Name :

Student Number :

Lab time:

Abstract:
What we are doing

Introduction
More detail and aim

Background
What does AVC mean, What the robot will be using to get through the maze, there will be no controls on the robot it is all controlled on the terminal.
What the Quads are.

Method

What did we do to get where we are.
What code we used
How we made the hardware parts

Results
When we increased the p constant it became more wobbly, and was over correcting, the correction was larger.

Discussion

How could we improve this
E.g doing 3rd quad, making it faster , more accurate, make a case to protect it.

Conclusion

References

Micheal

Tutor (Mayor)
Ir sensor
Athur