

Homework 5

Jesús Alberto Martínez Espinosa

AD1750270 CEM

1. The Helmholtz function of a certain gas is

$$A = -\frac{n^2 a}{V} - nRT \ln(V - nb) + J(T)$$

where J is a function of T only. Derive an expression for the pressure of the gas.

We know that $dA = -SdT - PdV$

$$\left(\frac{\partial A}{\partial V} \right)_T = -SdT - PdV = -P \left(\frac{\partial V}{\partial V} \right)_T$$

$$\left(\frac{\partial A}{\partial V} \right)_T = -P$$

Then,

$$\left(\frac{\partial A}{\partial V} \right)_T = \frac{n^2 a}{V^2} - nRT \left[\frac{1}{V - nb} \right] + \frac{\partial J(T)}{\partial V}$$

$$\left(\frac{\partial A}{\partial V} \right)_T = \frac{n^2 a}{V^2} - \frac{nRT}{V - nb} = -P$$

$$P = \frac{nRT}{V - nb} - \frac{n^2 a}{V^2}$$

2. The Gibbs function of a gas is given by

$$G = nRT \ln\left(\frac{P}{P_0}\right) - nBP$$

Where B is a function of T . Find the expression for:

(a) The equation of state

$$\partial G = -SdT + VdP$$

$$\left(\frac{\partial G}{\partial P}\right)_T = -\frac{S \partial T}{\partial P} + \frac{V \partial P}{\partial P} \rightarrow \left(\frac{\partial G}{\partial P}\right)_T = V$$

$$\left(\frac{\partial G}{\partial P}\right)_T = nRT \left[\ln(P) - \ln(P_0) \right] - nB$$

$$\left(\frac{\partial G}{\partial P}\right)_T = nRT \left[\frac{1}{P} \right] - nB$$

$$\left(\frac{\partial G}{\partial P}\right)_T = \frac{nRT}{P} - nB$$

$$V = \frac{nRT}{P} - nB \rightarrow PV = nRT - nPB$$

(b) The entropy

$$\left(\frac{\partial G}{\partial T}\right)_P = -S$$

$$\left(\frac{\partial G}{\partial T}\right)_P = nR \ln\left(\frac{P}{P_0}\right) - nP \frac{\partial B}{\partial T}$$

$$\left(\frac{\partial G}{\partial T}\right)_P = nR \ln\left(\frac{P}{P_0}\right) - nP \frac{\partial B}{\partial T}$$

$$S = nP \frac{\partial B}{\partial T} - nR \ln\left(\frac{P}{P_0}\right)$$

(c) The Helmholtz function

Using $A = U - TS$, $H = U + PV$, $G = H - TS$

$$G = U + PV - TS \rightarrow G = U - TS + PV$$

$$G = A + PV$$

$$A = G - PV \quad \text{from (a) and } = T \left(\frac{\partial G}{\partial T} \right)$$

$$A = nRT \ln \left(\frac{P}{P_0} \right) - nBP - PV$$

$$A = nRT \ln \left(\frac{P}{P_0} \right) - nBP - nRT + nPB$$

$$A = nRT \left[\ln \left(\frac{P}{P_0} \right) - 1 \right] - \left[\frac{1}{9} \right] T \Delta n = T \left(\frac{\partial G}{\partial T} \right)$$

3. Read the article by J. Pellier et al. "Thermodynamics of Rubber Elasticity."

4. With the information from Pellier's paper

(a) Write an expression for conformation work for a elastic system at constant volume.

We can use the following equations from the appendix.

$$dU = Tds - pdv + \tau dl$$

the term $-pdv = 0$ owing to V constant, then

$$dw = \tau dl$$

$$w = \tau \int_{L_0}^L dl$$

(b) What is the relation between the constant K in this paper and the Young's modulus of the elastic material?
 K is a constant (intensive) and is not possible to determine

$$F = -K \Delta x$$

$$E = \sigma / \epsilon$$

E is an intensive quantity and depends on the material, E is determined experimentally. In the equation $\gamma = KT \left[\frac{L}{L_0} - \left(\frac{L_0}{L} \right)^2 \right]$

K depends only on the composition and geometry and L_0 without stress. In Hooke's Law, the constant is defined by the composition and geometry as well.

(c) Derive equations 2, 3, 6, 7, 9 and 10.

Equation (2)

$$dU = Tds - pdv + \gamma dL$$

$$dU = Tds + \gamma dL$$

$$\left(\frac{\partial U}{\partial L} \right)_{T,V} = T \left(\frac{\partial s}{\partial L} \right)_{T,V} + \gamma \left(\frac{\partial L}{\partial L} \right)_{T,V}$$

$$\left(\frac{\partial U}{\partial L} \right)_{T,V} = \gamma + T \left(\frac{\partial s}{\partial L} \right)_{T,V}$$

Equation (3) $\gamma = KT \left[\frac{L}{L_0} - \left(\frac{L_0}{L} \right)^2 \right]$ $\left(\frac{\partial U}{\partial L} \right)_{T,V} = \gamma + T \left(\frac{\partial s}{\partial L} \right)_{T,V}$

$$\left(\frac{\partial \gamma}{\partial T} \right)_{L,V} = KT \left[-\frac{L}{L_0^2} \frac{\partial L_0}{\partial T} - \frac{2}{L} \left(\frac{L_0}{L} \right) \frac{\partial L_0}{\partial T} \right]$$

$$\left(\frac{\partial s}{\partial L} \right)_{T,V} = - \left(\frac{\partial \gamma}{\partial T} \right)_{L,V}$$

$$\left(\frac{\partial \gamma}{\partial T} \right)_{L,V} = KT \left[-\frac{1}{L_0} \left(\frac{L}{L_0} \right) \frac{\partial L_0}{\partial T} - \frac{2L_0}{L^2} \frac{\partial L_0}{\partial T} \left(\frac{L_0}{L_0} \right) \right]$$

$$\gamma_0 = \frac{1}{L_0} \frac{\partial L_0}{\partial T}$$

$$\left(\frac{\partial \gamma}{\partial T} \right)_{L,V} = KT \left[-\left(\frac{L}{L_0} \right) \frac{1}{L_0} \frac{\partial L_0}{\partial T} - \frac{2L_0^2}{L^2} \left(\frac{1}{L_0} \right) \frac{\partial L_0}{\partial T} \right]$$

$$\left(\frac{\partial \gamma}{\partial T} \right)_{L,V} = KT \left[-\left(\frac{L}{L_0} \right) \gamma_0 - 2 \left(\frac{L_0}{L} \right)^2 \gamma_0 \right]$$

$$-T \left(\frac{\partial \gamma}{\partial T} \right)_{L,V} = KT^2 \left(\frac{L}{L_0} \right) \gamma_0 + 2KT^2 \left(\frac{L_0}{L} \right)^2 \gamma_0$$

$$-T \left(\frac{\partial \gamma}{\partial T} \right)_{L,V} = KT^2 \gamma_0 \left[\frac{L}{L_0} + 2 \left(\frac{L_0}{L} \right)^2 \right]$$

$$\left(\frac{\partial U}{\partial L} \right)_{T,V} = \gamma + T \left(\frac{\partial s}{\partial L} \right)_{T,V}$$

$$\left(\frac{\partial U}{\partial L} \right)_{T,V} = KT^2 \gamma_0 \left[\frac{L}{L_0} + 2 \left(\frac{L_0}{L} \right)^2 \right]$$

↓
 is the coefficient
 of linear expansion
 of rubber under
 zero stress

$$\gamma = 0$$

Equation (6)

$$\gamma_{T,N} \equiv \frac{1}{L} \left(\frac{\partial L}{\partial T} \right)_{T,N} = \gamma_0 - \frac{1}{T} \frac{\left(\frac{L}{L_0} \right)^3 - 1}{\left(\frac{L}{L_0} \right)^3 + 2}$$

$$-\left(\frac{\partial \tau}{\partial T} \right)_{L,N} = KT \left[(L(-1)) \left(\frac{1}{L_0^2} \right) \frac{\partial L_0}{\partial T} + \frac{1}{L_0} \frac{\partial L}{\partial T} - (L_0^2(-2)) \left(\frac{1}{L^3} \right) \frac{\partial L}{\partial T} + \frac{2L_0}{L^2} \frac{\partial L_0}{\partial T} \right]$$

$$-\left(\frac{\partial \tau}{\partial T} \right)_{L,N} = KT \left[-\frac{L}{L_0} \gamma_0 + \frac{1}{L_0} \frac{\partial L}{\partial T} + \frac{2L_0^2}{L^3} \frac{\partial L}{\partial T} - \frac{2L_0^2}{L^2} \gamma_0 \right]$$

$$0 = KT \left[-\frac{L}{L_0} \gamma_0 + \frac{1}{L_0} \frac{\partial L}{\partial T} + \frac{2L_0^2}{L^3} \frac{\partial L}{\partial T} - \frac{2L_0^2}{L^2} \gamma_0 \right] + \frac{\partial \tau}{\partial T}$$

$$0 = KT \left[-\frac{1}{L_0} \gamma_0 + \frac{1}{L_0} \frac{\partial L}{\partial T} + \frac{2L_0^2}{L^3} \frac{\partial L}{\partial T} - \frac{2L_0^2}{L^2} \gamma_0 \right] + \frac{\partial}{\partial T} KT \left[\frac{L}{L_0} - \frac{L_0^3}{L^2} \right]$$

$$0 = KT \left[-\frac{1}{L_0} \gamma_0 + \frac{1}{L_0} \frac{\partial L}{\partial T} + \frac{2L_0^2}{L^3} \frac{\partial L}{\partial T} - \frac{2L_0^2}{L^2} \gamma_0 \right] + K \left[\frac{L}{L_0} - \frac{L_0^3}{L^2} \right] \frac{\partial T}{\partial T}$$

$$0 = -\frac{KT}{L_0} \gamma_0 + \frac{KT}{L_0} \frac{\partial L}{\partial T} + \frac{2KT L_0^2}{L^3} \frac{\partial L}{\partial T} - \frac{2KT L_0^2}{L^2} \gamma_0 + \frac{L}{L_0} - \frac{L_0^3}{L^2}$$

$$\left(\frac{L^2}{L_0^2} \right) 0 = \left[\gamma_0 \left(-\frac{KT}{L_0} - \frac{2KT L_0^2}{L^2} \right) + \frac{\partial L}{\partial T} \left(\frac{KT}{L_0} + \frac{2KT L_0^2}{L^3} \right) + \frac{L}{L_0} - \frac{L_0^3}{L^2} \right] \frac{L^2}{L_0^2}$$

$$0 = \gamma_0 \left(-\frac{KT}{L_0^3} - 2T \right) + \frac{\partial L}{\partial T} \left(\frac{KT}{L_0^3} + \frac{2T}{L} \right) + \left(\frac{L^3}{L_0^3} - 1 \right)$$

$$\left(\frac{1}{L} \frac{\partial L}{\partial T} \right) \left(\frac{KT}{L_0^3} + 2T \right) = \gamma_0 \left(\frac{KT}{L_0^3} + 2T \right) - \left(\frac{L^3}{L_0^3} - 1 \right)$$

$$\frac{1}{L} \left(\frac{\partial L}{\partial T} \right)_{T,N} = \gamma_0 \frac{\left(\frac{KT}{L_0^3} + 2T \right)}{\left(\frac{KT}{L_0^3} + 2T \right)} - \frac{\left(\frac{L^3}{L_0^3} - 1 \right)}{\left(\frac{KT}{L_0^3} + 2T \right)}$$

$$\frac{1}{L} \left(\frac{\partial L}{\partial T} \right)_{T,N} = \gamma_0 - \frac{1}{T} \frac{\left[\left(\frac{L}{L_0} \right)^3 - 1 \right]}{\left[\left(\frac{L}{L_0} \right)^3 + 2 \right]}$$

Equation (7)

$$L_0(T) = L_0(T_0) \exp[\lambda_0(T - T_0)]$$

Using (4)

$$\lambda_0 = \frac{1}{L_0} \frac{\partial L_0}{\partial T}$$

$$\int_{T_0}^T \lambda_0 \partial T = \int_{L_0}^{\partial L_0} \frac{\partial L_0}{L_0} \rightarrow \lambda_0(T - T_0) + C = \ln(L_0)$$

$$\rightarrow e^{\lambda_0(T - T_0) + C} = e^{\ln(L_0)}$$

$$e^{\lambda_0(T - T_0)} e^C = L_0$$

$$e^{\lambda_0(T - T_0)} K = L_0$$

where K may take the initial conditions of the rubber, then

$$e^{\lambda_0(T - T_0)} L_0(T_0) = L_0(T)$$

Equation 9.

Using equations 7 and 6

$$\lambda_0 = \lambda_{\infty, v} + \frac{1}{T} \frac{[L/L_0(T)]^3 - 1}{[L/L_0(T)]^3 + 2}$$

$$L_0(T) = L_0(T_0) \exp[\lambda_0(T - T_0)]$$

Then

$$L_0(T) = L_0(T_0) \exp \left\{ \lambda_{\infty, v} + \frac{1}{T} \frac{[L/L_0(T)]^3 - 1}{[L/L_0(T)]^3 + 2} (T - T_0) \right\}$$

Substituting in eq. (1)

$$\tau = KT \left[\frac{L}{L_0} - \left(\frac{L_0}{L} \right)^2 \right] = KT \left[e^{(T-T_0)\lambda_{\infty, v}} \left(\frac{1}{e^{(T-T_0)\lambda_{\infty, v}}} \right)^2 \right]$$

$$\left(\frac{\partial \tau}{\partial T} \right)_{L, v} = KT \left[e^{(T-T_0)\lambda_{\infty, v}} \left(- \left(\frac{1}{e^{(T-T_0)\lambda_{\infty, v}}} \right)^2 \right) \right] - KT \left[\frac{L}{L_0} - \left(\frac{L_0}{L} \right)^2 \right]$$

$$\left(\frac{\partial \tau}{\partial T} \right)_{L, v} = K \left\{ e^{(T-T_0)\lambda_{\infty, v}} - \left(\frac{1}{e^{(T-T_0)\lambda_{\infty, v}}} \right)^2 + T \left[e^{(T-T_0)\lambda_{\infty, v}} \lambda_{\infty, v} (T - T_0) + 2 \left(e^{(T-T_0)\lambda_{\infty, v}} \right)^3 e^{(T-T_0)\lambda_{\infty, v}} \lambda_{\infty, v} (T - T_0) \right] \right\}$$

$$\left(\frac{\partial \tau}{\partial T} \right) = -K \lambda_{\infty, v} T \left[\alpha_0 e^{[\lambda_0(T-T_0)]} + \frac{2}{\alpha_0^2} e^{[2\lambda_0(T-T_0)]} \right]$$

$$(10) \tau = kT \left[\frac{L}{L_0} - \left(\frac{L_0}{L} \right)^2 \right]$$

$$\left(\frac{\partial \tau}{\partial T} \right)_{L,v} = k \left[\frac{L}{L_0} - \left(\frac{L_0}{L} \right)^2 \right] + kT \left[-\frac{1}{L_0^2} \left(\frac{\partial L_0}{\partial T} \right)_{L,v} + \frac{2L_0}{L^2} \left(\frac{\partial L_0}{\partial T} \right)_{L,v} \right]$$

Using $L_0(T) = L_0(T_0) e^{[T-T_0]}$

$$\left(\frac{\partial L_0(T)}{\partial T} \right)_{\tau,v} = \tau_0 L_0(T)$$

$$\left(\frac{\partial \tau}{\partial T} \right)_{L,v} = k \left[\frac{L}{L_0} - \left(\frac{L_0}{L} \right)^2 \right] + kT \left[-\frac{1}{L_0^2} (\tau_0 L_0) + \frac{2L_0^2 \tau_0}{L^2} \right]$$

$$S(T, L) = S_0(T) + \int_{L_0}^L \left(\frac{\partial S}{\partial L} \right)_{T,v} dL$$

$$\int \left(\frac{\partial S}{\partial L} \right)_{T,v} dL = - \int_{L_0}^L \left(\frac{\partial \tau}{\partial T} \right)_{L,v} dL$$

$$= -k \int_{L_0}^L \left[\left(\frac{L}{L_0} - \left(\frac{L_0}{L} \right)^2 \right) - T \left(\frac{\tau_0 L}{L_0^2} - 2\tau_0 \left(\frac{L_0}{L} \right)^2 \right) \right] dL$$

$$= -kL_0 \left[\frac{L^2}{2L_0^2} + \frac{L_0}{L} - \frac{3}{2} - \tau_0 T \left(\frac{L^2}{2L_0^2} - \frac{2L_0}{L} + \frac{3}{2} \right) \right]$$

$$S(T, L) = S_0(T) + \int_{L_0}^L \left(\frac{\partial S}{\partial L} \right)_{T,v} dL$$

$$\rightarrow S_0(T) - \int_{L_0}^L \left(\frac{\partial \tau}{\partial T} \right)_{L,v} dL$$

$$S(T, L) = S_0(T) - kL_0 \left[\frac{L^2}{2L_0^2} + \frac{L_0}{L} - \frac{3}{2} - \tau_0 T \left(\frac{L^2}{2L_0^2} - \frac{2L_0}{L} + \frac{3}{2} \right) \right]$$

(e) Why is it that rubberlike elasticity is an entropic effect? (10)

According to (i)

$$\left(\frac{\partial S}{\partial L}\right)_T = \left(\frac{\partial L}{\partial T}\right)_F \left(\frac{\partial F}{\partial L}\right)_T$$

If we consider a change in the sign, determined by observing the temperature dependence of the elastic bond length under the condition of constant tension $\left(\frac{\partial L}{\partial T}\right)_\tau$. The determination of

$\left(\frac{\partial L}{\partial T}\right)_\tau$ will give the sign of $\left(\frac{\partial S}{\partial L}\right)_T$.

Using deformation force, which has an energetic and entropic effect

$$f = \left(\frac{\partial U}{\partial L}\right)_{V,T} - T \left(\frac{\partial S}{\partial L}\right)_{V,T}$$

When stretching a rubber, the force exerted is not used to vary the internal energy but to make variations of conformation that decrease entropy. Then

$$f = \cancel{\left(\frac{\partial U}{\partial L}\right)_{V,T}} - T \left(\frac{\partial S}{\partial L}\right)_{V,T}$$

$$f = -T \left(\frac{\partial S}{\partial L}\right)_{V,T}$$

5. Demonstrate the following thermodynamic relations:

$$(a) C_p = C_v + \frac{\alpha^2 TV}{K_T}$$

We can modify the equation

$$C_p - C_v = \frac{\alpha^2 TV}{K_T}$$

$$S = S(v, T) \quad v = v(T, p)$$

$$dS = \left(\frac{\partial S}{\partial T} \right)_v dT + \left(\frac{\partial S}{\partial v} \right)_T dv$$

$$dv = \left(\frac{\partial v}{\partial T} \right)_p dT + \left(\frac{\partial v}{\partial p} \right)_T dp$$

$$dS = \left(\frac{\partial S}{\partial T} \right)_v dT + \left(\frac{\partial S}{\partial v} \right)_T \left[\left(\frac{\partial v}{\partial T} \right)_p dT + \left(\frac{\partial v}{\partial p} \right)_T dp \right]$$

$$dS = \left(\frac{\partial S}{\partial T} \right)_v dT + \left(\frac{\partial S}{\partial v} \right)_T \left(\frac{\partial v}{\partial T} \right)_p dT + \left(\frac{\partial S}{\partial v} \right)_T \left(\frac{\partial v}{\partial p} \right)_T dp$$

$$dS = \left[\left(\frac{\partial S}{\partial T} \right)_v + \left(\frac{\partial S}{\partial v} \right)_T \left(\frac{\partial v}{\partial T} \right)_p \right] dT + \left(\frac{\partial S}{\partial v} \right)_T \left(\frac{\partial v}{\partial p} \right)_T dp$$

Deriving at P constant

$$\left(\frac{\partial S}{\partial T} \right)_p = \left[\left(\frac{\partial S}{\partial T} \right)_v + \left(\frac{\partial S}{\partial v} \right)_T \left(\frac{\partial v}{\partial T} \right)_p \right] + \left(\frac{\partial S}{\partial v} \right)_T \left(\frac{\partial v}{\partial p} \right)_T \left(\frac{\partial p}{\partial T} \right)_p$$

$$\left(\frac{\partial S}{\partial T} \right)_p = \left(\frac{\partial S}{\partial T} \right)_v + \left(\frac{\partial S}{\partial v} \right)_T \left(\frac{\partial v}{\partial T} \right)_p + \left(\frac{\partial S}{\partial v} \right)_T \left(\frac{\partial v}{\partial p} \right)_T \left(\frac{\partial p}{\partial T} \right)_p$$

$$\left(\frac{\partial S}{\partial T} \right)_p - \left(\frac{\partial S}{\partial T} \right)_v = \left(\frac{\partial S}{\partial v} \right)_T \left(\frac{\partial v}{\partial T} \right)_p + \left(\frac{\partial S}{\partial v} \right)_T \left(\frac{\partial v}{\partial p} \right)_T \left(\frac{\partial p}{\partial T} \right)_p$$

$$\frac{C_p - C_v}{T} = \frac{\alpha}{K_T} (v\alpha)$$

$$C_p - C_v = \frac{TV\alpha^2}{K_T}$$

$$(b) \quad k_T - k_S = \frac{\alpha^2 \bar{V} T}{C_p} \quad \text{where} \quad k_S = -\frac{1}{\bar{V}} \left(\frac{\partial \bar{V}}{\partial P} \right)_S$$

$$-\frac{1}{\bar{V}} \left(\frac{\partial \bar{V}}{\partial P} \right)_T + \frac{1}{\bar{V}} \left(\frac{\partial \bar{V}}{\partial P} \right)_S$$

$$\frac{1}{\bar{V}} \left[-\left(\frac{\partial \bar{V}}{\partial P} \right)_T + \left(\frac{\partial \bar{V}}{\partial P} \right)_S \right]$$

$$\frac{1}{\bar{V}} \left[k_T \bar{V} + \left(\frac{\partial \bar{V}}{\partial P} \right)_S \right]$$

$$\partial \bar{V} = \left(\frac{\partial \bar{V}}{\partial T} \right)_P dT + \left(\frac{\partial \bar{V}}{\partial P} \right)_T dP$$

$$\left(\frac{\partial \bar{V}}{\partial P} \right)_S = \left(\frac{\partial \bar{V}}{\partial T} \right)_P \left(\frac{\partial T}{\partial P} \right)_S + \left(\frac{\partial \bar{V}}{\partial P} \right)_T \left(\frac{\partial P}{\partial P} \right)_S$$

$$\left(\frac{\partial \bar{V}}{\partial P} \right)_S = \bar{V} \alpha \left(\frac{\partial T}{\partial P} \right)_S + (-k_T \bar{V})$$

$$\text{Finding } \left(\frac{\partial T}{\partial P} \right)_S = -\frac{\left(\frac{\partial S}{\partial P} \right)_T}{\left(\frac{\partial S}{\partial T} \right)_P} = \frac{\bar{V} \alpha}{\frac{C_p}{T}} = \frac{T \bar{V} \alpha}{C_p}$$

$$\left(\frac{\partial \bar{V}}{\partial P} \right)_S = \bar{V} \alpha \left(\frac{T \bar{V} \alpha}{C_p} \right) - k_T \bar{V}$$

$$\frac{1}{\bar{V}} \left[k_T \bar{V} + \frac{\bar{V}^2 \alpha^2 T}{C_p} - k_T \bar{V} \right]$$

$$\frac{1}{\bar{V}} \left[\frac{\bar{V}^2 \alpha^2 T}{C_p} \right] = \frac{\bar{V} \alpha^2 T}{C_p}$$

$$(c) \frac{K_T}{K_S} = \frac{\bar{C}_p}{\bar{C}_v}$$

We know that $\frac{C_p}{T} = \left(\frac{\partial S}{\partial T} \right)_p$ and $\frac{C_v}{T} = \left(\frac{\partial S}{\partial T} \right)_v$

and $K_T = -\frac{1}{V} \left(\frac{\partial V}{\partial p} \right)_T$; $K_S = -\frac{1}{V} \left(\frac{\partial V}{\partial p} \right)_S$

$$\frac{C_p}{C_v} = \frac{T \left(\frac{\partial S}{\partial T} \right)_p}{T \left(\frac{\partial S}{\partial T} \right)_v} = \frac{\left(\frac{\partial S}{\partial T} \right)_p}{\left(\frac{\partial S}{\partial T} \right)_v}$$

But, It is necessary to find other expression for

Using $\left(\frac{\partial S}{\partial T} \right)_p$ and $\left(\frac{\partial S}{\partial T} \right)_v$

$$\left(\frac{\partial y}{\partial x} \right)_z \left(\frac{\partial z}{\partial y} \right)_x \left(\frac{\partial x}{\partial z} \right)_y = -1$$

$$\left(\frac{\partial S}{\partial T} \right)_p = \frac{-1}{\left(\frac{\partial p}{\partial S} \right)_T \left(\frac{\partial T}{\partial p} \right)_S} \quad \text{and}$$

$$\left(\frac{\partial S}{\partial T} \right)_v = \frac{-1}{\left(\frac{\partial v}{\partial S} \right)_T \left(\frac{\partial T}{\partial v} \right)_S}$$

Then

$$\frac{\left(\frac{\partial S}{\partial T} \right)_p}{\left(\frac{\partial S}{\partial T} \right)_v} = \frac{\frac{-1}{\left(\frac{\partial p}{\partial S} \right)_T \left(\frac{\partial T}{\partial p} \right)_S}}{\frac{-1}{\left(\frac{\partial v}{\partial S} \right)_T \left(\frac{\partial T}{\partial v} \right)_S}} = \frac{-\left(\frac{\partial v}{\partial S} \right)_T \left(\frac{\partial T}{\partial v} \right)_S}{-\left(\frac{\partial p}{\partial S} \right)_T \left(\frac{\partial T}{\partial p} \right)_S}$$

$$\rightarrow \frac{\left(\frac{\partial v}{\partial S} \right)_T \left(\frac{\partial T}{\partial v} \right)_S}{\left(\frac{\partial p}{\partial S} \right)_T \left(\frac{\partial T}{\partial p} \right)_S} = \text{using } \left(\frac{\partial x}{\partial y} \right)_z = \frac{1}{\left(\frac{\partial y}{\partial x} \right)_z} \text{ and } \left(\frac{\partial y}{\partial z} \right)_x \left(\frac{\partial z}{\partial y} \right)_x = \left(\frac{\partial y}{\partial y} \right)_x = 1$$

$$\rightarrow \frac{\left(\frac{\partial v}{\partial S} \right)_T \left(\frac{\partial S}{\partial p} \right)_T}{\left(\frac{\partial v}{\partial T} \right)_S \left(\frac{\partial T}{\partial p} \right)_S} = \frac{\left(\frac{\partial v}{\partial p} \right)_T \cdot \left(-\frac{1}{V} \right)}{\left(\frac{\partial v}{\partial p} \right)_S \cdot \left(-\frac{1}{V} \right)} = \frac{-\frac{1}{V} \left(\frac{\partial v}{\partial p} \right)_T}{-\frac{1}{V} \left(\frac{\partial v}{\partial p} \right)_S} = \frac{K_T}{K_S}$$

$$(d) \left(\frac{\partial H}{\partial V} \right)_S = \frac{-C_p}{K_T C_V}$$

$$\partial H = T \partial S + V \partial P$$

$$\left(\frac{\partial H}{\partial V} \right)_S = T \left(\frac{\partial S}{\partial V} \right)_S + V \left(\frac{\partial P}{\partial V} \right)_S$$

$$\left(\frac{\partial H}{\partial V} \right)_S = V \left(\frac{\partial P}{\partial V} \right)_S$$

$$\left(\frac{\partial V}{\partial P} \right)_S = \frac{\bar{V}^2 \alpha^2 T}{C_p} = K_T \bar{V} \rightarrow \text{from exercise two}$$

$$\left(\frac{\partial P}{\partial V} \right)_S = \frac{1}{\frac{\bar{V}^2 \alpha^2 T}{C_p} - K_T \bar{V} \left(\frac{C_p}{\bar{V}} \right)} = \frac{1}{\frac{\bar{V}^2 \alpha^2 T}{C_p} - K_T \bar{V} C_p}$$

$$\left(\frac{\partial P}{\partial V} \right)_S = \frac{C_p}{\bar{V}^2 \alpha^2 T - K_T \bar{V} C_p}$$

$$\left(\frac{\partial H}{\partial V} \right)_S = \bar{V} \left(\frac{C_p}{\bar{V}^2 \alpha^2 T - K_T \bar{V} C_p} \right)$$

$$\left(\frac{\partial H}{\partial V} \right)_S = \frac{C_p}{\bar{V} \alpha^2 T - K_T C_p}$$

$$\left(\frac{\partial H}{\partial V} \right)_S = \frac{C_p}{-K_T C_V}$$

$$\left(\frac{\partial H}{\partial V} \right)_S = - \frac{C_p}{K_T C_V}$$

from exercise (1)

$$K_T(C_V) = \left(C_p - \frac{\alpha^2 T V}{K_T} \right) K_T$$

$$(-1) (K_T(C_V)) = (C_p K_T - \alpha^2 T V) (-1)$$

$$-K_T(C_V) = \alpha^2 T V - C_p K_T$$

(e) $\left(\frac{\partial C_p}{\partial p}\right)_T = -TV\left(\alpha^2 + \frac{\partial \alpha}{\partial T}\right)_p$

$C_p = \left(\frac{\partial S}{\partial T}\right)_p \rightarrow \bar{C}_p = T\left(\frac{\partial S}{\partial T}\right)_p$

$\left(\frac{\partial C_p}{\partial p}\right)_T = T \frac{\partial}{\partial p} \left(\frac{\partial S}{\partial T}\right)_p$

$\left(\frac{\partial S}{\partial p}\right)_T = -\left(\frac{\partial V}{\partial T}\right)_p$

$\left(\frac{\partial C_p}{\partial p}\right)_T = T \frac{\partial}{\partial p} \left(-\frac{\partial V}{\partial T}\right)_p$

$dS = \frac{C_p}{T} dT - \alpha V dp$

$\left(\frac{\partial C_p}{\partial p}\right)_T = -T \left(\frac{\partial^2 V}{\partial T^2}\right)_p$

$dV = \left(\frac{\partial V}{\partial T}\right)_p dT + \left(\frac{\partial V}{\partial p}\right)_T dp$

$\left(\frac{\partial V}{\partial T}\right)_p = \left(\frac{\partial V}{\partial T}\right)_p \left(\frac{\partial T}{\partial T}\right)_p$

$\left(\frac{\partial V}{\partial T}\right)_p = \bar{V} \alpha$

$\frac{\partial}{\partial p} \left(\frac{\partial V}{\partial T}\right)_p = \bar{V} \left(\frac{\partial \alpha}{\partial T}\right)_p + \alpha \left(\frac{\partial \bar{V}}{\partial p}\right)_p$

$= T \left(\bar{V} \left(\frac{\partial \alpha}{\partial T}\right)_p + \alpha \alpha \right)$

$= -T \bar{V} \left[\left(\frac{\partial \alpha}{\partial T}\right)_p + \alpha^2 \right]$