

Calibration results

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Camera-system parameters:

cam0 (/cam0/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [0.12654702 -0.2140766 0.00091269 -0.00317508] +- [0.0040596 0.00870865 0.00051723 0.00074716]

projection: [910.34857558 913.38968507 649.26933459 377.10979606] +- [1.53736639 1.53089921 1.47436842 1.28915134]

reprojection error: [0.000000, 0.000000] +- [0.287041, 0.277600]

Target configuration

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Type: aprilgrid

Tags:

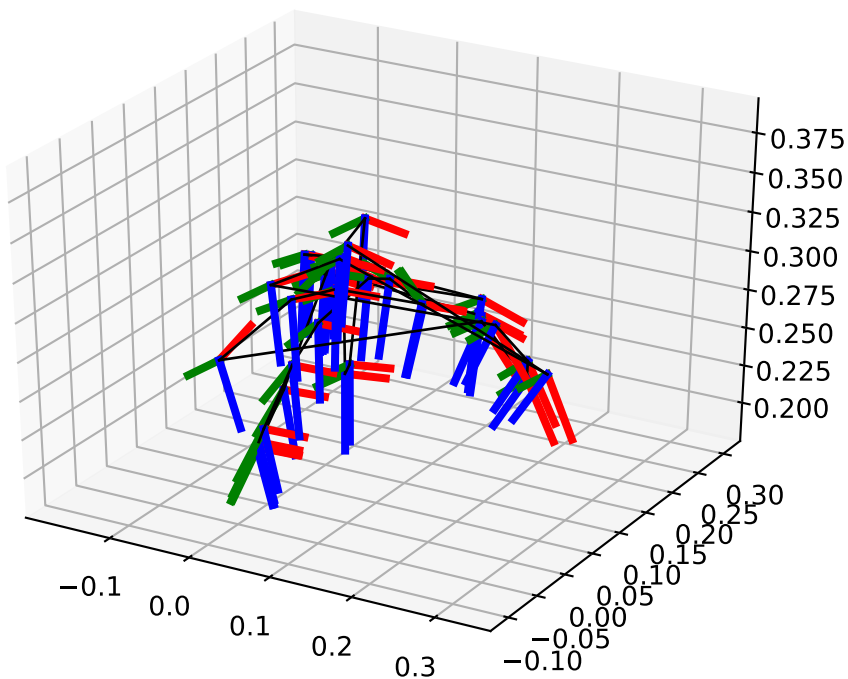
Rows: 6

Cols: 6

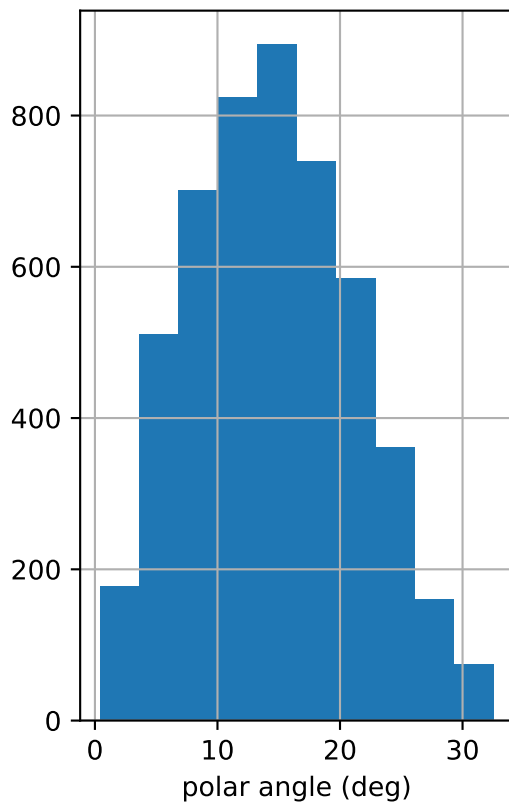
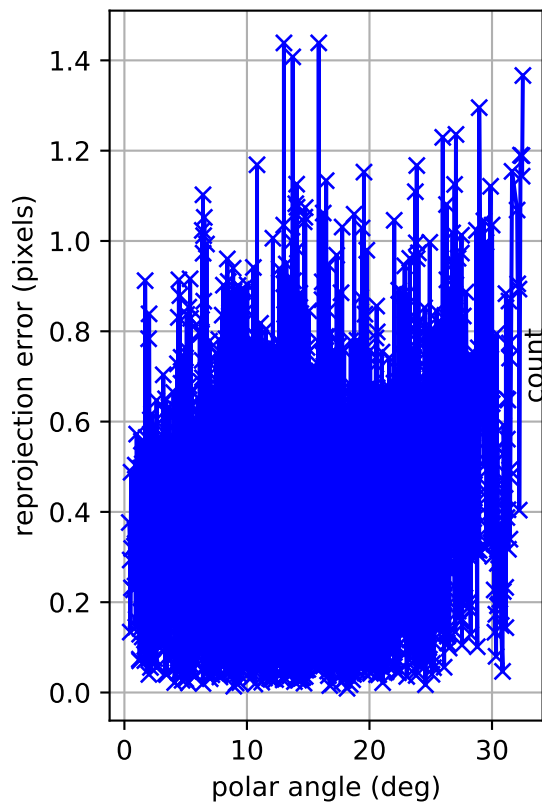
Size: 0.02 [m]

Spacing 0.005 [m]

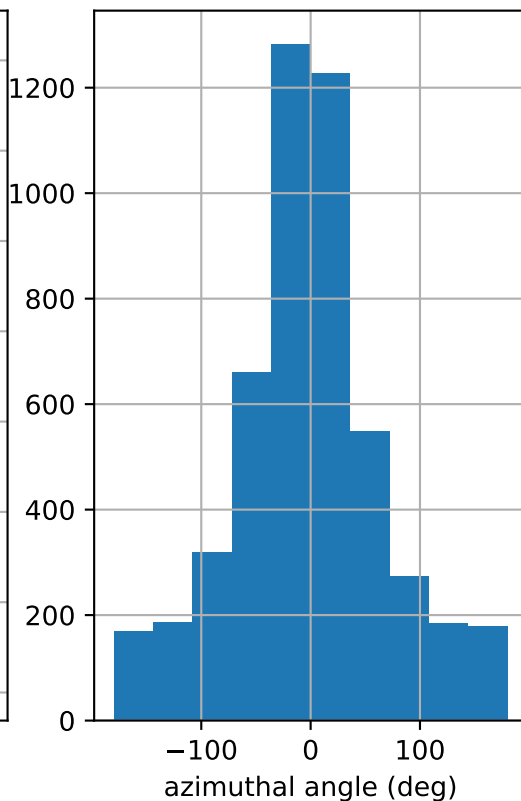
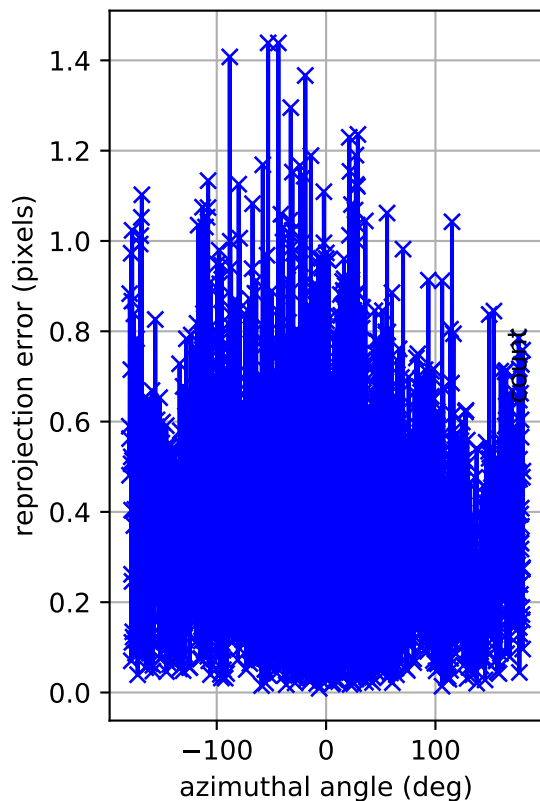
cam0: estimated poses



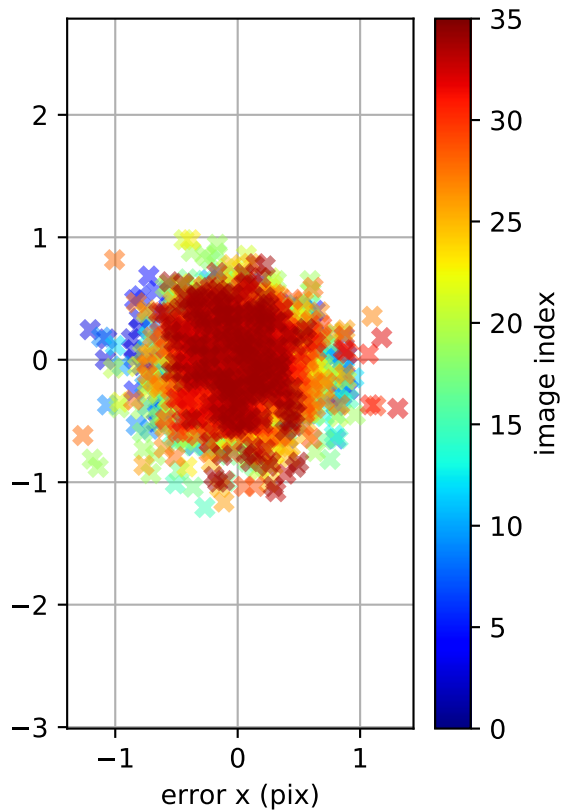
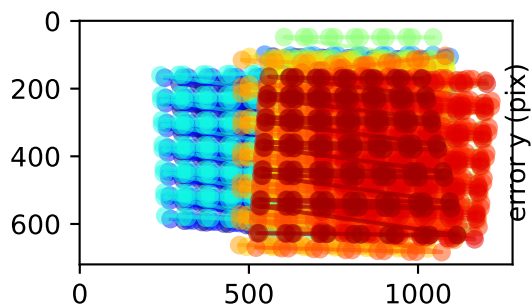
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

