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Class	Operating System: Three Easy Pieces
□ Date	@February 16, 2022

[Ch30] Condition Variables

There are many cases where a thread wishes to check whether a condition is true before continuing its execution.

For example, a parent thread might wish to check whether a child thread has completed before continuing.

```
void *child(void *arg) {
    printf("child\n");
    // XXX how to indicate we are done?
    return NULL;
}
int main(int argc, char *argv[]) {
    printf("parent: begin\n");
    pthread_t c;
    Pthread_create(&c, NULL, child, NULL); // create child
    // XXX how to wait for child?
    printf("parent: end\n");
    return 0;
}
```

Figure 30.1: A Parent Waiting For Its Child

What we would like to see here is the following output:

```
parent: begin
child
parent: end
```

We could let the parent thread spin wait for the child thread to finish, but this can be super inefficient:

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```
volatile int done = 0;
2
  void *child(void *arg) {
      printf("child\n");
       done = 1;
       return NULL;
  }
   int main(int argc, char *argv[]) {
       printf("parent: begin\n");
10
      pthread_t c;
      Pthread_create(&c, NULL, child, NULL); // create child
12
       while (done == 0)
13
           ; // spin
      printf("parent: end\n");
15
16
       return 0;
   }
```

Figure 30.2: Parent Waiting For Child: Spin-based Approach

30.1 Definition and Routines

To wait for a condition to become true, a thread can make use of what is known as a condition variable.

A condition variable is an explicit queue that threads can put themselves on when some state of execution(i.e. some condition) is not as desired(by waiting on the condition); some other thread, when it changes said state, can then wake one of those waiting threads and thus allow them to continue.

To declare such a condition variable, one simple writes something like this:

pthread_cond_t c;, which declares c as a condition variable. A condition variable has
two operations associated with it: wait() and signal(). The wait() call is executed
when a thread wishes to put itself to sleep; the signal() call is executed when a thread
has changed something in the program and thus wants to wake a sleeping thread
waiting on this condition.

```
pthread_cond_wait(pthread_cond_t *c, pthread_mutex_t *m);
pthread_cond_signal(pthread_cond_t *c);
```

wait() call also takes a mutex as a parameter; it assumes that this mutex is locked when wait() is called.

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The responsibility of wait() is to release the lock and put the calling thread to sleep; when the thread wakes up, it must re-acquire the lock before returning to the caller. This complexity stems from the desire to prevent certain race conditions from occurring when a thread is trying to put itself to sleep.

```
int done = 0;
pthread_mutex_t m = PTHREAD_MUTEX_INITIALIZER;
3 pthread_cond_t c = PTHREAD_COND_INITIALIZER;
5 void thr_exit() {
      Pthread_mutex_lock(&m);
      done = 1;
7
      Pthread_cond_signal(&c);
8
      Pthread_mutex_unlock(&m);
9
  }
10
11
void *child(void *arg) {
      printf("child\n");
13
      thr_exit();
14
      return NULL;
15
16
17
  void thr_join() {
18
     Pthread_mutex_lock(&m);
      while (done == 0)
20
           Pthread_cond_wait(&c, &m);
21
22
      Pthread_mutex_unlock(&m);
23 }
24
int main(int argc, char *argv[]) {
    printf("parent: begin\n");
26
27
      pthread_t p;
28
      Pthread_create(&p, NULL, child, NULL);
      thr_join();
29
      printf("parent: end\n");
30
      return 0;
31
```

Figure 30.3: Parent Waiting For Child: Use A Condition Variable

There are two cases to consider:

1. In the first, the parents creates the child thread but continues running itself and thus immediately calls into thr_join() to wait for the child thread to complete. In this case, it will acquire the lock, check if the child is done, and put itself to sleep by calling wait().

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The child will eventually run, print the message "child", and call thr_exit() to wake the parent thread; this code just grabs the lock, sets the state variable done, and signals the parents thus waking it.

Finally, the parent will run, unlock the lock, and print the final message "parent: end".

In the second case, the child runs immediately upon creation, sets done to 1, calls signal to wake a sleeping thread(but there is none, so it just returns), and is done.
The parent then runs, calls thr_join(), sees that done is 1, and thus does not wait and returns.

Note: Just an if statement when deciding whether to wait on the condition will suffice our need here. It is always a good idea to use while.

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