CHAPTER 12

RED-BLACK TREES

Objectives

- To know what a red-black tree is (§43.1).
- To convert a red-black tree to a 2–4 tree and vice versa (§43.2).
- To design the RBTree class that extends the BST class (§43.3).
- To insert an element in a red-black tree and resolve the double-red violation if necessary (§43.4).
- To delete an element from a red-black tree and resolve the double-black problem if necessary (§43.5).
- To implement and test the RBTree class (§§43.6–43.7).
- To compare the performance of AVL trees, 2–4 trees, and RBTree (§43.8).





43.1 Introduction



A red-black tree is a balanced binary search tree derived from a 2–4 tree. A red-black tree corresponds to a 2-4 tree.

Each node in a red-black tree has a *color attribute* red or black, as shown in Figure 43.1(a). A node is called *external* if its left or right subtree is empty. Note that a leaf node is external, but an external node is not necessarily a leaf node. For example, node 25 is external, but it is not a leaf. The *black depth* of a node is defined as the number of black nodes in a path from the node to the root. For example, the black depth of node 25 is 2, and that of node 27 is 2.



Note

The red nodes appear in blue in the text.

A red-black tree has the following properties:

- 1. The root is black.
- 2. Two adjacent nodes cannot be both red.
- 3. All external nodes have the same black depth.

The red-black tree in Figure 43.1(a) satisfies all three properties. A red-black tree can be converted to a 2-4 tree, and vice versa. Figure 43.1(b) shows an equivalent 2-4 tree for the red-black tree in Figure 43.1(a).

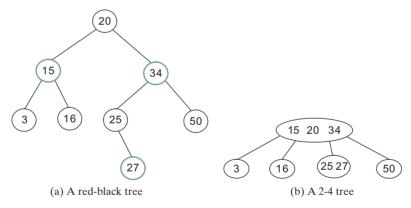


FIGURE 43.1 A red-black tree can be represented using a 2-4 tree, and vice versa.

43.2 Conversion between Red-Black Trees and 2-4 Trees



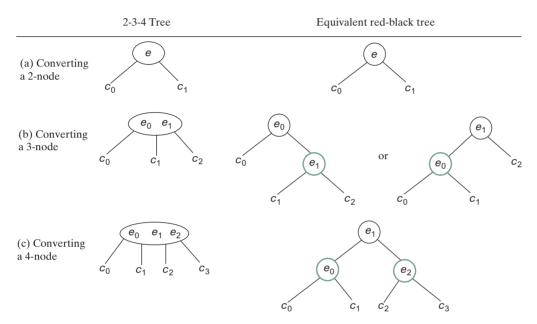
This section discusses the correspondence between a red-black tree and a 2-4 tree.

You can design insertion and deletion algorithms for red-black trees without having knowledge of 2-4 trees. However, the correspondence between red-black trees and 2-4 trees provides useful intuition about the structure of red-black trees and operations. For this reason, this section discusses the correspondence between these two types of trees.

To convert a red-black tree to a 2-4 tree, simply merge every red node with its parent to create a 3-node or a 4-node. For example, the red nodes **15** and **34** are merged to their parent to create a 4-node, and the red node **27** is merged to its parent to create a 3-node, as shown in Figure 43.1(b).

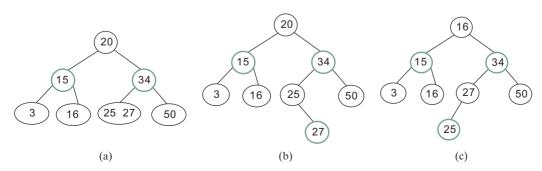
To convert a 2-4 tree to a red-black tree, perform the following transformations for each node u:

- 1. If u is a 2-node, color it black, as shown in Figure 43.2(a).
- 2. If u is a 3-node with element values e_0 and e_1 , there are two ways to convert it. Either make e_0 the parent of e_1 or make e_1 the parent of e_0 . In any case, color the parent black and the child red, as shown in Figure 43.2(b).
- 3. If u is a 4-node with element values e_0 , e_1 , and e_2 , make e_1 the parent of e_0 and e_2 . Color e_1 black and e_0 and e_2 red, as shown in Figure 43.2(c).



A node in a 2-4 tree can be transformed to nodes in a red-black tree.

Let us apply the transformation for the 2-4 tree in Figure 43.1(b). After transforming the 4-node, the tree is as shown in Figure 43.3(a). After transforming the 3-node, the tree is as shown in Figure 43.3(b). Note the transformation for a 3-node is not unique. Therefore, the conversion from a 2-4 tree to a red-black tree is not unique. After transforming the 3-node, the tree could also be as shown in Figure 43.3(c).



The conversion from a 2-4 tree to a red-black tree is not unique. FIGURE 43.3

You can prove the conversion results in a red-black tree that satisfies all three properties.

Property 1. The root is black.

Proof: If the root of a 2-4 tree is a 2-node, the root of the red-black tree is black. If the root of a 2-4 tree is a 3-node or 4-node, the transformation produces a black parent at the root.

Property 2. Two adjacent nodes cannot be both red.

Proof: Since the parent of a red node is always black, no two adjacent nodes can be both red.

Property 3. All external nodes have the same black depth.

Proof: When you covert a node in a 2-4 tree to red-black tree nodes, you get one black node and zero, one, or two red nodes as its children, depending on whether the original node is a 2-, 3-, or 4-node. Only a leaf 2-4 node may produce external red-black nodes. Since a 2-4 tree is perfectly balanced, the number of black nodes in any path from the root to an external node is the same.



- **43.2.1** What is a red-black tree? What is an external node? What is black depth?
- **43.2.2** Describe the properties of a red-black tree.
- **43.2.3** How do you convert a red-black tree to a 2-4 tree? Is the conversion unique?
- **43.2.4** How do you convert a 2-4 tree to a red-black tree? Is the conversion unique?



43.3 Designing Classes for Red-Black Trees

A red-black tree designs a class for a red-black tree.

A red-black tree is a binary search tree. So, you can define the RBTree class to extend the BST class, as shown in Figure 43.4. The BST and TreeNode classes are defined in §26.2.5.

Each node in a red-black tree has a color property. Because the color is either red or black, it is efficient to use the **boolean** type to denote it. The **RBTreeNode** class can be defined to extend **BST.TreeNode** with the color property. For convenience, we also provide the methods for checking the color and setting a new color. Note that **TreeNode** is defined as a static inner class in **BST.RBTreeNode** will be defined as a static inner class in **RBTree.** Note that **BSTNode** contains the data fields **element**, **left**, and **right**, which are inherited in **RBTreeNode**. So, **RBTreeNode** contains four data fields, as pictured in Figure 43.5.

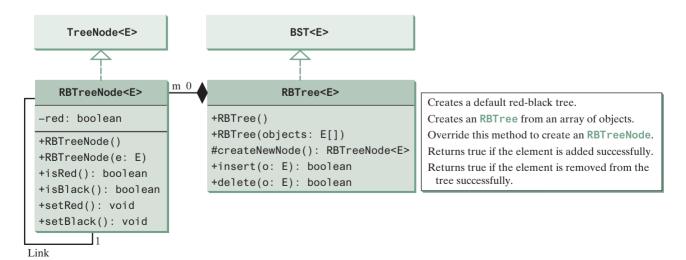


FIGURE 43.4 The RBTree class extends BST with new implementations for the insert and delete methods.

node: RBTreeNode<E>
#element: E
-red: boolean

#left: TreeNode
#right: TreeNode

FIGURE 43.5 An RBTreeNode contains data fields element, red, left, and right.

In the BST class, the createNewNode() method creates a TreeNode object. This method is overridden in the RBTree class to create an RBTreeNode. Note the return type of the createNewNode() method in the BST class is TreeNode, but the return type of the createNewNode() method in RBTree class is RBTreeNode. This is fine, since RBTreeNode is a subtype of TreeNode.

Searching an element in a red-black tree is the same as searching in a regular binary search tree. So, the search method defined in the BST class also works for RBTree.

The **insert** and **delete** methods are overridden to insert and delete an element and perform operations for coloring and restructuring if necessary to ensure that the three properties of the red-black tree are satisfied.



Pedagogical Note

Run from http://liveexample.pearsoncmg.com/dsanimation/ RBTree.html to see how a red-black tree works, as shown in Figure 43.6.

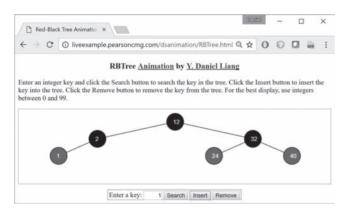


FIGURE 43.6 The animation tool enables you to insert, delete, and search elements in a red-black tree visually.

43.4 Overriding the insert Method

This section discusses how to insert an element to red-black tree.

A new element is always inserted as a leaf node. If the new node is the root, color it black. Otherwise, color it red. If the parent of the new node is red, it violates Property 2 of the red-black tree. We call this a *double-red* violation.

Let u denote the new node inserted, v the parent of u, w the parent of v, and x the sibling of v. To fix the double-red violation, consider two cases:

Case 1: x is black or x is null. There are four possible configurations for u, v, w, and x, as shown in Figures 43.7(a), 43.8(a), 43.9(a), and 43.10(a). In this case, u, v, and w form a 4-node in the corresponding 2-4 tree, as shown in Figures 43.7(c), 43.8(c), 43.9(c), and 43.10(c), but are represented incorrectly in the red-black tree. To correct this error, restructure and recolor three nodes u, v, and w, as shown in Figures 43.7(b), 43.8(b), 43.9(b), and 43.10(b). Note x, y_1 , y_2 , and y_3 may be null.



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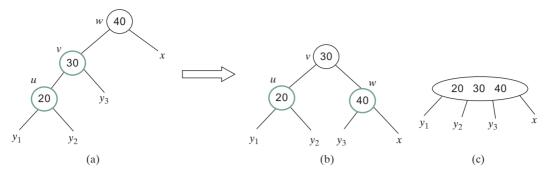


FIGURE 43.7 Case 1.1: u < v < w.

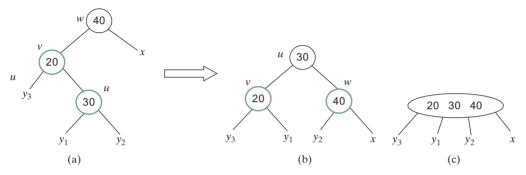


FIGURE 43.8 Case 1.2: v < u < w

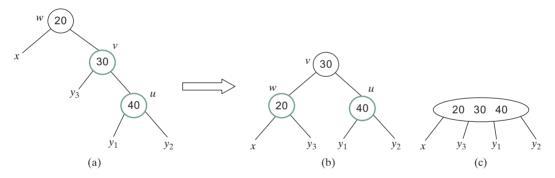
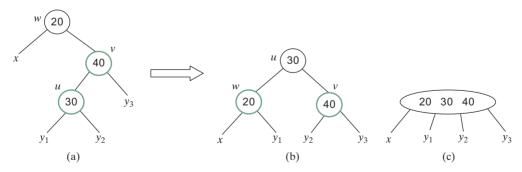


FIGURE 43.9 Case 1.3: w < v < u



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FIGURE 43.10 Case 1.4: w < u < v

Case 2: x is red. There are four possible configurations for u, v, w, w, and x, as shown in Figures 43.11(a), 43.11(b), 43.11(c), and 43.11(d). All of these configurations correspond to an overflow situation in the corresponding 4-node in a 2-4 tree, as shown in Figure 43.12(a). A splitting operation is performed to fix the overflow problem in a 2-4 tree, as shown in Figure 43.12(b). We perform an equivalent recoloring operation to fix the problem in a red-black tree. Color w and u red and color two children of w black. Assume u is a left child of v, as shown

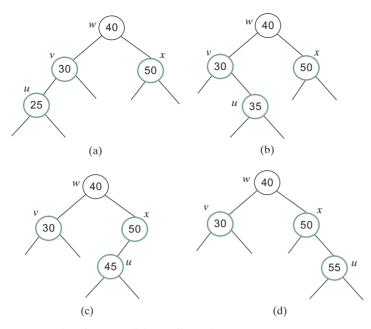


FIGURE 43.11 Case 2 has four possible configurations.

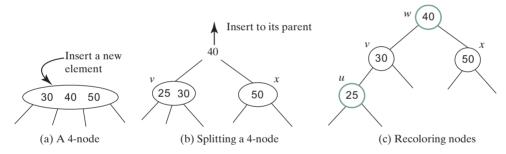


FIGURE 43.12 Splitting a 4-node corresponds to recoloring the nodes in the red-black tree.

in Figure 43.11(a). After recoloring, the nodes are shown in Figure 43.12(c). Now w is red, if w's parent is black, the double-red violation is fixed. Otherwise, a new double-red violation occurs at node w. We need to continue the same process to eliminate the double-red violation at w, recursively.

A more detailed algorithm for inserting an element is described in Listing 43.1.

LISTING 43.1 Inserting an Element to a Red-Black Tree

```
public boolean insert(E e) {
2
      boolean successful = super.insert(e);
 3
      if (!successful)
 4
        return false; // e is already in the tree
5
      else {
6
        ensureRBTree(e);
7
8
9
      return true; // e is inserted
10
    }
11
12
    /** Ensure that the tree is a red-black tree */
    private void ensureRBTree(E e) {
13
14
      Get the path that leads to element e from the root.
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```

```
15
      int i = path.size() - 1; // Index to the current node in the path
16
     Get u, v from the path. u is the node that contains e and v
17
        is the parent of u.
18
      Color u red:
19
20
      if (u == root) // If e is inserted as the root, set root black
21
        u.setBlack();
22
      else if (v.isRed())
23
        fixDoubleRed(u, v, path, i); // Fix double-red violation at u
24
   }
25
26
   /** Fix double-red violation at node u */
27
   private void fixDoubleRed(RBTreeNode<E> u, RBTreeNode<E> v,
        ArrayList<TreeNode<E>> path, int i) {
29
      Get w from the path. w is the grandparent of u.
30
31
      // Get v's sibling named x
32
      RBTreeNode<E> x = (w.left == v) ?
33
        (RBTreeNode<E>)(w.right) : (RBTreeNode<E>)(w.left);
34
35
      if (x == null \mid\mid x.isBlack()) {
36
        // Case 1: v's sibling x is black
37
        if (w.left == v && v.left == u) {
38
          // Case 1.1: u < v < w, Restructure and recolor nodes
39
        }
40
        else if (w.left == v && v.right == u) {
41
          // Case 1.2: v < u < w, Restructure and recolor nodes
42
43
        else if (w.right == v && v.right == u) {
44
          // Case 1.3: w < v < u. Restructure and recolor nodes
45
        }
46
        else {
47
          // Case 1.4: w < u < v, Restructure and recolor nodes
48
49
50
      else { // Case 2: v's sibling x is red
51
        Color w and u red
52
        Color two children of w black.
53
54
        if (w is root) {
55
          Set w black;
56
57
        else if (the parent of w is red) {
58
          // Propagate along the path to fix new double-red violation
59
          u = w;
          v = parent of w;
60
61
          fixDoubleRed(u, v, path, i - 2); // i - 2 propagates upward
62
63
      }
64
   }
```

The insert (E e) method (lines 1–10) invokes the insert method in the BST class to create a new leaf node for the element (line 2). If the element is already in the tree, return false (line 4). Otherwise, invoke ensureRBTree(e) (line 6) to ensure that the tree satisfies the color and black depth property of the red-black tree.

The ensureRBTree (E e) method (lines 13–24) obtains the path that leads to e from the root (line 14), as shown in Figure 43.13. This path plays an important role to implement the algorithm. From this path, you get nodes u and v (lines 16–17). If u is the root, color u black (lines 20–21). If v is red, a double-red violation occurs at node u. Invoke fixDoubleRed to fix the problem.

FIGURE 43.13 The path consists of the nodes from u to the root.

The <code>fixDoubleRed</code> method (lines 27–63) fixes the double-red violation. It first obtains w (the parent of v) from the path (line 29) and x (the sibling of v) (lines 32–33). If x is empty or a black node, restructure and recolor three nodes u, v, and w to eliminate the problem (lines 35–49). If x is a red node, recolor the nodes u, v, w, and x (lines 51–52). If w is the root, color w black (lines 54–56). If the parent of w is red, the double-red violation reappears at w. Invoke <code>fixDoubleRed</code> with new u and v to fix the problem (line 61). Note that now i – 2 points to the new u in the path. This adjustment is necessary to locate the new nodes w and parent of w along the path.

Figure 43.14 shows the steps of inserting 34, 3, 50, 20, 15, 16, 25, and 27 into an empty red-black tree. When inserting 20 into the tree in (d), Case 2 applies to recolor 3 and 50 to black. When inserting 15 into the tree in (g), Case 1.4 applies to restructure and recolor nodes 15, 20, and 3. When inserting 16 into the tree in (i), Case 2 applies to recolor nodes 3 and 20 to black and nodes 15 and 16 to red. When inserting 27 into the tree in (l), Case 2 applies to recolor nodes 16 and 25 to black and nodes 20 and 27 to red. Now a new double-red problem occurs at node 20. Apply Case 1.2 to restructure and recolor nodes. The new tree is shown in (n).

43.5 Overriding the delete Method

This section discusses how to delete an element to red-black tree.

To delete an element from a red-black tree, first search the element in the tree to locate the node that contains the element. If the element is not in the tree, the method returns false. Let u be the node that contains the element. If u is an internal node with both left and right children, find the rightmost node in the left subtree of u. Replace the element in u with the element in the rightmost node. Now we will only consider deleting external nodes.

Let u be an external node to be deleted. Since u is an external node, it has at most one child, denoted by *childOfu*. *childOfu* may be **null**. Let *parentOfu* denote the parent of u, as shown in Figure 43.15(a). Delete u by connecting *childOfu* with *parentOfu*, as shown in Figure 43.15(b).

Consider the following case:

- \blacksquare If u is red, we are done.
- If *u* is black and *childOfu* is red, color *childOfu* black to maintain the black height for *childOfu*.
- Otherwise, assign *childOfu* a fictitious *double black*, as shown in Figure 43.16(a). We call this a *double-black problem*, which indicates that the black depth is short by 1, caused by deleting a black node u.



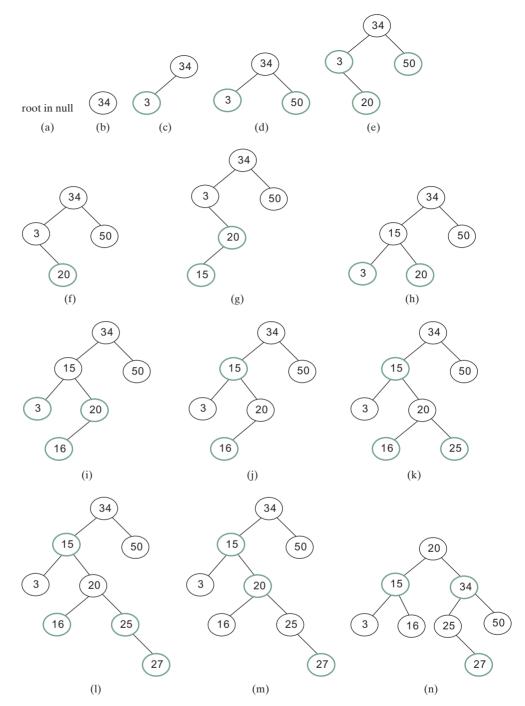


FIGURE 43.14 Inserting into a red-black tree: (a) initial empty tree; (b) inserting 34; (c) inserting 3; (d) inserting 50; (e) inserting 20 causes a double red; (f) after recoloring (Case 2); (g) inserting 15 causes a double red; (h) after restructuring and recoloring (Case 1.4); (i) inserting 16 causes a double red; (j) after recoloring (Case 2); (k) inserting 25; (l) inserting 27 causes a double red at 27; (m) a double red at 20 reappears after recoloring (Case 2); and (n) after restructuring and recoloring (Case 1.2).

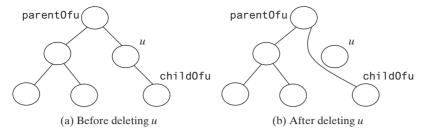


FIGURE 43.15 u is an external node and childOfu may be null.

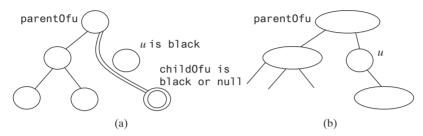


FIGURE 43.16 (a) childOfu is denoted double black. (b) u corresponds to an empty node in a 2-4 tree.

A double black in a red-black tree corresponds to an empty node for u (i.e., underflow situation) in the corresponding 2-4 tree, as shown in Figure 43.16(b). To fix the double-black problem, we will perform equivalent transfer and fusion operations. Consider three cases:

Case 1: The sibling y of childOfu is black and has a red child. This case has four possible configurations, as shown in Figures 43.17(a), 43.18(a), 43.19(a), and 43.20(a). The dashed circle denotes that the node is either red or black. To eliminate the double-black problem, restructure and recolor the nodes, as shown in Figures 43.17(b), 43.18(b), 43.19(b), and 43.20(b).

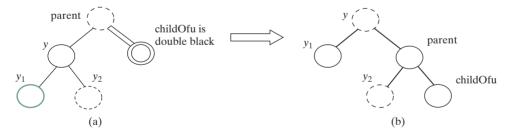


FIGURE 43.17 Case 1.1: The sibling y of childOfu is black and y1 is red.

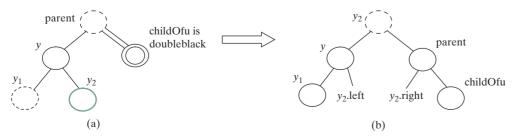


FIGURE 43.18 Case 1.2: The sibling y of childOfu is black and y2 is red.

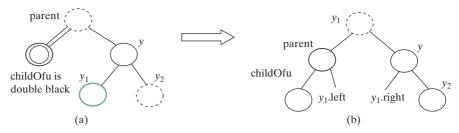


FIGURE 43.19 Case 1.3: The sibling y of childOfu is black and y1 is red.

parent
$$y$$
 parent y_2 childOfu is y_1 double black y_2 y_2 y_3 y_4 y_5 y_6 y_1 y_1 y_2 y_1 y_2 y_3 y_4 y_5 y_6 y_1 y_1 y_2 y_2 y_1 y_2 y_1 y_2 y_1 y_2 y_2 y_1 y_2 y_2 y_1 y_2 y_2 y_1 y_2 y_1 y_2 y_1 y_2 y_2 y_2 y_1 y_2 y_2 y_2 y_1 y_2 y_2 y_2 y_1 y_2 y_2 y_1 y_2 y_1 y_2 y_2 y_1 y_2 y_1 y_2 y_1 y_2 y_2 y_1 y_1 y_2 y_1 y_1 y_2 y_2 y_1 y_1 y_2 y_1 y_1 y_2 y_1 y_1 y_2 y_1 y_1 y_2 y_2 y_1 y_1 y_2 y_2 y_1 y_2 y_1 y_1 y_2 y_2 y_1 y_1 y_2 y_1 y_1 y_2 y_2 y_1 y_2 y_1 y_2 y_2 y_1 y_2 y_2 y_1 y_2 y_2 y_1 y_2 y_1 y_2 y_1 y_2 y_2 y_1 y_2 y_2 y_1 y_2 y_2 y_1 y_2 y_1 y_2 y_2 y_2 y_1 y_2 y_2 y_1 y_2 y_2 y_1 y_2

FIGURE 43.20 Case 1.4: the sibling y of childOfu is black and y2 is red.



Note

Case I corresponds to a *transfer* operation in the 2-4 tree. For example, the corresponding 2-4 tree for Figure 43.17(a) is shown in Figure 43.21(a), and it is transformed into Figure 43.21(b) through a transfer operation.

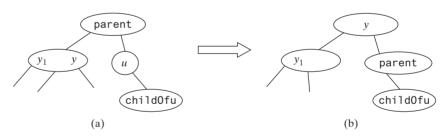


Figure 43.21 Case I corresponds to a transfer operation in the corresponding 2-4 tree.

Case 2: The sibling y of *childOfu* is black and its children are black or null. In this case, change y's color to red. If parent is red, change it to black, and we are done, as shown in Figure 43.22. If parent is black, we denote parent double black, as shown in Figure 43.23. The double-black problem *propagates* to the parent node.

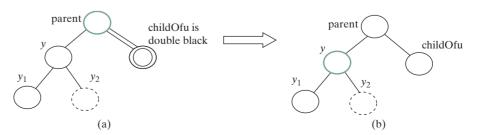


FIGURE 43.22 Case 2: Recoloring eliminates the double-black problem if parent is red.

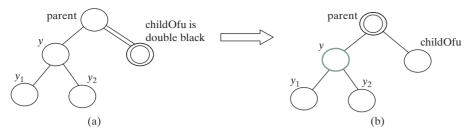


FIGURE 43.23 Case 2: Recoloring propagates the double-black problem if parent is black.



Note

Figures 43.22 and 43.23 show that **childOfu** is a right child of **parent**. If **childOfu** is a left child of **parent**, recoloring is performed identically.



Note

Case 2 corresponds to a *fusion* operation in the 2-4 tree. For example, the corresponding 2-4 tree for Figure 43.22(a) is shown in Figure 43.24(a), and it is transformed into Figure 43.24(b) through a fusion operation.

Case 3: The sibling y of *childOfu* is red. In this case, perform an *adjustment* operation. If y is a left child of parent, let y1 and y2 be the left and right children of y, as shown in Figure 43.25. If y is a right children of parent, let y1 and y2 be the left and right child of y, as shown in Figure 43.26. In both cases, color y black and parent red. childOfu is still a fictitious double-black node. After the adjustment, the sibling of childOfu is now black, and either Case 1 or Case 2 applies. If Case 1 applies, a one-time restructuring and recoloring operation eliminates the double-black problem. If Case 2 applies, the double-black problem cannot reappear, since parent is now red. Therefore, one-time application of Case 1 or Case 2 will complete Case 3.



Note

Case 3 results from the fact that a 3-node may be transformed in two ways to a red-black tree, as shown in Figure 43.27.

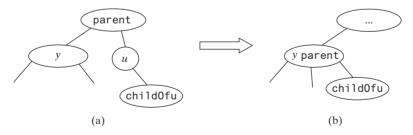


FIGURE 43.24 Case 2 corresponds to a fusion operation in the corresponding 2-4 tree.

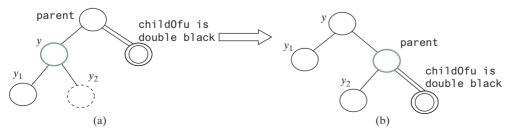


Figure 43.25 Case 3.1: y is a left red child of parent.

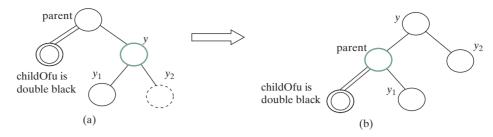


FIGURE 43.26 Case 3.2: y is a right red child of parent.

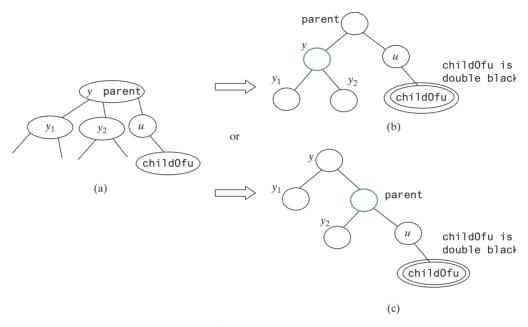


FIGURE 43.27 A 3-node may be transformed in two ways to red-black tree nodes.

Based on the foregoing discussion, Listing 43.2 presents a more detailed algorithm for deleting an element.

LISTING 43.2 Deleting an Element from a Red-Black Tree

```
1
   public boolean delete(E e) {
      Locate the node to be deleted
 3
      if (the node is not found)
 4
        return false;
 5
      if (the node is an internal node) {
 6
 7
        Find the rightmost node in the subtree of the node;
 8
        Replace the element in the node with the one in rightmost;
 9
        The rightmost node is the node to be deleted now;
10
11
12
      Obtain the path from the root to the node to be deleted;
13
14
      // Delete the last node in the path and propagate if needed
15
      deleteLastNodeInPath(path);
16
```

```
17
      size--: // After one element deleted
18
      return true; // Element deleted
19 }
20
21 /** Delete the last node from the path. */
   public void deleteLastNodeInPath(ArrayList<TreeNode<e>> path) {
23
      Get the last node u in the path;
24
      Get parentOfu and grandparentOfu in the path;
25
      Get childOfu from u:
26
      Delete node u. Connect childOfu with parentOfu
27
28
      // Recolor the nodes and fix double black if needed
29
      if (childOfu == root || u.isRed())
30
        return; // Done if childOfu is root or if u is red
31
      else if (childOfu != null && childOfu.isRed())
32
        childOfu.setBlack(); // Set it black, done
33
      else // u is black, childOfu is null or black
34
        // Fix double black on parentOfu
35
        fixDoubleBlack(grandparentOfu, parentOfu, childOfu, path, i);
36
      }
37
      /** Fix the double black problem at node parent */
38
39
      private void fixDoubleBlack(
40
          RBTreeNode<E> grandparent, RBTreeNode<E> parent,
41
          RBTreeNode<E> db, ArrayList<TreeNode<E>> path, int i) {
42
        Obtain y, y1, and y2
43
44
        if (y.isBlack() && y1 != null && y1.isRed()) {
45
          if (parent.right == db) {
46
            // Case 1.1: y is a left black sibling and y1 is red
47
            Restructure and recolor parent, y, and y1 to fix the problem;
48
          }
49
          else {
50
            // Case 1.3: y is a right black sibling and y1 is red
51
            Restructure and recolor parent, y1, and y to fix the problem;
52
          }
53
54
        else if (y.isBlack() && y2 != null && y2.isRed()) {
55
          if (parent.right == db) {
56
            // Case 1.2: y is a left black sibling and y2 is red
57
            Restructure and recolor parent, y2, and y to fix the problem;
58
          }
59
          else {
60
            // Case 1.4: y is a right black sibling and y2 is red
61
            Restructure and recolor parent, y, and y2 to fix the problem;
62
        }
63
64
        else if (y.isBlack()) {
65
          // Case 2: y is black and y's children are black or null
66
          Recolor y to red;
67
68
          if (parent.isRed())
69
            parent.setBlack(); // Done
70
          else if (parent != root) {
71
            // Propagate double black to the parent node
72
            // Fix new appearance of double black recursively
73
            db = parent;
74
            parent = grandparent;
75
            grandparent =
76
              (i \ge 3) ? (RBTreeNode<E>)(path.get(i - 3)) : null;
```

```
77
          fixDoubleBlack(grandparent, parent, db, path, i - 1);
78
        }
79
      }
80
      else if (y.isRed()) {
81
        if (parent.right == db) {
82
          // Case 3.1: y is a left red child of parent
83
          parent.left = y2;
84
          y.right = parent;
85
        }
86
        else {
87
          // Case 3.2: y is a right red child of parent
88
          parent.right = y.left;
89
          y.left = parent;
90
        }
91
        parent.setRed(); // Color parent red
92
93
        y.setBlack(); // Color y black
94
        connectNewParent(grandparent, parent, y); // y is new parent
95
        fixDoubleBlack(y, parent, db, path, i - 1);
96
      }
   }
97
```

The delete(E e) method (lines 1–19) locates the node that contains e (line 2). If the node does not exist, return false (lines 3–4). If the node is an internal node, find the right most node in its left subtree and replace the element in the node with the element in the right most node (lines 6–9). Now the node to be deleted is an external node. Obtain the path from the root to the node (line 12). Invoke deleteLastNodeInPath(path) to delete the last node in the path and ensure that the tree is still a red-black tree (line 15).

The deleteLastNodeInPath method (lines 22–36) obtains the last node u, parent0fu, grandparend0fu, and child0fu (lines 23–26). If child0fu is the root or u is red, the tree is fine (lines 29–30). If child0fu is red, color it black (lines 31–32). We are done. Otherwise, u is black and child0fu is null or black. Invoke fixDoubleBlack to eliminate the double-black problem (line 35).

The fixDoubleBlack method (lines 39–97) eliminates the double-black problem. Obtain y, y1, and y2 (line 42). y is the sibling of the double-black node. y1 and y2 are the left and right children of y. Consider three cases:

- 1. If y is black and one of its children is red, the double-black problem can be fixed by one-time restructuring and recoloring in Case 1 (lines 44–63).
- If y is black and its children are null or black, change y to red. If parent of y is black, denote parent to be the new double-black node and invoke fixDoubleBlack recursively (line 77).
- 3. If y is red, adjust the nodes to make parent a child of y (lines 84, 89) and color parent red and y black (lines 92–93). Make y the new parent (line 94). Recursively invoke fixDoubleBlack on the same double-black node with a different color for parent (line 95).

Figure 43.28 shows the steps of deleting elements. To delete 50 from the tree in Figure 43.28(a), apply Case 1.2, as shown in Figure 43.28(b). After restructuring and recoloring, the new tree is as shown in Figure 43.28(c).

When deleting 20 in Figure 43.28(c), 20 is an internal node, and it is replaced by 16, as shown in Figure 43.28(d). Now Case 2 applies to deleting the rightmost node, as shown in Figure 43.28(e). Recolor the nodes results in a new tree, as shown in Figure 43.28(f).

When deleting 15, connect node 3 with node 20 and color node 3 black, as shown in Figure 43.28(g). We are done.

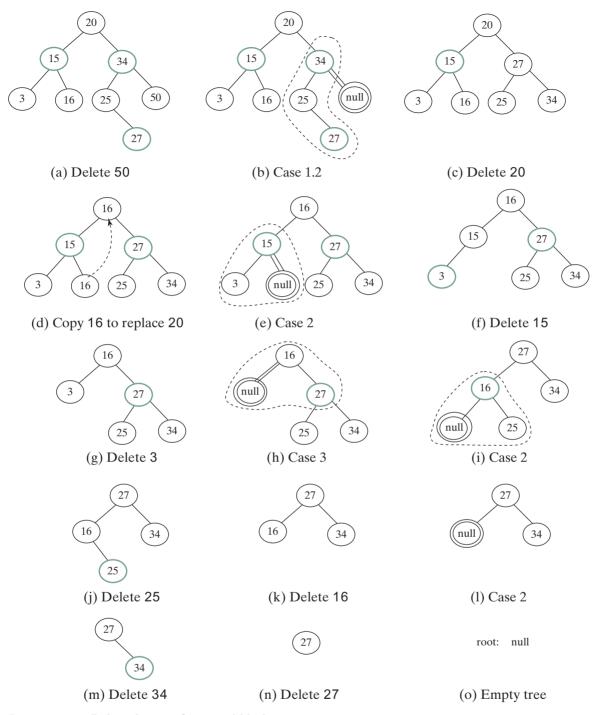


FIGURE 43.28 Delete elements from a red-black tree.

After deleting 25, the new tree is as shown in Figure 43.28(j). Now delete 16. Apply Case 2, as shown in Figure 43.28(k). The new tree is shown in Figure 43.28(l).

After deleting 34, the new tree is as shown in Figure 43.28(m).

After deleting 27, the new tree is as shown in Figure 43.28(n).



- **43.5.1** What are the data fields in RBTreeNode?
- **43.5.2** How do you insert an element into a red-black tree and how do you fix the double-red violation?
- **43.5.3** How do you delete an element from a red-black tree and how do you fix the double-black problem?
- **43.5.4** Show the change of the tree when inserting 1, 2, 3, 4, 10, 9, 7, 5, 8, and 6 into it, in this order.
- **43.5.5** For the tree built in the preceding question, show the change of the tree after deleting 1, 2, 3, 4, 10, 9, 7, 5, 8, and 6 from it in this order.



43.6 Implementing RBTree Class

This section implements the RBTree class.

Listing 43.3 gives a complete implementation for the RBTree class.

LISTING 43.3 RBTree.java

```
import java.util.ArrayList;
1
2
3
   public class RBTree<E extends Comparable<E>> extends BST<E> {
4
      /** Create a default RB tree */
5
      public RBTree() {
6
7
8
      /** Create an RB tree from an array of elements */
      public RBTree(E[] elements) {
9
        super(elements);
10
11
12
      @Override /** Override createNewNode to create an RBTreeNode */
13
14
      protected RBTreeNode<E> createNewNode(E e) {
15
        return new RBTreeNode<E>(e);
16
17
      @Override /** Override the insert method to
18
19
       balance the tree if necessary */
20
      public boolean insert(E e) {
        boolean successful = super.insert(e);
21
22
       if (!successful)
          return false; // e is already in the tree
23
24
        else {
25
          ensureRBTree(e);
26
27
28
       return true; // e is inserted
29
      }
30
      /** Ensure that the tree is a red-black tree */
31
32
      private void ensureRBTree(E e) {
33
       // Get the path that leads to element e from the root
       ArrayList<TreeNode<E>> path = path(e);
34
35
36
       int i = path.size() - 1; // Index to the current node in the path
37
38
        // u is the last node in the path. u contains element e
39
        RBTreeNode<E> u = (RBTreeNode<E>)(path.get(i));
```

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```
40
41
         // v is the parent of of u, if exists
 42
         RBTreeNode<E> v = (u == root) ? null :
 43
           (RBTreeNode<E>)(path.get(i - 1));
 44
 45
         u.setRed(); // It is OK to set u red
 46
 47
         if (u == root) // If e is inserted as the root, set root black
 48
           u.setBlack():
 49
         else if (v.isRed())
 50
           fixDoubleRed(u, v, path, i); // Fix double-red violation at u
 51
 52
       /** Fix double-red violation at node u */
 53
 54
       private void fixDoubleRed(RBTreeNode<E> u, RBTreeNode<E> v,
 55
           ArrayList<TreeNode<E>> path, int i) {
 56
         // w is the grandparent of u
 57
         RBTreeNode<E> w = (RBTreeNode<E>)(path.get(i - 2));
 58
         RBTreeNode<E> parentOfw = (w == root) ? null :
 59
           (RBTreeNode < E >) path.get(i - 3);
 60
 61
         // Get v's sibling named x
 62
         RBTreeNode<E> x = (w.left == v) ?
 63
           (RBTreeNode<E>)(w.right) : (RBTreeNode<E>)(w.left);
 64
 65
         if (x == null \mid\mid x.isBlack()) {
 66
           // Case 1: v's sibling x is black
 67
           if (w.left == v && v.left == u) {
 68
             // Case 1.1: u < v < w, Restructure and recolor nodes
 69
             restructureRecolor(u, v, w, w, parent0fw);
 70
 71
             w.left = v.right; // v.right is y3 in Figure 43.6
 72
             v.right = w;
 73
           }
 74
           else if (w.left == v && v.right == u) {
 75
             // Case 1.2: v < u < w. Restructure and recolor nodes
 76
             restructureRecolor(v, u, w, w, parent0fw);
 77
             v.right = u.left;
 78
             w.left = u.right;
 79
             u.left = v;
 80
             u.right = w;
 81
           }
 82
           else if (w.right == v && v.right == u) {
 83
             // Case 1.3: w < v < u, Restructure and recolor nodes
 84
             restructureRecolor(w, v, u, w, parentOfw);
 85
             w.right = v.left;
 86
             v.left = w;
 87
           }
 88
           else {
 89
             // Case 1.4: w < u < v, Restructure and recolor nodes
 90
             restructureRecolor(w, u, v, w, parentOfw);
 91
             w.right = u.left;
 92
             v.left = u.right;
             u.left = w;
 93
 94
             u.right = v;
95
           }
96
         }
97
         else { // Case 2: v's sibling x is red
98
           // Recolor nodes
99
           w.setRed();
100
           u.setRed();
```

```
101
           ((RBTreeNode<E>)(w.left)).setBlack();
102
           ((RBTreeNode<E>)(w.right)).setBlack();
103
104
           if (w == root) {
105
             w.setBlack();
106
107
           else if (((RBTreeNode<E>)parentOfw).isRed()) {
             // Propagate along the path to fix new double-red violation
108
109
             u = w:
110
             v = (RBTreeNode < E >) parent0fw;
             fixDoubleRed(u, v, path, i - 2); // i - 2 propagates upward
111
112
           }
         }
113
114
       }
115
       /** Connect b with parentOfw and recolor a, b, c for a < b < c */
116
117
       private void restructureRecolor(RBTreeNode<E> a, RBTreeNode<E> b,
118
           RBTreeNode<E> c, RBTreeNode<E> w, RBTreeNode<E> parentOfw) {
119
         if (parentOfw == null)
120
           root = b:
121
         else if (parent0fw.left == w)
122
           parentOfw.left = b;
123
         e1se
124
           parent0fw.right = b;
125
126
         b.setBlack(); // b becomes the root in the subtree
127
         a.setRed(); // a becomes the left child of b
128
         c.setRed(); // c becomes the right child of b
129
       }
130
       @Override /** Delete an element from the RBTree.
131
132
          * Return true if the element is deleted successfully
         ^{\star} Return false if the element is not in the tree ^{\star}/
133
134
       public boolean delete(E e) {
135
         // Locate the node to be deleted
136
         TreeNode<E> current = root:
137
         while (current != null) {
138
           if (e.compareTo(current.element) < 0) {</pre>
139
             current = current.left;
140
           }
141
           else if (e.compareTo(current.element) > 0) {
142
             current = current.right;
143
           else
144
145
             break; // Element is in the tree pointed by current
146
147
148
         if (current == null)
149
           return false; // Element is not in the tree
150
151
         java.util.ArrayList<TreeNode<E>> path;
152
         // current node is an internal node
153
154
         if (current.left != null && current.right != null) {
155
           // Locate the rightmost node in the left subtree of current
           TreeNode<E> rightMost = current.left;
156
157
           while (rightMost.right != null) {
             rightMost = rightMost.right; // Keep going to the right
158
159
160
```

```
161
           path = path(rightMost.element); // Get path before replacement
162
163
           // Replace the element in current by the element in rightMost
164
           current.element = rightMost.element;
165
         }
166
         e1se
167
           path = path(e); // Get path to current node
168
169
         // Delete the last node in the path and propagate if needed
170
         deleteLastNodeInPath(path);
171
         size--: // After one element deleted
172
173
         return true; // Element deleted
174
       }
175
176
       /** Delete the last node from the path. */
177
       public void deleteLastNodeInPath(ArrayList<TreeNode<E>> path) {
178
         int i = path.size() - 1; // Index to the node in the path
179
         // u is the last node in the path
180
         RBTreeNode<E> u = (RBTreeNode<E>)(path.get(i));
         RBTreeNode<E> parent0fu = (u == root) ? null :
181
182
           (RBTreeNode<E>)(path.get(i - 1));
183
         RBTreeNode<E> grandparentOfu = (parentOfu == null ||
184
           parentOfu == root) ? null :
185
           (RBTreeNode<E>)(path.get(i - 2));
186
         RBTreeNode<E> childOfu = (u.left == null) ?
187
           (RBTreeNode<E>)(u.right) : (RBTreeNode<E>)(u.left);
188
189
         // Delete node u. Connect childOfu with parentOfu
190
         connectNewParent(parentOfu, u, childOfu);
191
192
         // Recolor the nodes and fix double black if needed
193
         if (childOfu == root || u.isRed())
194
           return; // Done if childOfu is root or if u is red
195
         else if (childOfu != null && childOfu.isRed())
196
           childOfu.setBlack(); // Set it black, done
         else // u is black, childOfu is null or black
197
198
           // Fix double black on parentOfu
199
           fixDoubleBlack(grandparentOfu, parentOfu, childOfu, path, i);
200
         }
201
202
       /** Fix the double-black problem at node parent */
203
       private void fixDoubleBlack(
204
           RBTreeNode<E> grandparent, RBTreeNode<E> parent,
205
           RBTreeNode<E> db, ArrayList<TreeNode<E>> path, int i) {
206
         // Obtain y, y1, and y2
207
         RBTreeNode<E> y = (parent.right == db) ?
208
           (RBTreeNode<E>)(parent.left) : (RBTreeNode<E>)(parent.right);
209
         RBTreeNode<E> y1 = (RBTreeNode<E>)(y.left);
210
         RBTreeNode<E> y2 = (RBTreeNode<E>)(y.right);
211
212
         if (y.isBlack() && y1 != null && y1.isRed()) {
213
           if (parent.right == db) {
             // Case 1.1: y is a left black sibling and y1 is red
214
215
             connectNewParent(grandparent, parent, y);
216
             recolor(parent, y, y1); // Adjust colors
217
218
             // Adjust child links
219
             parent.left = y.right;
```

```
220
             y.right = parent;
221
           }
222
           else {
223
             // Case 1.3: y is a right black sibling and y1 is red
224
             connectNewParent(grandparent, parent, y1);
225
             recolor(parent, y1, y); // Adjust colors
226
227
             // Adjust child links
228
             parent.right = y1.left;
229
             y.left = y1.right;
230
             y1.left = parent;
231
             y1.right = y;
232
           }
233
         }
234
         else if (y.isBlack() && y2 != null && y2.isRed()) {
235
           if (parent.right == db) {
236
             // Case 1.2: y is a left black sibling and y2 is red
237
             connectNewParent(grandparent, parent, y2);
238
             recolor(parent, y2, y); // Adjust colors
239
240
             // Adjust child links
241
             y.right = y2.left;
242
             parent.left = y2.right;
243
             y2.1eft = y;
244
             y2.right = parent;
245
            }
246
           else {
247
             // Case 1.4: y is a right black sibling and y2 is red
248
             connectNewParent(grandparent, parent, y);
249
             recolor(parent, y, y2); // Adjust colors
250
             // Adjust child links
251
252
             y.left = parent;
253
             parent.right = y1;
254
           }
         }
255
256
         else if (y.isBlack()) {
           // Case 2: y is black and y's children are black or null
257
258
           y.setRed(); // Change y to red
259
           if (parent.isRed())
260
             parent.setBlack(); // Done
261
           else if (parent != root) {
262
             // Propagate double black to the parent node
263
             // Fix new appearance of double black recursively
264
             db = parent;
265
             parent = grandparent;
266
             grandparent =
267
               (i \ge 3) ? (RBTreeNode<E>)(path.get(i - 3)) : null;
268
             fixDoubleBlack(grandparent, parent, db, path, i - 1);
269
           }
270
         }
271
         else { // y.isRed()
272
           if (parent.right == db) {
273
             // Case 3.1: y is a left red child of parent
274
             parent.left = y2;
275
             y.right = parent;
276
           }
277
           else {
278
             // Case 3.2: y is a right red child of parent
279
             parent.right = y.left;
280
               y.left = parent;
```

```
281
             }
282
283
             parent.setRed(); // Color parent red
284
             y.setBlack(); // Color y black
285
             connectNewParent(grandparent, parent, y); // y is new parent
286
             fixDoubleBlack(y, parent, db, path, i - 1);
287
           }
         }
288
289
290
         /** Recolor parent, newParent, and c. Case 1 removal */
291
         private void recolor(RBTreeNode<E> parent,
292
             RBTreeNode<E> newParent, RBTreeNode<E> c) {
293
           // Retain the parent's color for newParent
294
           if (parent.isRed())
295
             newParent.setRed();
296
           else
297
             newParent.setBlack();
298
299
           // c and parent become the children of newParent; set them black
300
           parent.setBlack();
301
           c.setBlack();
302
303
304
         /** Connect newParent with grandParent */
305
         private void connectNewParent(RBTreeNode<E> grandparent,
306
             RBTreeNode<E> parent, RBTreeNode<E> newParent) {
307
           if (parent == root) {
308
             root = newParent:
309
             if (root != null)
310
               newParent.setBlack();
311
           }
312
           else if (grandparent.left == parent)
313
             grandparent.left = newParent;
314
           else
315
             grandparent.right = newParent;
316
         }
317
         @Override /** Preorder traversal from a subtree */
318
319
         protected void preorder(TreeNode<E> root) {
320
           if (root == null) return;
321
           System.out.print(root.element +
             (((RBTreeNode<E>)root).isRed() ? " (red) " : " (black) "));
322
323
           preorder(root.left);
324
           preorder(root.right);
325
         }
326
         /** RBTreeNode is TreeNode plus color indicator */
327
         protected static class RBTreeNode<E extends Comparable<E>> extends
328
329
             BST.TreeNode<E> {
330
           private boolean red = true; // Indicate node color
331
332
           public RBTreeNode(E e) {
333
             super(e);
334
335
336
           public boolean isRed() {
337
             return red;
338
           }
339
           public boolean isBlack() {
340
341
             return !red:
```

```
342
         }
343
344
         public void setBlack() {
345
           red = false;
346
347
348
         public void setRed() {
349
           red = true;
350
351
352
         int blackHeight;
353
       }
354
    }
```

The RBTree class extends BST. Like the BST class, the RBTree class has a no-arg constructor that constructs an empty RBTree (lines 5–6) and a constructor that creates an initial RBTree from an array of elements (lines 9–11).

The **createNewNode**() method defined in the **BST** class creates a **TreeNode**. This method is overridden to return an **RBTreeNode** (lines 14–16). This method is invoked in the insert method in **BST** to create a node.

The insert method in RBTree is overridden in lines 20–29. The method first invokes the insert method in BST, then invokes ensureRBTree (e) (line 25) to ensure that tree is still a red-black tree after inserting a new element.

The ensureRBTree (E e) method first obtains the path of nodes that lead to element e from the root (line 34). It obtains u and v (the parent of u) from the path. If u is the root, color u black (lines 47–48). If v is red, invoke fixDoubleRed to fix the double red on both u and v (lines 49–50).

The fixDoubleRed (u, v, path, i) method fixes the double-red violation at node u. The method first obtains w (the grandparent of u from the path) (line 57), parent0fw if exists (lines 58–59), and x (the sibling of v) (lines 62–63). If x is null or black, consider four subcases to fix the double-red violation (lines 67–96). If x is red, color w and u red and color w's two children black (lines 101–104). If w is the root, color w black (lines 104–106). Otherwise, propagate along the path to fix the new double-red violation (lines 109–111).

The delete (E e) method in RBTree is overridden in lines 134–174. The method locates the node that contains e (lines 136–146). If the node is null, no element is found (lines 148–149). The method considers two cases:

- If the node is internal, find the rightmost node in its left subtree (lines 156–159). Obtain a path from the root to the rightmost node (line 161), and replace the element in the node with the element in the rightmost node (line 164).
- If the node is external, obtain the path from the root to the node (line 167).

The last node in the path is the node to be deleted. Invoke **deleteLastNodeInPath(path)** to delete it and ensure the tree is a red-black after the node is deleted (line 170).

The deleteLastNodeInPath(path) method first obtains u, parent0fu, grand-parend0fu, and child0fu (lines 180–187). u is the last node in the path. Connect child0fu as a child of parent0fu (line 190). This in effect deletes u from the tree. Consider three cases:

- If childOfu is the root or childOfu is red, we are done (lines 193–194).
- Otherwise, if childofu is red, color it black (lines 195–196).
- Otherwise, invoke fixDoubleBlack to fix the double-black problem on childOfu (line 199).

The fixDoubleBlack method first obtains y, y1, and y2 (lines 207–210). y is the sibling of the first double-black node, and y1 and y2 are the left and right children of y. Consider three cases:

- If y is black and y1 or y2 is red, fix the double-black problem for Case 1 (lines 213–255).
- Otherwise, if y is black, fix the double-black problem for Case 2 by recoloring the nodes. If parent is black and not a root, propagate double black to parent and recursively invoke fixDoubleBlack (lines 264–268).
- Otherwise, y is red. In this case, adjust the nodes to make parent the child of y (lines 272–281). Invoke fixDoubleBlack with the adjusted nodes (line 286) to fix the double-black problem.

The preorder (TreeNode<E> root) method is overridden to display the node colors (lines 319–325).

43.7 Testing the RBTree Class

This section gives a test program that uses the RBTree class.

Listing 43.4 gives a test program. The program creates an **RBTree** initialized with an array of integers **34**, **3**, and **50** (lines 4–5), inserts elements in lines 10–22, and deletes elements in lines 25–46.



LISTING 43.4 TestRBTree.java

```
public class TestRBTree {
2
      public static void main(String[] args) {
 3
        // Create an RB tree
 4
        RBTree<Integer> tree =
 5
          new RBTree<Integer>(new Integer[]{34, 3, 50});
 6
        printTree(tree);
 7
 8
        tree.insert(20);
9
        printTree(tree);
10
11
        tree.insert(15);
12
        printTree(tree);
13
14
        tree.insert(16);
15
        printTree(tree);
16
17
        tree.insert(25);
18
        printTree(tree);
19
20
        tree.insert(27);
21
        printTree(tree);
22
23
        tree.delete(50);
24
        printTree(tree);
25
26
        tree.delete(20);
27
        printTree(tree);
28
29
        tree.delete(15);
30
        printTree(tree);
31
```

```
32
        tree.delete(3);
33
        printTree(tree);
34
35
       tree.delete(25);
36
       printTree(tree);
37
38
       tree.delete(16);
39
      printTree(tree);
40
41
       tree.delete(34);
42
       printTree(tree);
43
44
       tree.delete(27);
45
       printTree(tree);
46
      }
47
48
      public static <E extends Comparable<E>>
49
      void printTree(BST <E> tree) {
50
       // Traverse tree
51
       System.out.print("\nInorder (sorted): ");
52
       tree.inorder();
53
        System.out.print("\nPostorder: ");
54
       tree.postorder();
55
       System.out.print("\nPreorder: ");
56
       tree.preorder();
        System.out.print("\nThe number of nodes is " + tree.getSize());
57
58
        System.out.println();
59
      }
60 }
```



```
Inorder (sorted): 3 34 50
Postorder: 3 50 34
Preorder: 34 (black) 3 (red) 50 (red)
The number of nodes is 3
Inorder (sorted): 3 20 34 50
Postorder: 20 3 50 34
Preorder: 34 (black) 3 (black) 20 (red) 50 (black)
The number of nodes is 4
Inorder (sorted): 3 15 20 34 50
Postorder: 3 20 15 50 34
Preorder: 34 (black) 15 (black) 3 (red) 20 (red) 50 (black)
The number of nodes is 5
Inorder (sorted): 3 15 16 20 34 50
Postorder: 3 16 20 15 50 34
Preorder: 34 (black) 15 (red) 3 (black) 20 (black) 16 (red) 50 (black)
The number of nodes is 6
Inorder (sorted): 3 15 16 20 25 34 50
Postorder: 3 16 25 20 15 50 34
Preorder: 34 (black) 15 (red) 3 (black) 20 (black) 16 (red) 25 (red)
  50 (black)
The number of nodes is 7
Inorder (sorted): 3 15 16 20 25 27 34 50
Postorder: 3 16 15 27 25 50 34 20
```

```
Preorder: 20 (black) 15 (red) 3 (black) 16 (black) 34 (red) 25 (black)
  27 (red) 50 (black)
The number of nodes is 8
Inorder (sorted): 3 15 16 20 25 27 34
Postorder: 3 16 15 25 34 27 20
Preorder: 20 (black) 15 (red) 3 (black) 16 (black) 27 (red)
  25 (black) 34 (black)
The number of nodes is 7
Inorder (sorted): 3 15 16 25 27 34
Postorder: 3 15 25 34 27 16
Preorder: 16 (black) 15 (black) 3 (red) 27 (red) 25 (black) 34 (black)
The number of nodes is 6
Inorder (sorted): 3 16 25 27 34
Postorder: 3 25 34 27 16
Preorder: 16 (black) 3 (black) 27 (red) 25 (black) 34 (black)
The number of nodes is 5
Inorder (sorted): 16 25 27 34
Postorder: 25 16 34 27
Preorder: 27 (black) 16 (black) 25 (red) 34 (black)
The number of nodes is 4
Inorder (sorted): 16 27 34
Postorder: 16 34 27
Preorder: 27 (black) 16 (black) 34 (black)
The number of nodes is 3
Inorder (sorted): 27 34
Postorder: 34 27
Preorder: 27 (black) 34 (red)
The number of nodes is 2
Inorder (sorted): 27
Postorder: 27
Preorder: 27 (black)
The number of nodes is 1
Inorder (sorted):
Postorder:
Preorder:
The number of nodes is 0
```

Figure 43.14 shows how the tree evolves as elements are added to it, and Figure 43.28 shows how the tree evolves as elements are deleted from it.

43.8 Performance of the RBTree Class

This search, insertion, and deletion operations take O(logn) time in a red-black tree.

The search, insertion, and deletion times in a red-black tree depend on the height of the tree. A red-black tree corresponds to a 2–4 tree. When you convert a node in a 2–4 tree to red-black tree nodes, you get one black node and zero, one, or two red nodes as its children, depending on whether the original node is a 2-node, 3-node, or 4-node. So, the height of a red-black tree



TABLE 43.1 Time Complexities for Methods in RBTree, AVLTree, and Tree234

Methods	Red-Black Tree	AVL Tree	2-4 Tree
search (e: E)	$O(\log n)$	$O(\log n)$	$O(\log n)$
insert (e: E)	$O(\log n)$	$O(\log n)$	$O(\log n)$
delete (e: E)	$O(\log n)$	$O(\log n)$	$O(\log n)$
getSize()	O(1)	O(1)	O(1)
isEmpty()	O(1)	O(1)	O(1)

is at most as twice that of its corresponding 2–4 tree. Since the height of a 2–4 tree is $\log n$, the height of a red-black tree is $2\log n$.

A red-black tree has the same time complexity as an AVL tree, as shown in Table 43.1. In general, a red-black is more efficient than an AVL tree, because a red-black tree requires only one-time restructuring of the nodes for insert and delete operations.

A red-black tree has the same time complexity as a 2–4 tree, as shown in Table 43.1. In general, a red-black is more efficient than a 2–4 tree for two reasons:

- 1. A red-black tree requires only one-time restructuring of the nodes for insert and delete operations. However, a 2–4 tree may require many splits for an insert operation and fusion for a delete operation.
- 2. A red-black tree is a binary search tree. A binary tree can be implemented more space efficiently than a 2–4 tree, because a node in a 2–4 tree has at most three elements and four children. Space is wasted for 2-nodes and 3-nodes in a 2–4 tree.

Listing 43.5 gives an empirical test of the performance of AVL trees, 2–4 trees, and red-black trees.

Listing 43.5 TreePerformanceTest.java

```
public class TreePerformanceTest {
2
      public static void main(String[] args) {
 3
        final int TEST_SIZE = 500000; // Tree size used in the test
 4
 5
        // Create an AVL tree
 6
        Tree<Integer> tree1 = new AVLTree<Integer>();
 7
        System.out.println("AVL tree time: " +
          getTime(tree1, TEST_SIZE) + " milliseconds");
 8
 9
10
        // Create a 2-4 tree
        Tree<Integer> tree2 = new Tree24<Integer>();
11
12
        System.out.println("2-4 tree time:
13
          + getTime(tree2, TEST_SIZE) + " milliseconds");
14
15
        // Create a red-black tree
        Tree<Integer> tree3 = new RBTree<Integer>();
16
17
        System.out.println("RB tree time:
18
          + getTime(tree3, TEST_SIZE) + " milliseconds");
19
20
21
      public static long getTime(Tree<Integer> tree, int testSize) {
22
        long startTime = System.currentTimeMillis(); // Start time
23
24
        // Create a list to store distinct integers
25
        java.util.List<Integer> list = new java.util.ArrayList<Integer>();
```

```
26
        for (int i = 0; i < testSize; i++)</pre>
27
          list.add(i);
28
29
        java.util.Collections.shuffle(list); // Shuffle the list
30
31
        // Insert elements in the list to the tree
32
        for (int i = 0; i < testSize; i++)</pre>
33
          tree.insert(list.get(i));
34
35
        java.util.Collections.shuffle(list); // Shuffle the list
36
37
        // Delete elements in the list from the tree
38
        for (int i = 0; i < testSize; i++)</pre>
39
          tree.delete(list.get(i));
40
41
        // Return elapse time
42
        return System.currentTimeMillis() - startTime;
43
      }
44 }
```

```
AVL tree time: 7609 milliseconds
2-4 tree time: 8594 milliseconds
RB tree time: 5515 milliseconds
```

The **getTestTime** method creates a list of distinct integers from **0** to **testSize** – **1** (lines 25–27), shuffles the list (line 29), adds the elements from the list to a tree (lines 32–33), shuffles the list again (line 35), removes the elements from the tree (lines 38–39), and finally returns

The program creates an AVL (line 6), a 2-4 tree (line 11), and a red-black tree (line 16). The program obtains the execution time for adding and removing 500000 elements in the three trees.

As you see, the red-black tree performs the best, followed by the AVL tree.



Note

the execution time (line 42).

The <code>java.util.TreeSet</code> class in the Java API is implemented using a red-black tree. Each entry in the set is stored in the tree. Since the <code>search</code>, <code>insert</code>, and <code>delete</code> methods in a red-black tree take $O(\log n)$ time, the <code>get</code>, <code>add</code>, <code>remove</code>, and <code>contains</code> methods in <code>java.util.TreeSet</code> take $O(\log n)$ time.



Note

The <code>java.util.TreeMap</code> class in the Java API is implemented using a red-black tree. Each entry in the map is stored in the tree. The order of the entries is determined by their keys. Since the <code>search</code>, <code>insert</code>, and <code>delete</code> methods in a red-black tree take $O(\log n)$ time, the <code>get</code>, <code>put</code>, <code>remove</code>, and <code>containsKey</code> methods in <code>java.util</code>. TreeMap take $O(\log n)$ time.

KEY TERMS

black depth 43-2 external node 43-9 double-black violation 43-11 red-black tree 43-2 double-red violation 43-7

CHAPTER SUMMARY

- **1.** A red-black tree is a binary search tree, derived from a 2-4 tree. A red-black tree corresponds to a 2-4 tree. You can convert a red-black tree to a 2-4 tree or vice versa.
- **2.** In a red-black tree, each node is colored red or black. The root is always black. Two adjacent nodes cannot be both red. All external nodes have the same black depth.
- 3. Since a red-black tree is a binary search tree, the RBTree class extends the BST class.
- **4.** Searching an element in a red-black tree is the same as in binary search tree, since a red-black tree is a binary search tree.
- **5.** A new element is always inserted as a leaf node. If the new node is the root, color it black. Otherwise, color it red. If the parent of the new node is red, we have to fix the *double-red violation* by reassigning the color and/or restructuring the tree.
- **6.** If a node to be deleted is internal, find the rightmost node in its left subtree. Replace the element in the node with the element in the rightmost node. Delete the rightmost node.
- 7. If the external node to be deleted is red, simply reconnect the parent node of the external node with the child node of the external node.
- **8.** If the external node to be deleted is black, you need to consider several cases to ensure that black height for external nodes in the tree is maintained correctly.
- **9.** The height of a red-black tree is $O(\log n)$. So, the time complexities for the search, insert, and delete methods are $O(\log n)$.



Quiz

Answer the guiz for this chapter online at the book Companion Website.

MyProgrammingLab*

PROGRAMMING EXERCISES

- *43.1 (red-black tree to 2-4 tree) Write a program that converts a red-black tree to a 2-4 tree
- *43.2 (2-4 tree to red-black tree) Write a program that converts a red-black tree to a 2-4 tree.
- ***43.3 (red-black tree animation) Write a GUI program that animates the red-black tree insert, delete, and search methods, as shown in Figure 43.6.
- **43.4 (Parent reference for RBTree) Suppose the TreeNode class defined in BST contains a reference to the node's parent, as shown in Exercise 26.17. Implement the RBTree class to support this change. Write a test program that adds numbers 1, 2, ..., 100 to the tree and displays the paths for all leaf nodes.