

【OS】 Day30(3)

▼ Class	Operating System: Three Easy Pieces
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【Ch26】 Concurrency: Introduction Homework

Question 1

1. Let's examine a simple program, "loop.s". First, just read and understand it. Then, run it with these arguments (`./x86.py -p loop.s -t 1 -i 100 -R dx`) This specifies a single thread, an interrupt every 100 instructions, and tracing of register %dx. What will %dx be during the run? Use the `-c` flag to check your answers; the answers, on the left, show the value of the register (or memory value) *after* the instruction on the right has run.

loop.s:

```
.main
.top
;Loop dx + 1 times
sub $1,%dx
test $0,%dx
jgte .top
halt
```

```
dx      Thread 0
0
-1  1000 sub  $1,%dx
-1  1001 test $0,%dx
-1  1002 jgte .top
-1  1003 halt
```

Question 2

2. Same code, different flags: (`./x86.py -p loop.s -t 2 -i 100 -a dx=3, dx=3 -R dx`) This specifies two threads, and initializes each `%dx` to 3. What values will `%dx` see? Run with `-c` to check. Does the presence of multiple threads affect your calculations? Is there a race in this code?

```

dx      Thread 0      Thread 1
3
2 1000 sub $1,%dx
2 1001 test $0,%dx
2 1002 jgte .top
1 1000 sub $1,%dx
1 1001 test $0,%dx
1 1002 jgte .top
0 1000 sub $1,%dx
0 1001 test $0,%dx
0 1002 jgte .top
-1 1000 sub $1,%dx
-1 1001 test $0,%dx
-1 1002 jgte .top
-1 1003 halt
3 ----- Halt;Switch ----- ----- Halt;Switch -----
2 1000 sub $1,%dx
2 1001 test $0,%dx
2 1002 jgte .top
1 1000 sub $1,%dx
1 1001 test $0,%dx
1 1002 jgte .top
0 1000 sub $1,%dx
0 1001 test $0,%dx
0 1002 jgte .top
-1 1000 sub $1,%dx
-1 1001 test $0,%dx
-1 1002 jgte .top
-1 1003 halt

```

The presence of multiple threads do not affect the calculation because the interrupt timer frequency enables one thread to finish before executing the next one.

There isn't a data race in the code. (

Question 3

3. Run this: `./x86.py -p loop.s -t 2 -i 3 -r -a dx=3, dx=3 -R dx` This makes the interrupt interval small/random; use different seeds (`-s`) to see different interleavings. Does the interrupt frequency change anything?

```

dx      Thread 0      Thread 1
3
2 1000 sub $1,%dx
2 1001 test $0,%dx
2 1002 jgte .top
3 ----- Interrupt -----
2      1000 sub $1,%dx
2      1001 test $0,%dx
2      1002 jgte .top
2 ----- Interrupt -----
1 1000 sub $1,%dx
1 1001 test $0,%dx
2 ----- Interrupt -----
1      1000 sub $1,%dx
1 ----- Interrupt -----
1 1002 jgte .top
0 1000 sub $1,%dx
1 ----- Interrupt -----
1      1001 test $0,%dx
1      1002 jgte .top
0 ----- Interrupt -----
0 1001 test $0,%dx
0 1002 jgte .top
-1 1000 sub $1,%dx
1 ----- Interrupt -----
0      1000 sub $1,%dx
-1 ----- Interrupt -----
-1 1001 test $0,%dx
-1 1002 jgte .top
0 ----- Interrupt -----
0      1001 test $0,%dx
0      1002 jgte .top
-1 ----- Interrupt -----
-1 1003 halt
0 ----- Halt;Switch -----
-1      1000 sub $1,%dx
-1      1001 test $0,%dx
-1 ----- Interrupt -----
-1      1002 jgte .top
-1      1003 halt

```

Question 4

- Now, a different program, `looping-race-nolock.s`, which accesses a shared variable located at address 2000; we'll call this variable `value`. Run it with a single thread to confirm your understanding: `./x86.py -p looping-race-nolock.s -t 1 -M 2000` What is `value` (i.e., at memory address 2000) throughout the run? Use `-c` to check.

```

2000          Thread 0
0
0  1000 mov 2000, %ax
0  1001 add $1, %ax
1  1002 mov %ax, 2000
1  1003 sub $1, %bx
1  1004 test $0, %bx
1  1005 jgt .top
1  1006 halt

```

Question 5

- Run with multiple iterations/threads: `./x86.py -p looping-race-nolock.s -t 2 -a bx=3 -M 2000` Why does each thread loop three times? What is final value of value?

Since the starting value in bx is 3, each thread will loop 3 times. Each time it increments the value at 2000 by 1, and thus result in a final answer of 6.

```

2000      Thread 0      Thread 1
0
0 1000 mov 2000, %ax
0 1001 add $1, %ax
1 1002 mov %ax, 2000
1 1003 sub $1, %bx
1 1004 test $0, %bx
1 1005 jgt .top
1 1000 mov 2000, %ax
1 1001 add $1, %ax
2 1002 mov %ax, 2000
2 1003 sub $1, %bx
2 1004 test $0, %bx
2 1005 jgt .top
2 1000 mov 2000, %ax
2 1001 add $1, %ax
3 1002 mov %ax, 2000
3 1003 sub $1, %bx
3 1004 test $0, %bx
3 1005 jgt .top
3 1006 halt
3 ----- Halt;Switch -----
3 1000 mov 2000, %ax
3 1001 add $1, %ax
4 1002 mov %ax, 2000
4 1003 sub $1, %bx
4 1004 test $0, %bx
4 1005 jgt .top
4 1000 mov 2000, %ax
4 1001 add $1, %ax
5 1002 mov %ax, 2000
5 1003 sub $1, %bx
5 1004 test $0, %bx
5 1005 jgt .top
5 1000 mov 2000, %ax
5 1001 add $1, %ax
6 1002 mov %ax, 2000
6 1003 sub $1, %bx
6 1004 test $0, %bx
6 1005 jgt .top
6 1006 halt

```

Question 6

- Run with random interrupt intervals: `./x86.py -p looping-race-nolock.s -t 2 -M 2000 -i 4 -r -s 0` with different seeds (`-s 1`, `-s 2`, etc.) Can you tell by looking at the thread interleaving what the final value of `value` will be? Does the timing of the interrupt matter? Where can it safely occur? Where not? In other words, where is the critical section exactly?

Run with see -0:

2000	Thread 0	Thread 1
0		
0	1000 mov 2000, %ax	
0	1001 add \$1, %ax	
1	1002 mov %ax, 2000	
1	1003 sub \$1, %bx	
1	----- Interrupt -----	----- Interrupt -----
1		1000 mov 2000, %ax
1		1001 add \$1, %ax
2		1002 mov %ax, 2000
2		1003 sub \$1, %bx
2	----- Interrupt -----	----- Interrupt -----
2	1004 test \$0, %bx	
2	1005 jgt .top	
2	----- Interrupt -----	----- Interrupt -----
2		1004 test \$0, %bx
2		1005 jgt .top
2	----- Interrupt -----	----- Interrupt -----
2	1006 halt	
2	----- Halt;Switch -----	----- Halt;Switch -----
2		1006 halt

Run with see -1:

2000	Thread 0	Thread 1
0		
0	1000 mov 2000, %ax	
0	----- Interrupt -----	----- Interrupt -----
0		1000 mov 2000, %ax
0		1001 add \$1, %ax
1		1002 mov %ax, 2000
1		1003 sub \$1, %bx
1	----- Interrupt -----	----- Interrupt -----
1	1001 add \$1, %ax	
1	1002 mov %ax, 2000	
1	1003 sub \$1, %bx	
1	1004 test \$0, %bx	
1	----- Interrupt -----	----- Interrupt -----
1		1004 test \$0, %bx
1		1005 jgt .top
1	----- Interrupt -----	----- Interrupt -----
1	1005 jgt .top	
1	1006 halt	
1	----- Halt;Switch -----	----- Halt;Switch -----
1	----- Interrupt -----	----- Interrupt -----
1		1006 halt

Whether the value of ax is pushed back affects the result.

Question 7

7. Now examine fixed interrupt intervals: `./x86.py -p looping-race-nolock.s -a bx=1 -t 2 -M 2000 -i 1` What will the final value of the shared variable `value` be? What about when you change `-i 2`, `-i 3`, etc.? For which interrupt intervals does the program give the “correct” answer?

Run with `i = 1`:

```

2000          Thread 0          Thread 1
0
0 1000 mov 2000, %ax
0 ----- Interrupt ----- ----- Interrupt -----
0                                     1000 mov 2000, %ax
0 ----- Interrupt ----- ----- Interrupt -----
0 1001 add $1, %ax
0 ----- Interrupt ----- ----- Interrupt -----
0                                     1001 add $1, %ax
0 ----- Interrupt ----- ----- Interrupt -----
1 1002 mov %ax, 2000
1 ----- Interrupt ----- ----- Interrupt -----
1                                     1002 mov %ax, 2000
1 ----- Interrupt ----- ----- Interrupt -----
1 1003 sub $1, %bx
1 ----- Interrupt ----- ----- Interrupt -----
1                                     1003 sub $1, %bx
1 ----- Interrupt ----- ----- Interrupt -----
1 1004 test $0, %bx
1 ----- Interrupt ----- ----- Interrupt -----
1                                     1004 test $0, %bx
1 ----- Interrupt ----- ----- Interrupt -----
1 1005 jgt .top
1 ----- Interrupt ----- ----- Interrupt -----
1                                     1005 jgt .top
1 ----- Interrupt ----- ----- Interrupt -----
1 1006 halt
1 ----- Halt;Switch ----- ----- Halt;Switch -----
1 ----- Interrupt ----- ----- Interrupt -----
1                                     1006 halt

```

Run with `i = 2`:

2000	Thread 0	Thread 1
0		
0	1000 mov 2000, %ax	
0	1001 add \$1, %ax	
0	----- Interrupt -----	----- Interrupt -----
0		1000 mov 2000, %ax
0		1001 add \$1, %ax
0	----- Interrupt -----	----- Interrupt -----
1	1002 mov %ax, 2000	
1	1003 sub \$1, %bx	
1	----- Interrupt -----	----- Interrupt -----
1		1002 mov %ax, 2000
1		1003 sub \$1, %bx
1	----- Interrupt -----	----- Interrupt -----
1	1004 test \$0, %bx	
1	1005 jgt .top	
1	----- Interrupt -----	----- Interrupt -----
1		1004 test \$0, %bx
1		1005 jgt .top
1	----- Interrupt -----	----- Interrupt -----
1	1006 halt	
1	----- Halt;Switch -----	----- Halt;Switch -----
1		1006 halt

Run with i = 3:

2000	Thread 0	Thread 1
0		
0	1000 mov 2000, %ax	
0	1001 add \$1, %ax	
1	1002 mov %ax, 2000	
1	----- Interrupt -----	----- Interrupt -----
1		1000 mov 2000, %ax
1		1001 add \$1, %ax
2		1002 mov %ax, 2000
2	----- Interrupt -----	----- Interrupt -----
2	1003 sub \$1, %bx	
2	1004 test \$0, %bx	
2	1005 jgt .top	
2	----- Interrupt -----	----- Interrupt -----
2		1003 sub \$1, %bx
2		1004 test \$0, %bx
2		1005 jgt .top
2	----- Interrupt -----	----- Interrupt -----
2	1006 halt	
2	----- Halt;Switch -----	----- Halt;Switch -----
2		1006 halt

For i≥3 will the program give the correct answer.

Question 8

8. Run the same for more loops (e.g., set `-a bx=100`). What interrupt intervals (`-i`) lead to a correct outcome? Which intervals are surprising?

For intervals ≥ 597 (execute another thread after one finishes) or interval = $3 * x$, the program gives the correct answer.

Question 9

9. One last program: `wait-for-me.s`. Run: `./x86.py -p wait-for-me.s -a ax=1,ax=0 -R ax -M 2000` This sets the `%ax` register to 1 for thread 0, and 0 for thread 1, and watches `%ax` and memory location 2000. How should the code behave? How is the value at location 2000 being used by the threads? What will its final value be?

2000	ax	Thread 0	Thread 1
0	1		
0	1	1000 test \$1, %ax	
0	1	1001 je .signaller	
1	1	1006 mov \$1, 2000	
1	1	1007 halt	
1	0	----- Halt;Switch -----	----- Halt;Switch -----
1	0		1000 test \$1, %ax
1	0		1001 je .signaller
1	0		1002 mov 2000, %cx
1	0		1003 test \$1, %cx
1	0		1004 jne .waiter
1	0		1005 halt

Question 10

10. Now switch the inputs: `./x86.py -p wait-for-me.s -a ax=0,ax=1 -R ax -M 2000` How do the threads behave? What is thread 0 doing? How would changing the interrupt interval (e.g., `-i 1000`, or perhaps to use random intervals) change the trace outcome? Is the program efficiently using the CPU?

```

0      0      1002 mov  2000, %cx
0      0      1003 test $1, %cx
0      0      1004 jne  .waiter
0      0      1002 mov  2000, %cx
0      0      1003 test $1, %cx
0      0      1004 jne  .waiter
0      0      1002 mov  2000, %cx
0      0      1003 test $1, %cx
0      0      1004 jne  .waiter
0      0      1002 mov  2000, %cx
0      0      1003 test $1, %cx
0      0      1004 jne  .waiter
0      0      1002 mov  2000, %cx
0      0      1003 test $1, %cx
0      0      1004 jne  .waiter
0      0      1002 mov  2000, %cx
0      0      1003 test $1, %cx
0      0      1004 jne  .waiter
0      0      1002 mov  2000, %cx
0      0      1003 test $1, %cx
0      0      1004 jne  .waiter
0      0      1002 mov  2000, %cx
0      0      1003 test $1, %cx
0      0      1004 jne  .waiter
0      0      1002 mov  2000, %cx
0      0      1003 test $1, %cx
0      0      1004 jne  .waiter
0      0      1002 mov  2000, %cx
0      0      1003 test $1, %cx
0      0      1004 jne  .waiter
0      0      1002 mov  2000, %cx
0      0      1003 test $1, %cx
0      0      1004 jne  .waiter
0      0      1002 mov  2000, %cx
0      0      1003 test $1, %cx
0      0      1004 jne  .waiter
0      1      ----- Interrupt -----
0      1      1000 test $1, %ax
0      1      1001 je  .signaller
1      1      1006 mov  $1, 2000
1      1      1007 halt
1      0      ----- Halt;Switch -----
1      0      1002 mov  2000, %cx
1      0      1003 test $1, %cx
1      0      1004 jne  .waiter
1      0      1005 halt

```

The threads swapped. Thread 0 keeps running until thread 1 changes the value at 2000.

The CPU is not being efficiently used.