

# Electeng101

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# 1 Fundamentals of Electrical and Digital Systems

## 1.1 Electricity as Energy

The fundamental concept that underpins the modern electrical ‘cycle’ is:

Energy is used to separate charges i.e the chemical reaction in a cell.  
This becomes the electric potential energy of the circuit

Separation of charge causes a difference in electric potential energy. When this difference is applied to a closed circuit, charge will move around the circuit. The movement of charge through is called a current.

### 1.1.1 Charge

Electric charge is the physical property of matter that causes it to experience a force when placed in an electromagnetic field. ( $q$  or  $Q$ )

We (thanks to Benjamin Franklin) typically describe charge as having two states: positive (like a proton) and negative (like an electron). These are not inherent to the universe but are just what we have defined. Of course, the classic line is: ‘Like charges repel, opposite charges attract’. Modeling the wire as a pipe carrying water, charge would be the amount of water.

We model the strength of the electrostatic force as proportional to the charge of both particles and inversely proportional to the radius squared. This is known as Coulomb’s Law.

$$F \propto \frac{q_1 q_2}{r^2}$$

Charge is measured in Coulombs (symbol C). 1C is equivalent to approximately  $6.3 \times 10^{18}$  electrons.

### 1.1.2 Current

Current is the rate of flow of charge represented by  $i$  or  $I$ .

Current is defined numerically as the number of charges flowing through a particular point in one second. Mathematically, it is the derivative of the total number of charges  $q$  passing through a given section over time  $t$  (written as  $\frac{dq}{dt}$ ). Current thusly has units of Coulombs per second ( $\text{Cs}^{-1}$ ) but Electrical Engineers have given this another name, the *Ampere* (A).

$$I = \frac{q}{t}$$

or

$$I = \frac{dq}{dt}$$

Ampere also gave us the name current!

Current gives Electrical Engineers an idea of how *fast* energy is being used instead of how *much* energy it has received<sup>1</sup>. In the water analogy, current would be the speed of the water in the pipe.

<sup>1</sup> Note that most electrical devices require a continuous supply of energy to function so speed is generally much more useful than amount

### Conventional Current

Benjamin Franklin believed that electrical current was carried by positive charge ‘carriers’, this led to *centuries* of engineers using the wrong direction for current... Now we still use conventional current. BUT, electron flow is still in the other direction. Because of relative motion, a movement of negative charge in one direction is the **same thing** as a movement of positive charge in the other direction. Hence, it does not matter (for most things).

### Double-subscript notation

This notation indicates the directions charges are flowing in the order of **from** and **to**.

$$I_{ab}$$

$I_{ab}$  is the current flowing from a to b.

### Example

$$i = 0.5 \text{ A} t = 8 \text{ min} = 60 \times 8 \text{ seconds} = 480 \text{ seconds}$$

$$\begin{aligned} i &= \frac{dq}{dt} \\ \Rightarrow q &= \int_0^{480} 0.5 dt = [0.5t]_0^{480} \\ \therefore q &= 240 \text{ C} \end{aligned}$$

### 1.1.3 Voltage

Voltage is the difference in electrical potential energy of each unit of charge between two points represented by  $v$  or  $V$ .

Because a voltage is a difference, we must know what point in the circuit that the difference is measured relative to for it to make sense. Voltage is commonly called a potential difference (PD) and has units Joules per Coulomb ( $\text{JC}^{-1}$ ). Physically, it is the amount of energy lost or gained between two points. Using our water analogy, voltage would be the pressure of the water in the pipe.

Alessandro Volta decided that Joules per Coulomb ( $\text{JC}^{-1}$ ) was too difficult

and gave us the *Volt* (symbol V). Additionally, every voltage must be accompanied by a *voltage arrow*. This removes the ambiguity in which direction voltage is measured. The voltage arrow points in the direction of a *potential rise*.

The voltage at A, with respect to B, is  $V_{AB}$ .

### Common Reference or Ground

Voltages are always measured between two points. It is convenient to define a reference where we can talk about voltages ‘at’ a component. The location of ground is arbitrary and does not affect the actual voltages in the circuit. The ‘triangle’ ground is for digital circuits while the ‘line’ ground is for analog circuits.



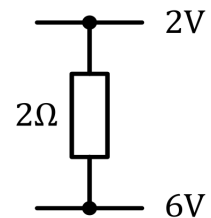
### Example

$$v = 2 - 6$$

$$v = iR$$

$$-4 = 2i$$

$$i = -2$$



### 1.1.4 Resistance

When electrical charge flows through a material, it must lose energy as it repels and collides with other charges. The amount of energy lost depends on how ‘difficult’ it is for the charge to flow. This difficulty depends on many factors including: stability of valence electrons, temperature, length and area. These properties are summarised by *resistance*.

$$v = i \times R$$

From Ohm’s Law, the amount of energy lost by the charges through a resistor is proportional to the rate at which charges flow through it. The constant of proportionality  $R$  from Ohm’s Law is known as resistance. From this law, we can see resistance has units of Resistance has  $\frac{V}{A}$ . We call this Ohms and give it the symbol Omega ( $\Omega$ ).

Thinner materials have a higher resistance!

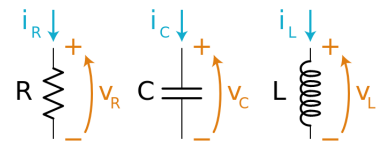
### Conductance

Conductance is the inverse of resistance and has the symbol G. It has units of *Siemens* symbol  $S$ . It mostly exists so that you can add parallel

conductances i.e for 2  $2S$  resistors in parallel, we have a conductance of  $4S$ . With conductance, we would write Ohm's Law as  $i = \nu G$ .

### The Passive-Sign Convention

When using Ohm's law there is an implicit sign convention that cannot be described by just the positive and negative symbols. A current is taken to be in the direction of a voltage drop. This makes sense because charges can only lose energy through a resistor.



### 1.1.5 Power

Power is the rate at which electric charges gain or lose electric potential energy. Given that voltage is the difference in energy per  $Q$  and current is the no. of  $Q$  per sec, we can easily derive an equation for power:

$$P = IV \qquad P = \frac{dE}{dt}$$

Dimensionally, this quantity would be measured in  $\text{Js}^{-1}$  (Joules per Second). This quantity is named the *Watt* (symbol W) named after James Watt for his work with steam engines.

Watt is the unit of power?

There is an assumed sign convention with power. If  $V$  and  $I$  are in opposite directions then  $p = vi$  otherwise  $p = -vi$ . This is the passive-sign convention again. Sticking to that, a negative power is power supplied.

## 1.2 Circuit Definitions

Here are some conventions used to describe all circuits:

load	‘destination’ of the electricity i.e. a lightbulb
topology	the nature of the connections between components
nodes	the point where two or more components meet
loop	a closed path starting and eventually returning to a node

When we are discussing values in a circuit, voltage is ‘across’ a component, current is ‘through’. This means the voltage through a branch but we could also talk about the voltage ‘at’ a component. ‘at’ means the PD is measured from the point to ground.

### Circuit Topologies

Closed

The circuit has both flow of charge and energy transfer.

### Open

No electric potential means no flow of charge and no energy transfer. The circuit could be disrupted, i.e there is an air gap with (theoretically) infinite resistance.

### Short

The circuit (or circuit section) has a 0v potential difference. This could mean a path of lower resistance meant no voltage ‘went’ down that path or that voltages cancelled etc.

## 1.3 Components

### 1.3.1 Ideal Wire

Ideal Wire has a resistance of  $0\Omega$ . This means that no energy is lost when a current goes through it. This is obviously useful as a model for electrical engineering but causes problems with some cases. For example, connecting an ideal wire across the terminal of a voltage source creates a theoretically *infinite* amount of energy.

### 1.3.2 Voltage and Current Sources

These sources can receive or output an *infinite* amount of energy without deviating from their specification. These are good models in most well-designed engineering applications because the sources are designed to operate within their limits.

Ideal Voltage Sources maintain a constant voltage across its terminals. This means it will draw (or supply) whatever current is necessary to maintain that voltage. Meaning the current is dependent on the topology of the circuit. Don’t connect them in parallel.

Ideal Current sources don’t actually exist. But they maintain a constant current through its terminals regardless of voltage. This behaviour means that the voltage across it depends on the topology of the circuit.

## 1.4 Tools

There are a number of mathematical tools that we have developed to make solving circuits easier.

### 1.4.1 KCL

Kirchoff’s Current Law describes the behaviour of current in a circuit, it is:



The algebraic sum of the currents leaving any point in a circuit equals zero.

This means the amount of charge arriving at any point in one second **must** equal the amount of charge leaving that point in one second. Therefore,

$$\sum I_{in} = \sum I_{out}$$

If we don't know the current direction, just make them all leaving and if the maths will show us if a current is entering because it will be negative. The general process is hence:

1. Assign current directions
2. Assign directions for voltages
3. Form an equation in terms of  $i_n$
4. Substitute unknowns for knowns using Ohm's Law

### 1.4.2 KVL

Kirchoff's Voltage Law describes the behaviour of voltages in a circuit, it is: By the conservation of energy, energy gained in a circuit equals the energy lost. Therefore, the total voltage rises must equal the total voltage drops. Hence,

The algebraic sum of the voltage rises around a loop in a circuit equals zero

Once again, if we assume a direction we can solve for the unknown directions. The process for KVL is generally:

1. Assign voltage polarities
2. Identify Loops
3. Form equations (taking voltage rises as positive)

#### | Example

Assign Voltage Polarities,

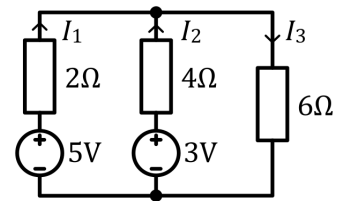
$$\text{Loop 1: } 5 - (2I_1) - (-4I_2) - 3 = 0$$

$$\text{Loop 2: } 3 - (4I_2) - (-6I_3) = 0$$

$$\text{Loop 3: } 5 - (2I_1) - (-6I_3) = 0$$

Then you can solve simultaneously using KCL

$$\text{KCL: } -I_1 - I_2 = I_3$$



### 1.4.3 Terminal Behaviour

To analyse a circuit (determine current and voltage through every component), we need Kirchoff's laws and the *terminal behaviour* of the components. From these, useful shortcuts and 'tricks' have been developed.

### 1.4.4 Equivalent Resistance

Equivalent Resistance is a way of helping us model the behaviour of a circuit as a resistor. This is a simplification we can make, modelling a load as a static resistor value (no matter what the load actually is). We can do this because from the source's 'perspective', it cannot tell the load apart from this fixed resistance.

In Series

$$r = r_1 + r_2 + \dots + r_n = \sum_{k=1}^N r_k$$

In Parallel

$$r = \frac{1}{\frac{1}{r_1} + \frac{1}{r_2} + \dots + \frac{1}{r_n}} = \frac{1}{\sum_{k=1}^N \frac{1}{r_k}}$$

In series,  $r$  is always larger than any one of the components. In parallel,  $r$  is smaller than the smallest resistor contributing to the resistance.

Series means there is only one path for the charges to flow through them (connected end-to-end)

Parallel components have both of their ends connected together

We can use a systematic method to simplify compound circuits i.e.

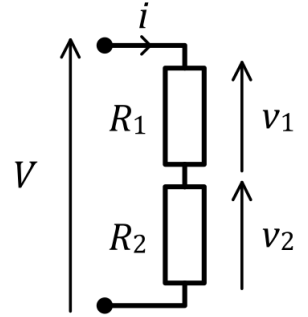
1. Begin as far away as possible from the source or component
2. Replace series or parallel resistors with equivalent resistors
3. Continue moving left and simplifying until we are left with only one

### 1.4.5 Voltage and Current Division

Voltage Division is an easy way to find the voltage over resistors in series. A voltage *divider* is two (or more) resistors in series so  $v_{\text{in}}$  is related to  $v_{\text{out}}$  by a ratio dependent on the resistance.

So for two resistors, where  $v_1$  is the voltage drop on the first resistor and  $v_2$  is the voltage drop on the second resistor:

$$v_1 = \left(\frac{R_1}{R_1 + R_2}\right)V_s$$
$$v_2 = \left(\frac{R_2}{R_1 + R_2}\right)V_s$$



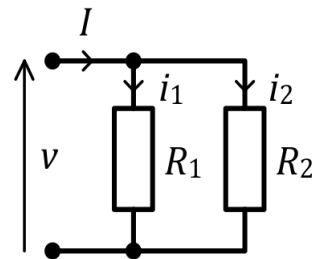
So for N resistors:

$$v_p = \left(\frac{R_p}{R_1 + R_2 + \dots + R_p}\right)V_s$$

Current Division is an easy way to find the *current* over resistors in parallel. Current in a current divider is related to a very similar ratio.

So for N resistors:

$$v_p = \left(\frac{\frac{1}{R_p}}{\frac{1}{R_1} + \frac{1}{R_2} + \dots + \frac{1}{R_p}}\right)I$$



### 1.4.6 Node-Voltage Analysis

Not all circuits can be simplified into series or parallel resistors. This brought around the need for node-voltage analysis. We of course could apply KCL and KVL to solve these circuits but these methods require some adhoc/non-systematic thinking.

Node-voltage analysis is the use of KCL to find the voltages at nodes by expressing the currents through these nodes in terms of their voltages.

Essential nodes are nodes that are connected to *three* or more paths.

1. Select one of the essential nodes as the reference (ground) node, in which all other node voltages will be calculated with respect to.
2. Write a KCL equation for each of the remaining essential nodes in terms of the unknown essential node voltages.
3. Solve the node-voltage equations simultaneously.

### 1.4.7 Superposition

Superposition is the ‘divide and conquer’ of EE. The Superposition Theorem states that: Any *linear* response in a circuit containing multiple sources is equal to the algebraic sum of the contributions to that response. A linear response means that you can only calculate current and voltage **NOT** power. However, you can separately calculate voltage and current and then calculate power. The steps are as follows:

1. Set all but one of your current and/or voltage supplies to zero
2. Solve this circuit for the desired values
3. Do this for each of your sources
4. Sum each of your results i.e  $i_1 = i_{1(a)} + i_{1(b)}$

Setting these to zero means different things! For a voltage supply, it becomes an ideal wire but a current source becomes a gap in the wiring!

### 1.4.8 Thévenin’s Theorem

This theorem from french physicist Léon Charles Thévenin allows you to simplify *any* collection of sources, wire and resistors into just one voltage source and one resistor (and the load).

1. Remove the load you want to base the circuit around
2. Calculate the Thévenin voltage ( $V_{TH}$ ) by calculating the voltage over the gap where the load was
3. Calculate the Thévenin resistance ( $R_{TH}$ ) by pretending to be a current starting at one end in the gap where the load was and going to the other end, the resistances you pass through add to become the  $R_{TH}$
4. Put it all together. A voltage source that outputs  $V_{TH}$  in series with a resistor  $R_{TH}$ , in series with the load.

## 1.5 Models

In Electrical Engineering (EE), a model is a description that communicates

- Physical Characteristics
- Electrical Function
- Magnitude

Models allow you to more easily handle complex systems. They compartmentalise systems into smaller sub-systems. In circuit diagrams, component symbols are models of the actual components. We can then focus on our actual engineering instead of *why* we are doing what we are doing (leave that to the physicists).

Mathematical Models, such as Ohm's Law, are still models. They simplify our calculations by making an approximation.

Some EE models include:

- Component Symbols
- Schematics
- Block Diagrams
- PCB Layouts

## 2 SMART Engineering

Systems of Monitoring, Analysis, and Response Technologies

### 2.1 Monitoring Technologies

#### 2.1.1 Strain Gauge

$$\frac{\Delta R}{R_0} = G \times \frac{\Delta l}{l_0}$$

#### 2.1.2 Resistance Thermometers

Making use of the fact that every resistor is temperature dependent, we can measure a change in temperature with a near linear relationship to resistance. (Remember from CHEMMAT121 that  $\alpha$  is a temperature coefficient, unique to a given material.)

$$R(T) = R_0(1 + \alpha(T - T_0))$$

The type of resistance thermometer is given in the form 'xy' where x is the metal the thermometer is made of and y is the resistance in ohms at 0°C

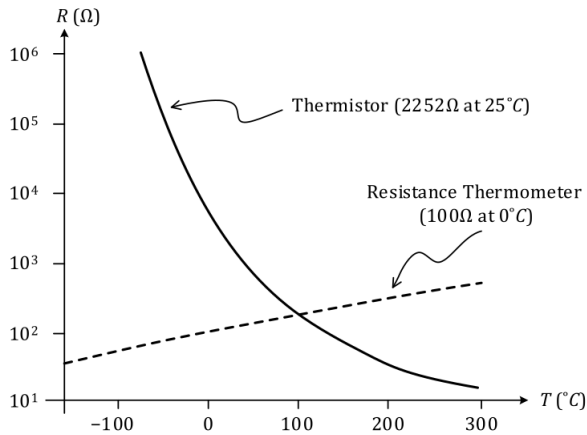
i.e. Pt100 will be a thermometer made of Platinum with a base resistance of  $100\Omega$ .

### 2.1.3 Thermistor

Resistance Thermometers are expensive and quite large. Bring in the thermistor, a small cheap alternative. A thermistor is another resistive input transducer used for temperature sensing. The thermistor is generally more responsive, however, the response is not linear.

$$R(T) = R_0 e^{\beta(\frac{1}{T} - \frac{1}{T_0})}$$

Where  $\beta$  is a material specific constant and  $R_0$  is the resistance at  $0^\circ\text{C}$ .



An important issue to consider with thermistors (and any resistive transducer) is the issue of  $i^2R$  heating. Because, resistance is negatively correlated with temperature due to the semiconductor material used in thermistors, this means an increase in temperature will decrease the resistance and then further increase the current until catastrophic failure of the thermistor (this is called *thermal runaway*).

### 2.1.4 Sensor Interface Circuitry

Sensor interface circuitry is circuitry that allows us to monitor the unknown resistance of whatever resistive transducer is in the circuit. This could be any one of the three we have covered (and more). The most primitive form of this circuitry is a simple voltage divider. The circuit produces a voltage output proportional to the resistance of the transducer. This allows us to more easily monitor the sensor.

Evaluating the equation for a voltage divider, we can derive an equation for  $R_x$  (the resistance we are solving for) given we know the other resistance  $R$  in the voltage divider.

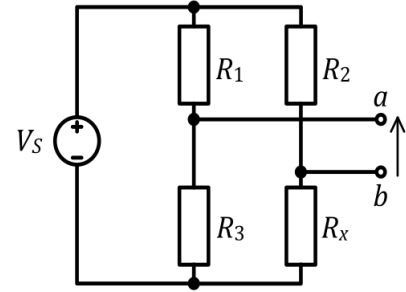
$$\nu_{\text{out}} = \nu_a - \nu_b = \left( \frac{R}{R + R_x} \right) \times V_s \implies R_x = \left( \frac{V_s}{V_{\text{out}}} - 1 \right) \times R$$

### 2.1.5 The Wheatstone Bridge

There are a number of issues with using a simple voltage divider to evaluate our resistive transducer:

- $v_{\text{out}}$  is a function of  $v_s$  (unstable)
- Temperature can confound measurement (resistance  $\propto$  temperature)
- There is always a DC offset in a voltage divider

The solution to that (invented by Charles Wheatstone) is the *Wheatstone Bridge*. If we take two voltage dividers in parallel, we can solve it using the voltage divider formula twice. Rearranging, if we can find resistor values so that the output voltage is zero, then we can make a formula for  $R_x$  that is *independent* of  $V_s$ .

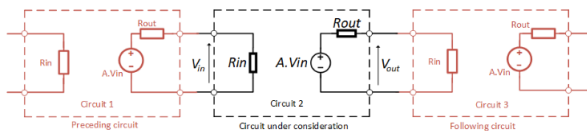


$$\frac{R_3}{R_1 + R_3} - \frac{R_2}{R_2 + R_x} = 0 \implies R_x = \frac{R_2 R_3}{R_1}$$

Since, in this bridge, our output voltage is a difference in voltages we have no DC offset. Additionally, if we change  $R_3$  for an identical gauge as  $R_x$ , both gauges will track in parallel. This cancels any change in temperature hence freeing us from temperature variation. And so, we have done it! The wheatstone bridge solves all the issues we had with the voltage divider.

## 2.2 Equivalent Circuit Model

The equivalent circuit model allows us to simplify any circuit into a resistor and a thevenin circuit. It is summarised by this diagram:



## 2.3 Operational Amplifiers

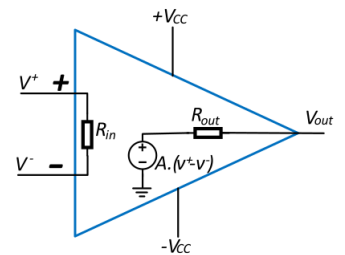
Amplifiers make things bigger. An ‘OpAmp’ amplifies a given voltage proportional to the difference of its inputs. Inside an OpAmp, the circuit is very complicated. Operational Amplifiers are commonly found in plastic packages called integrated circuits (ICs). An OpAmp is called a differential amplifier because its output is related by this difference:

$$V_{out} = A(V_+ - V_-)$$

- $A$  is the amplification factor (or open loop gain) of that specific OpAmp.
- $V_+$  is the non-inverting input voltage
- $V_-$  is the inverting input voltage

### 2.3.1 The Pins

OpAmps have two input pins and one output pin. The two input pins are the inverting and non-inverting pins (written as  $v^-$  and  $v^+$  respectively). There are also power supply pins that are commonly left off the circuit diagram that provide power, these are commonly labeled  $V_{CC}$  and  $V_{DD}$ .

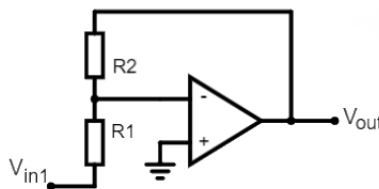
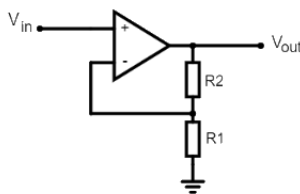


### 2.3.2 Negative Feedback OpAmps

Negative Feedback OpAmps ‘feed’ some of the voltage back into the inverting terminal. There are two types of these circuits, inverting and non-inverting. In a non-inverting circuit, as the input voltage increases the output voltage increases and as the input voltage decreases the output voltage decreases. For an inverting circuit, it is the opposite. It ‘inverts’ that behaviour.

For an Ideal OpAmp,

- $A = \infty$
- $R_{in} = \infty \Omega$
- $I_{in} = 0A$
- $R_{out} = 0\Omega$



The circuit on the left is non-inverting ( $\uparrow$ ). The circuit on the right is inverting.

### 2.3.3 Designing OpAmp Circuits

## 3 Electricity Supply