```
jaco_msgs::SetForceControl
ParamsRequest_< ContainerAllocator >

+ __connection_header
+ damping_angular
+ damping_linear
+ force_max_angular
+ force_max_linear
+ force_min_angular
+ force_min_linear
+ inertia angular
```

+ SetForceControlParamsRequest\_()
+ SetForceControlParamsRequest ()

+ inertia linear