

Behavior of Solids

Summer 2020

Effect of Molecular Weight on Shear Modulus

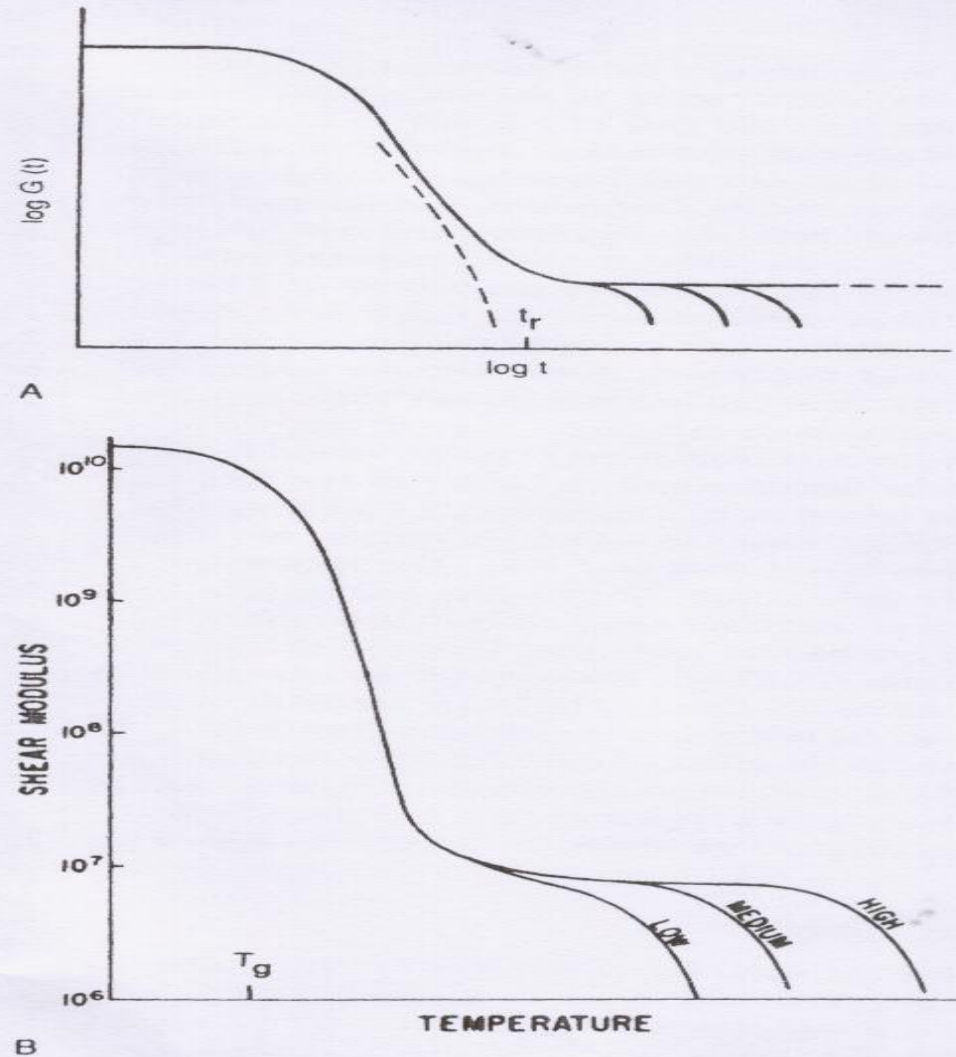
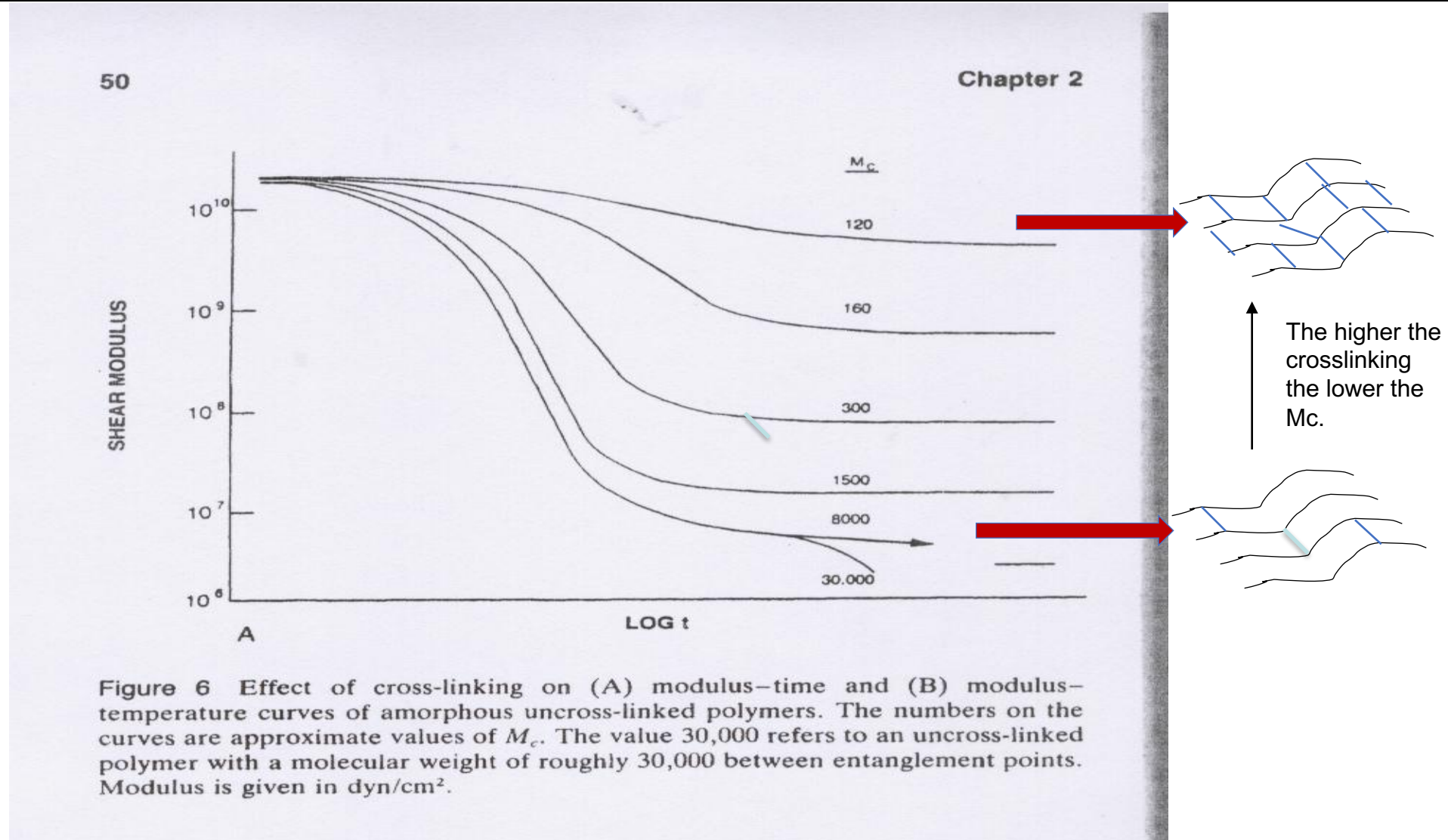


Figure 5 (A) Relaxation modulus at a fixed temperature of a polymer sample: (1) of very low molecular weight (dashed line on left), (2) of moderate to high molecular weight (solid lines), and (3) when cross-linked (dashed line on right). (B) Effect of molecular weight on the modulus-temperature curve of amorphous polymers. Modulus is given in dyn/cm². The characteristic or reference time is t_r ; the reference temperature, T_g .

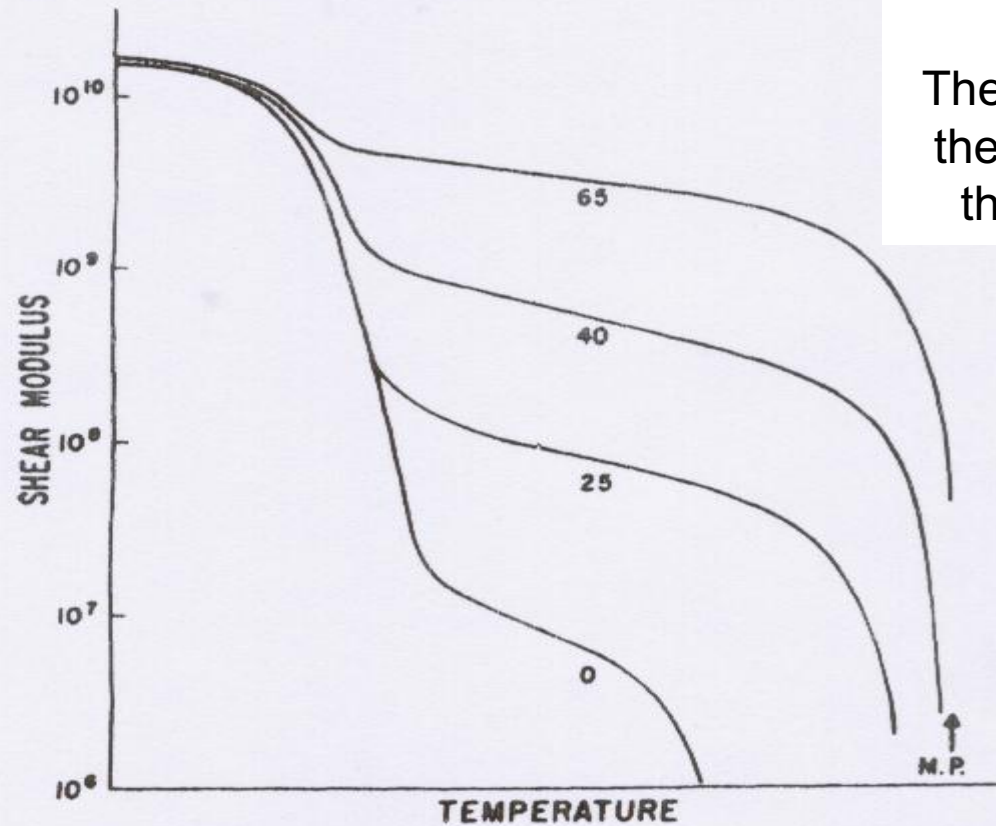
Effect of molecular weight between Crosslinks (M_c) on shear modulus



You can assume that this is what happens when a rubber is vulcanized, the more crosslinking material you add the shorter the distance between crosslinks

Effect of the degree of crystallinity on the shear modulus of a solid

52

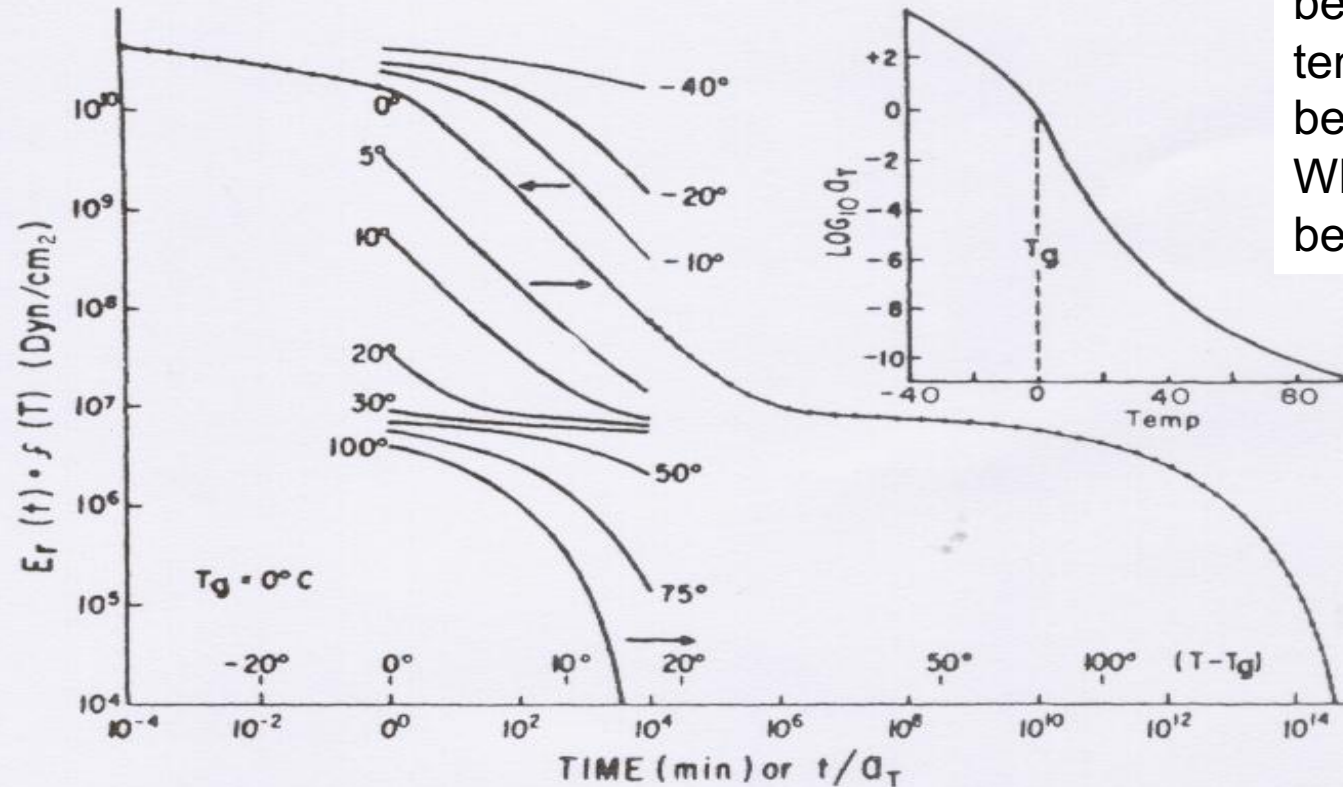


The higher the crystals content, the more difficult is to shear the material.

The size and shape of the crystals influence the shear modulus

Figure 7 Effect of crystallinity on the modulus-temperature curve. The numbers on the curves are rough approximations of the percent of crystallinity. Modulus is given in dyn/cm².

Effect of temperature on the stress relaxation of a solid and its use to create a master curve



Remember that because the temperatures are below $T_g + 100$, then the WLF equation should be used

Figure 8 WLF time-temperature superposition applied to stress-relaxation data obtained at several temperatures to obtain a master curve. The master curve, made by shifting the data along the horizontal axis by amounts shown in the insert for a_T , is shown with circles on a line.

Behavior when a constant load is applied to a solid (creep)

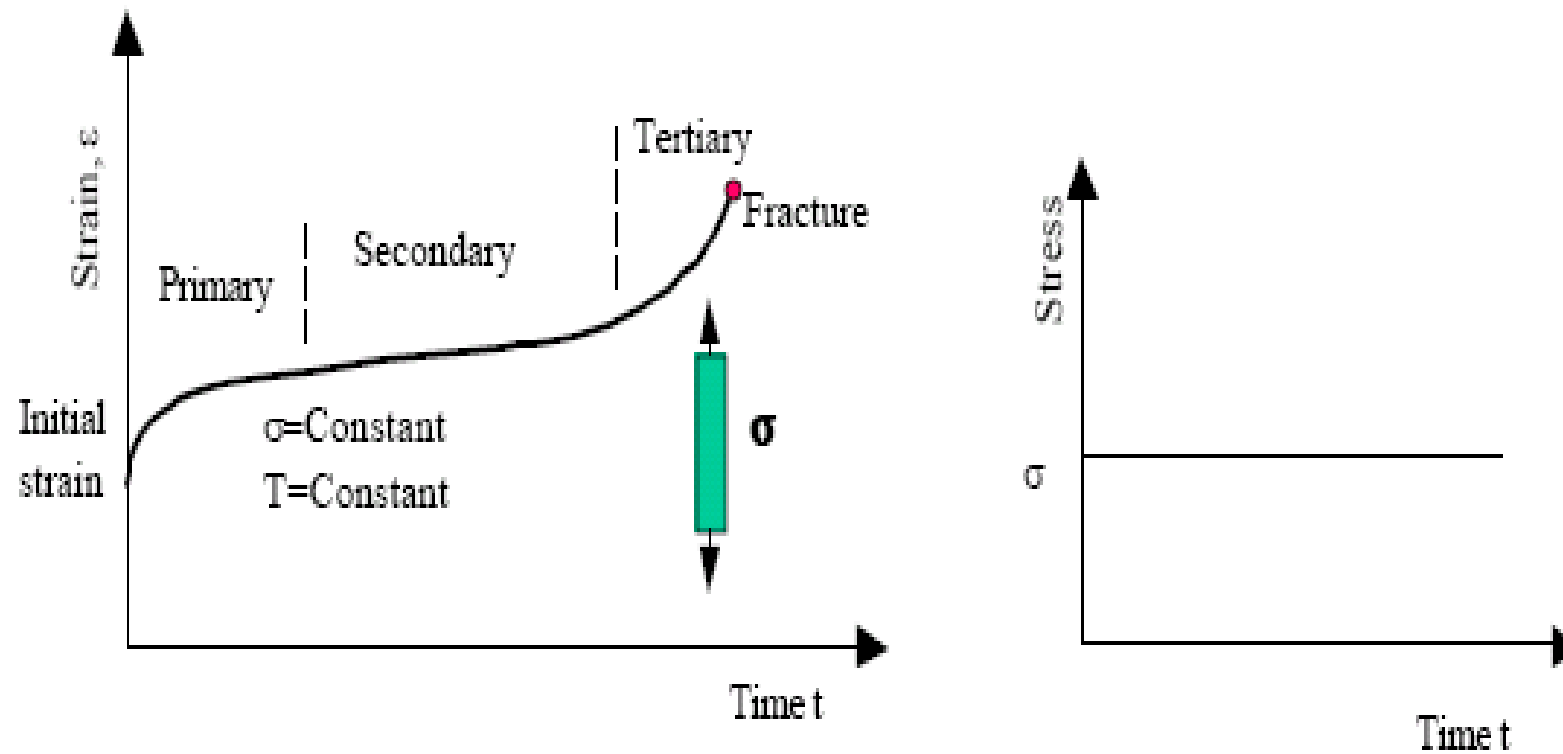
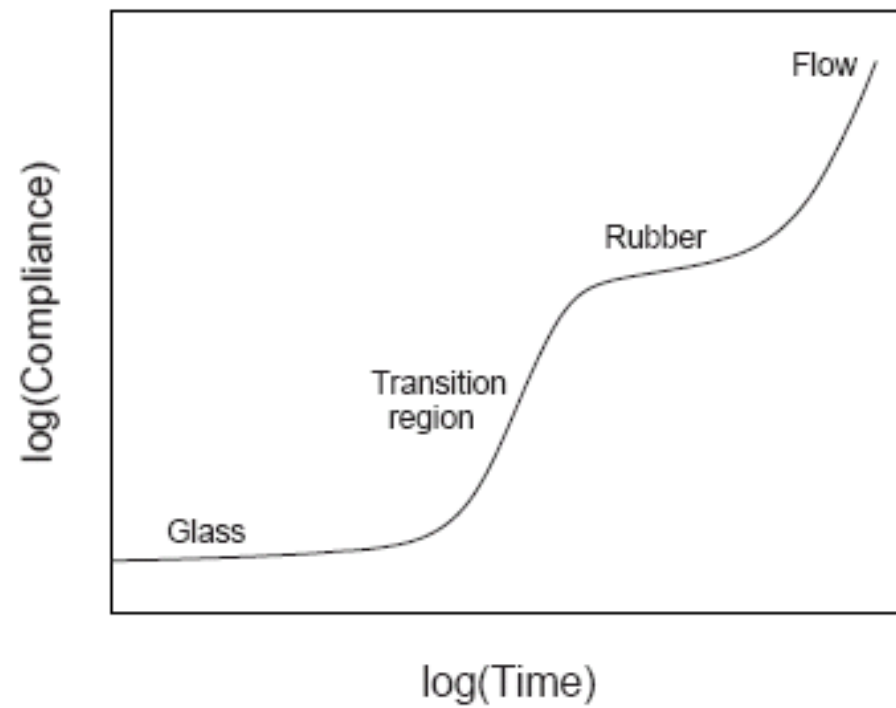


Figure 2. Creep curve for plastics, a constant load is applied [1]

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Schematic representation of the linear creep compliance versus time for a polymer glass at a fixed temperature.

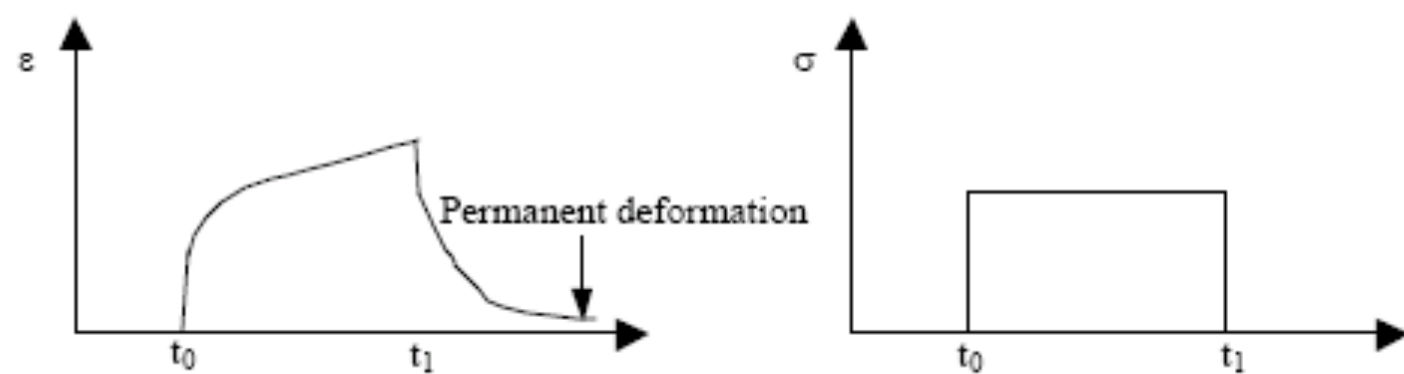
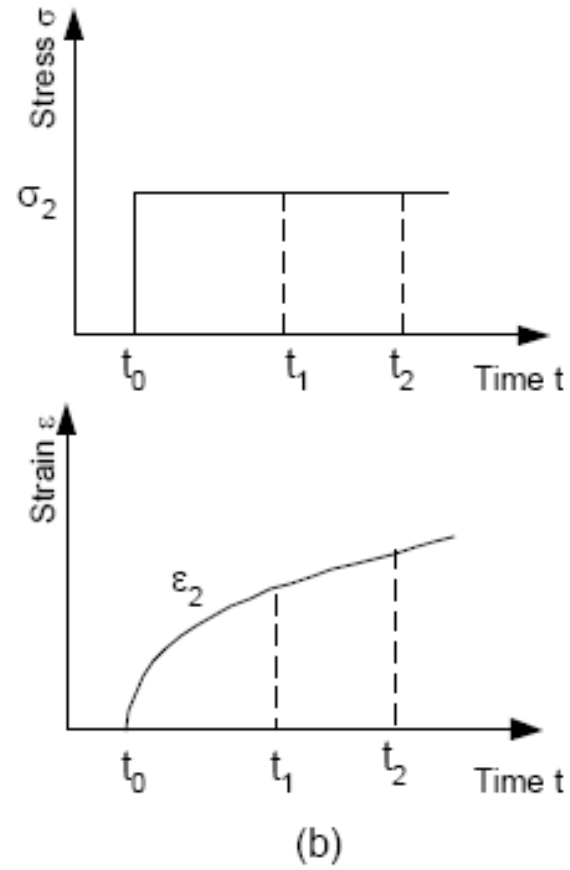
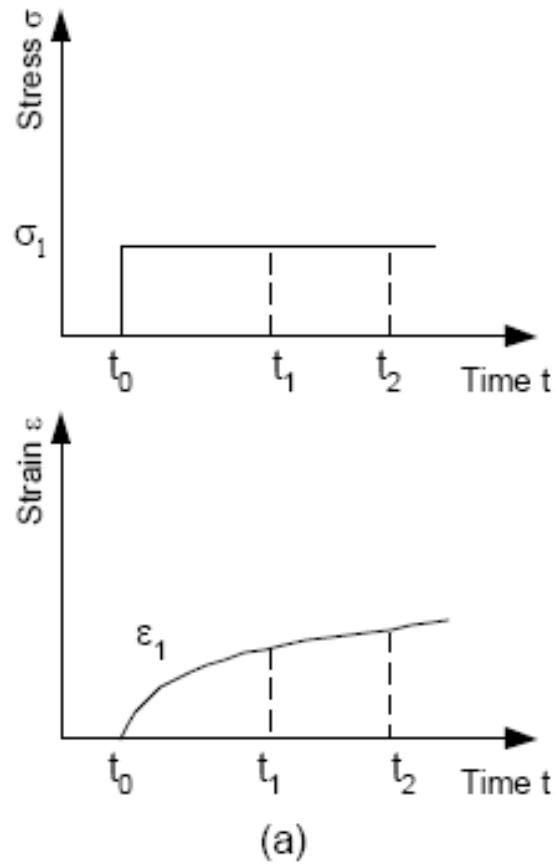


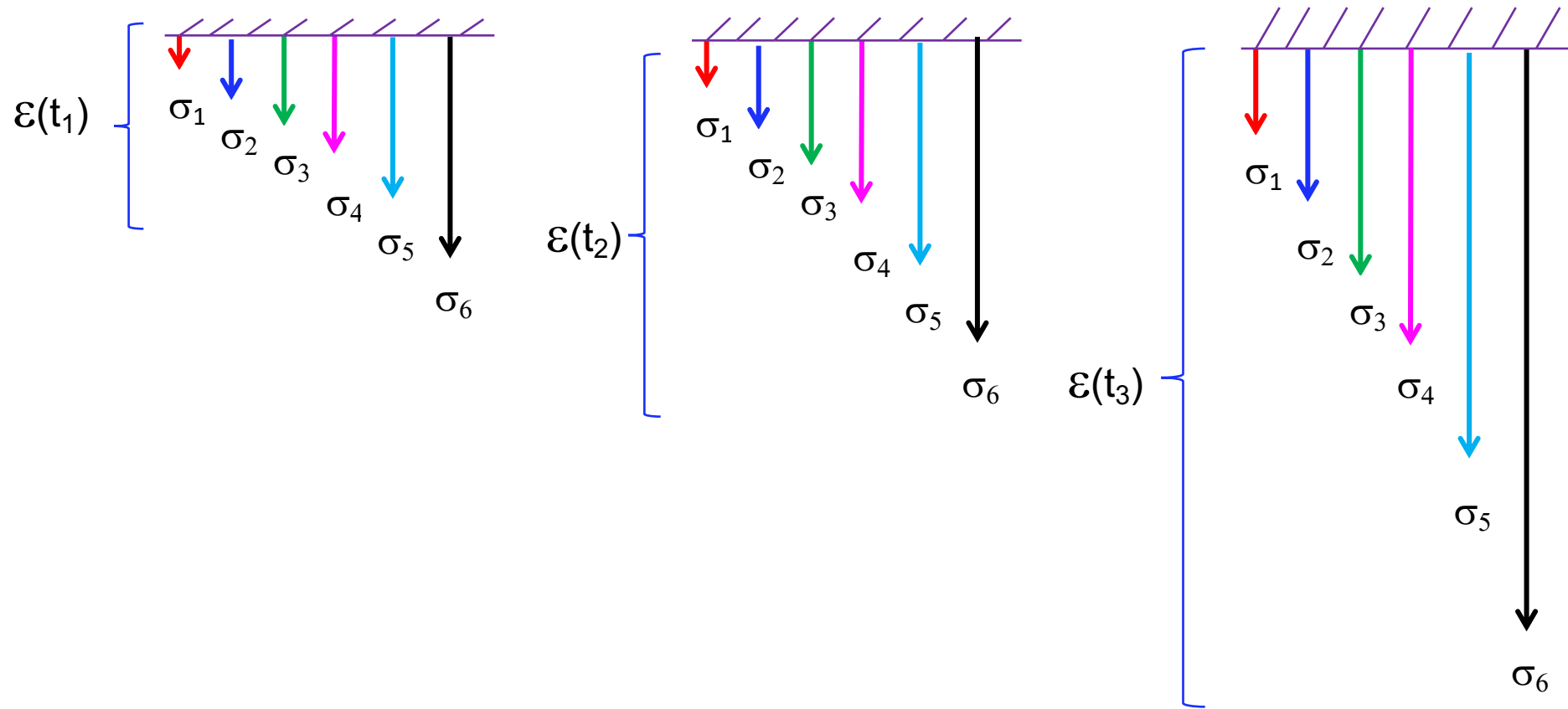
Figure 3. Creep curve with recovery. A constant load is applied at t_0 and removed at t_1

Applied stress and resulting strain

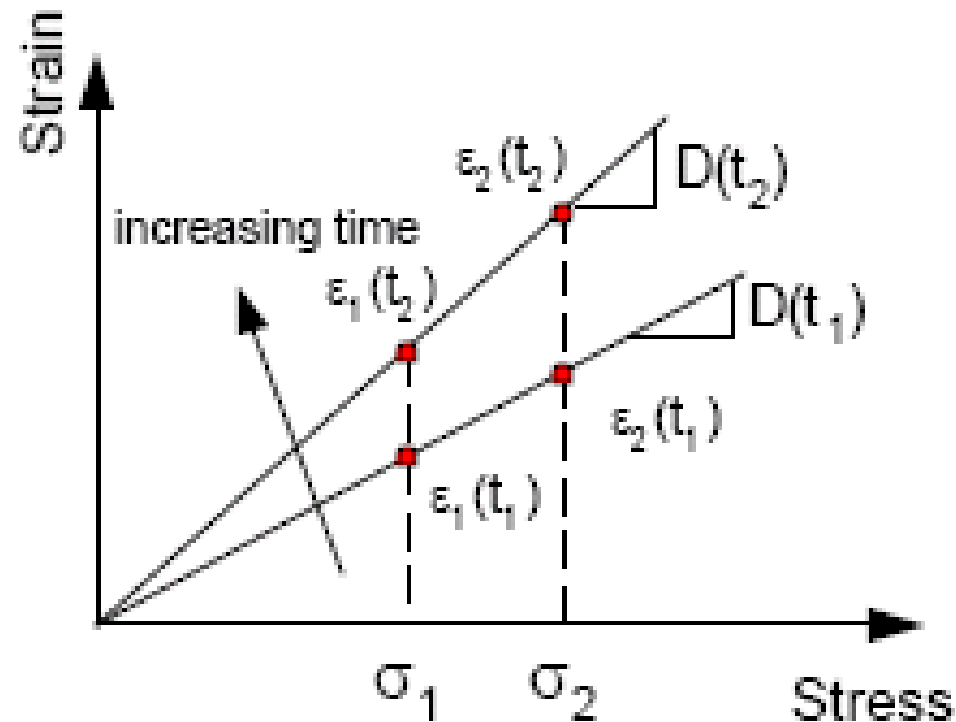


$$\underbrace{\frac{\text{Strain}}{\text{Stress}}}_{\text{Compliance}} = \mathbf{D}$$

Creating Isochrones



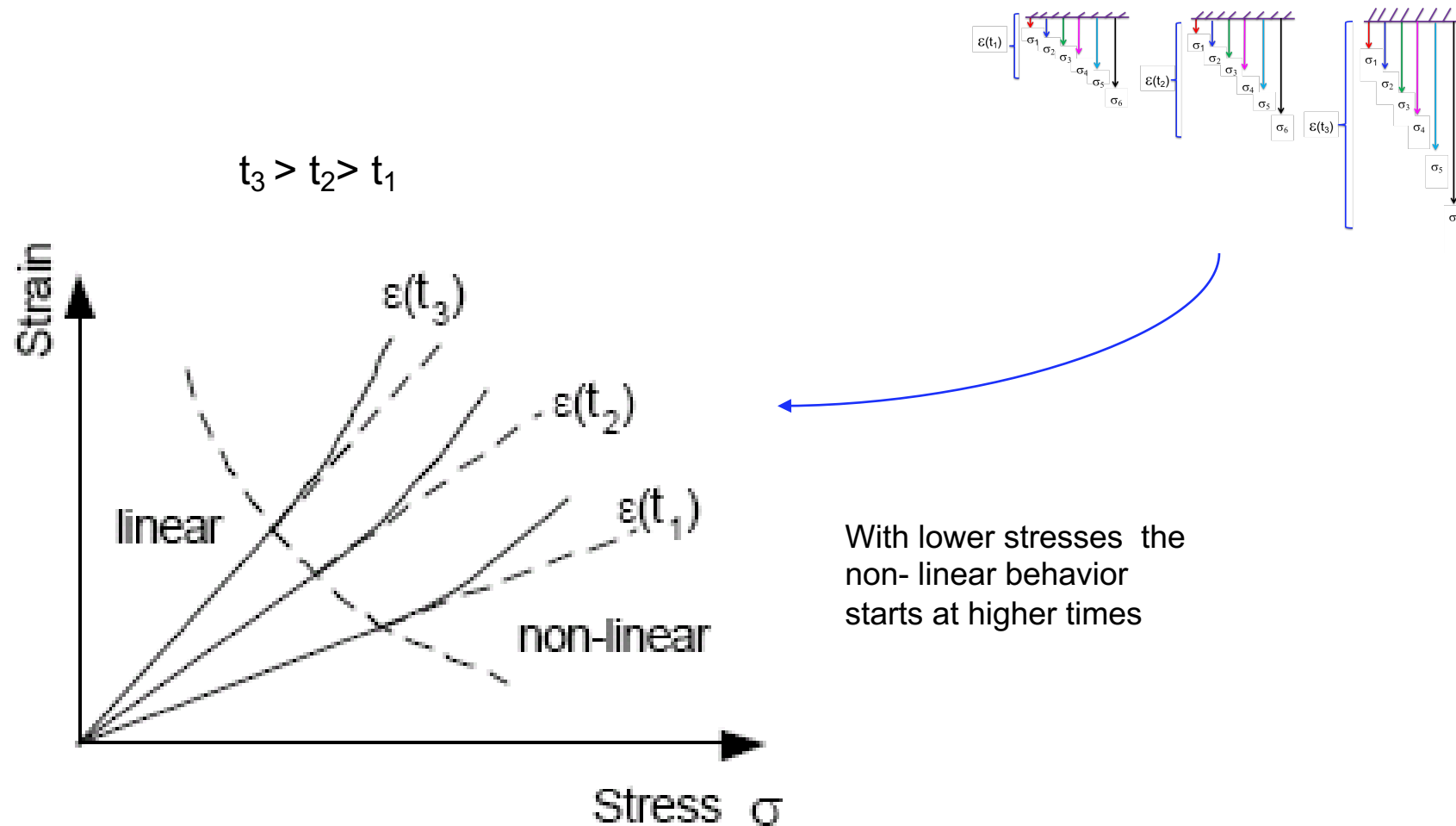
Building isochrones using information obtained from constant stress-strain curves (*see previous slide*)



$$\frac{\epsilon_1(t)}{\sigma_1(t)} = \frac{\epsilon_2(t)}{\sigma_2(t)}$$

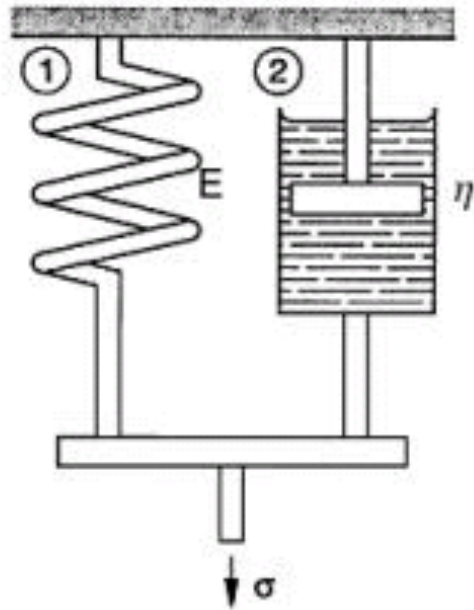
$$D(t) = \epsilon(t) / \sigma$$

Isochrones and onset of the non-linear behavior



Linear-nonlinear transition of stress strain relationship
with respect to different time levels [7]

Modeling the compliance with the Kelvin Model



Schematic diagram of Kelvin model [16]

$$\sigma = E\varepsilon + \eta\dot{\varepsilon},$$

$$\varepsilon(t) = \frac{\sigma_0}{E}(1 - e^{-t/\tau})$$

$$\tau = \eta / E$$

Tau has units of time and is called the retardation time.

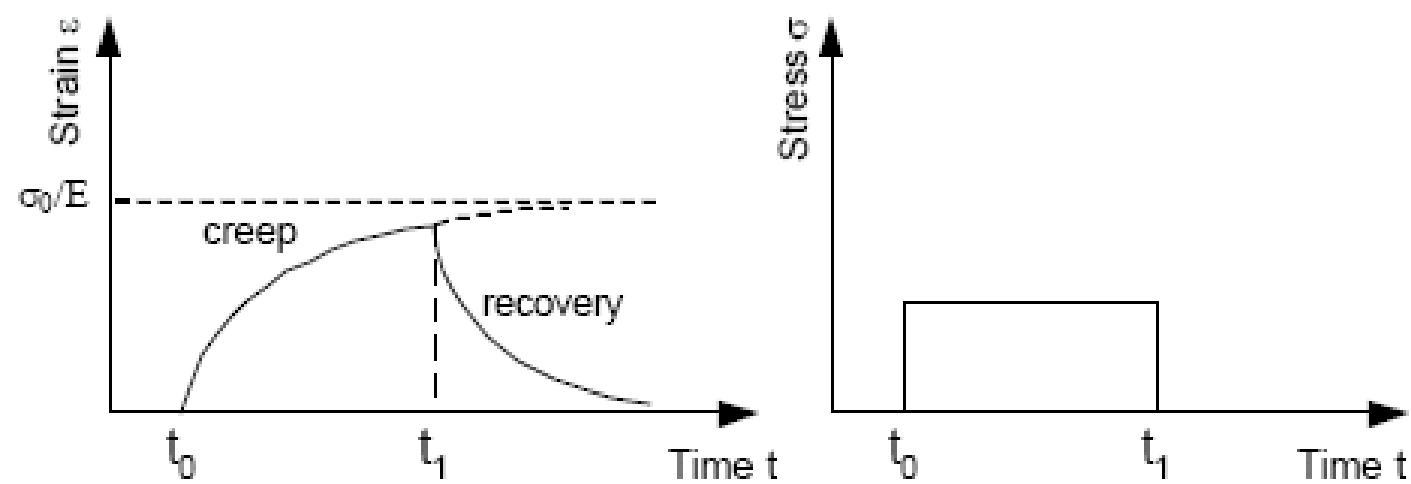


Figure 7. Creep and creep recovery response of Kelvin model

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Stress superposition principle

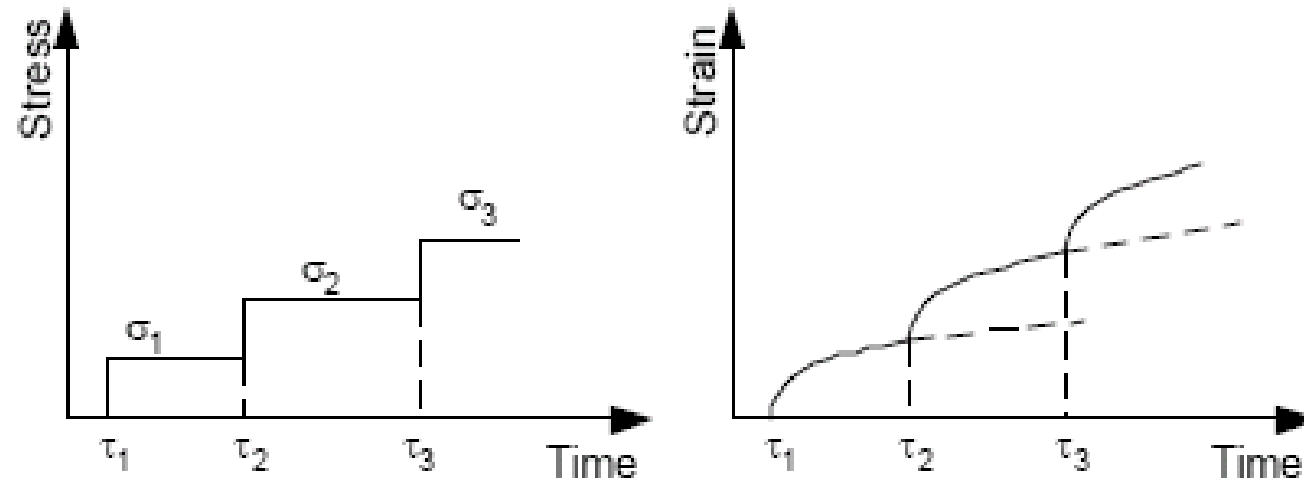


Figure 9. Boltzmann superposition principle

$$\varepsilon(t) = D(t - \tau_1)\sigma_1 + D(t - \tau_2)(\sigma_2 - \sigma_1) + \cdots + D(t - \tau_i)(\sigma_i - \sigma_{i-1})$$

$$\varepsilon(t) = \int_{-\infty}^t D(t - \tau) d\sigma(\tau)$$

Design criteria

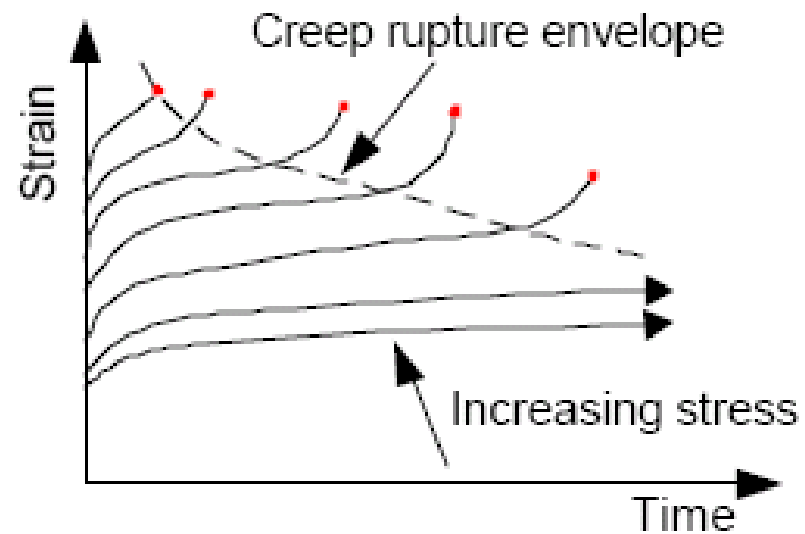


Figure 4. Creep rupture envelope [1]

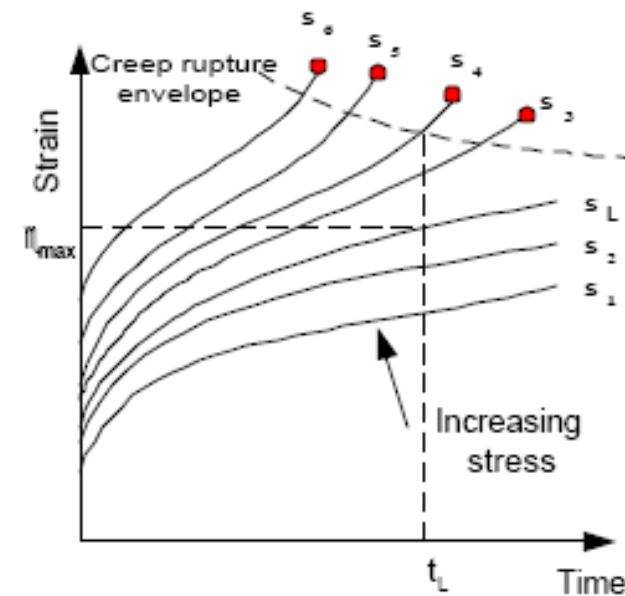


Figure 5. Design criteria by creep curves

Stress Relaxation Modulus for Solid PIB

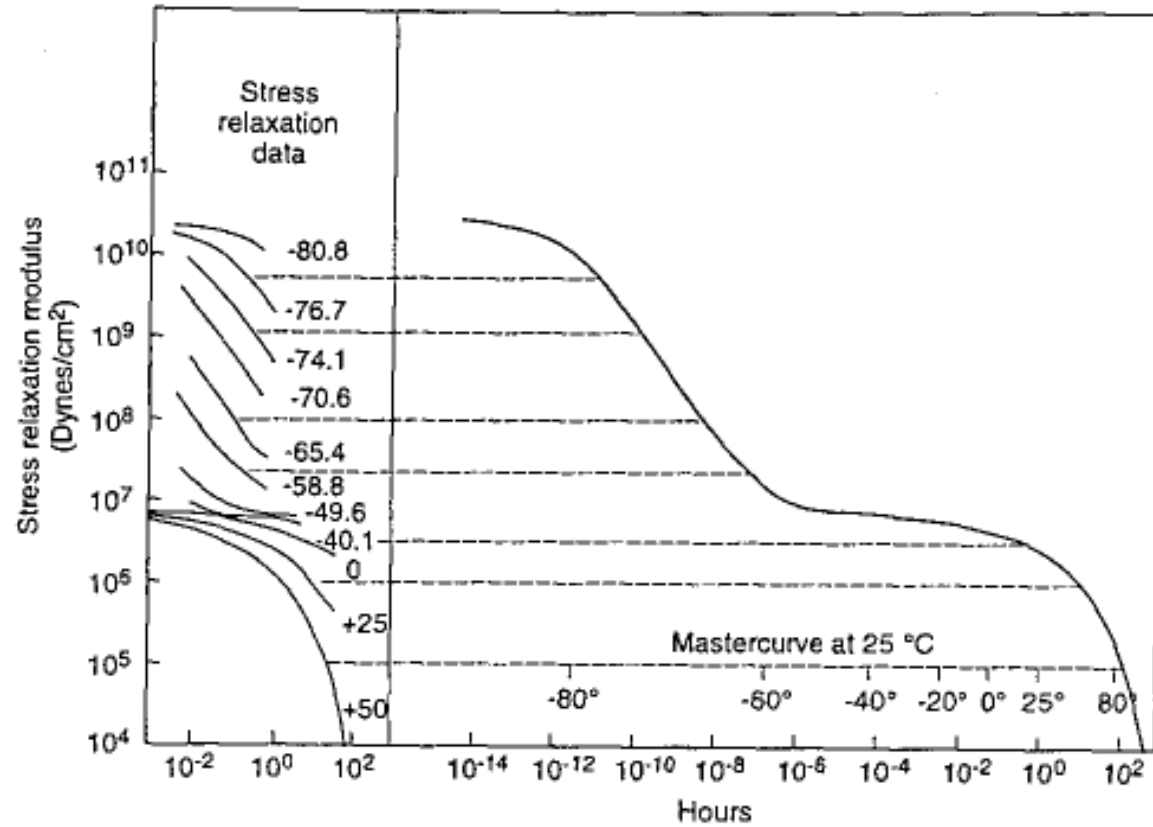


Figure 10. Relaxation modulus curves for polyisobutylene and corresponding master curve at 25 °C [24]

The effect of the average molecular weight on the master curve

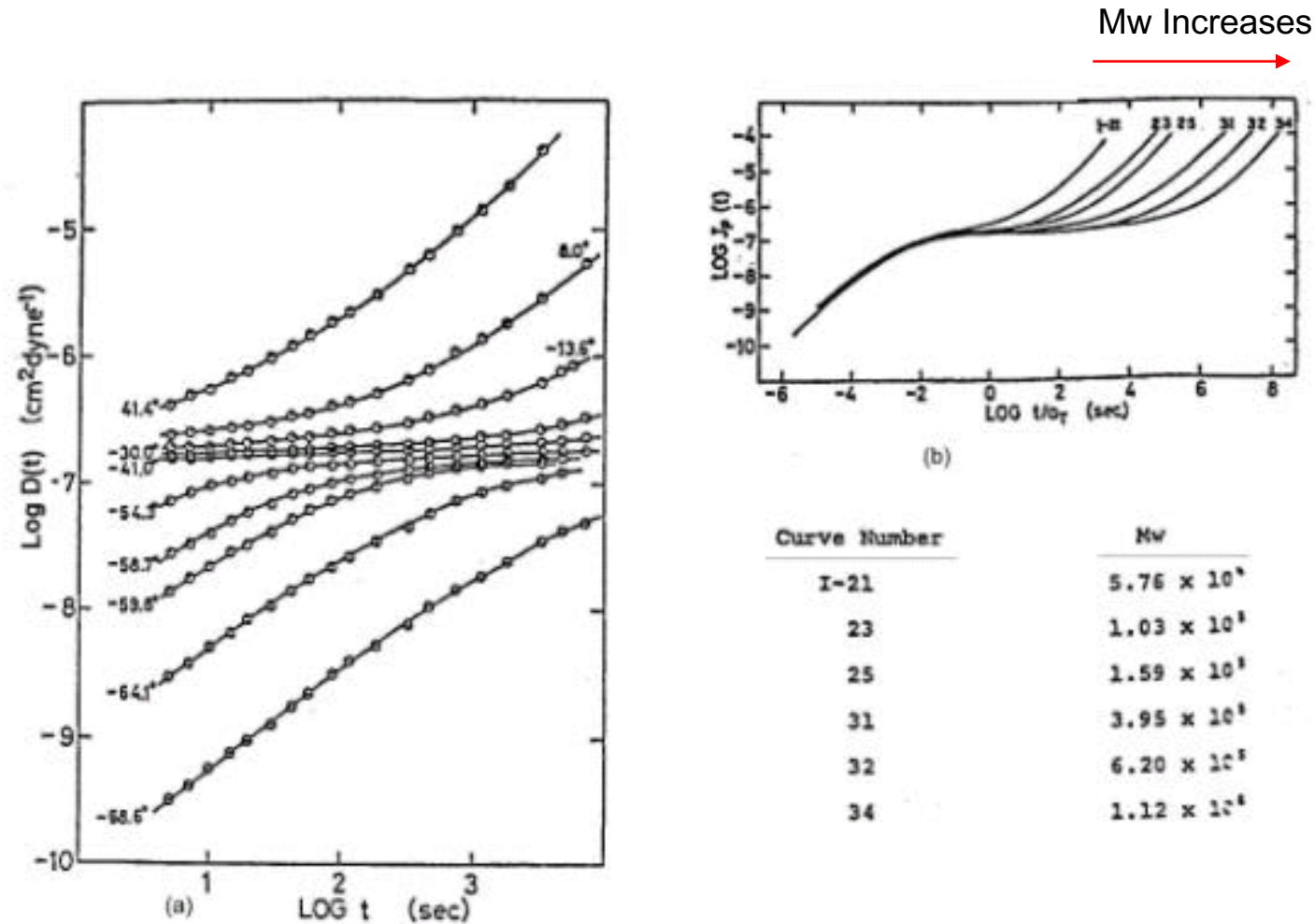
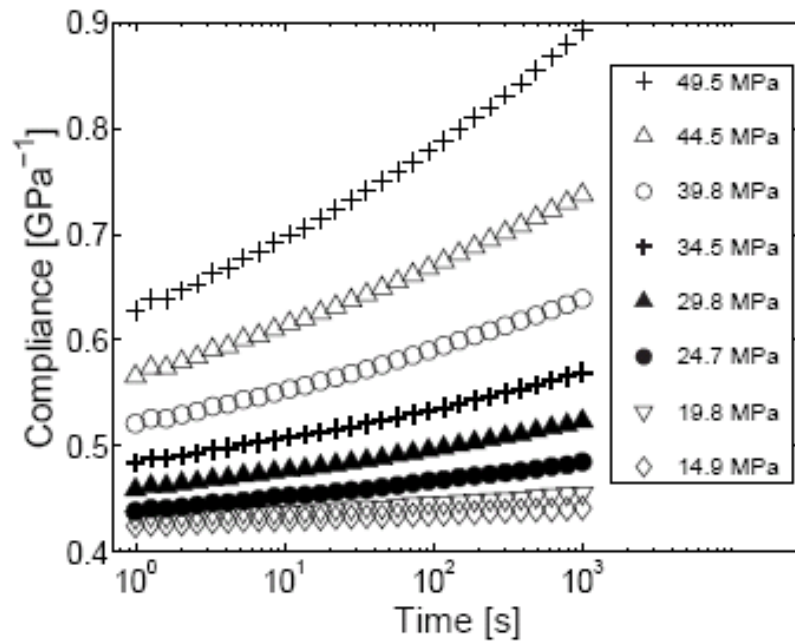
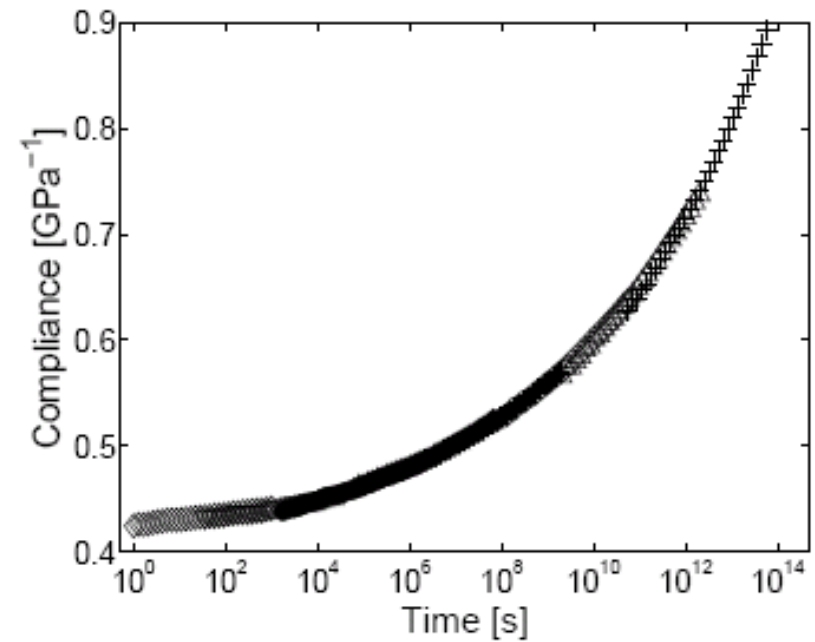


Figure 11. (a) Creep compliance of polyisoprene at different temperatures. Data for molecular weight 1.12×10^6 ; (b) Master curves for creep compliance of Polyisoprene with different molecular weight at reference temperature of -30°C [26]



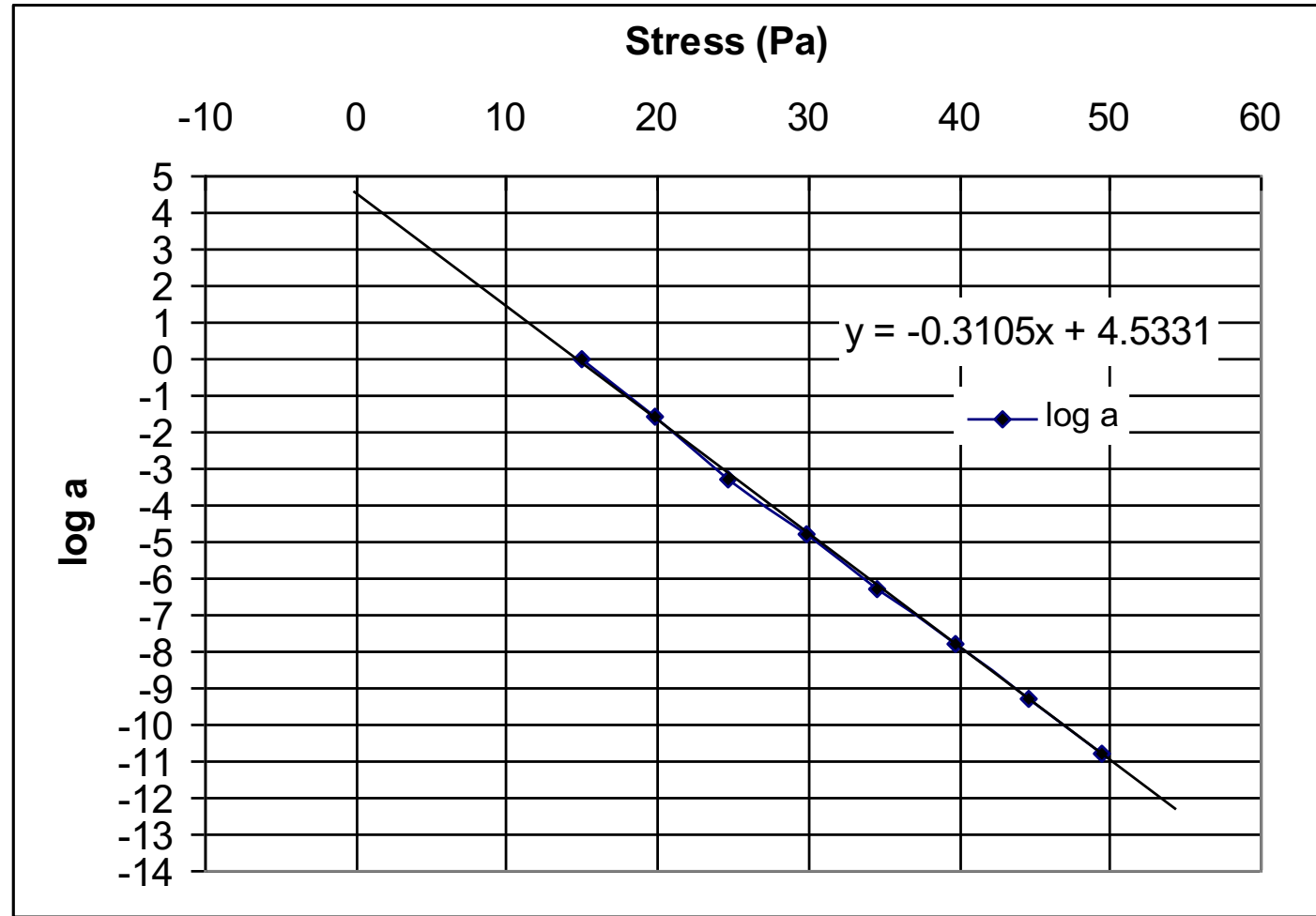
(a)
Creep compliance of polycarbonate at 22°C and at several loads

σ [MPa]	$\log(a_{15})$
14.9	0.00
19.8	-1.55
24.7	-3.25
29.8	-4.80
34.5	-6.25
39.8	-7.80
44.5	-9.30
49.5	-10.75



(b)
Creep compliance master curve at a reference stress of 14.9 Mpa (does not consider aging)

Shift factor for the stress-time superposition



Stress-strain-time

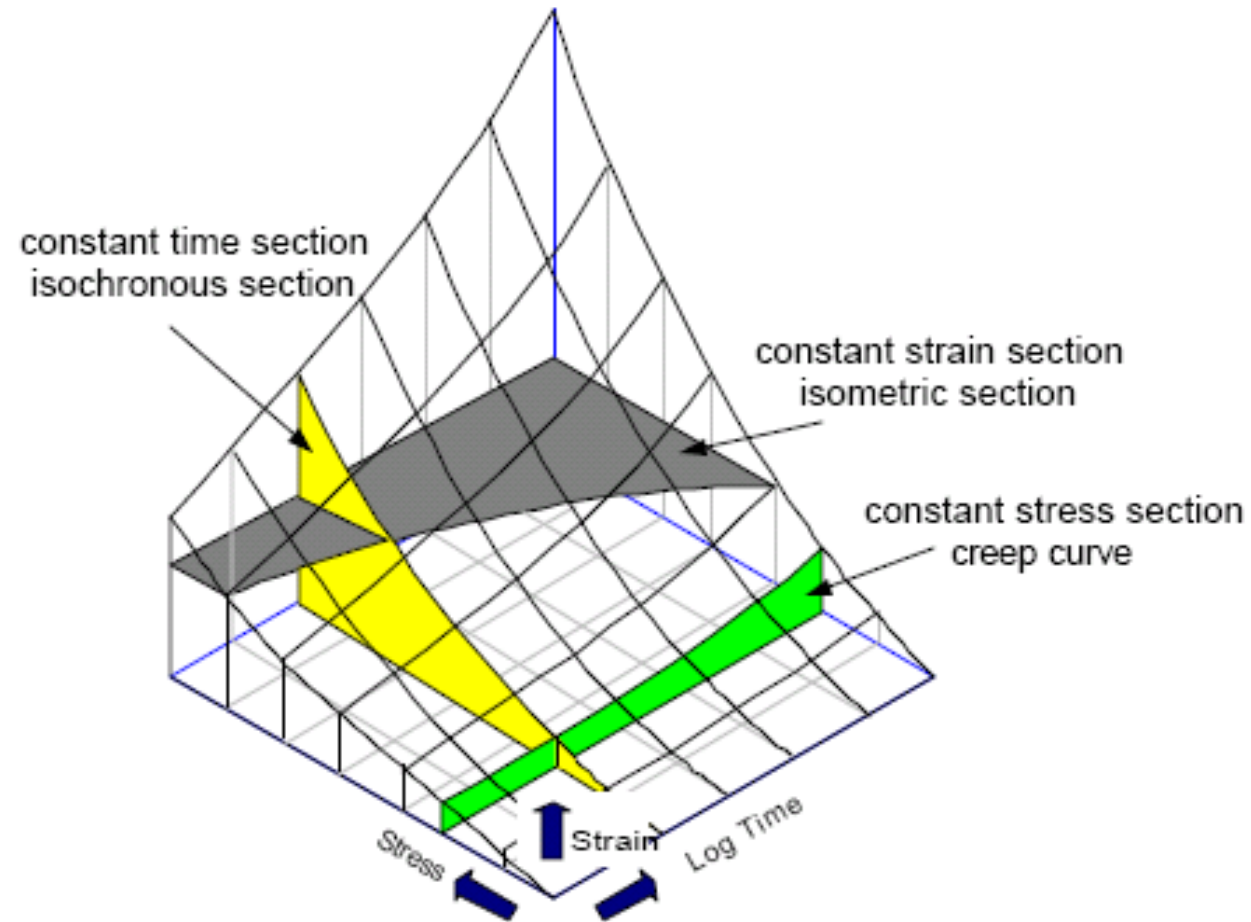
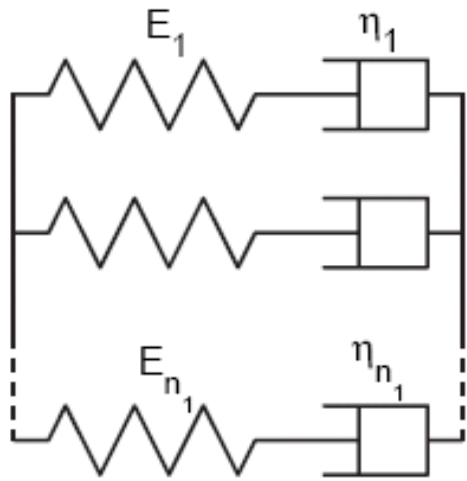


Figure 1. Constant stress-strain-time coordinates [1]

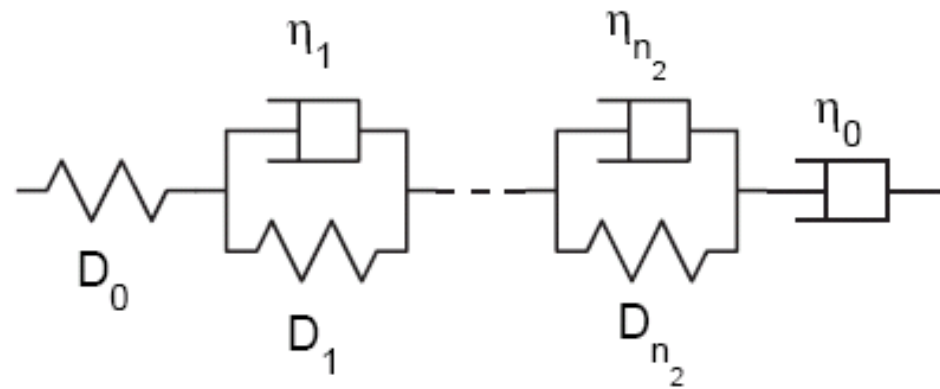
Modeling the creep compliance with more than one Kelvin-Voigt Model

$$E(t) = \sum_{i=1}^{n_1} E_i \exp\left(-\frac{t}{\tau_i}\right)$$

$$D(t) = D_0 + \sum_{i=1}^{n_2} D_i \left[1 - \exp\left(-\frac{t}{\tau_i}\right)\right] + \frac{t}{\eta_0}$$



(a)



(b)

Schematic representation of the generalized linear Maxwell model (a) and the generalized Kelvin-Voigt model (b).

Comparing relaxation modulus vs. Compliance modulus models

Relaxation modulus

$$E(t) = E_0 \exp\left(-\frac{t}{\tau(\sigma)}\right)$$

$$\tau(\sigma) = \tau_0 a_\sigma(\sigma)$$

$$\tau_0 = \eta_0 / E_0$$

For “ n_1 ” elements

$$E(t) = \sum_{i=1}^{n_1} E_i \exp\left(-\frac{t}{\tau_i(\sigma)}\right)$$

Compliance modulus

$$D(t) = D_0 + \frac{t}{\eta(\sigma)}$$

$$D_0 = 1/E_0$$

For “ n_2 ” elements

$$D(t) = D_0 + \sum_{i=1}^{n_2} D_i \left[1 - \exp\left(-\frac{t}{\tau_i(\sigma)}\right)\right] + \frac{t}{\eta_0(\sigma)}$$

Pseudo-Elastic Design Method

Supuestos:

- i) La deformaciones son pequeñas
- ii) El modulo es constante
- iii) La deformación es independiente de la rapidez con que se aplique el stress o la historia de los esfuerzos aplicados y la recuperación es inmediata
- iv) El material es isotrópico
- v) El material se comporta de la misma manera en tensión que en compresión.