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# iPic Laboratory - Rapid Prototyping

# Practical Report

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# 1 Introduction

## 1.1 Background

(Insert your content)

gghjbbnmmm

## 1.2 Problem statement

(Insert your content)

## 1.3 Objectives

(Insert your content)

## 1.4 Justification of the study

(Insert your content)

# 2 Literature Review

Itemization

- Item 1.
- Item 2.
- ...

$$\dot{x} = Ax + Bu + B_d w \tag{2.1}$$

Refering a chapter in the main text. For instance Chapter 2

$$E = 210000 \, \frac{\mathrm{N}}{\mathrm{mm}^2}$$

$$\rho = 7{,}85 \, \frac{\mathrm{g}}{\mathrm{cm}^3} = 7850 \, \frac{\mathrm{kg}}{\mathrm{m}^3}.$$

$$\Delta \boldsymbol{r}_k = \boldsymbol{r}_{\mathrm{GBE}_k} - \boldsymbol{r}_{\mathrm{C}_k} = (x_{\mathrm{GBE}_k} - x_{\mathrm{C}_k}, y_{\mathrm{GBE}_k} - y_{\mathrm{C}_k})^T = (\Delta x_k, \Delta y_k)^T \tag{2.2}$$

$k = 2 \ldots n$

$$||\boldsymbol{r}_{\mathrm{GBE}_k} - \boldsymbol{r}_{\mathrm{C}_k}|| \leq r_{kj}, \tag{2.3}$$

$k \; j$

Table 2.1: Caption for the table should be at the top of the table
It can also overflow to next line

| First column | Second column | Third column |
|---|---|---|
| 1 | 2 | 4 |
| 4 | 6 | 23 |
| 34 | 2 | 0 |

$$\operatorname{rank} \boldsymbol{Q}_{\mathrm{B}} = \operatorname{rank} \begin{bmatrix} \boldsymbol{C} \\ \boldsymbol{CA} \\ \boldsymbol{CA}^2 \\ \vdots \\ \boldsymbol{CA}^{n-1} \end{bmatrix} = n. \tag{2.4}$$

$$K_{\varphi} = 3.64 \, \frac{\mathrm{V}}{\mathrm{rad}} \quad \text{and} \tag{2.5}$$

$$K_x = 28.32 \, \frac{\mathrm{V}}{\mathrm{m}}. \tag{2.6}$$

## 2.1 Name of a subsection

$q_1, q_2$ and $q_3$ (see Fig. **??**).

## 2.2 Another subsection

# 3 Methodology. . .

This is

# 4 Expected Outcomes

# References

[1] J. Njiri and D. Söffker, "State-of-the-art in wind turbine control: Trends and challenges," *Renewable and Sustainable Energy Reviews*, vol. 60, pp. 377–393, 2016.

[2] T. Kane and D. Levinson, *Dynamics: Theory and Applications*. McGraw-Hill Book Company, New York, 1985.