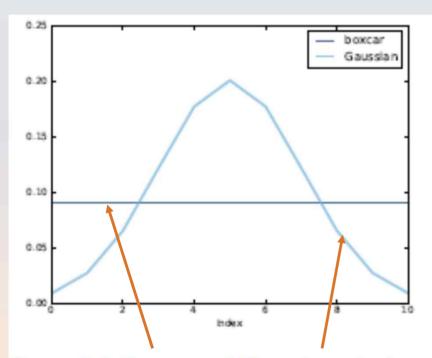
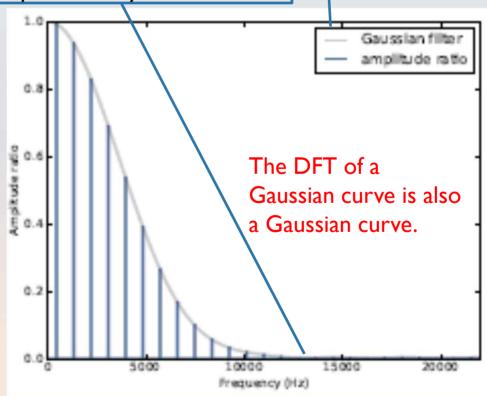


Figure 8.6: Boxcar and Gaussian windows.



Efficient convolution 1

- The FFT provides an efficient way to compute convolution, cross correlation and autocorrelation combined with the Convolution Theorem.
 - Convolution theorem : $DFT(f * g) = DFT(f) \cdot DFT(g)$
 - Convolution computation : $f * g = DFT (DFT(f) \cdot DFT(g))$
 - Complexity change : $O(N^2) \rightarrow O(NbgN)$ Pandas is a software library that

import pandas as pd

Pandas is a software library that offers data structures and operations for manipulating numerical tables and time series

```
names = ['date', 'open', 'high', 'low', 'close', 'volume']
df = pd.read_csv('fb.csv', header=0, names=names)
close = df.close.values[::-1]
```

close is a NumPy array of daily closing prices

Let's compare two computing methods

df is a dataframe provided by pandas.

Loading CSV file

Create dataframe (that we will be importing)

	first_name	last_name	age	preTestScore	postTestScore
0	Jason	Miller	42	4	25,000
1	Molly	Jacobson	52	24	94,000
2	Tina		36	31	57
3	Jake	Milner	24	ot.	62
4	Amy	Cooze	73		70

Efficient convolution 2

```
window = scipy.signal.gaussian(M=30, std=6)
window /= window.sum()
smoothed = np.convolve(close, window, mode='valid')
                             from np.fft import fft, ifft
 f * g
                             def fft_convolve(signal, window):
   DFT (DFT(f) \cdot DFT(g))
                                  fft_signal = fft(signal)
                                  fft_window = fft(window)
                                  return ifft(fft_signal * fft_window)
                              padded = zero_pad(window, N)
                              smoothed2 = fft_convolve(ys, padded)
   To remove bogus values at
                              M = len(window)
  the beginning. Why remove?
                              smoothed2 = smoothed2[M-1:]
```

Two versions are the same, within floating point error.

Efficient autocorrelation 1

- The difference between cross correlation and convolution
 - The window is reversed.

corrs = np.correlate(close, close, mode='same')

There's no apparent periodic behavior.

Why?? Hint: find peak.

same : the result has the same length as close $(-N/2 \sim N/2)$

But, the autocorrelation function drops off slowly. → pink noise!!

To compute autocorrelation using convolution, we have to zero-pad the signal to double the length. This is necessary because the FFT assumes that the signal is periodic.

→ If the signal is not periodic, adding zeros and trimming the result will remove the bogus values

Figure 8.8:

3500 000

3000 000

2500 000

1500 000

-400 -300 -200 -100 0 100 200 300 400

Lag

Figure 8.8: Autocorrelation functions computed by NumPy fft_correlate.

Efficient autocorrelation 2

- Convolution reverses the direction of the window in order to cancel the effect in previous slide.
 - So, reverse the direction of the window before calling fft_convolve.

```
Make signal length twice by adding zero.
```

Flips a NumPy array.

```
roll(array, int) : circular shifting to the right
```

```
def fft_autocorr(signal):
    N = len(signal)
    signal = thinkdsp.zero_pad(signal, 2*N)
    window = np.flipud(signal)

    corrs = fft_convolve(signal, window)
    corrs = np.roll(corrs, N//2+1)[:N]
    return corrs
```

Questions.

Why need zero padding?

Why trim the corrs to take first and last N/2?

Only using libraries is good strategy?