

Transcriptome Assembler

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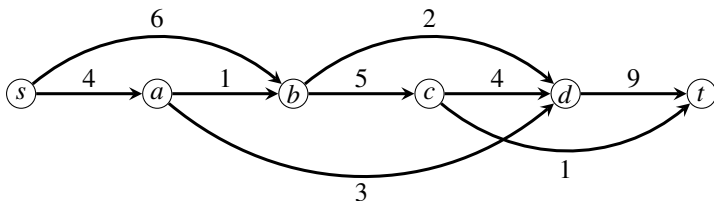
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Problem Statement

- **Input:** strongly connected DAG $G = (V, E)$ with a single source s and a single sink t , weight $w(e)$ for $e \in E$
- **Output:** a set of paths \mathcal{P} from s to t and capacity $c(P)$ for $P \in \mathcal{P}$, such that
 - $|\mathcal{P}|$ is minimized, and that
 - $\sum_{e \in E} |w(e) - \sum_{P \in \mathcal{P}} c(P)|$ is minimized



Existing Method: Cufflinks

- **Algorithm:** compute a minimum number of paths to cover all edges using Dilworth's Theorem
- **Disadvantage:** do not consider the weights of edges

Existing Method: Scripture

- **Algorithm:** output all possible paths
- **Disadvantage:** exponential number of paths

Existing Method: IsoLasso

- **Algorithm:** use quadratic programming

$$\begin{array}{ll}\min & \sum_{e \in E} |w(e) - \sum_{e \in P} c(P)|^2 \\ \text{s.t.} & \sum_{P \in \mathcal{P}} c(P) \leq \lambda\end{array}$$

- **Disadvantage:**
 - $|\mathcal{P}|$ is not bounded
 - exponential number of variables

Existing Method: Traph

- **Algorithm:** use a network flow formulation to compute a new weight $w'(e)$ for $e \in E$ such that $\sum_{e \in E} |w(e) - w'(e)|$ is minimized and that there *exists* a set of paths satisfying $\sum_{e \in E} |w'(e) - \sum_{e \in P} c(P)| = 0$ (i.e., there exists a flow decompositions of the new DAG)
- **Disadvantage:**
 - only the weights are updated; the paths are not returned; actually they use a greedy algorithm to compute paths (the same as StringTie)
 - the number of paths is not considered in this formulation

Existing Method: CLIQ

- **Algorithm:** use ILP to model this problem
- **Disadvantage:**
 - ILP itself is NP-complete
 - exponential number of variables

Existing Method: StringTie

■ Algorithm:

- use greedy algorithm to compute paths (transcripts):
iteratively compute heaviest path
- use network flow formulation to estimate abundance (a sophisticated way to handle reads spanning several vertices)

■ Disadvantage:

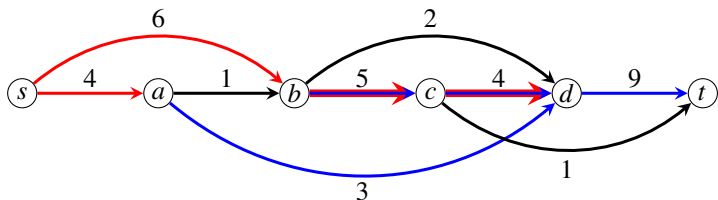
- when compute the current path, the tradeoff between weights is not considered

Our Algorithm

- 1 compute a (good) basis \mathcal{B} (with $|E| - |V| + 2$ paths) of the path space
- 2 use an LP to estimate the capacities of the paths in \mathcal{B}
- 3 try to reduce the number of paths in \mathcal{B}
 - for two paths with (almost) identical capacities, merge them into one path
 - discard paths with very small capacities
- 4 iterate between step 2 and step 3

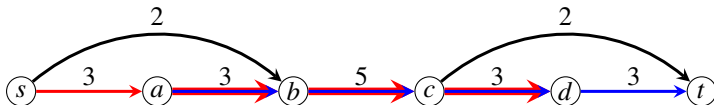
Compute Basis of the Path Space

- 1 for each vertex (except s and t), arbitrarily choose exactly an in-edge and an out-edge (the one with maximum weight);



- 2 for each vertex v (except s and t), there exists a unique path from s to v , and a unique path from v to t
- 3 output paths to cover all edges following these chosen edges

Merge Paths: Example



■ Optimal solution:

- $P_1^* : s \rightarrow a \rightarrow b \rightarrow c \rightarrow d \rightarrow t$, capacity = 3
- $P_2^* : s \rightarrow b \rightarrow c \rightarrow t$, capacity = 2

■ Our solution:

- $P_1 : s \rightarrow a \rightarrow b \rightarrow c \rightarrow d \rightarrow t$, capacity = 1
- $P_2 : s \rightarrow b \rightarrow c \rightarrow d \rightarrow t$, capacity = 2
- $P_3 : s \rightarrow a \rightarrow b \rightarrow c \rightarrow t$, capacity = 2

■ Merge P_2 and P_3

- $P_4 : s \rightarrow b \rightarrow c \rightarrow t$, capacity = 2
- $P_2 + P_3 = P_4 + P_1$, and P_1 must be in \mathcal{B}