Práctica en Julia y Optimización

Taller 3

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Métodos Cuantitativos



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Optimización 1

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Problem 1

Piense en el modelo de optimización:

$$Maxx_1^a x_2^b x_3^c$$

 $s.a$
 $p_1x_1 + p_2x_2 + p_3x_3 \le I$
 $x_3 \ge 2x_2$
 $x_1, x_2, x_3 \ge 0$

- 1. Resuelva el problema utilizando los conocimientos de las condiciones de Karush Kuhn Tucker. Suponga a,b,c >1, los precios p1, p2, p3 >0. Y el párametro I > 1.
 - 2. Resuelva en Julia, usando a=b=c=2, p1=100, p2=120 y p3=200, con I=100000.

Solution. 1. Planteamos el lagrangiano:

$$L = x_1^a x_2^b x_3^c - \lambda_1 \left[p_1 x_1 + p_2 x_2 + p_3 x_3 - I \right] - \lambda_2 \left[2 x_2 - x_3 \right]$$
 C.P.O

$$\begin{array}{l} \frac{\partial L}{\partial x_1} = ax_1^{a-1}x_2^bx_3^c - \lambda_1p_1 = 0\\ \frac{\partial L}{\partial x_2} = bx_1^ax_2^{b-1}x_3^c - \lambda_1p_2 + 2\lambda_2 = 0\\ \frac{\partial L}{\partial x_3} = cx_1^ax_2^bx_3^{c-1} - \lambda_1p_3 + \lambda_2 = 0\\ \frac{\partial L}{\partial \lambda_1} = I - p_1x_1 - p_2x_2 - p_3x_3 = 0\\ \frac{\partial L}{\partial \lambda_2} = 2x_2 - x_3 = 0\\ \lambda_1 \ge 0 \end{array}$$

$$\lambda_1 \ge 0$$

$$\lambda_2 \ge 0$$

$$p_1 x_1 + p_2 x_2 + p_3 x_3 \le I$$

$$2x_2 - x_3 \ge 0$$

$$x_1 \ge 0, x_2 \ge 0, x_3 \ge 0$$

Caso I:
$$\lambda_1 = \lambda_2 = 0$$

$$ax_1^{a-1}x_2^bx_3^c = 0$$
 $x_1 = x_2 = x_3 = 0$

$$2x_2 - x_3 = 2(0) - 0 = 0 < 0$$

No se cumple.

Caso II:
$$\lambda_1 > 0, \lambda_2 = 0$$

$$ax_1^{a-1}x_2^bx_3^c - \lambda_1 p_1 = 0 \ (1)$$

$$bx_1^a x_2^{b-1} x_3^c - \lambda_1 p_2 = 0 \ (2)$$

$$cx_1^a x_2^b x_3^{c-1} - \lambda_1 p_3 = 0$$
 (3)

$$p_1 x_1 + p_2 x_2 + p_3 x_3 = I \rightarrow x_1 = \frac{I - p_2 x_2 - p_3 x_3}{p_1}$$
 (4)

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2 Optimización

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Resolviendo (2) y (1):
$$\frac{\alpha y_1^{\alpha} + y_2^{\alpha} y_1^{\alpha}}{p_1} = \frac{b x_1^{\alpha} x_2^{\beta} - 1 x_2^{\alpha}}{p_2} \rightarrow x_1 = x_2 * \frac{p_2}{p_2} * \frac{a}{b} (5)$$
Resolviendo (3) y (1):
$$\frac{\alpha y_1^{\alpha} + x_2^{\alpha} y_2^{\alpha}}{p_1} = \frac{c x_1^{\alpha} x_2^{\alpha} y_2^{\alpha}}{p_3} \rightarrow x_1 = x_3 * \frac{p_3}{p_1} * \frac{a}{c} (6)$$
Resolviendo (5) y (6):
$$x_2 * \frac{p_2}{p_1} * \frac{a}{c} = x_3 * \frac{p_3}{p_1} * \frac{a}{c} \rightarrow x_2 = x_3 * \frac{p_3}{p_2} * \frac{b}{c} (7)$$
Resolviendo (5) y (4):
$$x_2 * \frac{p_2}{p_1} * \frac{a}{b} = \frac{I - p_2 x_2 - p_3 x_3}{p_1} \rightarrow p_2 x_2 + p_2 x_2 * \frac{a}{b} = I - p_3 x_3$$

$$p_2 x_2 + p_2 x_2 (1 + \frac{a}{b}) = I - p_3 x_2 \rightarrow x_2 = \frac{I - p_3 x_3}{p_2 (1 + \frac{a}{b})} (8)$$
Resolviendo (7) y (8):
$$x_3 * \frac{p_3}{p_2} * \frac{b}{c} = \frac{I - p_3 x_3}{p_1 (1 + \frac{a}{b})} \rightarrow p_3 x_3 + p_3 x_3 (1 + \frac{a}{b}) * \frac{b}{c} = I$$

$$p_3 x_3 (1 + \frac{a + b}{c}) = I \rightarrow x_3 = \frac{I}{p_3 (\frac{a + b + c}{a + b + c})} (9)$$
Resolviendo (9) y (7):
$$x_2 = \frac{I}{p_3 (\frac{a + b + c}{a + b + c})} * \frac{p_2}{p_3} * \frac{a}{c} \rightarrow x_1 = \frac{I}{p_1 (a + b + c)}$$
Resolviendo (9) y (6):
$$x_1 = \frac{I}{p_3 (\frac{a + b + c}{a + b + c})} * \frac{p_2}{p_1} * \frac{a}{c} \rightarrow x_1 = \frac{I}{p_1 (a + b + c)}$$
Caso III: $\lambda_1 = 0, \lambda_2 > 0$

$$ax_1^{-1} x_2^{b} x_3^{c} - \lambda_1 p_1 = 0$$

$$bx_1^{a} x_2^{b} x_3^{c} - \lambda_1 p_1 = 0$$

$$bx_1^{a} x_2^{b} x_3^{c} - \lambda_1 p_2 - 2\lambda_2 = 0$$
Cos ax_1^{-1} x_2^{b} x_3^{c} - \lambda_1 p_3 + \lambda_2 = 0
No se cumple.

Caso IV: $\lambda_1 > 0, \lambda_2 > 0$

$$ax_1^{-1} x_2^{b} x_3^{c} - \lambda_1 p_3 + \lambda_2 = 0$$
(3)
$$2x_2 - x_3 = 0$$
(4)
$$p_1 x_1 + p_2 x_2 + p_3 x_3 - I = 0$$
(5)
Resolviendo (1) y (2):
$$\frac{ax_1^{a} x_1^{b} x_2^{b} x_3^{c} - \lambda_1 p_3 + \lambda_2 = 0}{p_3} = 0$$
(6)
Resolviendo (1) y (3):
$$\frac{ax_1^{a} x_1^{b} x_2^{b} x_3^{c} + \frac{a^{b} x_2^{b} x_3^{c} - \lambda_2}{p_1} = \frac{a^{b} x_2^{b} x_3^{c} - \lambda_2}{p_2}$$
(7)
Resolviendo (6) y (7):
$$x_1^{a} x_2^{b} x_3^{c} (\frac{p_3 a}{p_1 + a}) = \frac{a^{b} x_1^{b} x_1^{b} x_1^{b} x_2^{b} x_3^{c} - \lambda_2}{p_3^{b} x_1^{b} x_1^{b} x_1^{b} x_2^{b} x_3^{c} - \frac{1}{2} (\frac{a}{x_1^{b} x_1^{b} x_1^{b} x_1^{b} - \frac{b}{x_2^{b}})$$
Resolviendo (4) y (5):
$$p_1 + x_1 + p_2 x_2 + p_3 (2x_2) - I = 0 \rightarrow x_1 = \frac{I - p_2 x_2 - p_3 x_2 x_2}{p_3 x_2 x_2^{b} x_$$



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Resolviendo (4) y (8):
$$\frac{p_3}{p_1} * \frac{a}{x_1} - \frac{c}{2x_1} = \left(-\frac{1}{2}\right) * \frac{a}{x_1} * \frac{p_2}{p_1} - \frac{b}{x_2} \rightarrow x_2 = \frac{ax_2p_2 + 2ax_2p_3}{p_1(c+b)}$$
 (10) Resolviendo (9) y (10:
$$\frac{I - p_2x_2 - p_32x_2}{p_1} = \frac{ax_2p_2 + 2ax_2p_3}{p_1(c+b)}$$

$$I(c+b) - p_2x_2(c+b) - 2x_2p_3(c+b) - ax_2p_2 - 2ax_2p_3 = 0$$

$$I(c+b) = x_2(cp_2 + bp_2 + 2cp_3 + 2bp_3 + ap_2 + 2ap_3)$$

$$x_2 = \frac{I(c+b)}{p_2(a+b+c)2p_3(a+b+c)} \rightarrow \frac{I(c+b)}{(p_2 + 2p_3)(a+b+c)}$$

$$x_1 = I - p_2 \left[\frac{I(c+b)}{(p_2 + 2p_3)(a+b+c)} \right] - 2p_3 \left[\frac{I(c+b)}{(p_2 + 2p_3)(a+b+c)} \right]$$

$$x_3 = 2 \left[\frac{I(c+b)}{(p_2 + 2p_3)(a+b+c)} \right]$$



4 Optimización

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2. La especificación del modelo es:

```
using JuMP
2 using Ipopt
 4 function solve_optimization()
      a = 2
      c = 2
      p1 = 100
      p2 = 120
10
      p3 = 200
      I = 100000
11
12
       model = Model(Ipopt.Optimizer)
       @variables(model, begin
          x1 >= 0
15
           x2 >= 0
16
           x3 >= 0
17
18
       end)
19
       @NLobjective(
20
           model,
21
           Max,
           x1^a * x2^b * x3^c
24
25
      @constraint(
26
27
           model,
           p1 * x1 + p2 * x2 + p3 * x3 <= I
29
30
       @constraint(
31
          model,
33
           x3 >= 2 * x2
34
35
       optimize!(model)
36
37
       println("Termination status: ", termination_status(model))
38
       println("Objective value: ", objective_value(model))
39
       println("x1: ", value(x1))
40
       println("x2: ", value(x2))
       println("x3: ", value(x3))
42
43 end
44
45 solve_optimization()
```