

Calibration results

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Camera-system parameters:

cam0 (/cam0/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.EquidistantDistortedPinholeCameraGeometry'>

distortion: [0.3629376 1.42254321 -7.57228568 11.99773121] +- [0.01616255 0.19283206 0.9154985 1.45497019]

projection: [911.05649263 915.36904269 654.54823528 375.66810191] +- [1.49848477 1.51083662 0.89229483 0.56625001]

reprojection error: [-0.000000, 0.000000] +- [0.282370, 0.271946]

Target configuration

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Type: aprilgrid

Tags:

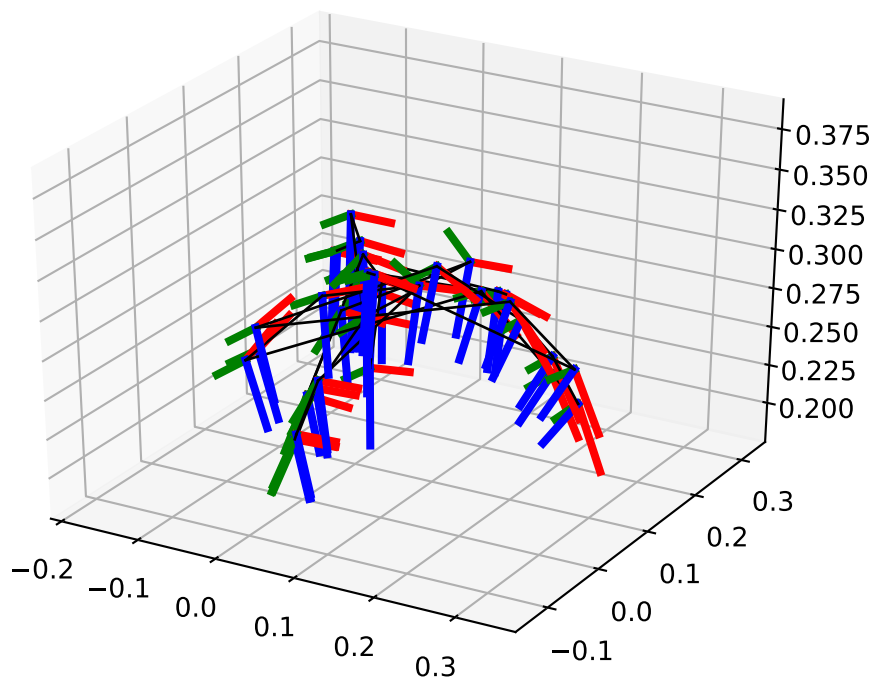
Rows: 6

Cols: 6

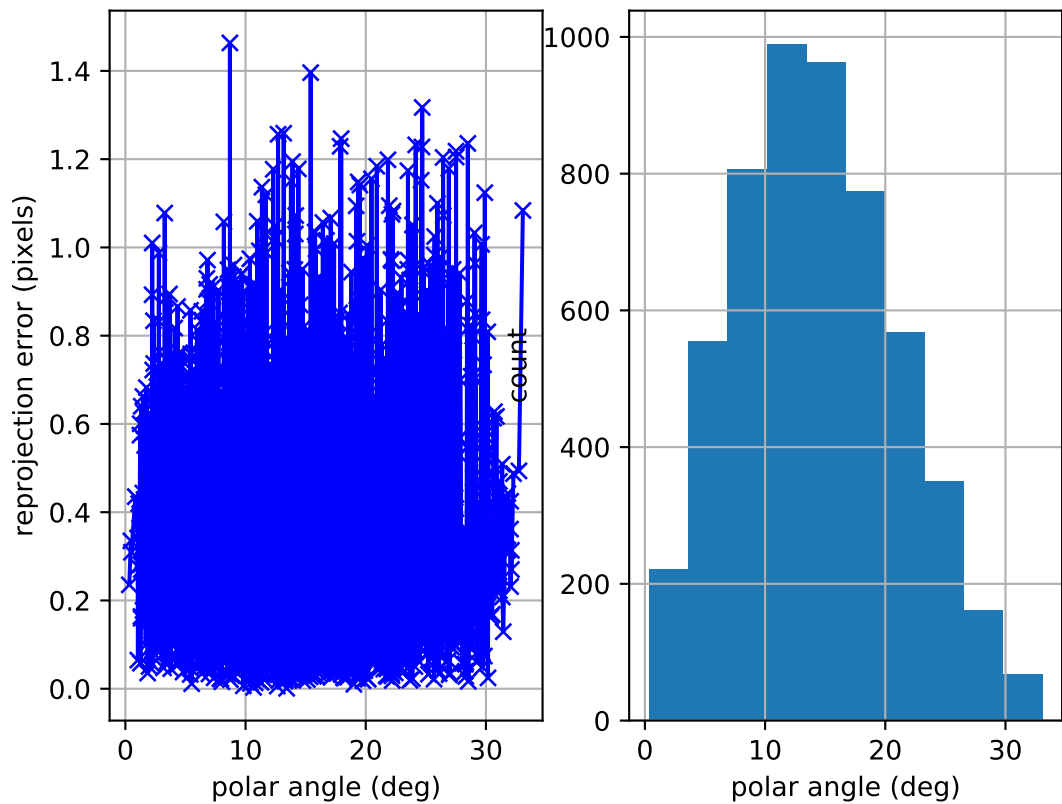
Size: 0.02 [m]

Spacing 0.005 [m]

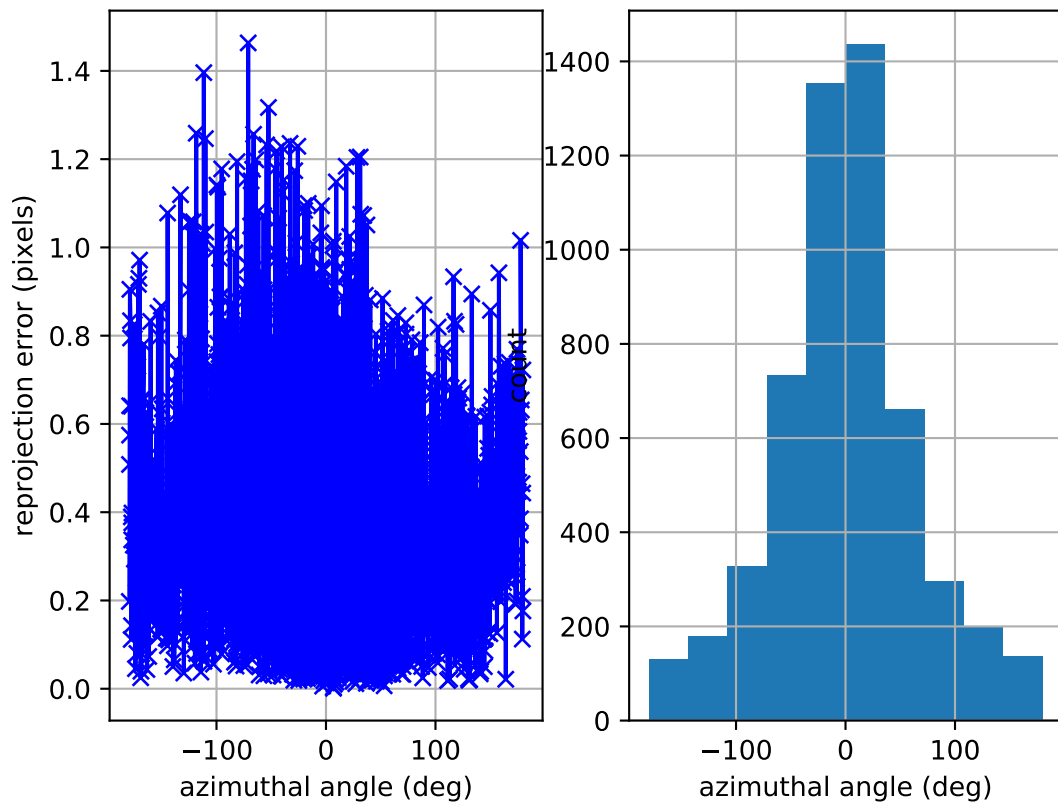
cam0: estimated poses



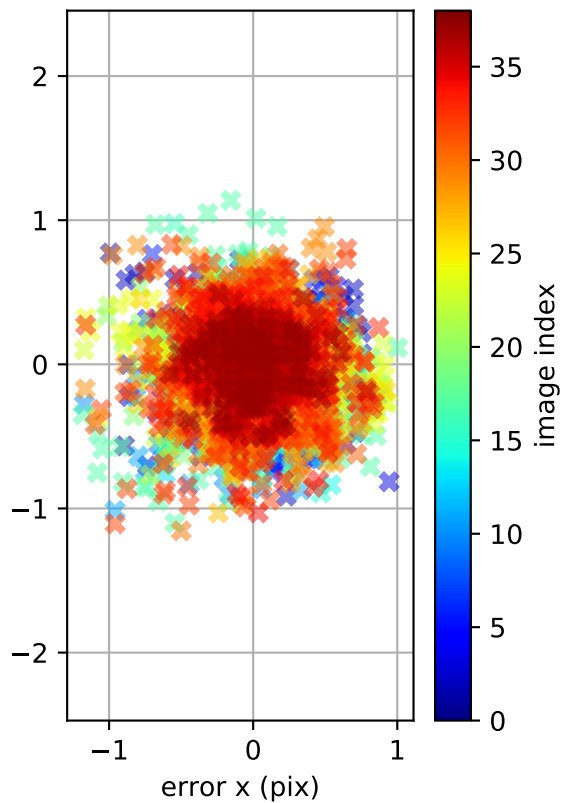
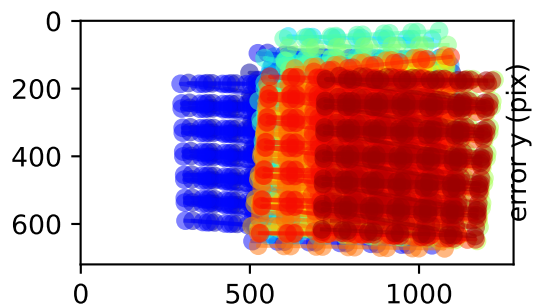
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

