

BLDC Motor Controller Design

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1 Motor Parameters

The motor selection is the first step taken in order to design the motor controller. The motor was selected based on the application it was to be used in. The vehicles average and maximum speeds, and peak acceleration/deceleration was used as the criterion. The motor selected was the **Turnigy G46 Brushless Outrunner**.

Parameter	Value
Recommended Battery	4-5 Cells @ 14.4-18.5V
RPM	670kv
Max Current	40A
No Load Current	10V/3.9A
Current Capacity	55A/15sec
Internal Resistance	0.04 ohm
Weight	303g
Diameter of Shaft	6mm
Dimensions	76x50mm

Figure 1: Motor Parameters

1.1 Motor Demands

The boundary parameters mentioned previously are also essential in selecting the components for the power stage of the motor controller. These parameters are as follows;

Parameter	Value
Average Speed	30 km h ⁻¹
Peak Speed	52 km h ⁻¹
Wheel diameter	0.6m
Wheel Reduction Ratio	1:10
Average RPM (for switching frequency)	2653 RPM
Peak RPM (for switching frequency)	4598 RPM
Peak Acceleration (for dv/dt FET capabilities)	0.856 RPM s ⁻¹

Figure 2: Motor Boundaries

2 MOSFETs

The selected MOSFET based on the motor parameters was the **IRF1405**

A summary of the MOSFETs parameters is below:

	Parameter	Value	Conditions
$V_{(BR)DSS}$	Drain-to-Source Breakdown Voltage	55V	$V_{GS} = 0V, I_D = 250\mu A$
I_D	Continuous Drain Current	169A	$V_{GS} = 10V, T_C = 25^\circ C$
I_D	Continuous Drain Current	118A	$V_{GS} = 10V, T_C = 100^\circ C$
I_{DM}	Pulsed Drain Current	680A	
T_J	Operating Junction Temperature Range	$-55^\circ C - 175^\circ C$	
Q_G	Total Gate Charge	$170nC - 260nC$	$I_D = 101A, V_{DS} = 44V, V_{GS} = 10V$
Q_{gs}	Gate-to-Source Charege	$44nC - 66nC$	$I_D = 101A, V_{DS} = 44V, V_{GS} = 10V$
Q_{gd}	Gate-to-Drain (Miller) Charge	$62nC - 93nC$	$I_D = 101A, V_{DS} = 44V, V_{GS} = 10V$
t_r	Rise time	190ns	$V_{DD} = 38V, I_D = 101A, R_G = 1.1\Omega, V_{GS} = 10V,$
t_f	Fall time	110ns	$V_{DD} = 38V, I_D = 101A, R_G = 1.1\Omega, V_{GS} = 10V,$

Figure 3: IRF1405 Specifications

3 Gate Driver

The N-Channel MOSFET gate driver is selected based on the MOSFET specifications. Additional criteria such as functionality and minimal power dissipation is secondary.

3.1 Peak Current Drive Requirements

This is the primary criterion for the driver selection. This is primarily based on how fast the application (motor) requires the MOSFET to be turned on and off (rise and fall time of the gate voltage).

This turn on/off speed, dT , is in turn related to how fast the gate capacitance of the MOSFET can be charged and discharged.

$$dT = \frac{[dV \times C]}{I} = \frac{Q}{I} \quad (1)$$

Where;

- dV = Gate voltage
- C = Gate capacitance
- I = Peak drive current
- Q = Total gate charge

In the case of the IRF1405, the total gate charge is 260nC and a turn on/off time of $t = t_r + t_f = 300ns$

Thus we have a required average current draw of

$$I = \frac{Q}{dT} = \frac{260 \times 10^{-9}}{300 \times 10^{-9}} = 0.9A \quad (2)$$

not sure,
used max
total gate
charge

3.2 Power Dissipation

There are three elements due to the charging and discharging of the gate capacitance of the MOSFET:

1. Power dissipation due to the charging and discharging of the gate capacitance of the MOSFET, P_C
2. Power dissipation due to quiescent current draw of the MOSFET driver, P_Q
3. Power dissipation due to cross-conduction (shoot-through) current in the MOSFET driver, P_S

The following equations apply:

$$P_C = C_G \cdot V_{DD}^2 \cdot F \quad (3a)$$

$$P_Q = (I_{QH} \cdot D + I_{QL} \cdot (1 - D)) \cdot V_{DD} \quad (3b)$$

$$P_S = CC \cdot F \cdot V_{DD} \quad (3c)$$

$$(3d)$$

Where;

- C_G is the MOSFET Gate Capacitance
- V_{DD} is the supply voltage of the MOSFET driver
- F is the switching frequency
- I_{QH} is the Quiescent current of the driver with the input in the high state
- D is the Duty cycle of the switching waveform
- I_{QL} the quiescent current of the driver with the input in the low side

3.3 IRS2181

The **IRS2181** was the selected MOSFET driver. It is fully operational up to 600V with 1.4-1.8A source/sink current capabilities.

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- 4 Microcontroller
 - 5 Regulation
 - 6 Current Sensing