17.Osamu_Katagiri.Individual_Infographic

Polymer Classification

Chemical Structure

- copolymer
  - graft
  - random
  - alternating
  - graft terpolymer
- Homopolymer
- graft copolymer
- Block copolymer

Structure

- Linear
- Branched
- Crosslinked

Tacticity

- Isotactic
- Syndiotactic
- Atactic

Intermolecular forces

- Elastomer
- Fiber

Thermal behavior

- Thermoplastic
- Thermoset
- (no change)

Source

- Natural ocurring
  - Starch
  - Cellulose
  - Proteins
- Synthetic
  - Plastics

Synthesis

- Addition polymerization
  - Free radical
  - Cationic/Anionic polymerization
  - Catalist
- Condensation polymerization

Monomer arrangement

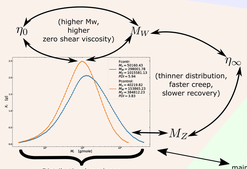
Polymerization

- Is a random process
- prone to mistakes in the spatial conformation

Chemical and Physical Properties

Molecular weight distribution (MWD)

- number of individual chains
- Number average molecular weight $M_n = \frac{\sum X_i}{\sum \frac{X_i}{M_i}}$
- mass fraction
- Weight average molecular weight $M_W = \frac{\sum X_i M_i}{\sum X_i}$
- Amount of high molecular weight chains
- Higher average molecular weight $M_Z = \frac{\sum X_i M_i^2}{\sum X_i M_i}$
- molecules with different molecular weight
- Polydispersity Index $PDI = \frac{M_W}{M_n}$



Chemical stability

- Temperature
- Strain
- Double bonds Free radicals
- Oxygen
- Ultraviolet exposure
- Avoid chain rupture with:
  - Thermal stabilizers
  - Additives
    - UV stabilizers
    - Antioxidant stabilizers
  - Avert high temperatures
  - Avoid frequent heating cycles
- Polymerization
- Degradation
- Molecular weight distribution

Processability

- Viscoelasticity
  - DPM
  - Additives
  - Temperature

Rheological test

- lower molecular weights maintain the Newtonian behavior at higher shear rates

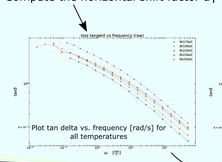
$$tan\ \delta = \frac{G''(\dot\gamma)}{G'(\dot\gamma)}$$

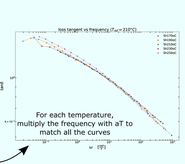
$$complex\ viscosity\ \eta^*(\dot\gamma) = \frac{\sqrt{|G^*(\dot\gamma)|}}{\dot\gamma}$$

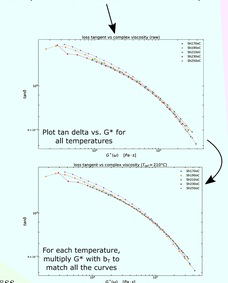
$$complex\ modulus\ G^*(\dot\gamma) = \left[(storage/elastic\ modulus\ G'(\dot\gamma)\ [Pa])^2 + (loss/viscous\ modulus\ G''(\dot\gamma)\ [Pa])^2\right]^{0.5}$$

Oscillation test

- Compute the horizontal shift factor a_T
- Compute the vertical shift factor b_T

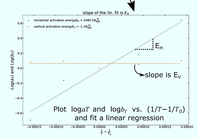






Time-Temperature Superposition TTS

- Get the activation energy E_H and E_V



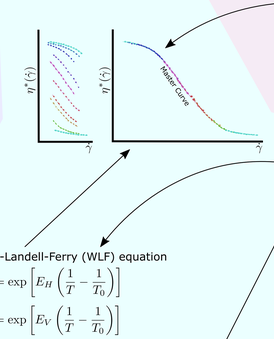
Williams-Landell-Ferry (WLF) equation

$$a_T = \exp\left[E_H\left(\frac{1}{T} - \frac{1}{T_0}\right)\right]$$

$$b_T = \exp\left[E_V\left(\frac{1}{T} - \frac{1}{T_0}\right)\right]$$

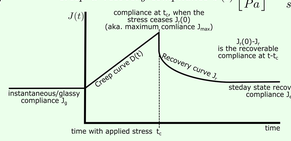
Compute a_T and b_T for arbitrary temperatures

"Get the master curve for a particular temperature"



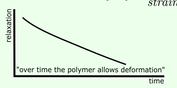
Constant stress test

$$creep\ \&\ recovery\ compliance\ J(t)\left[\frac{1}{Pa}\right] = \frac{strain}{stress}$$



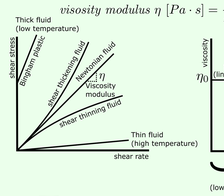
Constant strain test

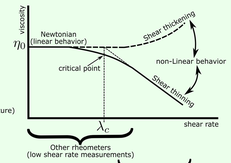
$$relaxation\ modulus\ G\ [Pa] = \frac{stress}{strain}$$



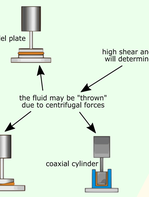
Constant shear rate test

$$viscosity\ modulus\ \eta\ [Pa \cdot s] = \frac{stress}{shear\ rate}$$

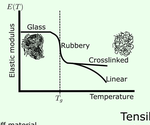




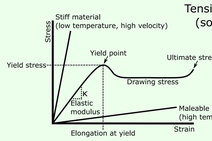
- high shear and low viscosities will determine the geometry
- the fluid may be "thrown" due to centrifugal forces



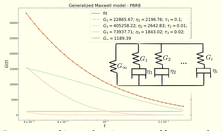
Thermal behavior (Glass tansition temperature)



Tensile test (solids)



Generalized Maxwell model



$$G(t) = G_\infty + \sum_{i=1}^{n} G_i e^{-\frac{G_i}{\eta_i}t}$$

G_∞ is the relaxation modulus at $t = \infty$
G_i is the relaxation modulus of the ith spring
η_i is the viscosity of the dashpot for the ith series
n is the number of spring-dashpot series
τ_i is the relaxation time for a single spring-dashpot series

$$\tau_i = \frac{\eta_i}{G_i}$$

$$\lambda_i = \frac{\eta_i}{G_i}$$

Empirical functions for viscosity data

$$\eta = \frac{a - b}{\left[1 + (c\dot\gamma)^2\right]^{\frac{1-d}{2}}} + b$$

Carreau

a = zero rate viscosity
b = infinite rate viscosity
c = consistency
d = rate index

$$\eta = \frac{a - b}{\left[1 + (c\dot\gamma)^2\right]^{\frac{1-d}{2}}} + b$$

Carreau-Yasuda

η = Viscosity
$\dot\gamma$ = Shear rate
η_∞ = Infinite shear rate viscosity
η_0 = Zero shear rate viscosity
κ = Time constant
n = The Power Law index
a = The width of the transition region between the zero shear viscosity and the Power Law region

$$\eta = a + b\dot\gamma^{c-1}$$

Sisko

a = infinite rate viscosity
b = consistency
c = rate index

$$\eta = \frac{a}{1 + (b\dot\gamma)^c}$$

Williamson

a = zero rate viscosity
b = consistency
c = rate index

$$\eta = m\dot\gamma^n$$

Power Law

η = viscosity
m = Consistency index
n = Power Law index

$$\eta = \frac{a - b}{1 + (c\dot\gamma)^d} + b$$

Cross

a = zero rate viscosity
b = infinite rate viscosity
c = consistency
d = rate index

Dymanic Mechanical data

$$G'(\omega) = \sum_{i=1}^{n} G_i \frac{\omega^2\lambda_i^2}{1 + \lambda_i^2\omega^2} \qquad G''(\omega) = \sum_{i=1}^{n} G_i \frac{\omega\lambda_i}{1 + \lambda_i^2\omega^2}$$

Memory function

- continuous
  - $m(s) = \int \frac{H(\lambda)}{\lambda} e^{\frac{-t}{\lambda}} dln\lambda$
  - $s = t - t'$
  - derivative of the relaxation modulus m(s) = G(s)/dt'
- discretized
  - $\mu(t) = a_i e^{\frac{-t}{\lambda_i}}$

$H(\lambda)$ in Pa

$H(\lambda) \longleftrightarrow G_i$ vs. λ_i plot

Discrete relaxation spectra

a distribution modull for the Generalized Maxwell model

$$G(t) = \int H(\lambda) e^{\frac{-t}{\lambda_i}} dln\lambda_i$$

$$J_e^0 = \frac{\int H(\lambda)\lambda^2 dln\lambda}{\left(\int H(\lambda)\lambda \cdot dln\lambda\right)^2}$$

steady state recoverable compliance

- instantaneous modulus
  - $G_g = \int H(\lambda) dln\lambda$
- zero shear viscosity
  - $\eta_0 = \int H(\lambda)\lambda \cdot dln\lambda$

Constitutive Models

The motion and energy equations (Navier-Stokes) explain the flow of polymers and require a stress tensor in function of various kinematic tensors

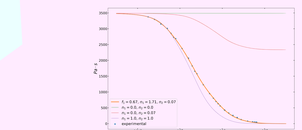
Kinematic tensors

- Finite Linear Viscoelasticity (Rubber-like liquid, or Lodge Network Theory)
- Non-Linear behavior (Stress is a function of shear rate)
- Linear Infinitesimal Viscoelasticity (LIVE) "non-zero normal stress with increasing shear rate"
  - Simple Shear
    - $\gamma_{ij}(t \geq 0) = \begin{bmatrix} 0 & \gamma_0 & 0 \\ \text{symmetric} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$
  - Simple Extension
    - $\gamma_{ij}(t \geq 0) = \begin{bmatrix} 2\varepsilon_0 & 0 & 0 \\ 0 & -\varepsilon_0 & 0 \\ 0 & 0 & -\varepsilon_0 \end{bmatrix}$
- Cauchy & Finger Strain Tensors
  - Simple Shear
    - $C_{ij}(t_1, t_2) = \begin{bmatrix} 1 & -\gamma(t_2) - \gamma(t_1) & 0 \\ -\gamma(t_2) - \gamma(t_1) & \{1 + [\gamma(t_2) - \gamma(t_1)]^2\} & 0 \\ 0 & 0 & 1 \end{bmatrix}$
    - $B_{ij}(t_1, t_2) = \begin{bmatrix} \{1 + [\gamma(t_2) - \gamma(t_2)]^2\} & \gamma(t_2) - \gamma(t_2) & 1 \\ -\gamma(t_2) - \gamma(t_2) & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
  - Simple Extension
    - $C_{ij}(t_1, t_2) = \begin{bmatrix} e^{2[\varepsilon(t_2) - \varepsilon(t_1)]} & 0 & 0 \\ 0 & e^{-[\varepsilon(t_2) - \varepsilon(t_1)]} & 0 \\ 0 & 0 & e^{-[\varepsilon(t_2) - \varepsilon(t_1)]} \end{bmatrix}$
    - $B_{ij}(t_1, t_2) = \begin{bmatrix} e^{2[\varepsilon(t_2) - \varepsilon(t_2)]} & 0 & 0 \\ 0 & e^{-[\varepsilon(t_2) - \varepsilon(t_2)]} & 0 \\ 0 & 0 & e^{-[\varepsilon(t_2) - \varepsilon(t_2)]} \end{bmatrix}$

PTT model (PanThienTanner)

- Entanglement density & Entanglement Molecular Weight Me
- Damping function

Wagner model



Fit the Wagner model at several shear rates with $t = \infty$

$$\eta(t = \infty, \dot\gamma_0) = f_1 \sum_{i=1}^{n} \frac{\alpha_i}{\alpha_i^2} + f_2 \sum_{i=1}^{n} \frac{\alpha_i}{\beta_i^2}$$

$\eta(t, \dot\gamma_0)$ = shear viscosity
t = time
$\dot\gamma_0$ = shear rate
α_i = the ith elastic value of the Maxwell element
λ_i = the ith characteristic time of the Maxwell element
f_1, f_2, n_1, n_2 are fitting parameters

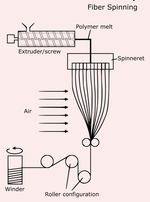
$$\alpha_i = \frac{1 + n_1\lambda_i\dot\gamma_0}{\lambda_i} \qquad \beta_i = \frac{1 + n_2\lambda_i\dot\gamma_0}{\lambda_i} \qquad f_2 = 1 - f_1$$

- with the fitted parameters, estimate:
  - Recovery compliance
  - Elongational viscosity
  - Stress growth
  - Creep compliance
  - First normal stress difference
    - at constant shear rate
    - at constant shear stress

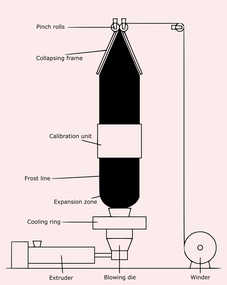
Polymer Processing

Extrusion

- Extrusion defects
  - Shrinkage (too much stress)
  - Surging (speed variations)
  - Lumpy surface (too cold)
  - Bubbles (moisture)
  - Pimples (resin gels)
  - Shark skin (overheating)
- Processing conditions
  - Polymer rheology
  - Cooling conditions
  - Die dimensions
  - Screw design
  - Relative draw speed to extrusion speed
- Fiber Spinning

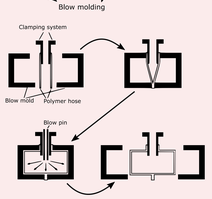


- Blown Film

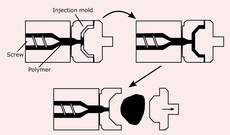


Injection

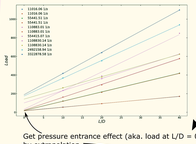
- Injection molding Defects
  - Warpage (unstructured design)
  - Jetting (high fill rate)
  - Splashes (clamp failure)
  - Charcoal-like edges (diesel effect)
  - Flash (high pressure)
  - Weld lines (uneven temperatures)
  - Ejector pin marks (early eject)
  - Sink marks (thick wall sections)
  - Short Shot (low pressure)
  - Silver-like surface (moisture)
- Processing conditions
  - Screw design
  - Injection Pressure
  - Mold layout
  - Clamping force
  - Shot size
- Blow molding



- Injection Molding



Bagley correction



- Get pressure entrance effect (aka. load at L/D = 0) by extrapolation

$$corrected\ Load = apparent\ Load - Load_{at\ L/D\ =\ 0}$$

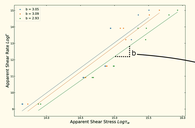
$$corrected\ Shear\ Stress = \tau_w = \frac{corrected\ Load}{2\pi \frac{Diameter_{capillary}}{2} Length_{die}}$$

$$viscosity\ \eta = \frac{\tau_w}{\dot\gamma}$$

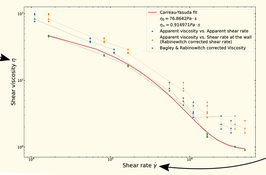
- Force applied
- applied pressure
- apparent shear stress
- corrected shear stress

Rabinowitch correction

- Capillary
- deformation/flow
- apparent shear rate
- corrected shear rate



$$Flow\ rate\ Q = Velocity\ \pi \frac{Diameter_{barrel}}{2}^2$$

$$apparent\ Shear\ Rate\ \Gamma = \frac{4Q}{\pi Radius_{capillary}^3}$$

$$corrected\ Shear\ Rate\ \dot\gamma = \frac{3 + b}{4}\Gamma$$