```
CartesianInfo
     + ThetaX
     + ThetaY
     + ThetaZ
     + X
     + Y
     + Z
     + InitStruct()
    jaco::JacoPose
+ constructPoseMsg()
+ constructWrenchMsg()
+ isCloseToOther()
+ JacoPose()
+ JacoPose()
+ JacoPose()
```