A PROJECT SYNOPSIS

ON

"Real Time Face Detection and Recognition"

Submitted in the partial fulfillment of the requirements for

The degree of

BACHELOR OF ENGINEERING IN COMPUTER ENGINEERING

By

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UNDER THE GUIDANCE OF

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Department of Computer Engineering Saraswati College of Engineering, Kharghar, Navi Mumbai University of Mumbai 2022-23

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- 3. Investigate Complex Computer engineering problems to find appropriate solution leading to valid conclusion.
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- 12. Identify educational needs and engage in lifelong learning in a Changing World of Technology.



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- Plan and develop efficient, reliable and secure system and customized application software using cost effective emerging software tools ethically.

DECLARATION

I declare that this written submission represents my ideas in my own words and where others' ideas or words have been included. I have adequately cited and referenced the original sources. I also declare that I have adhered to all principles of academic honesty and integrity and have not misrepresented or fabricated or falsified any idea/data/fact/source in my submission. I understand that any violation of the above will be cause for disciplinary action by the Institute and can also evoke penal action from the sources which have thus not been properly cited or from whom proper permission has not been taken when needed.

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Date:

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ABSTRACT

In today's fast-growing world everyone wants to save time as much as they can, one cannot relay dependent on older method if we want to recognize someone without asking them or verifying now days it can be only possible through a system where user authentication can be done through videos or images with the help of AI and ML.

Face detection is a popular application of object detection in computer vision. To detect faces in a digital image or video input requires the computer to utilize a series of algorithms or techniques. The technology of detecting faces has evolved proportional to its usage in various applications such as biometric security, autofocus in cameras, robotics, and social media applications. The aim of this project is to provide a description on the evolution of face detection and recognition.

It will be difficult for any organization to evaluate everyone one by one therefore it is necessary to have something at hand which can check or verify person if needed. Face detection is an important research direction in the field of target detection. For the input image, the position of the face is returned. In order to complete the task of face detection using deep learning, data input, feature extraction and face feature detection are three steps, among which feature extraction is the most important part. By studying the basic principles of current mainstream target detection algorithms, this paper compares the characteristics of Two-stage and one stage detection models and their application in face detection tasks.

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INTRODUCTON

1.1 GENERAL

The goal of face detection is to determine if there are any faces in the image or video. If multiple faces are present, each face is enclosed by a bounding box and thus we know the location of the faces. Human faces are difficult to model as there are many variables that can change for example facial expression, orientation, lighting conditions, and partial occlusions such as sunglasses, scarfs, masks, etc. The result of the detection gives the face location parameters, and it could be required in various forms, for instance, a rectangle covering the central part of the face, eye centres or landmarks including eyes, nose and mouth corners, eyebrows, nostrils, etc.

Computer vision is an extended disciplinary field of computer graphics. The term computer vision describes the process, or the action done by the computer that mimics the human visual system. Another interpretation of computer vision is creating a self-sufficient system that can carry out some of tasks of the human visual cortex. Most scientists use computer vision to extract information from digital images or videos the same way a human being's visual receptors do.

Face detection is one of the more popular applications of object detection in computer vision. The computer uses a series of mathematical algorithms, pattern recognition and image processing to identify faces from an image or video input. Over the years, the technology of detecting faces has evolved proportional to its usage in various applications. One of the earliest documented usage of face detection was traced back to the work of Woodrow Wilson Bledsoe in the 1960s, where his research using manual measurements to recognize faces paved the way to the various systems developed.

The general concept of face detection is most commonly achieved with the following three steps; the first step is to examine the picture or video frame to determine the regions of interest. This is usually done via a sliding window. The second step is to acquire the extracted features or patterns from the region of interest. This is where the main aspects of the face detection algorithm lie such as using Haar-like features, Histogram of Oriented Gradients or deep learning methods such as convolutional neural networks. Finally, the third step is to classify if the detected regions of interest into faces and non-faces for recognition.

1.2 OBJECTIVE AND PROBLEM STATEMENT

This project aims to build a system that can recognize faces in a real time to help the organization in determining the identification of particular person by integrating face detection and recognition software with IP Camera.

Functionality:

- > Extraction of frames from Ip camera video.
- Extraction faces from frames.
- > Recognition of extracted faces from frames.
- ➤ If face matched with any faces in face repository, then storing it in Index DB with corresponding frame time and location of camera.

LITERATURE REVIEW

Paper Name	Author	Year	Publication	Remark
A Real-Time	Rehmat Ullah , Hassan	2022	Hindadwi	Recognizes single face
Framework for	Hayat, Afsah Abid			from Image using PCA,
Human Face	Siddiqui, Uzma Abid			CNN and KNN.
Detection and	Siddiqui, Jebran Khan,			Average of 30 images
Recognition in	Farman Ullah, Shoaib			for each face before
CCTV Images [1]	Hassan, Laiq Hasan,			classifying accurately.
	Waleed Albattah,			
	Muhammad Islam, and			
	Ghulam Mohammad			
	Karami			
Face Recognition	Edwin Jose, Greeshma	2019	Institute of	Face detection and
based	M., Mithun Haridas T.		Electrical and	recognition of human
Surveillance	P. Haridas, M. H.		Electronics	faces using embedded
System Using	Supriya		Engineers	graphic card Jetson
FaceNet and				TX2 in IP camera.
MTCNN on				• Models used by the
Jetson TX2 [2]				authors are MTCNN
				and FaceNet.
Joint Face	Kaipeng Zhang,	2016	Institute of	Multitask Cascaded
Detection and	Zhanpeng Zhang,		Electrical and	Convolutional
Alignment Using	Zhifeng Li, Yu Qiao		Electronics	Networks is enhanced
Multitask			Engineers	version of Cascade
Cascaded				Classifier uses three

Convolutional				different layers of CNN
Networks [3]				for detection of faces.
				• Each layer uses 3 loss
				function.
FaceNet: A	Florian Schroff,	2015	Institute of	Learns an embedding
unified	Dmitry Kalenichenko,		Electrical and	into an Euclidean space
embedding for	James Philbin		Electronics	for face verification.
face recognition			Engineers	Based on two deep
and clustering [4]				network architectures.
Robust Real-	Paul Viola, Michael J.	2003	Kluwer	Cascade Classifiers.
Time Face	Jones		Academic	HAAR like features are
Detection [5]			Publishers	used.
				Best suited for real-
				time face detection.

PROBLEM STATEMENT AND SCOPE

3.1 PROBLEM STATEMENT

This project aims to build a system that can recognize faces in a real time to help the
organization in determining the identification of particular person by integrating face detection
and recognition software with IP Camera.

3.2 SCOPE

- Preventing the frauds at ATMs in India. A database of all customers with ATM cards in India can
 be created and facial recognition systems can be installed. So, whenever user will enter in ATM
 his photograph will be taken to permit the access after it is being matched with stored photo from
 the database.
- Reporting duplicate voters.
- Passport and visa verification can also be done using this technology.
- Also, driving license verification can be done using the same approach.
- In defence ministry, airports, and all other important places the technology can be used to ensure better surveillance and security.
- It can also be used during examinations such as Civil Services Exam, SSC, IIT, MBBS, and others
 to identify the candidates.

- This system can be deployed for verification and attendance tracking at various government offices and corporates.
- For access control verification and identification of authentic users it can also be installed in bank lockers and vaults.
- For identification of criminals the system can be used by police force also.

PROPOSED SYSTEM

4.1 ALGORITHM

Data Pre-processing:

Data pre-processing is a step of cleaning, transforming and aggregating data before it can work with algorithms. In this project we need to pre-process live video frames before they can be fed to a model using OpenCV [8] we can detect and extract face(s) from frames. OpenCV provides three different algorithms for detecting faces in a stream of images viz., Cascade Classifier and MTCNN (Multitask Convolution Neural Network) using Haar Basis functions with AdaBoost as its core component first created by Viola-Jones [5] and HOG (Histogram of Oriented Gradients) descriptor and object detector by Navneet Dalal and Bill Triggs. Cascade Classifier can process 25 images/second with precision of 95.24% and recall of 82.60%, MTCNN can process 3 images/second with precision of 98.02% and recall of 89.85% this reading is estimated using CPU it can be increased using better CPU or GPU. MTCNN can deal with scale and orientation of the face where Cascade Classifier cannot. For our purpose we will be using MTCNN for training face recognition algorithms and Cascade Classifier for real time face detection (MTCNN can also be used for real time face detection if GPU is in use).

Cascade Classifier:

Object Detection using Haar feature-based cascade classifiers is an effective object detection method proposed by Paul Viola and Michael Jones in their paper, "Rapid Object Detection using a Boosted

Cascade of Simple Features" in 2001 [5]. It is a machine learning based approach where a cascade function is trained from a lot of positive and negative images. It is then used to detect objects in other images.

Here we will work with face detection. Initially, the algorithm needs a lot of positive images (images of faces) and negative images (images without faces) to train the classifier. Then we need to extract features from it. For this, Haar like features (based on Haar Wavelet used for compression of wave further notion will like from Haar like features) shown in the below image are used. They are just like our convolutional kernel. Each feature is a single value obtained by subtracting sum of pixels under the white rectangle from sum of pixels under the black rectangle.

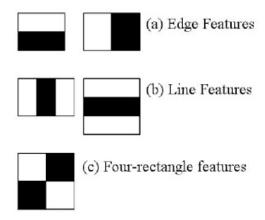


Figure 4.1.1. HAAR-like Features.

Now, all possible sizes and locations of each kernel are used to calculate lots of features. (Just imagine how much computation it needs? Even a 24x24 window results over 160000 features). For each feature calculation, we need to find the sum of the pixels under white and black rectangles. To solve this, they introduced the integral image (cumulative sum of pixels located at left top of corresponding pixel).

However large your image, it reduces the calculations for a given pixel to an operation involving just four pixels. Nice, isn't it? It makes things super-fast.

But among all these features we calculated, most of them are irrelevant. For example, consider the image below. The top row shows two good features. The first feature selected seems to focus on the property that the region of the eyes is often darker than the region of the nose and cheeks. The second feature selected relies on the property that the eyes are darker than the bridge of the nose. But the same windows applied to cheeks or any other place is irrelevant. So how do we select the best features out of 160000+ features? It is achieved by Adaboost.

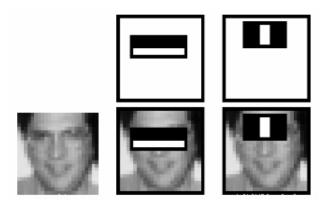


Figure 4.1.2. Example of HAAR-like features.

For this, we apply each and every feature on all the training images. For each feature, it finds the best threshold which will classify the faces to positive and negative. Obviously, there will be errors or misclassifications. We select the features with minimum error rate, which means they are the features that most accurately classify the face and non-face images. (The process is not as simple as this. Each image is given an equal weight in the beginning. After each classification, weights of misclassified images are increased. Then the same process is done. New error rates are calculated. Also new weights.

The process is continued until the required accuracy or error rate is achieved or the required number of features are found. There is a common trade-off between detection rate and precision for this classifier).

The final classifier is a weighted sum of these weak classifiers. It is called weak because it alone can't classify the image, but together with others forms a strong classifier. The paper says even 200 features provide detection with 95% accuracy. Their final setup had around 6000 features. (Imagine a reduction from 160000+ features to 6000 features. That is a big gain).

So now you take an image. Take each 24x24 window. Apply 6000 features to it. Check if it is face or not. Wow! Isn't it a little inefficient and time consuming? Yes, it is. The authors have a good solution for that.

In an image, most of the image is non-face region. So it is a better idea to have a simple method to check if a window is not a face region. If it is not, discard it in a single shot (further cascade classifiers don't need to process that part again rather concentrating on more complex features), and don't process it again. Instead, focus on regions where there can be a face. This way, we spend more time checking possible face regions.

For this they introduced the concept of Cascade of Classifiers. Instead of applying all 6000 features on a window, the features are grouped into different stages of classifiers and applied one-by-one. (Normally the first few stages will contain very many fewer features). If a window fails the first stage, discard it. We don't consider the remaining features on it. If it passes, apply the second stage of features and continue the process. The window which passes all stages is a face region. How is that plan!

The authors' detector had 6000+ features with 38 stages with 1, 10, 25, 25 and 50 features in the first five stages. (The two features in the above image are actually obtained as the best two features from Adaboost). According to the authors, on average 10 features out of 6000+ are evaluated per sub-window.

MTCNN:

MTCNN [3] is a multitask neural network model for face detection. In order to take into account the performance and accuracy, and avoid the huge performance consumption caused by traditional ideas such as sliding window and classifier, it first uses small model to generate target region candidate box with certain possibility, and then uses more complex model for fine classification and higher precision region box regression, and makes this step recursive to form a three-layer network, namely p-net, R-Net, o-net, to achieve fast and efficient face detection. In the input layer, image pyramid is used to transform the scale of the initial image, and p-net is used to generate a large number of candidate target area frames. After that, R-Net is used for the first selection and border regression of these target area frames, and most of the negative examples are excluded. Then, the more complex and higher precision network o-net is used to discriminate and regress the remaining target area frames.

For face classification, MTCNN sets the learning objective as a binary classification problem, and uses cross entropy loss function for each sample x_i

$$L_i^{det} = -(y_i^{det}\log(p_i) + (1 - y_i^{det})(1 - \log(p_i)))$$
----(1)

 P_i is the sample x_i predicted by neural network Probability of belonging to face the label of $\{1, 0\}$. 0 is the real image indicates that there is no face in the image, and 1 indicates that there is a face in the image.

For the candidate frame regression task, the bounding box regression algorithm is used to make the target frame predicted by the network model close to or coincide with the real target frame. MTCNN algorithm uses a 4dimensions vector (x, y, w, h) to output the predicted window, which represents the upper left coordinate of the prediction window and the width and height of the window respectively. For each human face candidate frame, the difference square loss function is used to predict the deviation between the candidate frame of network output and the nearest ground truth:

$$L_i^{box} = \|y_i - y_i^{box}\|^2$$
-----(2)

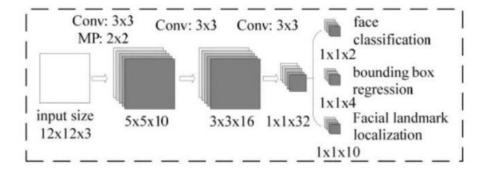


Figure 4.1.3. P-net Structure.

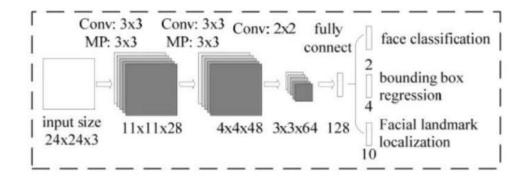


Figure 4.1.4. R-net Structure.

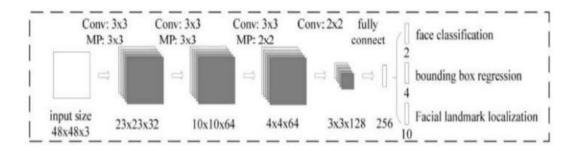


Figure 4.1.5. O-net Structure.

FaceNet Model:

FaceNet is a unified system for face verification [4], face recognition and clustering common faces. This system was developed by Google researchers that achieved FaceNet is a unified system for face verification, face recognition and clustering state-of-the-art results on variety of face recognition datasets. This system is based on extracting Euclidean embeddings from the detected faces which is used to verify a face. This model is made on taking into consideration two different deep convolutional network architecture. First architecture is based on Zeiler and Fergus Model which uses multiple interleaved layers of convolutions, non-linear activations, local response normalizations, max pooling layers and an

additional several 1x1xd convolutional layers. Second architecture is based on Inception Model of Szegedy et al. This model can take input from a range of dimensions, i.e., 96x96 pixels to 224x224 pixels, also supports RGB or Grayscale images. The output is a 128-byte 1 dimensional embedding vector. The unique features of the face are all boiled-down into a 1x128 dimensional vector. This network consists of a batch input followed by a deep architecture and a L2 normalization, which generates the embedding, which is followed by a triplet loss function during training. Triplet Loss function basically reduces the distance between an anchor and a positive identity (similar face) and increases the distance between an anchor and a negative identity (not so similar face). The first architecture has in total of 140 million parameters and 1.6 billion FLOPS. The second architecture has in total of 7.5 million parameter and 1.6 billion FLOPS. This architecture was built to run on mobile CPUs. FaceNet model accuracy is of 99.63% on Labelled Faces in the Wild (LFW) dataset and 95.12% on YouTube Faces DB. FaceNet is the best face recognition model till date as compared to Facebook's DeepFace Model.



Figure 4.1.6. FaceNet Model Structure.

Introduction of Kivy

We are creating desktop application to demonstrate our project using Kivy [11]. Kivy is open-source library or framework of python which freely available that allows us to develop multiplatform applications that run on Desktops like Windows, macOS, Linux and could also run-on iOS and android

devices. Kivy is flexible that give freedom to us to write code once and runs as it is on different platform. The application development using this kivy library helps to develop interactive applications with a simple GUI that is easy to use. The main advantage of using the kivy platform is that the application is developed in any platform, and after that it can be used in any type of device to help reuse the code and be deployed easily. The UI given by the kivy framework helps to develop interactive application that are user friendly. Kivy supports various type of input devices that include keyboard, mouse etc. Application that build by using kivy are very fast. It is completely based on python programming language that is very powerful and help to create the application in minimum time.

Desktop application

In our project we will be using Kivy to create desktop application which will be use by end-user. This desktop application work in offline mode (without internet) and because of that it is fast and more responsive compare to web application. This application is integrated with OpenCV model which detect the face. This application has an option to take an input as image as well as video. This input is stored in a local repository which is used to verify a face which is detected by the OpenCV model. If face matched with any faces in face repository, then storing it in Index CSV file with corresponding frame time and location of camera. The administrative user will be able see the required contents of CSV file.

4.2 DESIGN DETAILS

Realtime video will recorded through IP camera. Extraction of frames from IP camera video. Here it will process video using OpenCV as OpenCV is the huge open-source library for computer vision, machine learning, and image processing and now it plays a major role in real-time operation which is very important in today's systems. By using it, one can process images and videos to identify objects, faces of a human. When it integrated with various libraries, such as NumPy [9], python is capable of processing the OpenCV [8] array structure for analysis. To Identify image pattern and its various features we use vector space and perform mathematical operations on these features. Captured video frames will go to haar cascade classifier [5] which is an Object Detection Algorithm used to identify faces in an image or a real time video. Extraction faces from frames. Then extracted faces will go to FaceNet [4] model for further process. Recognition of extracted faces from frames. If face matched with any faces in face repository which is loaded using MTCNN [3], then storing it in Index DB with corresponding frame time and location of camera.

4.3 FLOWCHART

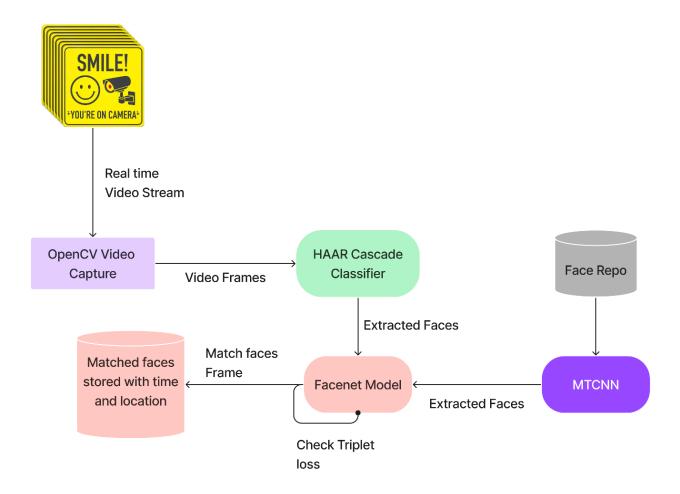


Figure 4.3.1. Flow diagram

REQUIREMENTS

5.1 HARDWARE AND SOFTWARE SPECIFICATIONS

5.1.1 HARDWARE:

1. RAM: Minimum 4GB

2. CPU: Intel Core i3 or higher

3. Hard Drive: 40 GB Free Space

4. IP Camera

5.1.2 SOFTWARE:

- 1. TensorFlow
- 2. Numpy
- 3. OpenCV
- 4. Python IDE
- 5. Kivy
- 6. Jupyter Notebook

IMPLEMENTATION PLAN FOR NEXT SEMESTER

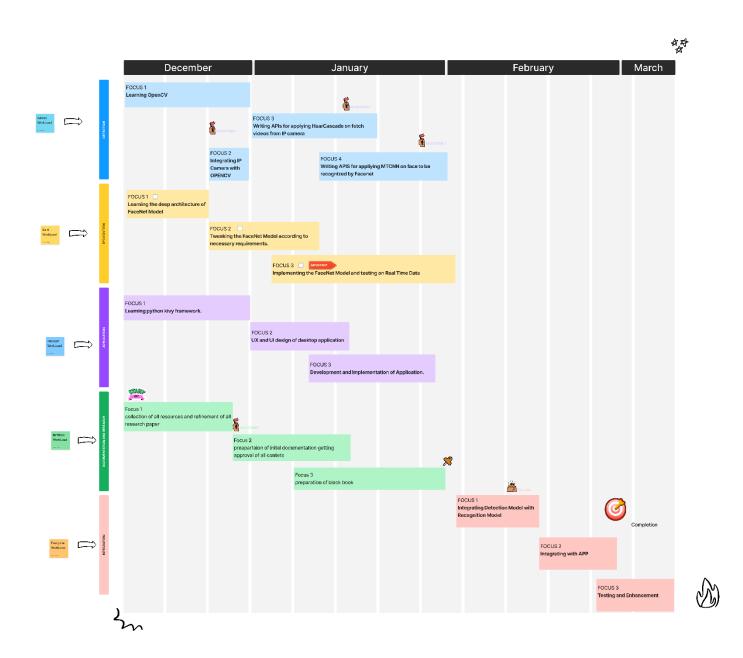


Fig 6.1: Gantt Chart

SUMMARY

This project will demonstrate a system for face recognition from surveillance video. The system will demonstrate to be robust to changes in illumination, scale, facial expression and reasonably robust to occlusions and changes in pose. Attention was given to performance considerations, and the system can operate in real time. All these features make this approach suitable for a video surveillance application. This work is a fully-fledged surveillance and suspect tracking system, using facial recognition and marking the suspects positions on the maps for more real time analysis. This system is a complete offline method and hence providing an inherent and enhanced security for our data.

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- [10] https://github.com/davidsandberg/facenet/tree/master/src/align
- [11] https://kivy.org/doc/stable/