

Total Positivity in Graphical Models

Tryggvi S. Kamban

Positive Definite Matrices and M-Matrices

Gaussian Graphical Models

Total Positivity in Graphical Models Master's Thesis

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University of Copenhagen

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Motivation/Objective

Total Positivity in Graphical Models

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Positive
Definite
Matrices and
M-Matrices

Gaussian Graphical Models The task was to tie together three articles on the subject of multivariate total positivity of order 2 (MTP₂).

- Shaun Fallat et al. (2017). "Total positivity in Markov structures"
- Steffen Lauritzen, Caroline Uhler, and Piotr Zwiernik (2017). "Maximum likelihood estimation in Gaussian models under total positivity"
- Steffen Lauritzen, Caroline Uhler, and Piotr Zwiernik (2019). "Total positivity in structured binary distributions"

The articles assume that the reader has spent years on research in theoretical statistics, hence there are many unfamiliar concepts that are not introduced.



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Gaussian Graphical Models We want to write the thesis with master's students as the target audience!



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Positive Definite Matrices and M-Matrices

Gaussian Graphica Models

Chapter 1: Convex Analysis and Optimization

- Intro to Convex Analysis
- Positive Definite Matrices and M-Matrices
- Convex Optimization

Chapter 2: Total Positivity

- Definitions and Basic Results
- Conditional Independence Models
- Markov Properties and Faithfulness



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Chapter 3: Binary Distributions

- Exponential Families
- Binary Distributions
- Binary Models over Graphs

Chapter 4: Quadratic Exponential Families

- Gaussian Graphical Models
- Gaussian Likelihood and Convex Optimization
- Totally Positive Gaussian Graphical Models

Chapter 5: Ising Models and Conditional Gaussian Distributions

- Ising Models
- Conditional Graphical Distributions



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Positive Definite Matrices and M-Matrices

Gaussian Graphical Models $V = \{1,...,d\}$ finite set

 $X = (X_v, v \in V)$ random vector with labels in V

 $\mathcal{X} = \prod_{v \in V} \mathcal{X}_v$ product space, where $\mathcal{X}_v \subseteq \mathbb{R}$ state space of X_v

 \mathcal{X}_v are either discrete finite sets, or open intervals on \mathbb{I}



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MTP₂ Property

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Gaussian Graphical Models A function f on $\mathcal X$ is multivariate totally positive of order 2 (MTP $_2$) if

$$f(x)f(y) \leq f(x \wedge y)f(x \vee y) \text{ for all } x,y \in \mathcal{X},$$

where

$$x \wedge y = (\min(x_v, y_v), v \in V) \text{ and } x \vee y = (\max(x_v, y_v), v \in V)$$

We say that a distribution P is MTP_2 if its density function is MTP_2



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Example

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Positive Definite Matrices and M-Matrices

Gaussian Graphical Models Let

$$x=\begin{pmatrix}1\\2\\3\end{pmatrix},\ y=\begin{pmatrix}3\\2\\1\end{pmatrix}.\ \text{Then}\ x\wedge y=\begin{pmatrix}1\\2\\1\end{pmatrix},\ x\vee y=\begin{pmatrix}3\\2\\3\end{pmatrix}$$

The function $f: \mathbb{R}^3 \to \mathbb{R}$ defined by

$$f(x_1, x_2, x_3) = x_1 x_2 x_3$$

is MTP₂. Indeed,

$$f(x)f(y) \le f(x \land y)f(x \lor y)$$

 $\Leftrightarrow 6 \times 6 \le 2 \times 18$



Cool Properties of MTP₂ Distributions

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Gaussian Graphical Models

Proposition 2.2.6

The MTP₂ property is preserved under

- taking products $(f, g \mathsf{MTP}_2 \Rightarrow fg \mathsf{MTP}_2)$
- conditioning
- marginalization

Proposition 2.2.7 (Modified)

If f is MTP $_2$ in any pair of arguments when the remaining arguments are held constant, and if f has full support, then f is MTP $_2$

A consequence of Proposition 2.2.7 is that in order to check whether a density function f is MTP₂ it is sufficient to consider only 2 variables at a time instead of all variables simultaneously.



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Gaussian Graphical Models

Positive Definite Matrices and M-Matrices



Positive Definite Matrices

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Positive Definite Matrices and M-Matrices

Gaussian Graphical Models A symmetric $p \times p$ matrix A is positive (semi-)definite $(A \succeq 0, A \succ 0)$ if for any $x \in \mathbb{R}^p \setminus \{\mathbf{0}\}$,

$$(x^T A x) \ge 0, \qquad x^T A x > 0$$

Example: The $p \times p$ identity matrix I is positive definite.

Lemma 1.2.3

Let A be a symmetric real-valued $p \times p$ matrix with eigenvalues $\lambda_i, i \in \{1,...,p\}$. Then $A \succeq 0 \iff \lambda_i \geq 0$ for all $i \in \{1,...,p\}$.



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A matrix A where A^{-1} is an M-matrix is called an *inverse* M-matrix.

Any M-matrix is inverse-positive.

Example

$$M = \begin{bmatrix} 1 & -0.2 & 0 \\ -0.2 & 1 & -0.4 \\ 0 & -0.4 & 1 \end{bmatrix}, \quad M^{-1} = \begin{bmatrix} 1.05 & 0.25 & 0.1 \\ 0.25 & 1.25 & 0.5 \\ 0.1 & 0.5 & 1.2 \end{bmatrix}$$

Eigenvalues: $\lambda_1 = 1, \lambda_2 = 1/\sqrt{5}, \lambda_3 = 1 - 1/\sqrt{5}$



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Totally Positive Gaussian Graphical Models

Total Positivity in Graphical Models

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Positive Definite Matrices and M-Matrices

Gaussian Graphical Models A multivariate Gaussian graphical model is MTP $_2$ if and only if the concentration matrix $K=\Sigma^{-1}$ is a symmetric M-matrix. Hence, all partial correlations will be non-negative

$$\rho_{X_iX_j|V\backslash\{i,j\}} = -\frac{K_{ij}}{\sqrt{K_{ii}K_{jj}}} \geq 0 \quad \text{for all} \quad i,j\in\{1,...,p\}$$

Because of this, Simpson's paradox is impossible in MTP₂ Gaussian graphical models!



Totally Positive Gaussian Graphical Models

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The wildest result (in my opinion)

Total Positivity in Graphical Models

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Positive Definite Matrices and M-Matrices

Gaussian Graphical Models We are used to the condition for existence of an MLE in Gaussian Models to be that the number of observations n must be at least as large as the number of parameters p.

Theorem 4.5.6 (Slawski and Hein)

Consider a Gaussian MTP₂ model and let S be the sample covariance matrix. If $S_{ij} < \sqrt{S_{ii}S_{jj}}$ for all $i \neq j$, then the MLE $\hat{\Sigma}$ (and \hat{K}) exists and it is unique. In particular, if the number n of observations satisfies $n \geq 2$, then the MLE exists with probability 1



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Thank you for listening, and stay Totally Positive!