Hashing

In the implementation of randomized algorithms, a strong need for data representation is needed. Truly independent hash functions are extremely useful in these situations. It allows generalization of arrays, where it is possible to access an arbitrary position in an array in O(1) time.

Introduction to hash functions

Imagine a universe of keys $U = \{u_0, u_1, ..., u_{m-1}\}$ and a range $[r] = \{0, 1, ..., m-1\}$ where u_i are integers module m. Given a hash function $h(x) \to [r]$ which takes any $u_i, i = 0, 1, ..m-1$ as argument, it should hold that $\forall u_i, \exists r_j \in [r]$ such that $h(u_i) = r_j$. What remains is to consider collisions, which we define as

$$\delta_h(x,y) = \begin{cases} 1 & \text{if } x \neq y \text{ and } f(x) = f(y) \\ 0 & \text{else} \end{cases}$$
 (1)

for a given hash function h and two keys x and y. The goal of a hashing algorithm is then to minimize the number of collisions across all possible keys. A truly random hash function can assure that there are no collision at all. Unfortunately, to implement such a function would require at least $|U|\log_2 m$ bits[?], defeating the purpose of hash functions altogether. Fixed hashing algorithms have attempted to solve this problem. Unfortunately, its dependence on input causes a worst case average retrieval time of $\Theta(m)$.[?]

Universal hashing can circumvent the memory and computation cost of both random- and fixed hashing, without losing much precision. An introduction to universal hashing will follow, alongside two applications of said hashing which will be tested later in this paper.

Universal hash functions

The first mention of universal hashing was in [?], in which they define universality of hash functions as follows:

Given a class of hash functions $H:U\to [r]$, H is said to be universal if $\forall x\forall y\in U$

$$\delta_H(x,y) \le |H|/|[r]|$$

where, with $S \subset U$

$$\delta_H(x,S) = \sum_{h \in H} \sum_{y \in S} \delta_h(x,y)$$

That is, H is said to be universal if

$$\Pr_h[h(x) = h(y)] \le 1/m \tag{2}$$

for a random $h \in H$. In many applications, $\Pr_h[h(x) = h(y)] \leq c/m$ for c = O(1) is sufficiently low collision probability.

Carter and Wegman[?]

Given a prime $p \ge m$ and a hash function $h_{a,b} : [U] \to [r]$,

$$h_{a,b}(x) = ((a * x + b) \mod p) \mod m \tag{3}$$

where a and b are integers mod m, where $a \neq 0$. We want to prove that $h_{a,b}(x)$ satisfies Eq. 2; thus proving that it is universal.

Let x and y be two randomly selected keys in U where $x \neq y$. For a given hash function $h_{a,b}$,

$$r = a \cdot x + b \mod p$$

$$q = a \cdot y + b \mod p$$

We see that $r \neq q$ since

$$r - s \equiv a(k - l) \pmod{p}$$

must be non-zero since p is prime and both a and (k-l) are non-zero module p, and therefore a(k-l) > 0 as two non-zero multiplied by each other cannot be positive, and therefore must also be non-zero module p. Therefore, $\forall a \forall b, h_{a,b}$ will map to distinct values for the given x and y, at least at the mod p level.

Dietzfelbinger et al.[?]

Also commonly referred to as **multiply-shift**, this state of the art scheme described in [?] reduces computation time by eliminating the need for the **mod** operator. This is especially useful when the key is larger than 32 bits, in which case Carter and Wegman's suggestion is quite costly[?].

Take a universe $U \ge 2^k$ which is all k-bit numbers. For $l = \{1, ..., k\}$, the hash functions $h_a(x) : \{0, ..., 2^k - 1\} \to \{0, ..., 2^l - 1\}$ are then defined as

$$h_a(x) = (a \cdot x \mod 2^k) \div 2^{k-l} \tag{4}$$

for a random odd number $0 < a < 2^k$. l is bitsize of the value the keys map to. This scheme only nearly satisfies Eq. 2, as for two distinct $x, y \in U$ and any allowed a

$$\Pr_{h_a}[h_a(x) = h_a(y)] \le \frac{1}{2^{l-1}} = \frac{2}{m}$$
 (5)