jaco::JacoAPI

+ closeAPI
+ eraseAllTrajectories
+ getActualTrajectoryInfo
+ getAngularCurrent
+ getAngularForce
+ getAngularPosition
+ getAngularVelocity
+ getAPIVersion
+ getCartesianForce
+ getCartesianPosition
and 27 more...

+ JacoAPI()

-jaco_api_

jaco::JacoComm

- api_mutex_
- is_software_stop_
- num_fingers_
- robot_type_

+ getCartesianForce()
+ getCartesianPosition()
+ getConfig()
+ getFingerPositions()
+ getJointAngles()
+ getJointTorques()
+ getJointVelocities()
+ getQuickStatus()
+ homeArm()
+ initFingers()
and 22 more...