

EECS 598 Deep Learning

Assignment 2

Shuyang HUANG 68621288

1. Transfer learning

All blank blocks are filled. Followings are some fragments of the outputs:

```
Finetune the pre-trained model
Performance of pre-trained model without finetuning
Training complete in 0m 4s
Best val Acc: 0.692810
Finetune the model
Epoch 0/24
-----
train Loss: 0.7278 Acc: 0.6639
val Loss: 0.4004 Acc: 0.8431
Epoch 1/24
-----
train Loss: 0.4132 Acc: 0.8402
val Loss: 0.2916 Acc: 0.8889

...
...
...

-----
train Loss: 0.3029 Acc: 0.8607
val Loss: 0.2142 Acc: 0.9281
Epoch 23/24
-----
train Loss: 0.2656 Acc: 0.8811
```

```

val Loss: 0.2085 Acc: 0.9281
Epoch 24/24
-----
train Loss: 0.2692 Acc: 0.8852
val Loss: 0.2116 Acc: 0.9346
Training complete in 2m 57s
Best val Acc: 0.934641
Freeze the parameters in pre-trained model and train the final fc layer
Performance of pre-trained model without finetuning
Training complete in 0m 3s
Best val Acc: 0.607843
Finetune the model
Epoch 0/24
-----
train Loss: 0.5131 Acc: 0.7336
val Loss: 0.2405 Acc: 0.9281
Epoch 1/24
-----
train Loss: 0.4564 Acc: 0.8033
val Loss: 0.2451 Acc: 0.9150

...
...
...

Epoch 22/24
-----
train Loss: 0.2971 Acc: 0.8852
val Loss: 0.1951 Acc: 0.9412
Epoch 23/24
-----
train Loss: 0.2605 Acc: 0.8893
val Loss: 0.1998 Acc: 0.9477
Epoch 24/24
-----
train Loss: 0.3293 Acc: 0.8484
val Loss: 0.1973 Acc: 0.9412
Training complete in 2m 24s
Best val Acc: 0.960784

```

As we can see, transfer learning gives us a higher correctness while using less time. Since the GPU acceleration is activated, the time consumings are close to each other, while in the full cpu mode, the difference of time consumption is clearly different.

2. Style Transfer

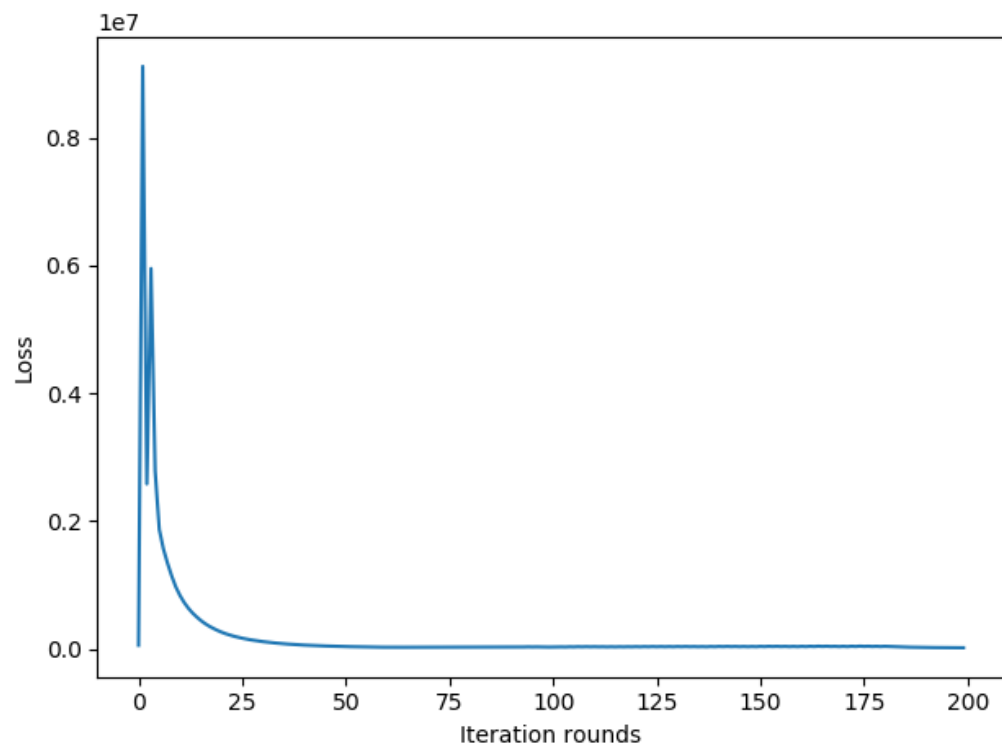
All blanks are filled. Followings are the results.

Content Source Img.



Style Source Img.

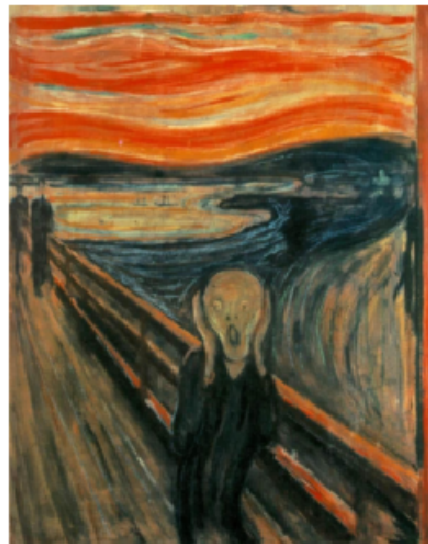


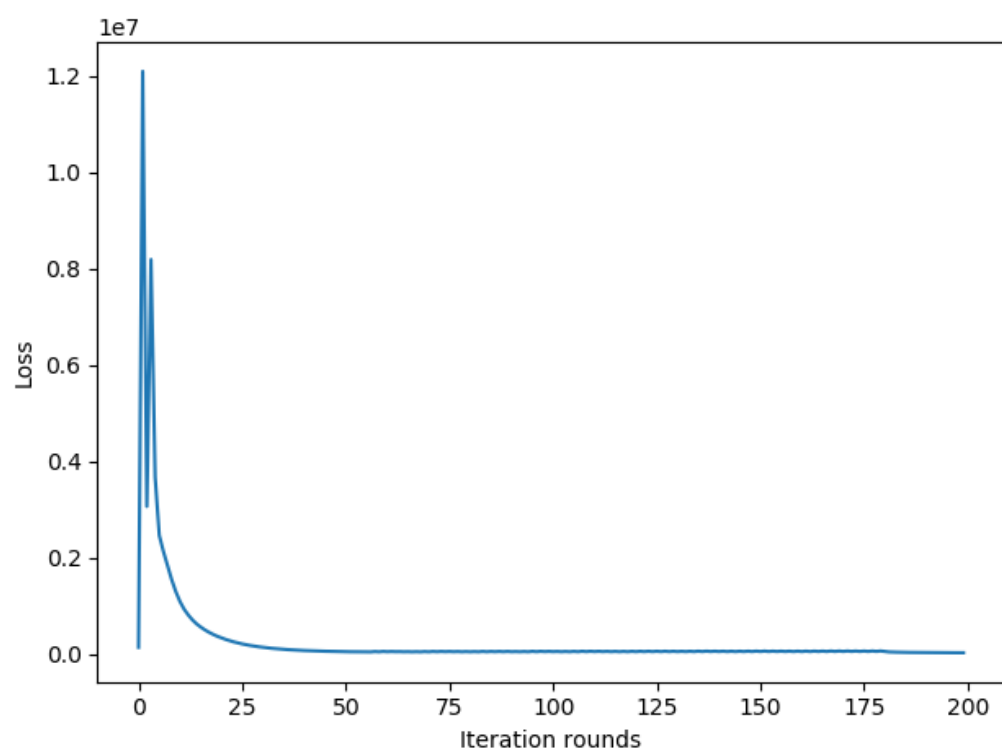


Content Source Img.



Style Source Img.

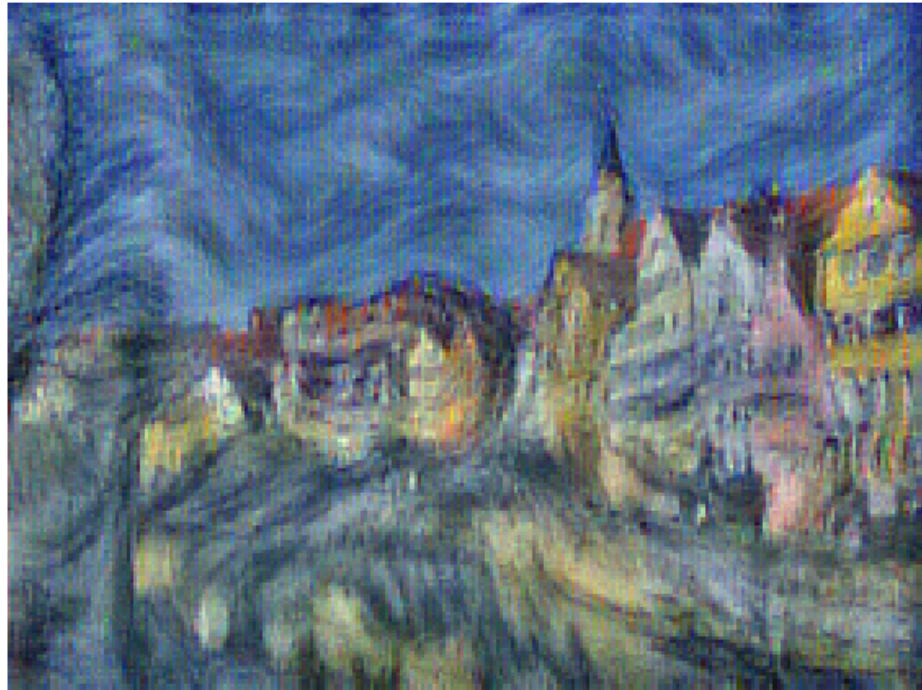


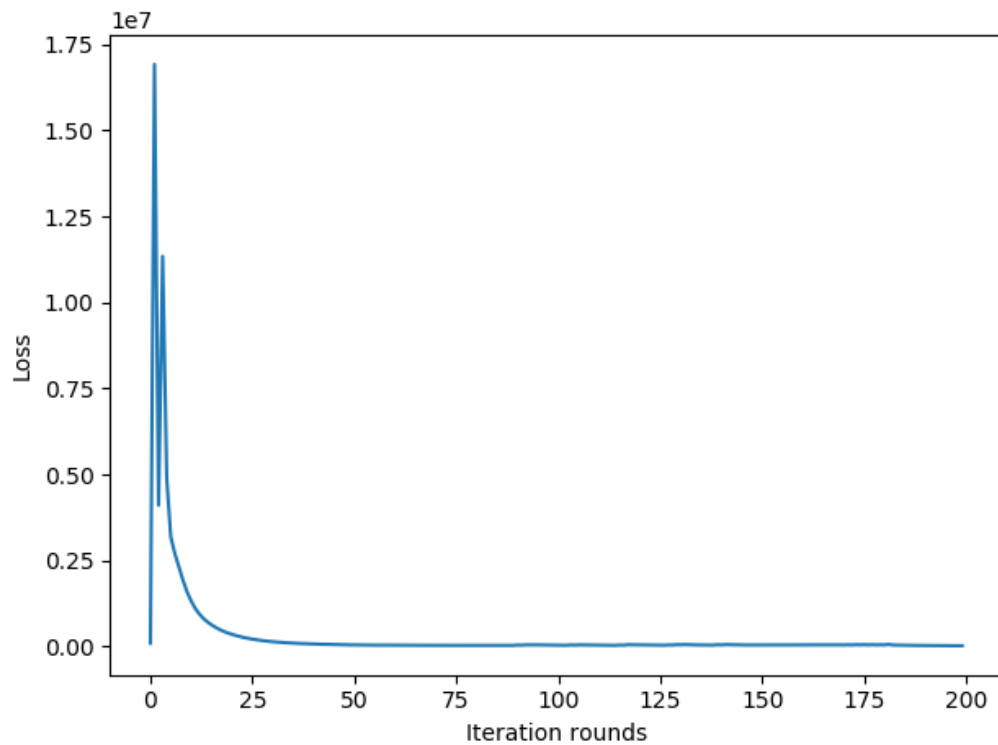


Content Source Img.



Style Source Img.





As we can see, style transfer works well. The losses decrease significantly, and the obtained figures somehow reflect the features the style source image.

3. Forward and Backward propagation module for RNN

All blanks are filled.

Pr.3.

(2). rnn step backward.

denote \otimes as the one by one multiplication.

$$\textcircled{1} \frac{\partial L}{\partial h_t} = (1 - h_t^2) \otimes \frac{\partial L}{\partial h_t}.$$

$$\textcircled{2} \frac{\partial L}{\partial x_t} = [(1 - h_t^2) \otimes \frac{\partial L}{\partial h_t}] \cdot w_x^T.$$

$$\textcircled{3} \frac{\partial L}{\partial h_{t-1}} = [(1 - h_t^2) \otimes \frac{\partial L}{\partial h_t}] \cdot w_h^T.$$

$$\textcircled{4} \frac{\partial L}{\partial w_x} = x_t^T \cdot [(1 - h_t^2) \otimes \frac{\partial L}{\partial h_t}].$$

$$\textcircled{5} \frac{\partial L}{\partial w_h} = h_{t-1}^T [(1 - h_t^2) \otimes \frac{\partial L}{\partial h_t}].$$

$$\textcircled{6} \frac{\partial L}{\partial b} = \frac{\partial L}{\partial h_t} = (1 - h_t^2) \otimes \frac{\partial L}{\partial h_t}.$$

(4) rnn back word.

$$\textcircled{1} \frac{\partial L}{\partial x_t} = [(1 - h_t^2) \otimes f(t)] \cdot w_x^T.$$

$$\textcircled{2} \frac{\partial L}{\partial h_t} = [(1 - h_t^2) \otimes f(t)] w_h^T.$$

$$\textcircled{3} \frac{\partial L}{\partial w_x} = \sum_{t=1}^T x_t^T [(1 - h_t^2) \otimes f(t)].$$

$$\textcircled{4} \frac{\partial L}{\partial w_h} = \sum_{t=1}^T h_t^T [(1 - h_t^2) \otimes f(t)].$$

$$\textcircled{5} \frac{\partial L}{\partial b} = \sum_{t=1}^T (1 - h_t^2) \otimes f(t).$$

$$\text{Where } f(t) = \begin{cases} \frac{\partial L}{\partial h_t}, & t = T. \\ \frac{\partial L}{\partial h_t} + [(1 - h_{t+1}^2) \otimes f(t+1)] w_h^T & 1 \leq t \leq T-1. \end{cases}$$

4. Forward and Backward propagation module for LSTM

All blanks are filled.

Pr. 4

(2) 1stn step backward.

$$\text{denote: } \mathcal{L}(t) = \frac{\partial \mathcal{L}}{\partial h_t} \otimes \mathcal{O}_t \otimes [1 - \tanh^2(G_t)] + \frac{\partial \mathcal{L}}{\partial a_t}$$

$$\frac{\partial \mathcal{L}}{\partial W_x^f} = x_t^T \cdot [\mathcal{L}(t) \otimes G_{t-1} \otimes f_t \otimes (1-f_t)],$$

$$\frac{\partial \mathcal{L}}{\partial W_h^f} = h_{t-1}^T \cdot [\mathcal{L}(t) \otimes G_{t-1} \otimes f_t \otimes (1-f_t)],$$

$$\frac{\partial \mathcal{L}}{\partial b^f} = \mathcal{L}(t) \otimes G_{t-1} \otimes f_t \otimes (1-f_t),$$

$$\frac{\partial \mathcal{L}}{\partial W_x^c} = x_t^T [\mathcal{L}(t) \otimes \tilde{a}_t \otimes \tilde{r}_t \otimes (1-\tilde{r}_t)],$$

$$\frac{\partial \mathcal{L}}{\partial W_h^c} = h_{t-1}^T [\mathcal{L}(t) \otimes \tilde{a}_t \otimes \tilde{r}_t \otimes (1-\tilde{r}_t)],$$

$$\frac{\partial \mathcal{L}}{\partial b^c} = \mathcal{L}(t) \otimes \tilde{a}_t \otimes \tilde{r}_t \otimes (1-\tilde{r}_t)$$

$$\frac{\partial \mathcal{L}}{\partial W_x^e} = x_t^T [\mathcal{L}(t) \otimes \tilde{r}_t \otimes (1-\tilde{a}_t^2)],$$

$$\frac{\partial \mathcal{L}}{\partial W_h^e} = h_{t-1}^T [\mathcal{L}(t) \otimes \tilde{r}_t \otimes (1-\tilde{a}_t^2)]$$

$$\frac{\partial \mathcal{L}}{\partial b^e} = \mathcal{L}(t) \otimes \tilde{r}_t \otimes (1-\tilde{a}_t^2)$$

$$\frac{\partial \mathcal{L}}{\partial W_x^p} = x_t^T \left[\frac{\partial \mathcal{L}}{\partial h_t} \otimes \tanh(G_t) \otimes \mathcal{O}_t \otimes (1-\mathcal{O}_t) \right],$$

$$\frac{\partial \mathcal{L}}{\partial W_h^p} = h_{t-1}^T \left[\frac{\partial \mathcal{L}}{\partial h_t} \otimes \tanh(G_t) \otimes \mathcal{O}_t \otimes (1-\mathcal{O}_t) \right],$$

$$\frac{\partial \mathcal{L}}{\partial b^p} = \frac{\partial \mathcal{L}}{\partial h_t} \otimes \tanh(G_t) \otimes \mathcal{O}_t \otimes (1-\mathcal{O}_t)$$

$$\frac{\partial \mathcal{L}}{\partial h_{t+1}} = [\mathcal{L}(t) \otimes (x_{t+1} \otimes f_t \otimes (1-f_t))] W_h^f{}^T + [\mathcal{L}(t) \otimes \tilde{a}_t \otimes \tilde{r}_t \otimes (1-\tilde{r}_t)] W_h^c{}^T,$$

$$+ [\mathcal{L}(t) \otimes \tilde{r}_t \otimes (1-\tilde{a}_t^2)] W_h^e{}^T + \left[\frac{\partial \mathcal{L}}{\partial h_t} \otimes \tanh(G_t) \otimes \mathcal{O}_t \otimes (1-\mathcal{O}_t) \right] W_h^p{}^T.$$

$$\frac{\partial \mathcal{L}}{\partial x_t} = [\mathcal{L}(t) \otimes G_{t-1} \otimes f_t \otimes (1-f_t)] W_x^f{}^T + [\mathcal{L}(t) \otimes \tilde{a}_t \otimes \tilde{r}_t \otimes (1-\tilde{r}_t)] W_x^c{}^T,$$

$$+ [\mathcal{L}(t) \otimes \tilde{r}_t \otimes (1-\tilde{a}_t^2)] W_x^e{}^T + \left[\frac{\partial \mathcal{L}}{\partial h_t} \otimes \tanh(G_t) \otimes \mathcal{O}_t \otimes (1-\mathcal{O}_t) \right] W_x^p{}^T.$$

(4) LSTM backward.

$$\begin{aligned} \text{Let } \mathcal{L}^*(c_t) &= \mathcal{L}(c_t) \otimes 0_t \otimes [1 - \tanh^2(C_t)] + \frac{\partial \mathcal{L}}{\partial c_t} \\ \mathcal{L}(c_t) &= \frac{\partial \mathcal{L}}{\partial h_t} [\mathcal{L}^*(c_{t+1}) \otimes \hat{c}_t \otimes f_{t+1} \otimes (1 - f_{t+1})] W_h^T + [\mathcal{L}^*(c_{t+1}) \otimes \hat{c}_{t+1} \otimes \hat{i}_{t+1} \otimes (1 - \hat{i}_{t+1})] W_i^T \\ &\quad + [\mathcal{L}^*(c_{t+1}) \otimes \hat{i}_{t+1} \otimes (1 - \hat{c}_{t+1}^2)] W_f^T + [\mathcal{L}(c_{t+1}) \otimes \tanh(C_{t+1}) \otimes 0_{t+1} \otimes (1 - 0_{t+1})] W_o^T. \end{aligned}$$

Thus:

$$\begin{aligned} \frac{\partial \mathcal{L}}{\partial x_t} &= [\mathcal{L}^*(c_t) \otimes \hat{c}_{t-1} \otimes f_t \otimes (1 - f_t)] W_x^T + [\mathcal{L}^*(c_t) \otimes \hat{c}_t \otimes \hat{i}_t \otimes (1 - \hat{i}_t)] W_i^T \\ &\quad + [\mathcal{L}^*(c_t) \otimes \hat{i}_t \otimes (1 - \hat{c}_t^2)] W_f^T + [\mathcal{L}(c_t) \otimes \tanh(C_t) \otimes 0_t \otimes (1 - 0_t)] W_o^T. \end{aligned}$$

$$\frac{\partial \mathcal{L}}{\partial W_x^T} = \sum_{t=1}^T x_t^T [\mathcal{L}^*(c_t) \otimes \hat{c}_{t-1} \otimes f_t \otimes (1 - f_t)]$$

$$\frac{\partial \mathcal{L}}{\partial W_i^T} = \sum_{t=1}^T h_{t-1}^T [\mathcal{L}^*(c_t) \otimes \hat{c}_{t-1} \otimes f_t \otimes (1 - f_t)]$$

$$\frac{\partial \mathcal{L}}{\partial b_i^T} = \sum_{t=1}^T \mathcal{L}^*(c_t) \otimes \hat{c}_{t-1} \otimes f_t \otimes (1 - f_t)$$

$$\frac{\partial \mathcal{L}}{\partial W_f^T} = \sum_{t=1}^T x_t^T [\mathcal{L}^*(c_t) \otimes \hat{c}_t \otimes \hat{i}_t \otimes (1 - \hat{i}_t)]$$

$$\frac{\partial \mathcal{L}}{\partial W_o^T} = \sum_{t=1}^T h_{t-1}^T [\mathcal{L}^*(c_t) \otimes \hat{c}_t \otimes \hat{i}_t \otimes (1 - \hat{i}_t)]$$

$$\frac{\partial \mathcal{L}}{\partial b_o^T} = \sum_{t=1}^T \mathcal{L}^*(c_t) \otimes \hat{c}_t \otimes \hat{i}_t \otimes (1 - \hat{i}_t)$$

$$\frac{\partial \mathcal{L}}{\partial W_x^T} = \sum_{t=1}^T x_t^T [\mathcal{L}^*(c_t) \otimes \hat{i}_t \otimes (1 - \hat{c}_t^2)]$$

$$\frac{\partial \mathcal{L}}{\partial W_o^T} = \sum_{t=1}^T h_{t-1}^T [\mathcal{L}^*(c_t) \otimes \hat{i}_t \otimes (1 - \hat{c}_t^2)]$$

$$\frac{\partial \mathcal{L}}{\partial b_o^T} = \sum_{t=1}^T \mathcal{L}^*(c_t) \otimes \hat{i}_t \otimes (1 - \hat{c}_t^2)$$

$$\frac{\partial \mathcal{L}}{\partial W_x^T} = \sum_{t=1}^T x_t^T [\mathcal{L}(c_t) \otimes \tanh(C_t) \otimes 0_t \otimes (1 - 0_t)]$$

$$\frac{\partial \mathcal{L}}{\partial W_o^T} = \sum_{t=1}^T h_{t-1}^T [\mathcal{L}(c_t) \otimes \tanh(C_t) \otimes 0_t \otimes (1 - 0_t)]$$

$$\frac{\partial \mathcal{L}}{\partial b_o^T} = \sum_{t=1}^T \mathcal{L}(c_t) \otimes \tanh(C_t) \otimes 0_t \otimes (1 - 0_t)$$

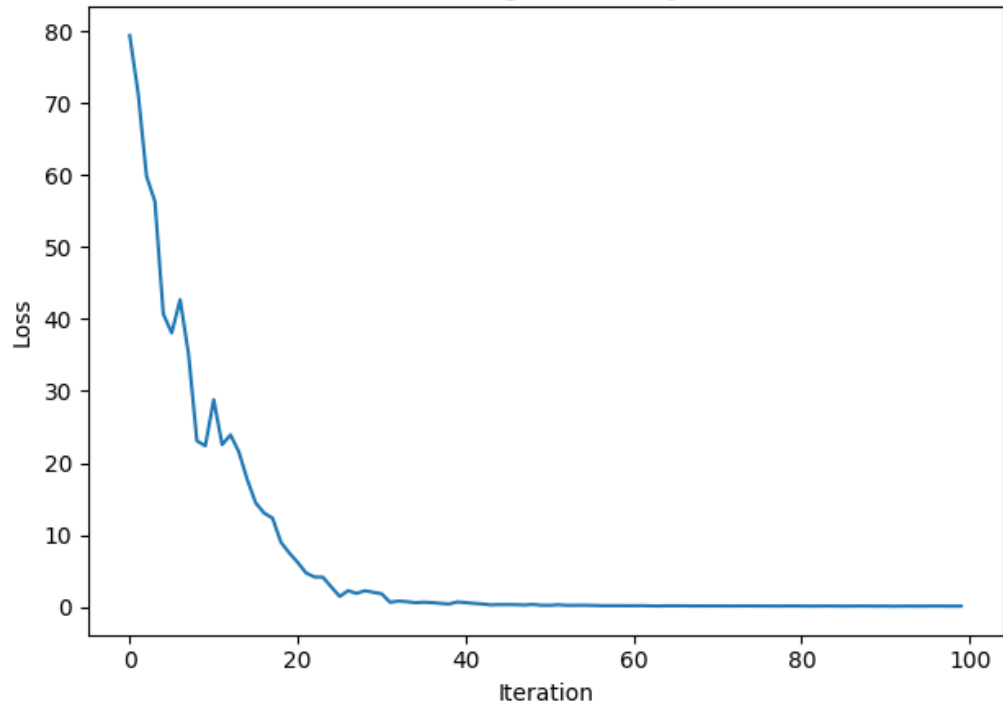
$$\frac{\partial \mathcal{L}}{\partial h_0} = [\mathcal{L}^*(c_1) \otimes \hat{c}_0 \otimes f_1 \otimes (1 - f_1)] W_h^T + [\mathcal{L}^*(c_1) \otimes \hat{c}_1 \otimes \hat{i}_1 \otimes (1 - \hat{i}_1)] W_i^T$$

$$+ [\mathcal{L}^*(c_1) \otimes \hat{i}_1 \otimes (1 - \hat{c}_1^2)] W_f^T + [\mathcal{L}(c_1) \otimes \tanh(C_{c_1}) \otimes 0_1 \otimes (1 - 0_1)] W_o^T$$

5. Application to Image Captioning

All blanks are filled. Followings are the results for image caption.

Training loss history



train

TART> the baby is <UNK> in the <UNK> <UNK> several picture books <EN
:START> the baby is <UNK> in the <UNK> <UNK> several picture books <E



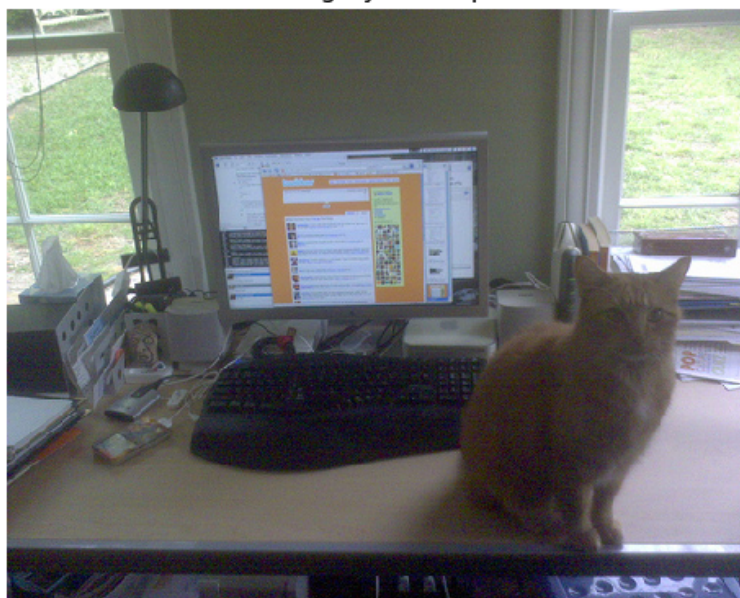
train

<START> a boy on a skateboard takes to the air <END>
GT:<START> a boy on a skateboard takes to the air <END>



val

<START> a man is <UNK> a <UNK> its in a of <END>
GT:<START> a cat is sitting by a computer on a desk <END>



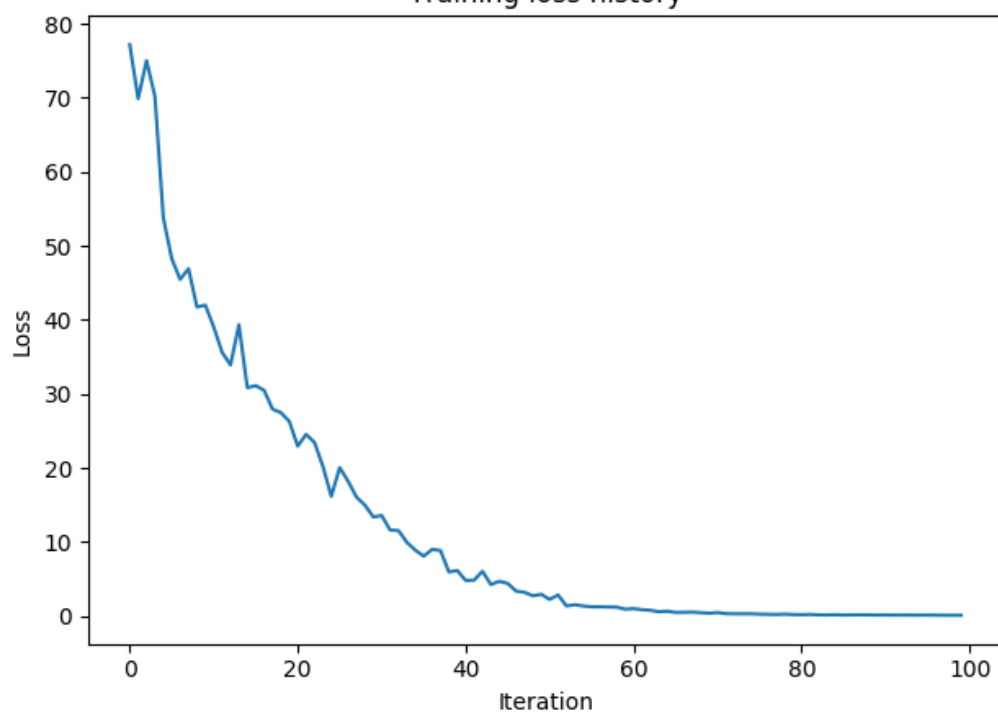
val

<START> the is holding on a a <UNK> sandwich on <UNK> <END>

GT:<START> two slices of pizza sit on a plate with an orange drink <END>



Training loss history



train

<START> <UNK> <UNK> not <UNK> what the image is <UNK> <END>
GT:<START> <UNK> <UNK> not <UNK> what the image is <UNK> <END>



train

<START> a number of boxes and luggage bags on the ground <END>
GT:<START> a number of boxes and luggage bags on the ground <END>



val

<START> this is a <UNK> on a <UNK> <END>

TART> a meal at a table which contains bread carrots <UNK> and <UNK> <

