

$$1. (a) \bigwedge_{i=1}^n \left(\bigvee_{j=1}^K \text{color}_{ij} \right)$$

$$(b) \bigwedge_{i=1}^n \left(\bigvee_{j=1}^K (\text{color}_{i1} \wedge \neg \text{color}_{i2} \wedge \dots \wedge \neg \text{color}_{ij-1}) \wedge \text{color}_{ij} \wedge \neg \text{color}_{i(j+1)} \wedge \dots \wedge \neg \text{color}_{iK}) \right)$$

$$(c) \bigwedge_{i,j=1}^n \bigwedge_{t=1}^K \neg (\text{color}_{it} \wedge \text{color}_{jt}) \vee \neg \text{neighbor}_{ij}$$

$$(d) \left(\bigwedge_{i=1}^n \left(\bigvee_{j=1}^K \text{color}_{ij} \right) \right) \wedge$$

$$\left(\bigwedge_{i=1}^n \left(\bigvee_{j=1}^K (\text{color}_{i1} \wedge \neg \text{color}_{i2} \wedge \dots \wedge \neg \text{color}_{ij-1}) \wedge \text{color}_{ij} \wedge \neg \text{color}_{i(j+1)} \wedge \dots \wedge \neg \text{color}_{iK}) \right) \right) \wedge$$

$$\left(\bigwedge_{i,j=1}^n \bigwedge_{t=1}^K \neg (\text{color}_{it} \wedge \text{color}_{jt}) \vee \neg \text{neighbor}_{ij} \right)$$

Σ (a) 时间

优先级队列

事件

0

S(0)

Add S(0).

1

A(9)

Pop S(0).

Add A(9)

B(5)

Add B(5)

A(9)

B(5)

Add C(10)

A(9)

C(10)

Σ.

A(9)

Pop B(5)

C(10)

A(8)

Add A(8)

A(9)

C(10)

3.

A(9)
/
C(10)

Pop A(8).

A(9)
/
C(10)
 \
 T(15)

Add T(15)

4.

C(10)
 \
 T(15)

Pop A(9)

5.

T(15)

Pop C(10).

T(15)
 \
 D(15)

Add D(15)

6.

D(15)

Pop T(15)

因此, 最短路径 $S \rightarrow B \rightarrow A \rightarrow T$. 代价 15.

节点离开顺序 $S(0), B(5), A(8), A(9), C(10), T(15),$

(b) $H(x, y) = \max\{17 - x, 15 - y\}$

理由: 返回切比雪夫距离. 观察到, 任一边 cost 都 \geq 两点间切比雪夫距离
因此满足一致性和可接受性.

3.

$C_1: \neg x_1 \vee x_2 \vee x_4$

$C_2: x_1 \vee x_3$

$C_3: \neg x_4 \vee \neg x_2$

$C_4: \neg x_4 \vee \neg x_1 \vee x_2$

$C_5: x_3 \vee \neg x_1$

$C_6: \neg x_3 \vee \neg x_2 \vee x_4$

$C_7: x_1 \vee x_4$

$C_8: \neg x_2 \vee x_1$

$C_9: \neg x_3 \vee \neg x_2$

$x_1 = T @ 1$

C_5

$x_3 = T @ 1$

$x_2 = T @ 2$

C_3

$x_4 = F @ 2$

C_6

K

$x_1 = T @ 1$

C_5

$x_3 = T @ 1$

$x_2 = F @ 2$

C_1

C_1

$x_4 = T @ 2$

C_4

C_4

C_4

K

$x_1 = F @ 1$

C_2

$x_3 = T @ 1$

C_7

$x_4 = T @ 1$

C_3

$x_2 = F @ 1$

✓

∴

$\left\{ \begin{array}{l} x_1 = F \\ x_2 = F \\ x_3 = T \\ x_4 = T \end{array} \right.$

$\nabla : \min$ 