```
std::basic string<
        char >
      std::string
            -tf prefix
jaco::JacoKinematics
- base_to_api_
- base_to_j1_
- broadcaster
- j1 to j2
- j2_to_j3
- j3_offset
- i3 to i4
- j4_to_j5
```

- j5 bend degrees

- j6 bend degrees

- j5 to j6

- j6\_to\_end\_ + degToRad() + JacoKinematics() + updateForward()