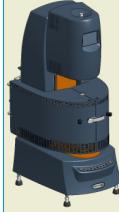




TA Instruments – Waters LLC



**Materials Characterization by  
Rheological Methods**



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TA Instruments – US West  
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1

## Rheology: An Introduction

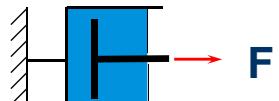


Rheology: The study of the flow and deformation of matter.  
Rheological behavior affects every aspect of our lives.

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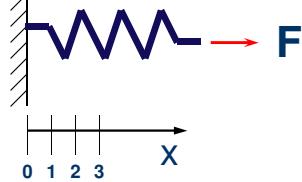
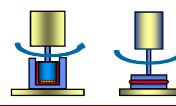
2

## Rheology: The study of the flow and deformation of matter



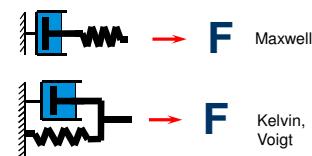
Flow: Fluid Behavior; Viscous Nature

$$F = F(v); F \neq F(x)$$



Deformation: Solid Behavior  
Elastic Nature

$$F = F(x); F \neq F(v)$$



Viscoelastic Materials: Force depends on both Deformation and Rate of Deformation and vice versa.

Maxwell

Kelvin, Voigt

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## Basic Material Behaviors

Water

Oil

Soap

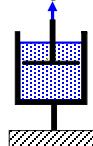
Egg white

Polymer Melt

Ceramic ?

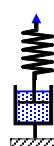
Metal

Flow



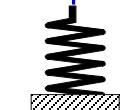
Viscous Liquids

Flow & Deformation



Viscoelastic

Deformation



Elastic Solids

$$\text{Viscosity} = \frac{\text{Stress}}{\text{Strain Rate}}$$

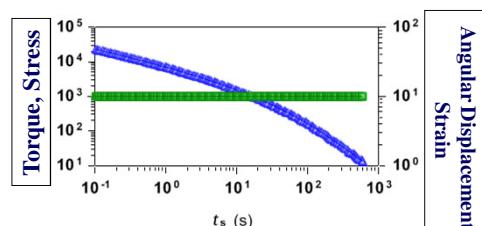
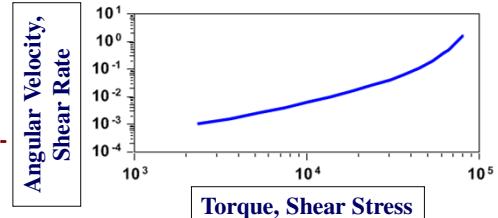
$$\text{Modulus} = \frac{\text{Stress}}{\text{Strain}}$$

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## Rheological Testing - Rotational

- **2 Basic Rheological Methods**
- 1. Apply Force (Torque) and measure Deformation and/or Deformation Rate (Angular Displacement, Angular Velocity) - Controlled Force, Controlled Stress
- 2. Control Deformation and/or Deformation Rate and measure Force needed (Controlled Displacement or Rotation, Controlled Strain or Shear Rate)

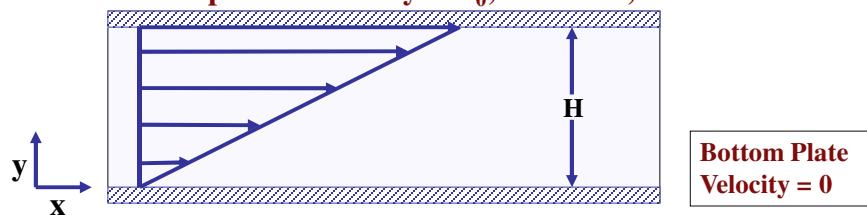


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## Steady Simple Shear Flow

Top Plate Velocity =  $V_0$ ; Area =  $A$ ; Force =  $F$



$$v_x = (y/H)*V_0$$

$$\dot{\gamma} = dv_x/dy = V_0/H \quad \text{Shear Rate, sec}^{-1}$$

$$\sigma = F/A \quad \text{Shear Stress, Pascals}$$

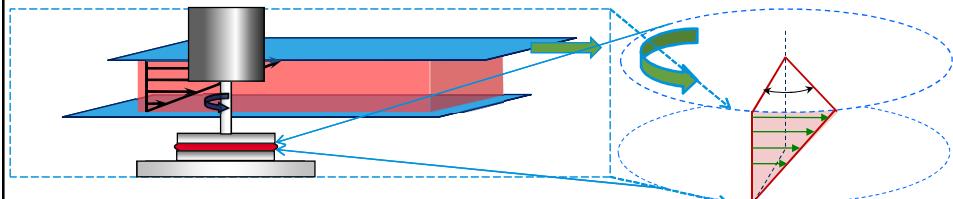
$$\eta = \sigma/\dot{\gamma} \quad \text{Viscosity, Pa-sec}$$

➤ These are the fundamental flow parameters. Shear rate is always a change in velocity with respect to distance.

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## Parallel Plate Shear Flow



<b>Stress</b>	$\sigma$	Force or torque
<b>Strain</b>	$\gamma$	Linear or angular displacement
<b>Strain Rate</b>	$\dot{\gamma}$	Linear or angular velocity

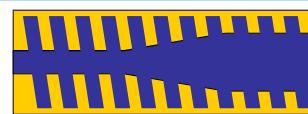
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## SHEAR RATE CALCULATIONS IN EXTRUSION

**Extruder:**  $\dot{\gamma} = \pi DN/(60 \cdot h)$

D = Diameter; N = rpm; h = gap



**Circular, Rod:**  $\dot{\gamma} = 32Q/(\pi D^3)$   
compounding, cable



Q = Output rate;  
D = orifice diameter

**Rectangular, Slit:**  $\dot{\gamma} = 6Q/(wh^2)$   
cast film, sheet



Q = Output rate;  
w = width  
h = gap

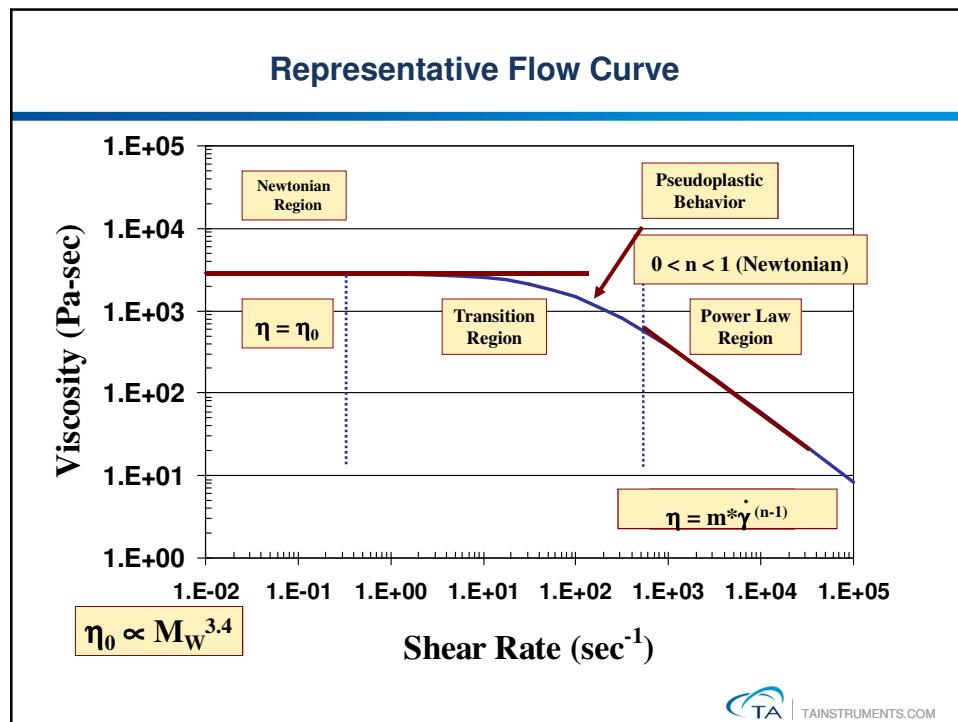
**Annulus:**  $\dot{\gamma} = 12Q/(\pi(D_1+D_2)h^2)$   
blown film, blow molding



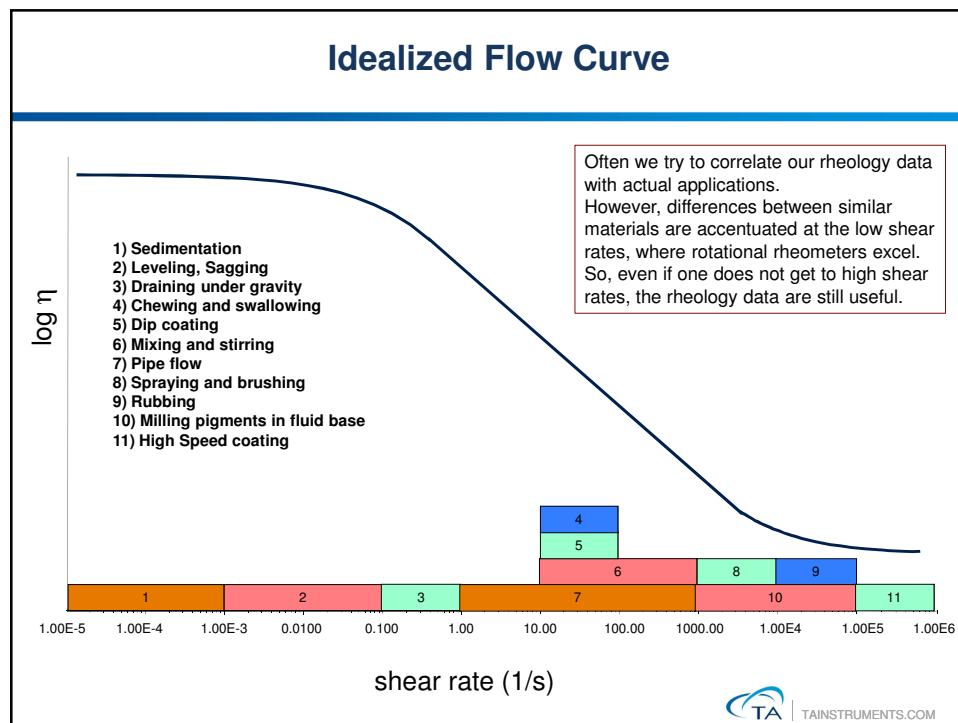
Q = Output rate;  
D1 = Inner diameter  
D2 = Outer diameter  
h = gap

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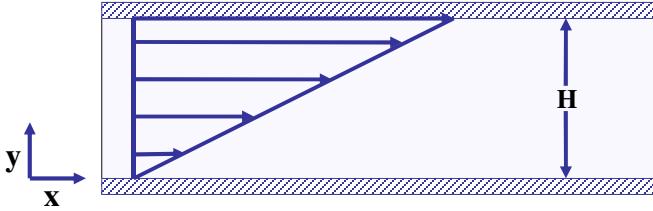
9



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## Simple Shear Deformation

**Top Plate Displacement =  $X_0$ ; Area = A; Force = F**



**Bottom Plate Displacement = 0**

$$x = (y/H) * X_0$$

$$\gamma = dx_x/dy = X_0/H \quad \text{Shear Strain, unitless}$$

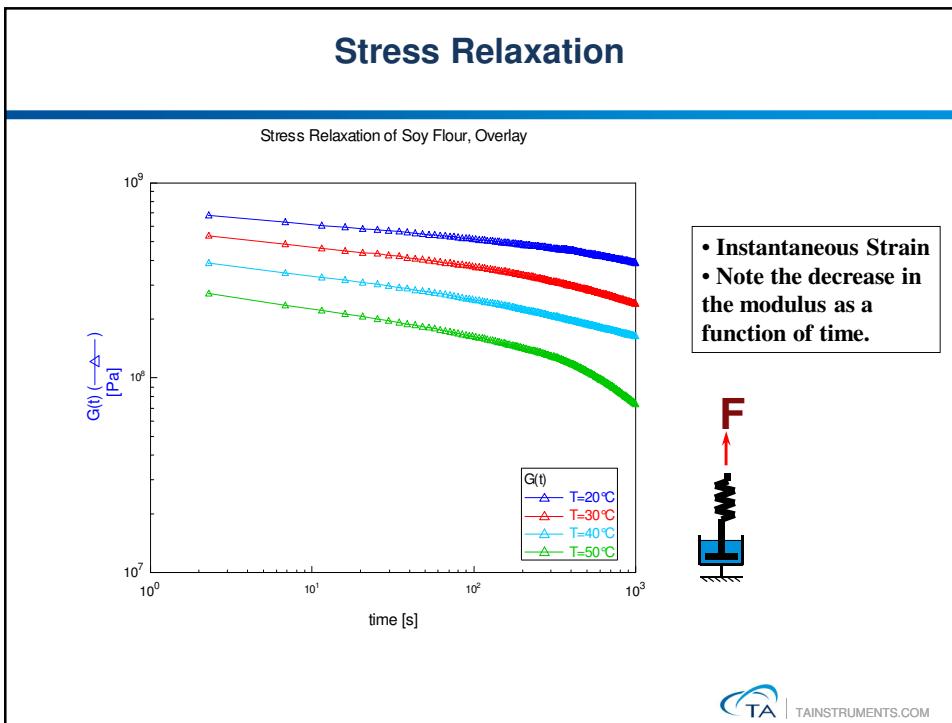
$$\sigma = F/A \quad \text{Shear Stress, Pascals}$$

$$G = \sigma/\gamma \quad \text{Modulus, Pa}$$

► These are the fundamental deformation parameters. Shear strain is always a change in displacement with respect to distance.

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Rheological Parameters			
FLUIDS TESTING			
Parameter	Shear	Elongation	Units
Rate	$\dot{\gamma}$	$\dot{\epsilon}$	Seconds <sup>-1</sup>
Stress	$\sigma$	$\tau$	Pascals
Viscosity	$\eta = \sigma/\dot{\gamma}$	$\eta_E = \tau/\dot{\epsilon}$	Pascal-seconds
SOLIDS TESTING			
Parameter	Shear	Elongation	Units
Strain	$\gamma$	$\epsilon$	Unitless
Stress	$\sigma$	$\tau$	Pascals
Modulus	$G(t) = \sigma/\gamma$	$E = \tau/\epsilon$	Pascals

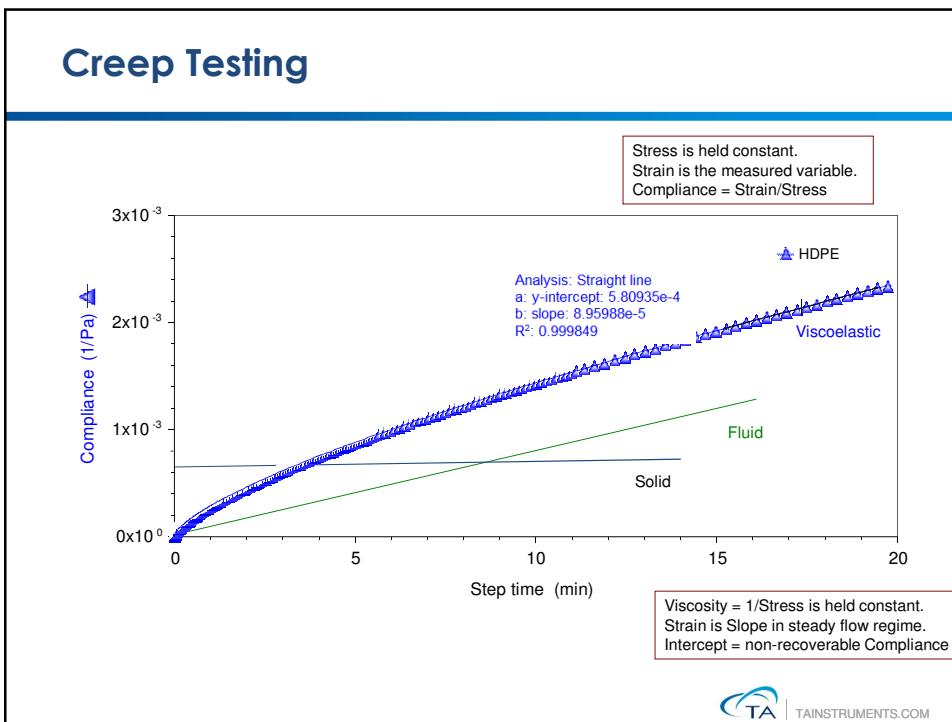
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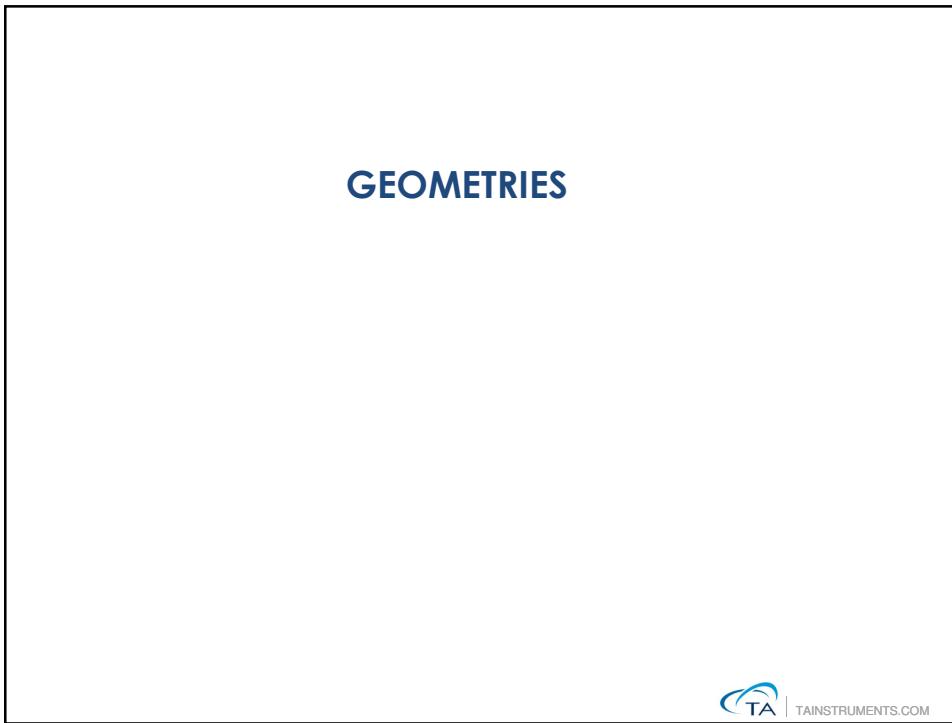
Rheological Parameters			
CREEP TESTING			
Parameter	Shear	Elongation	Units
Stress	$\sigma$	$\tau$	Pascals
Strain	$\gamma$	$\epsilon$	Unitless
Compliance	$J = \gamma/\sigma$	$D = \epsilon/\tau$	1/Pascals

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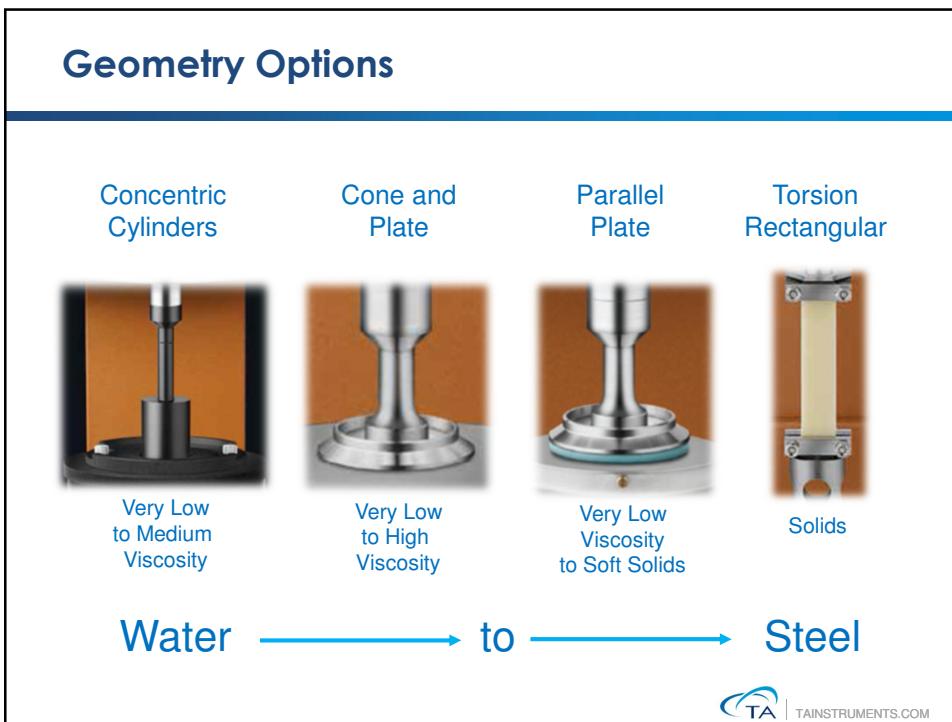
14



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### Converting Machine to Rheological Parameters in Rotational Rheometry

$$\frac{M \times K_\sigma}{\Omega \times K_\gamma} = \frac{\sigma}{\dot{\gamma}} = \eta$$

$$\frac{M \times K_\sigma}{\theta \times K_\gamma} = \frac{\sigma}{\gamma} = G$$

**Machine Parameters**

M: Torque

$\Omega$  : Angular Velocity

$\theta$ : Angular Displacement

---

**Conversion Factors**

$K_\sigma$ : Stress Conversion Factor

$K_\gamma$ : Strain (Rate) Conversion Factor

---

**Rheological Parameters**

$\sigma$ : Shear Stress (Pa)

$\dot{\gamma}$ : Shear Rate (sec<sup>-1</sup>)

$\eta$ : Viscosity (Pa·sec)

$\gamma$ : Shear Strain

G: Shear Modulus (Pa)

The conversion factors,  $K_\sigma$  and  $K_\gamma$ , will depend on the following:

Geometry of the system – concentric cylinder, cone and plate,  
parallel plate, and torsion rectangular

Dimensions – gap, cone angle, diameter, thickness, etc.

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## Shear Rate and Shear Stress Calculations

Conversion Factor	Geometry		
	Couette	Cone & Plate	Parallel Plates
$K_\gamma$	$R_{avg}/(R_o - R_i)$	$1/\beta$	$R/h$
$K_\sigma$	$1/(2\pi R_i^2 L)$	$3/(2\pi R^3)$	$2/(\pi R^3)$



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## Choosing a Geometry Size



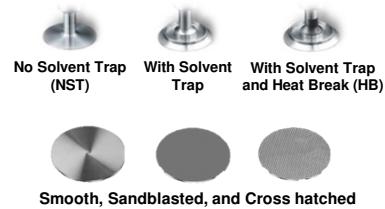
- Assess the 'viscosity' of your sample
- When a variety of cones and plates are available, select diameter appropriate for viscosity of sample
  - Low viscosity (milk) - 60mm geometry
  - Medium viscosity (honey) - 40mm geometry
  - High viscosity (caramel) – 20 or 25mm geometry
- Examine data in terms of absolute instrument variables **torque/displacement/speed** and modify geometry choice to move into optimum working range
- You may need to reconsider your selection after the first run!



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## Geometry Options

- With the variety of cones, plates, cups and rotors available, select a geometry based on desired experimental parameters and the material properties

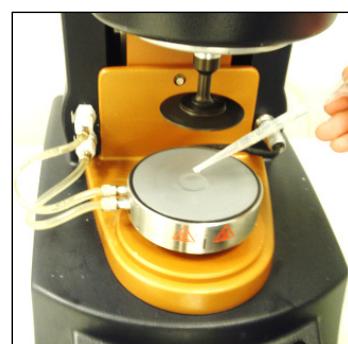


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## When to use Cone and Plate

- Very Low to High Viscosity Liquids
- High Shear Rate measurements
- Normal Stress Growth
- Unfilled Samples
- Isothermal Tests
- Small Sample Volume

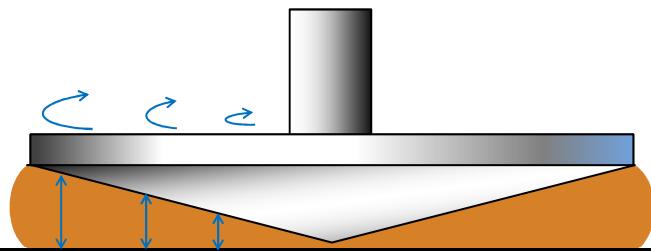


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## Shear Rate is Normalized across a Cone

- The cone shape produces a smaller gap height closer to the inside, so the shear on the sample is constant

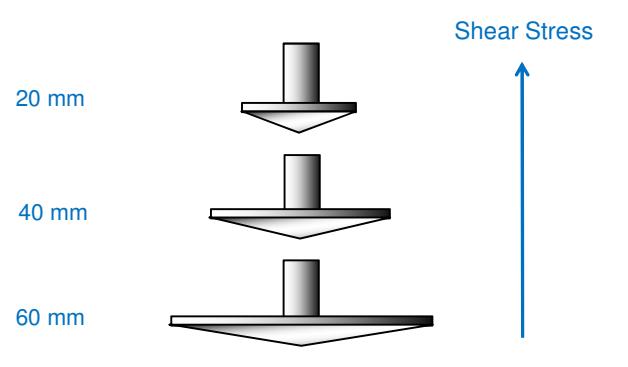


$$\gamma = \frac{dx}{h} \quad h \text{ increases proportionally to } dx, \gamma \text{ is uniform}$$

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## Cone Diameters

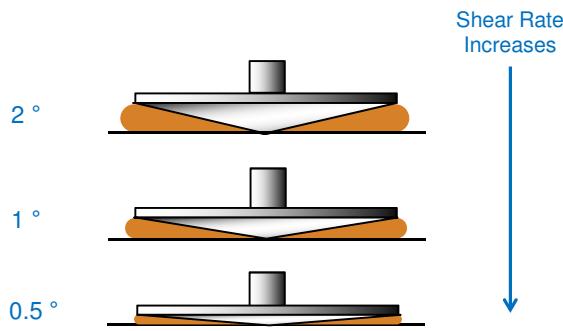


As diameter decreases, shear stress increases  $\sigma = M \frac{3}{2\pi r^3}$

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## Cone Angles

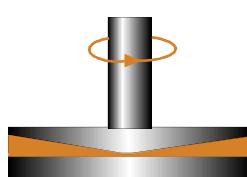


As cone angle decreases, shear rate increases  $\dot{\gamma} = \Omega \frac{1}{\beta}$

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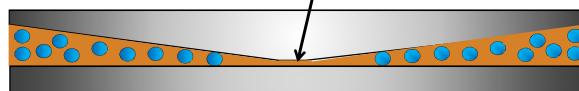
## Limitations of Cone and Plate



Typical Truncation Heights:  
 1° degree ~ 20 - 30 microns  
 2° degrees ~ 60 microns  
 4° degrees ~ 120 microns

Cone & Plate

Truncation Height = Gap

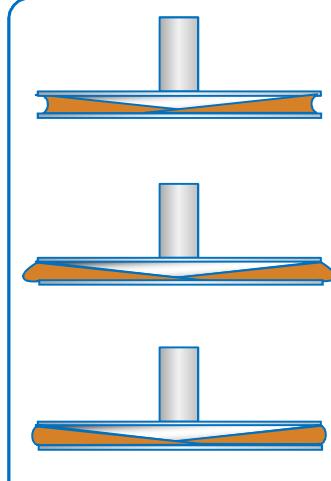


Gap must be > or = 10 [particle size]!!

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## Correct Sample Loading



✗ **Under Filled sample:**  
Lower torque contribution

✗ **Over Filled sample:**  
Additional stress from  
drag along the edges

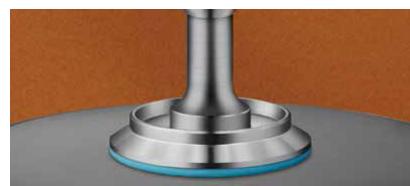
✓ **Correct Filling**

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## When to use Parallel Plates

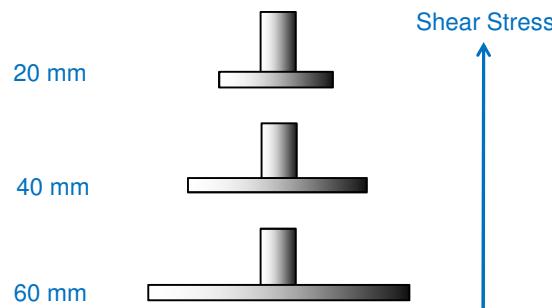
- Low/Medium/High Viscosity Liquids
- Soft Solids/Gels
- Thermosetting materials
- Samples with large particles
- Samples with long relaxation time
- Temperature Ramps/ Sweeps
- Materials that may slip
  - Crosshatched or Sandblasted plates
- Small sample volume



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## Plate Diameters

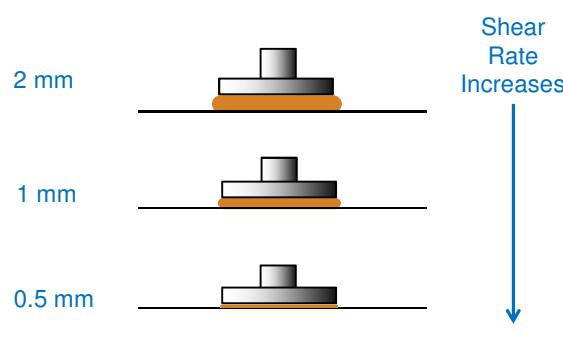


As diameter decreases, shear stress increases     $\sigma = M \frac{2}{\pi r^2}$

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## Plate Gaps



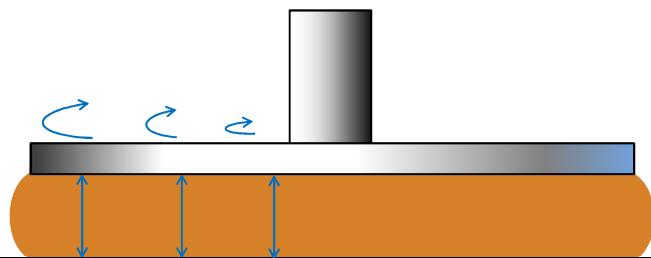
As gap height decreases, shear rate increases     $\dot{\gamma} = \Omega \frac{r}{h}$

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## Effective Shear Rate varies across a Parallel Plate

- For a given angle of deformation, there is a greater arc of deformation at the edge of the plate than at the center



$$\gamma = \frac{dx}{h} \quad dx \text{ increases further from the center, } h \text{ stays constant}$$

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## When to Use Concentric Cylinders



- Low to Medium Viscosity Liquids
- Unstable Dispersions and Slurries
- Minimize Effects of Evaporation
- Weakly Structured Samples (Vane)
- High Shear Rates

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## Peltier Concentric Cylinders



Double Gap Rotor & Cup    DIN Rotor & Standard Cup    Starch Pasting Impeller & Cup    Helical Rotor & Cup    Vane Rotor & Grooved Cup

Concentric Cylinder Cup and Rotor Compatibility Chart

Cup/Rotor	DIN	Recessed End	Starch Impeller	Vane	Wide Gap Vane	Double Gap	Helical Rotor
Standard (rad= 15 mm)	●	●		●	●		
Large Diameter (rad= 22 mm)	●	●	●	●	●		●
Starch (rad= 18.5 mm)	●	●	●	●	●		●
Grooved				●	●		
Double Gap						●	
Helical (rad= 17 mm)						●	

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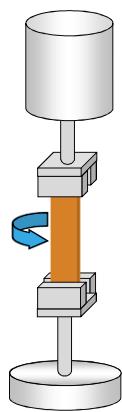
## Geometry Information – Estimated Min and Max Shear Rates

Geometry	Diameter (mm)	Degree	Gap (micron)	Sample Volume (mL)	Max Shear Rate (approx) 1/s	Min Shear Rate (approx) 1/s
Parallel Plate and Cone and Plate	8	0	1000	0.05	<b>1.20E+03</b>	4.00E-07
		0	500	0.03		
		0.5	18	1.17E-03		
		1	28	2.34E-03		
		2	52	4.68E-03		
	20	4	104	9.37E-03		
		0	1000	0.31	<b>3.00E+03</b>	1.00E-06
		0.5	18	0.02	<b>3.44E+04</b>	1.15E-05
		1	28	0.04	<b>1.72E+04</b>	5.73E-06
		2	52	0.07	<b>8.60E+03</b>	2.87E-06
	25	4	104	0.15	<b>4.30E+03</b>	1.43E-06
		0	1000	0.49	<b>3.75E+03</b>	1.25E-06
		0.5	18	0.04		
		1	28	0.07		
		2	52	0.14		
	40	4	104	0.29		
0		1000	1.26	<b>6.00E+03</b>	2.00E-06	
0.5		18	0.15	<b>3.44E+04</b>	1.15E-05	
1		28	0.29	<b>1.72E+04</b>	5.73E-06	
2		52	0.59	<b>8.60E+03</b>	2.87E-06	
60	4	104	1.17	<b>4.30E+03</b>	1.43E-06	
	0	1000	2.83	<b>9.00E+03</b>	3.00E-06	
	0	500	1.41			
	0.5	18	0.49	<b>3.44E+04</b>	1.15E-05	
	1	28	0.99	<b>1.72E+04</b>	5.73E-06	
	2	52	1.97	<b>8.60E+03</b>	2.87E-06	
	4	104	3.95	<b>4.30E+03</b>	1.43E-06	
	Conical Din Rotor			19.6	<b>4.36E+03</b>	1.45E-06
Concentric Cylinder	Recessed End		6.65	<b>4.36E+03</b>	1.45E-06	
Double Wall			11.65	<b>1.59E+04</b>	5.31E-06	
Pressure Cell			9.5			
Standard Vane			28.72			

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## Torsion Rectangular



$$K_Y = \frac{t}{l \left[ 1 - 0.378 \left( \frac{t}{w} \right)^2 \right]}$$

$$K_T = \frac{(3 + \frac{1.8}{w})}{(w \cdot t^2)}$$

w = Width

l = Length

t = Thickness

### Advantages:

- High modulus samples
- Small temperature gradient
- Simple to prepare

### Disadvantages:

- No pure Torsion mode for high strains

Torsion cylindrical also available

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## Torsion and DMA Measurements



- Torsion and DMA geometries allow solid samples to be characterized in a temperature controlled environment
- Torsion measures G', G'', and Tan δ
- DMA measures E', E'', and Tan δ
  - ARES G2 DMA is standard function (50 μm amplitude)
  - DMA is an optional DHR function (100 μm amplitude)



Rectangular and  
cylindrical torsion



DMA 3-point bending and tension  
(cantilever not shown)

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## Examples for Common Configurations

Geometry	Examples	
Concentric Cylinder	Coatings Slurries (vane rotor option) Starch pasting	Beverages
Cone and Plate	Low viscosity fluids Viscosity standards Sparse materials Polymer melts in steady shear	
Parallel Plate	Widest range of materials Adhesives Hydrogels Curing of thermosetting materials Foods	Polymer melts Asphalt Cosmetics
Torsion Rectangular	Thermoplastic solids Thermoset solids	



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## Geometry Overview

Geometry	Application	Advantage	Disadvantage
Cone/plate	fluids, melts viscosity > 10mPas	true viscosities	temperature ramp difficult
Parallel Plate	fluids, melts viscosity > 10mPas	easy handling, temperature ramp	shear gradient across sample
Couette	low viscosity samples < 10 mPas	high shear rate	large sample volume
Double Wall Couette	very low viscosity samples < 1mPas	high shear rate	cleaning difficult
Torsion Rectangular	solid polymers, composites	glassy to rubbery state	Limited by sample stiffness
DMA	Solid polymers, films, Composites	Glassy to rubbery state	Limited by sample stiffness (Oscillation and stress/strain)



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## Geometry Size Selection

- DHR
  - Most common is 40-mm parallel plate; 1000 micron gap
  - Use 60-mm cone and plate and parallel plate for low viscosity materials, say, up to 100 mPa-sec, but 40-mm geometries can often handle these materials too.
  - 20-mm plates are often used at higher viscosities.
  - 25-mm parallel plates are the preferred choice for polymer melts.
  - 40-mm 2-degree is the most common cone geometry. This is often used to verify an instrument with a viscosity standard.
  - 8-mm plates are often used for pressure sensitive adhesives and for asphalt around room temperature.
- ARES-G2
  - The most common geometry on the ARES-G2 is the 25-mm parallel plate. Examples would be polymer melts and thermosetting materials.
  - Low viscosity fluids are run with 50-mm plates or cone-and-plate.
  - Again, 8-mm plates are used for adhesives and asphalt at room temperature.



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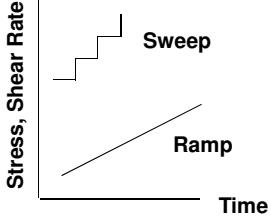
## TEST METHODS UNIDIRECTIONAL



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## Rheological Methods – Unidirectional Testing

- Flow
  - Stress/Rate Ramp
  - Stress/Rate Sweep
  - Time sweep/Peak Hold/Stress Growth
  - Temperature Ramp
  - Creep (constant stress)
  - Stress Relaxation (constant strain)




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## Procedure for Rate Ramp Up/Ramp Down

**1: Flow Ramp**

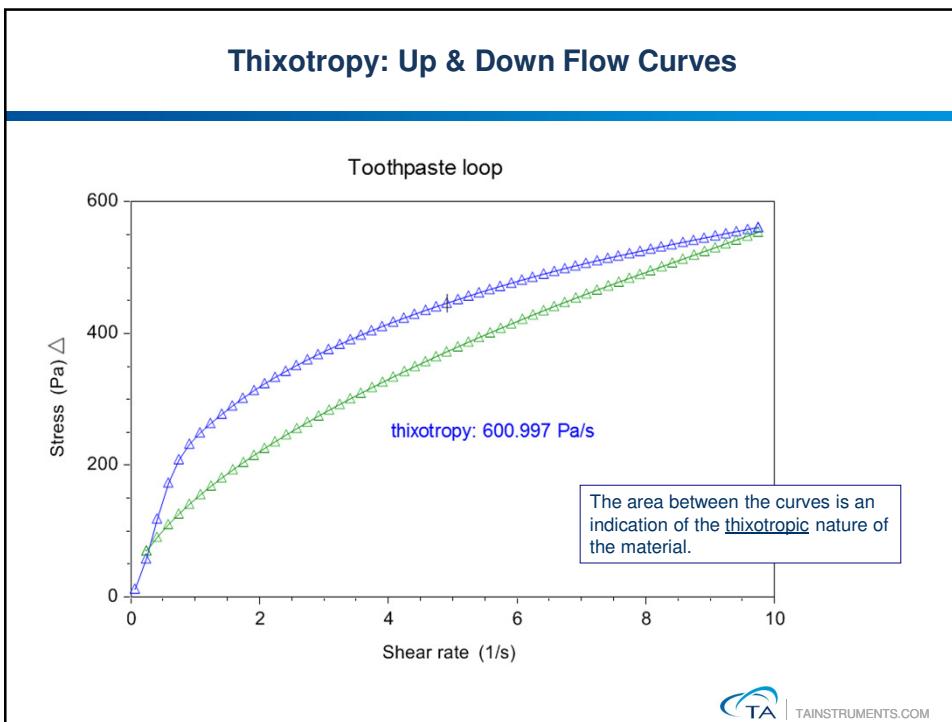
Environmental Control	
Temperature	25 °C
Soak Time	00:02:00 hh:mm:ss
<input type="checkbox"/> Inherit Set Point	
<input checked="" type="checkbox"/> Wait For Temperature	
Test Parameters	
Duration	00:01:40 hh:mm:ss
Mode	<input checked="" type="radio"/> Linear <input type="radio"/> Log
Initial shear rate	0.0 to final 100.0 1/s
<input type="checkbox"/> Inherit initial value	
<input type="checkbox"/> Inherit duration	
Sampling interval	1.0 s/pt
Controlled Rate Advanced	
Data acquisition	
End of step	Maintain final torque/velocity

**2: Flow Ramp**

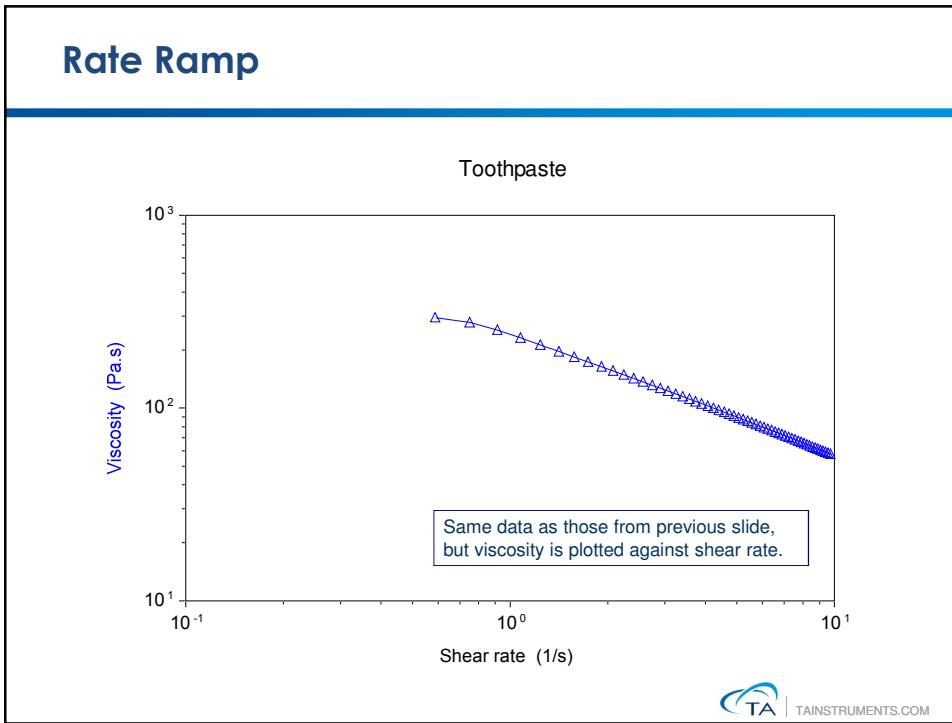
Environmental Control	
Temperature	25 °C
Soak Time	00:00:00 hh:mm:ss
<input type="checkbox"/> Inherit Set Point	
<input type="checkbox"/> Wait For Temperature	
Test Parameters	
Duration	00:01:40 hh:mm:ss
Mode	<input checked="" type="radio"/> Linear <input type="radio"/> Log
Initial shear rate	100.0 to final 0.0 1/s
<input type="checkbox"/> Inherit initial value	
<input type="checkbox"/> Inherit duration	
Sampling interval	1.0 s/pt
Controlled Rate Advanced	
Data acquisition	
End of step	Zero velocity

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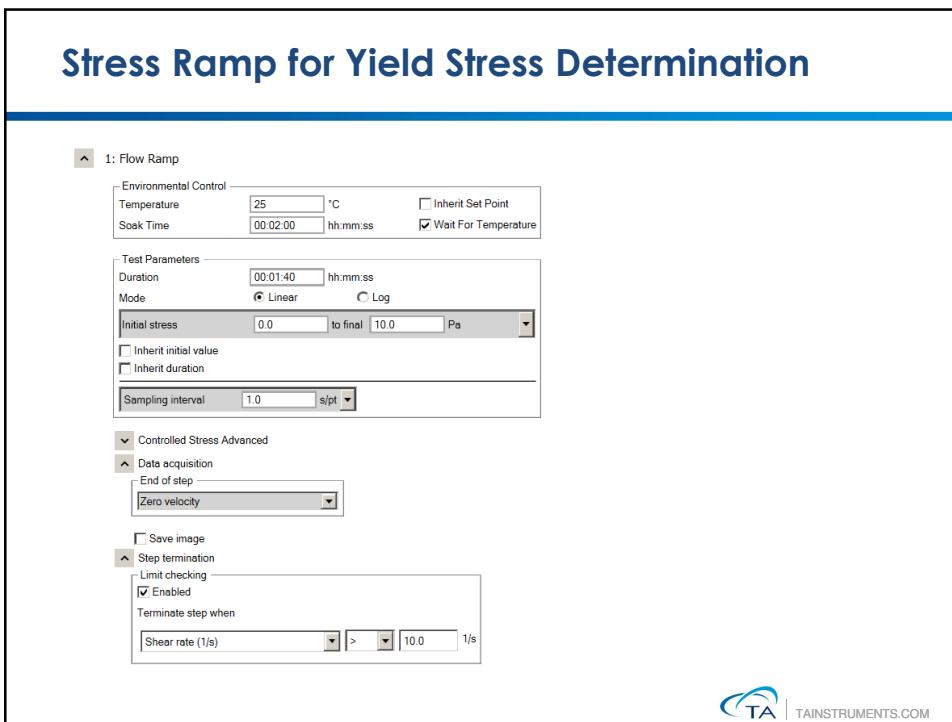
42



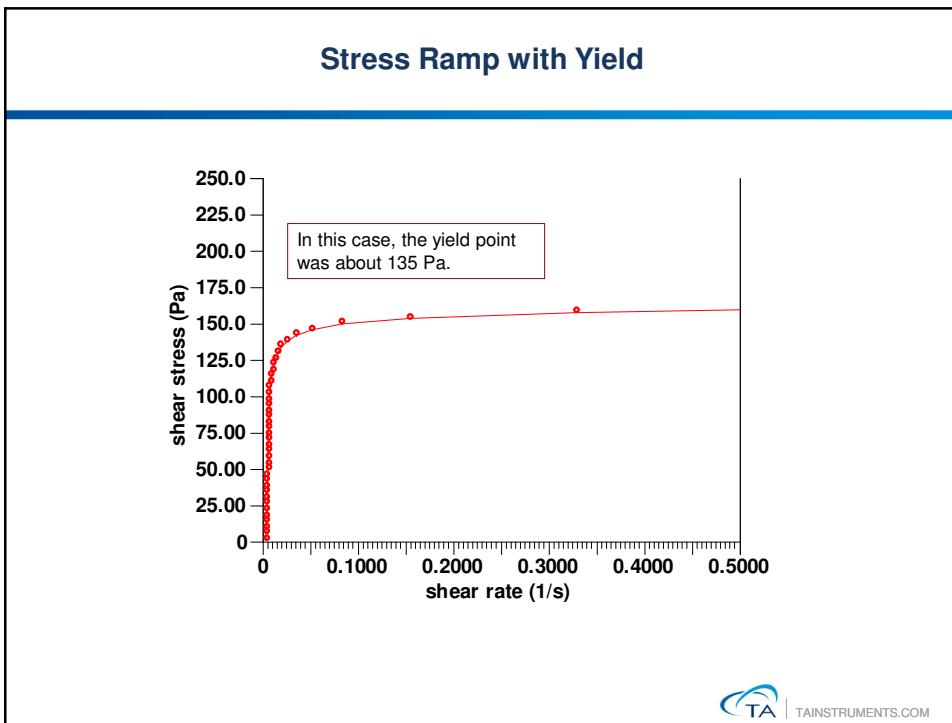
43



44



45



46

## Ramp Selection

- Do a ramp as a preliminary scouting test, prior to the more fundamentally sound rate or stress sweep.
- For rate ramps, a common acceleration rate is  $1 \text{ sec}^{-1}$  per second. For example, 0 to  $100 \text{ sec}^{-1}$  in 100 seconds. This is a starting point. The operator can select a rate or a range that is more appropriate for the sample in question.
- Ramp up/Ramp down tests are common for determining thixotropy. The area between the up and down curves is often reported as a thixotropy parameter.
- There have been times when the reproducibility is better with the down curve than it is with the up curve.
- Ramps are good for characterizing materials that may slip or exude from the gap as the shear rate is increased. Often one can get to higher shear rates with ramps than with sweeps because one doesn't dwell at the high rates as long.
- Stress ramps are often used to get the yield point of a material. Sometimes these are not always clear-cut. Also, one has to be cautious when working with models. There have been instances where negative (!?) yield stresses are determined by software for the selected model.
- For stress ramps, use the Step Termination feature to prevent over-speed.



47

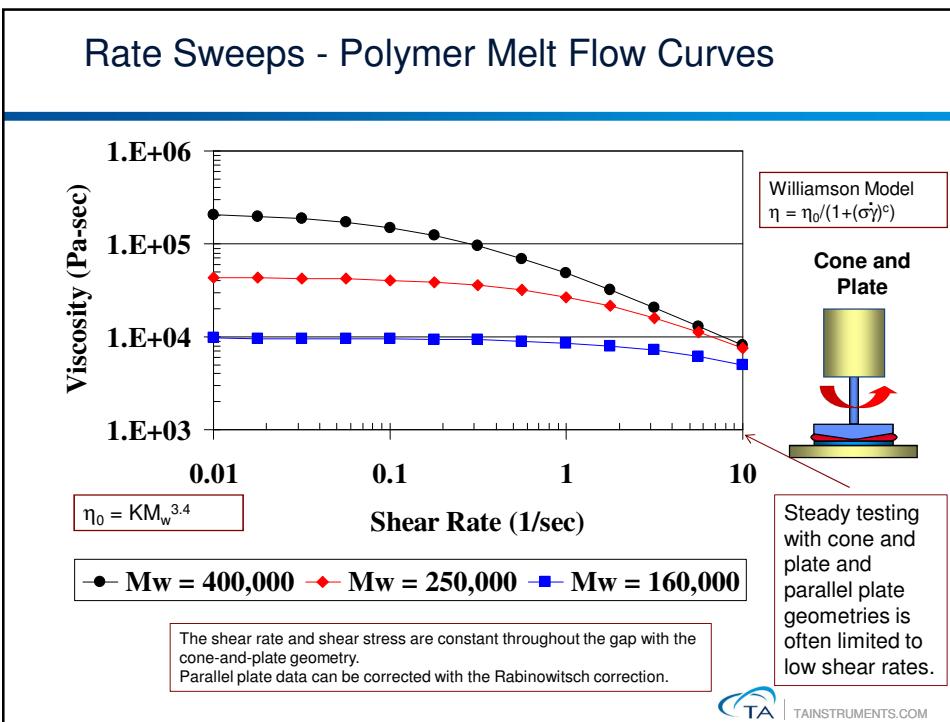
## Steady State Flow Test

### 1: Flow Sweep

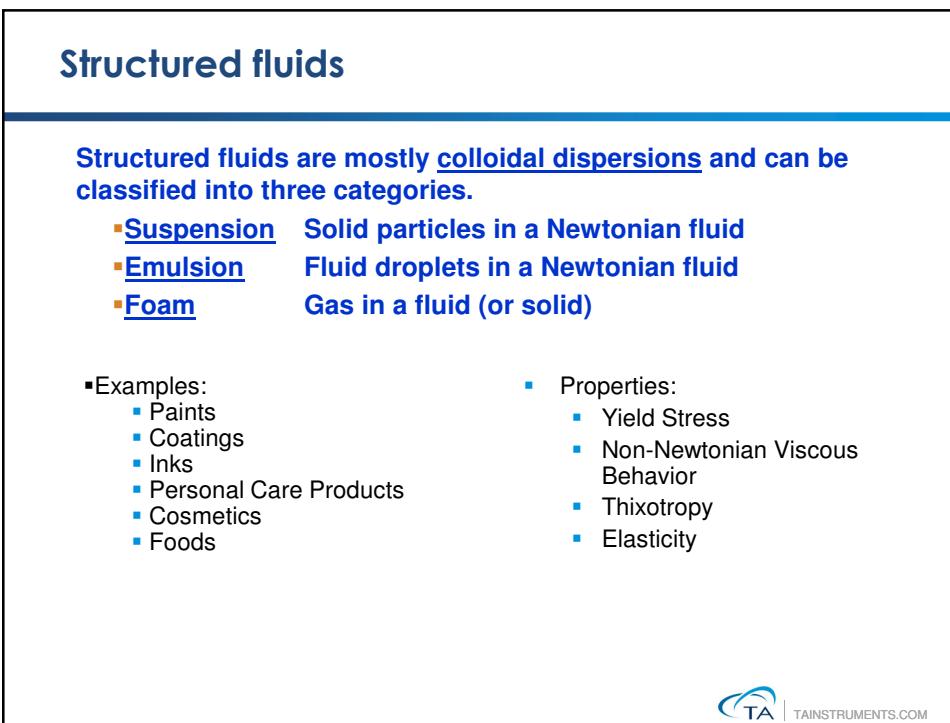
Environmental Control	
Temperature	<input type="text" value="25"/> °C
Soak Time	<input type="text" value="00:02:00"/> hh:mm:ss
<input type="checkbox"/> Inherit Set Point <input checked="" type="checkbox"/> Wait For Temperature	
Test Parameters	
<input type="button" value="Logarithmic sweep"/> Logarithmic sweep	
Shear rate	<input type="text" value="0.1"/> to <input type="text" value="100.0"/> 1/s
Points per decade	<input type="text" value="5"/>
<input checked="" type="checkbox"/> Steady state sensing	
Max. equilibration time	<input type="text" value="00:01:00"/> hh:mm:ss
Sample period	<input type="text" value="00:00:05"/> hh:mm:ss
% tolerance	<input type="text" value="5.0"/>
Consecutive within	<input type="text" value="3"/>
<input type="checkbox"/> Scaled time average	



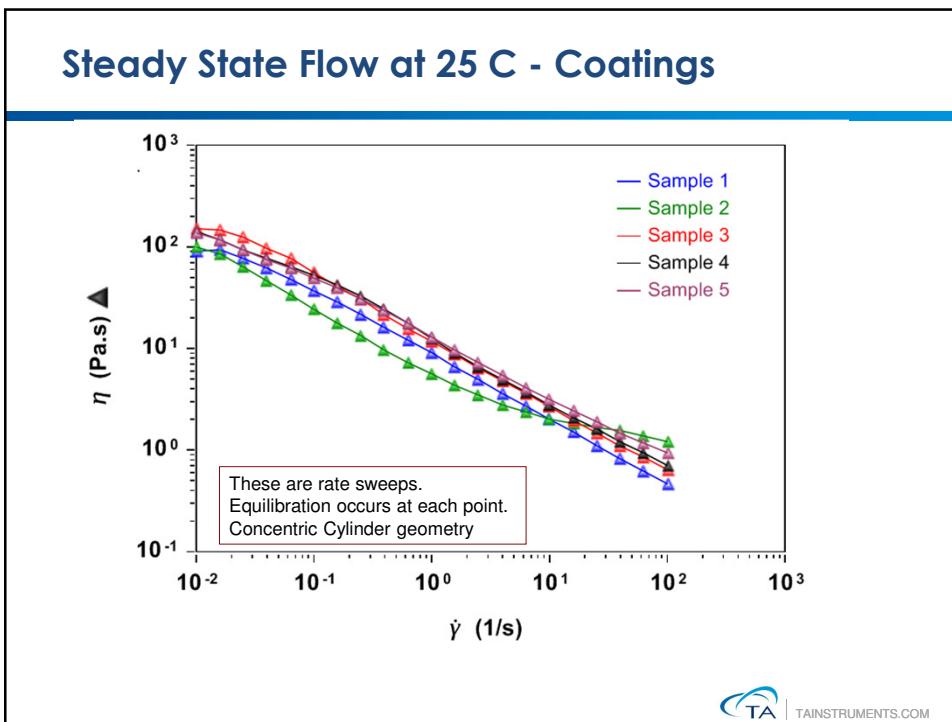
48



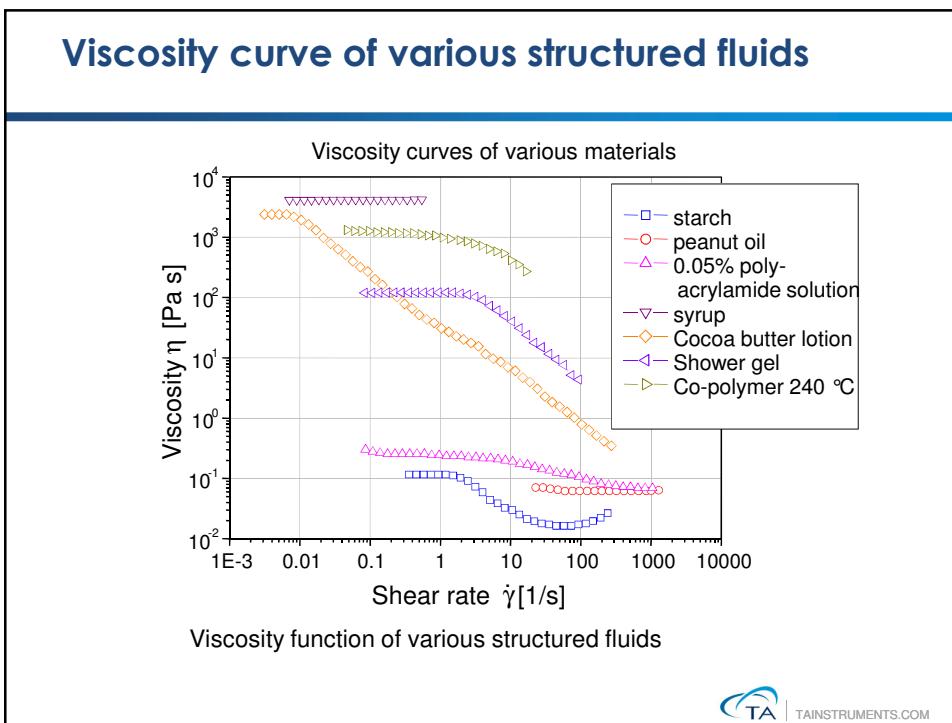
49



50

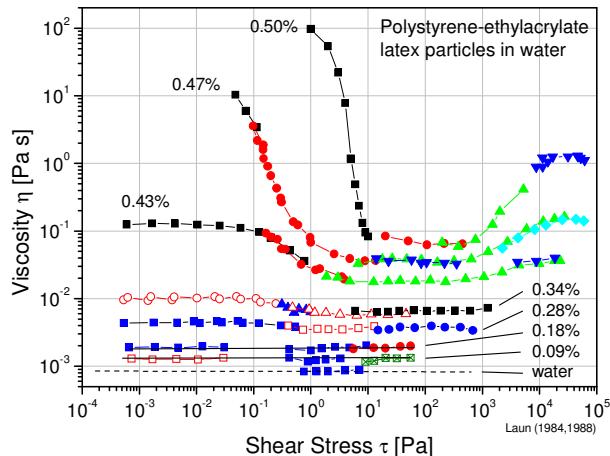


51



52

## Viscous response of suspensions



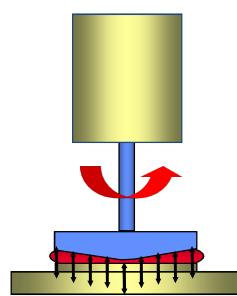
Rheological parameters of interest: Yield stress, viscosity, time dependence, linear viscoelasticity

H.M. Laun *Angew. Makromol. Chem.* 335, 124 (1984)

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## Normal Force Measurements with Cone & Plate

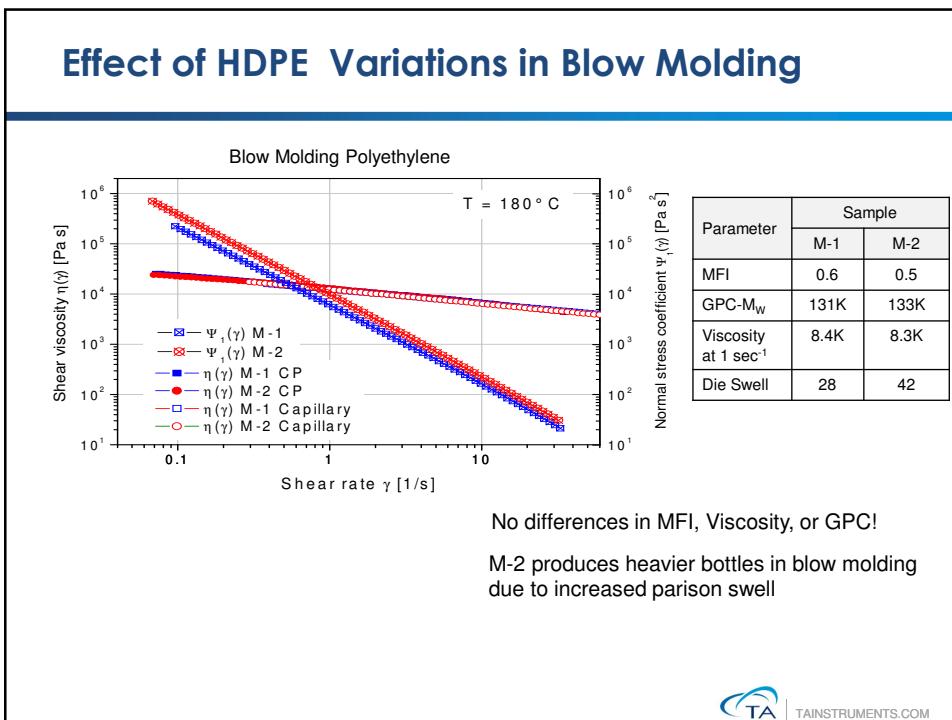


### Normal Stress Difference:

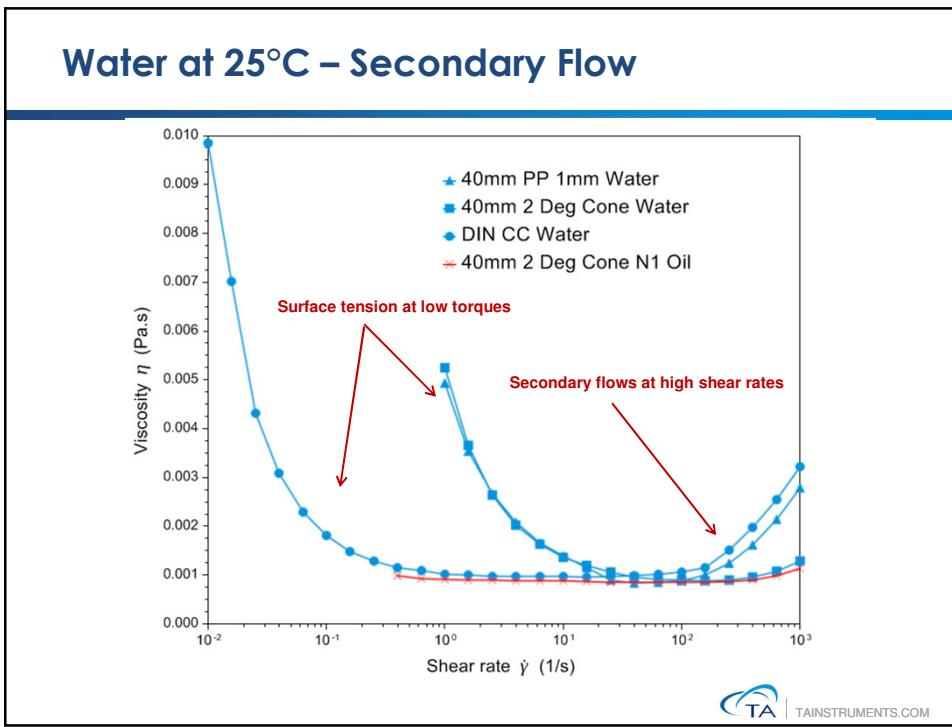
- In steady flow, polymeric materials can exert a force that tries to separate the cone and the plate.
- A parameter to measure this is the Normal Stress Difference,  $N_1$ , which equals  $\sigma_{xx} - \sigma_{yy}$  from the Stress Tensor.
- $N_1 = 2F/(\pi R^2)$ , where  $F$  is the measured force.
- $\Psi_1 = N_1/\dot{\gamma}^2$  This is the primary normal stress coefficient.

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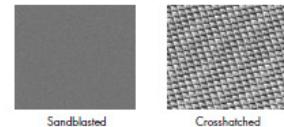
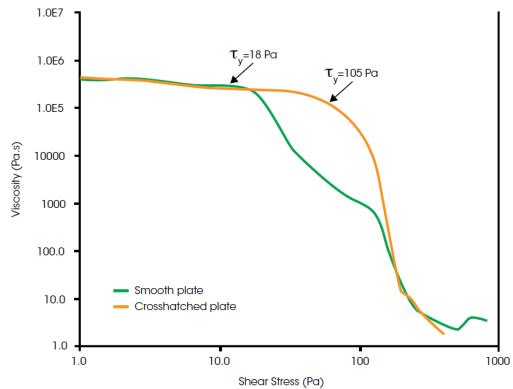
55



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## Wall Slip

Yield Stress Measurements on Toothpaste

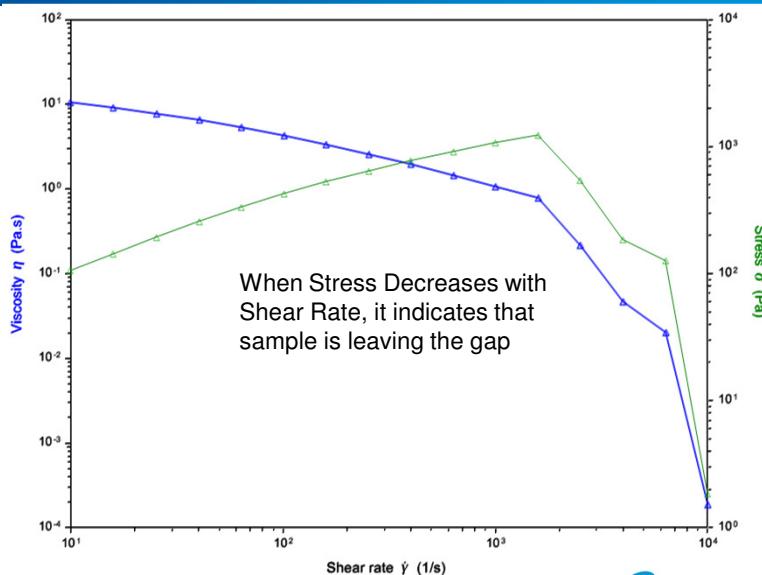


- Wall slip can manifest as “apparent double yielding”
- Can be tested by running the same test at different gaps
- For samples that don’t slip, the results will be independent of the gap

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## Shear Thinning or Sample Instability?



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## Rate and Stress Sweeps

- Sweeps are preferable to ramps because the material is given a chance to equilibrate at a particular shear rate or stress.
- These are useful tests to see how materials will perform in flow, such as transporting fluid through pipes and tubing, after structure has been broken.
- The most common rate range is 0.1 to 100 1/sec, 5 points per logarithmic decade.
- The Steady State sensing feature is a useful tool to perform valid rate or stress sweeps in the shortest amount of time.
- For materials that exhibit flow instability, the ramp may be preferable. With sweeps, the material is exposed to high shear rates for prolonged periods, whereas, with ramps, the dwell time at a particular rate is shorter.



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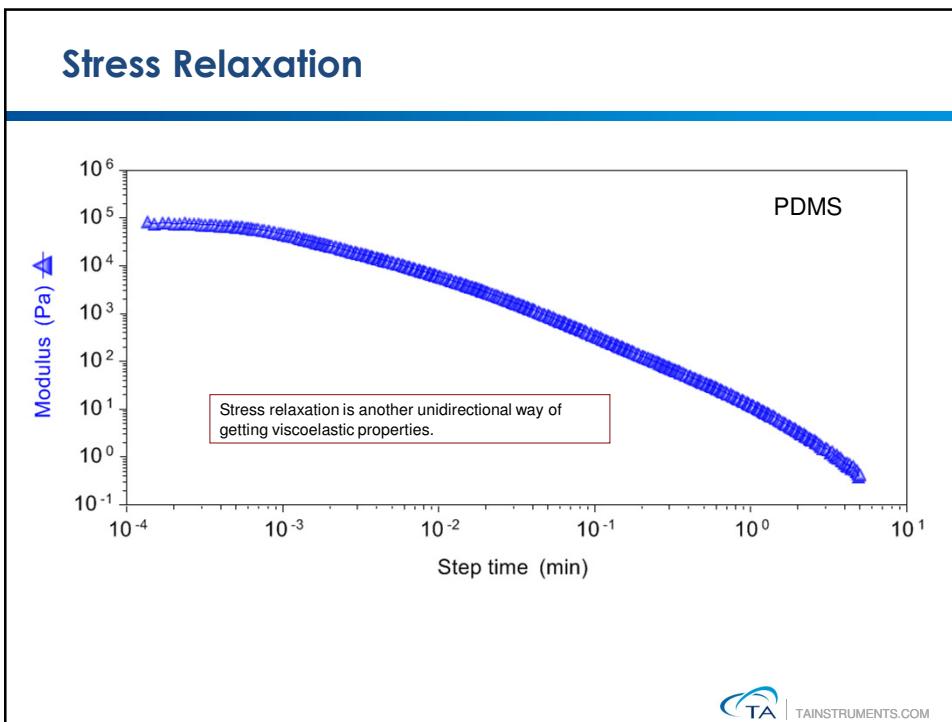
## Stress Relaxation

▲ 1: Step (Transient) Stress Relaxation

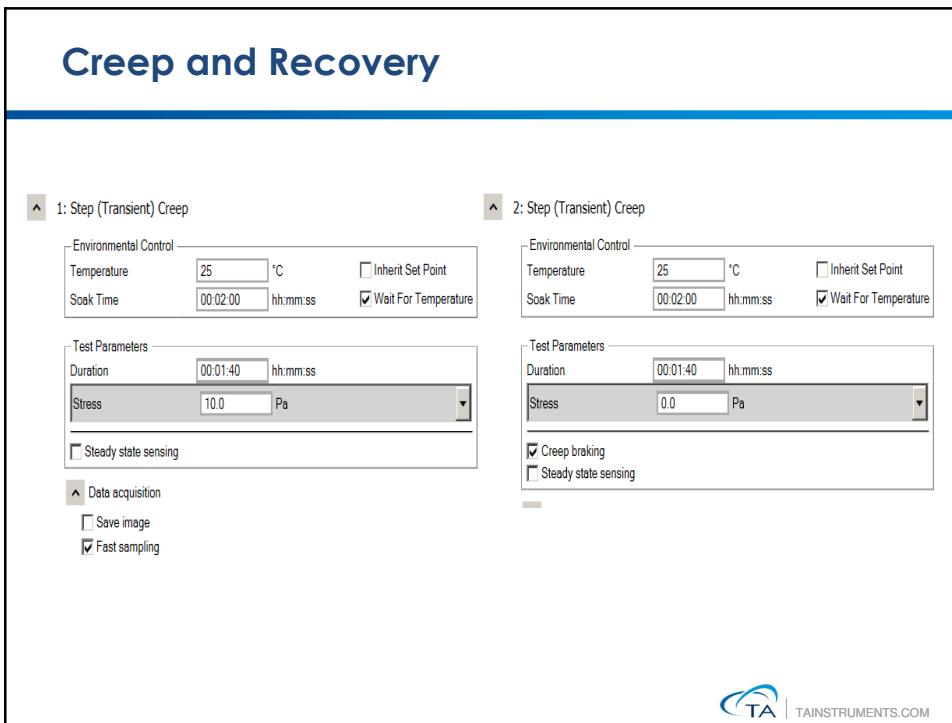
Environmental Control		
Temperature	25 <input type="text"/> °C	<input type="checkbox"/> Inherit Set Point
Soak Time	00:02:00 <input type="text"/> hh:mm:ss	<input checked="" type="checkbox"/> Wait For Temperature
Test Parameters		
Duration	00:01:40 <input type="text"/> hh:mm:ss	<input type="checkbox"/>
% Strain	<input type="text"/> 0.1 %	<input type="button" value="▼"/>
<input type="checkbox"/> Steady state sensing		
<span style="background-color: #cccccc; border: 1px solid black; padding: 2px;">▲</span> Advanced		
Strain rise time <input type="text"/> 0.01 s		
<span style="background-color: #cccccc; border: 1px solid black; padding: 2px;">▲</span> Data acquisition		
<input type="checkbox"/> Save image		
<input checked="" type="checkbox"/> Fast sampling		



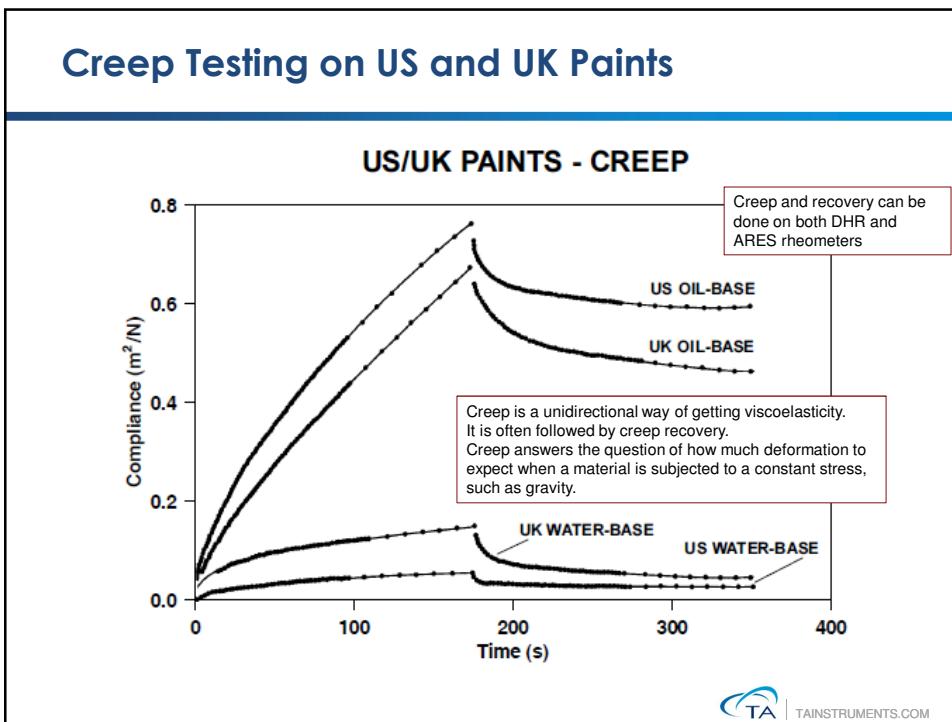
60



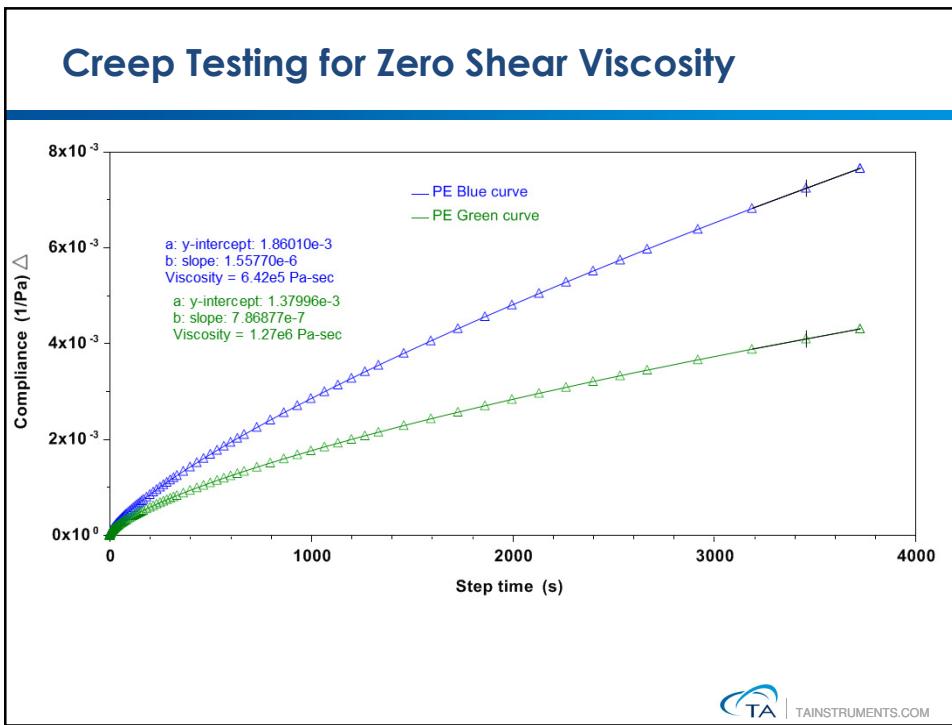
61



62

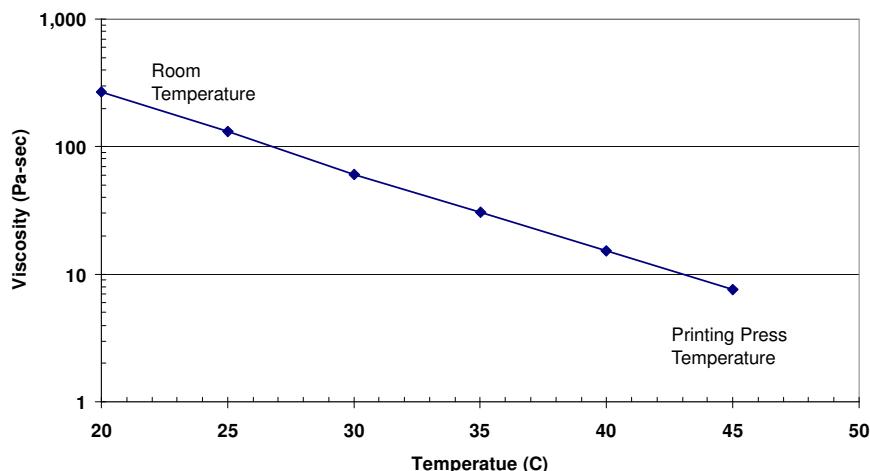


63



64

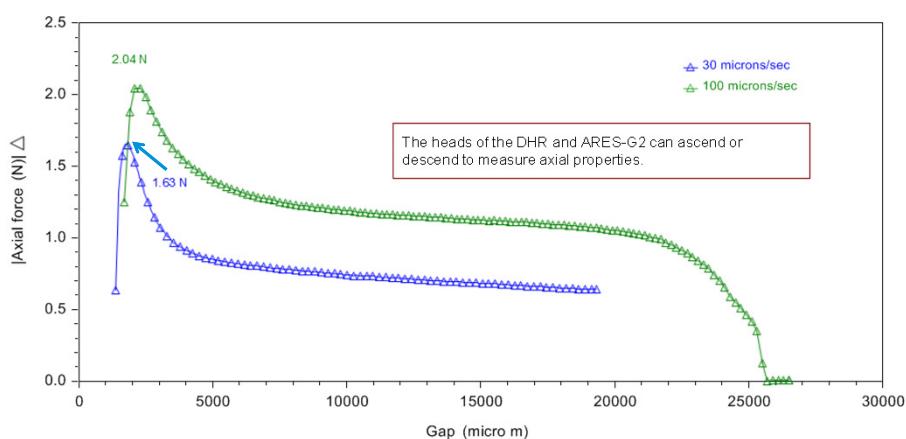
## Flow Temperature Ramp – Printing Inks



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## Tack Testing



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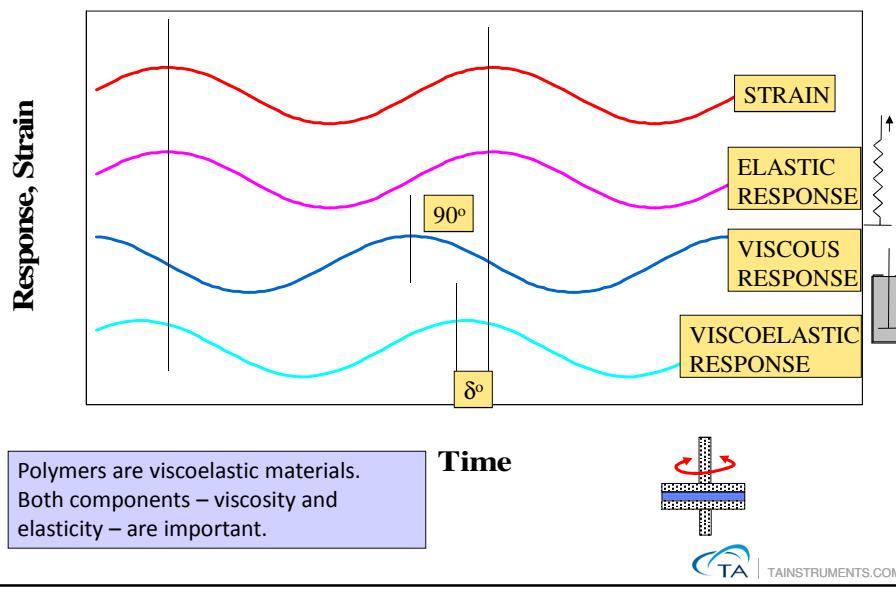
66

## TEST METHODS DYNAMIC TESTING

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### Dynamic Testing



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## Dynamic Rheological Parameters

Parameter	Shear	Elongation	Units
Strain	$\gamma = \gamma_0 \sin(\omega t)$	$\epsilon = \epsilon_0 \sin(\omega t)$	---
Stress	$\sigma = \sigma_0 \sin(\omega t + \delta)$	$\tau = \tau_0 \sin(\omega t + \delta)$	Pa
Storage Modulus (Elasticity)	$G' = (\sigma_0/\gamma_0) \cos \delta$	$E' = (\tau_0/\epsilon_0) \cos \delta$	Pa
Loss Modulus (Viscous Nature)	$G'' = (\sigma_0/\gamma_0) \sin \delta$	$E'' = (\tau_0/\epsilon_0) \sin \delta$	Pa
Tan $\delta$	$G''/G'$	$E''/E'$	---
Complex Modulus	$G^* = (G'^2 + G''^2)^{0.5}$	$E^* = (E'^2 + E''^2)^{0.5}$	Pa
Complex Viscosity	$\eta^* = G^*/\omega$	$\eta_E^* = E^*/\omega$	Pa·sec

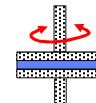
Cox-Merz Rule for Linear Polymers:  $\eta^*(\omega) = \eta(\dot{\gamma}) @ \dot{\gamma} = \omega$



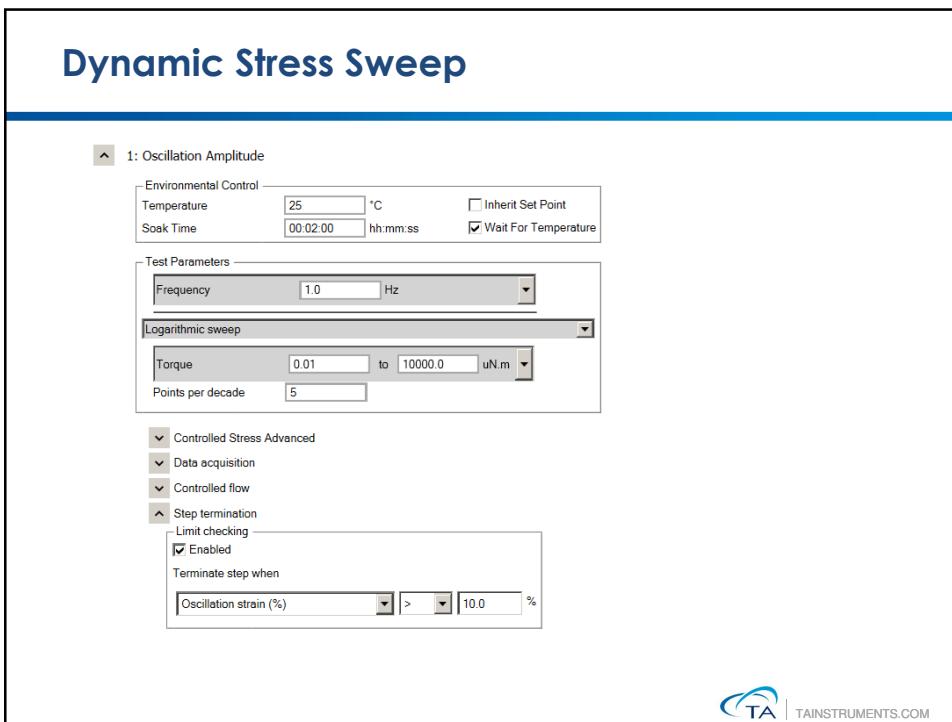
69

## Rheological Methods – Dynamic Oscillatory Testing

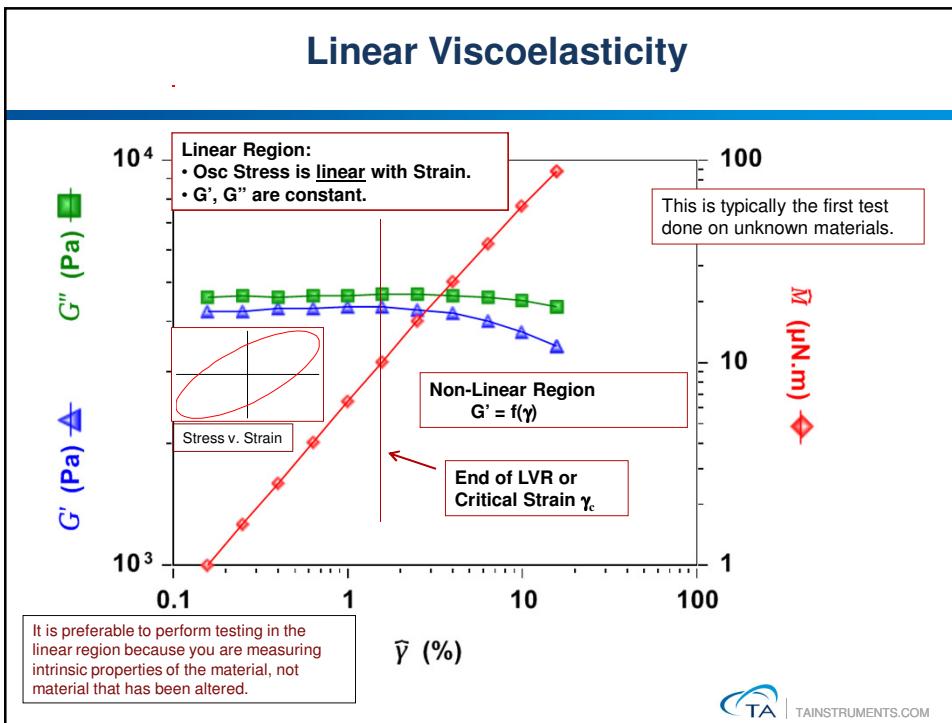
- Dynamic Strain Sweep/Dynamic Stress Sweep
- Isothermal Dynamic Time Sweep
- Isothermal Dynamic Frequency Sweep
- Dynamic Temperature Ramp
- Dynamic Temperature Sweep at 1 or Multiple Frequencies.



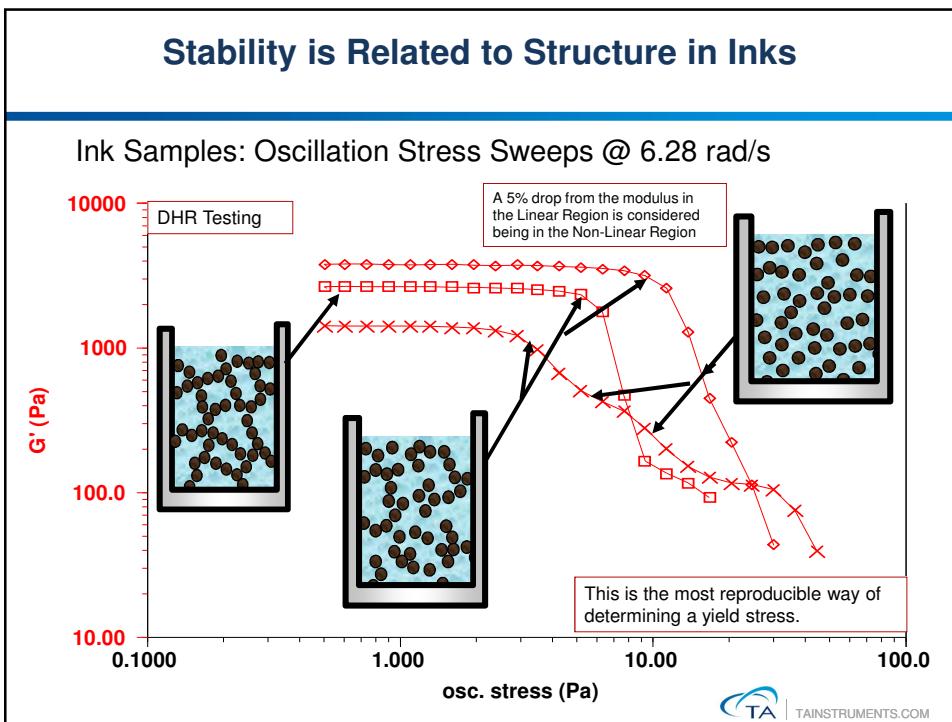
70



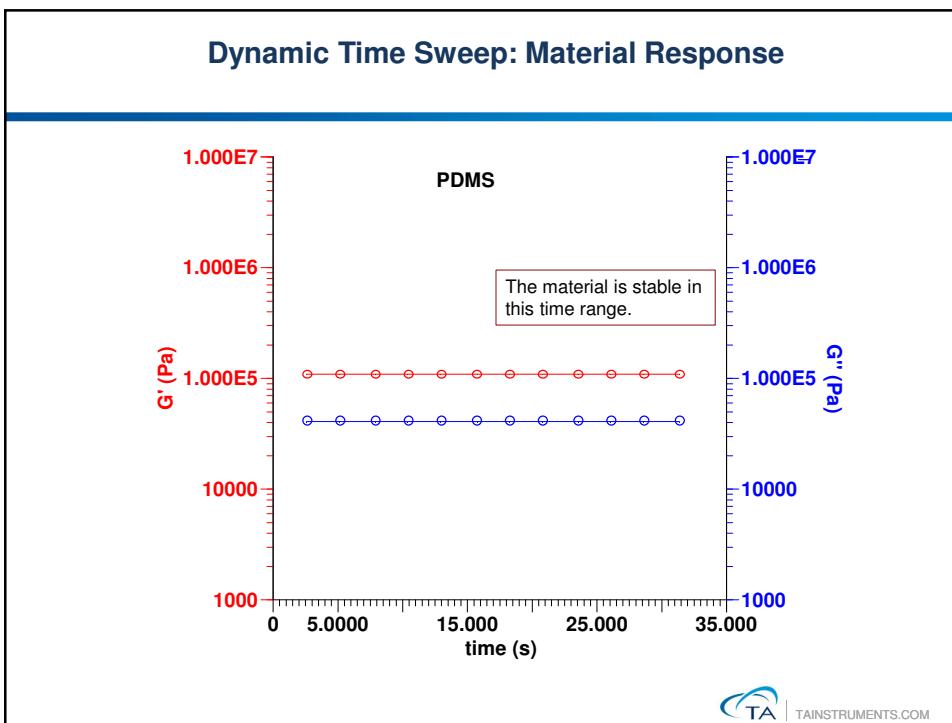
71



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73



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## Dynamic Time Sweep for Curing

**1: Conditioning Options**

Axial force adjustment

Mode: Active

Tension  Compression

Axial force: 0.0 N  Set initial value

Sensitivity: 0.2 N

**Advanced**

Gap change limit up: 500.0 um

Gap change limit down: 500.0 um

Return to window  Return to initial value

Purge gas only (no active cooling)

**Auto strain adjustment**

Mode: Disabled

**2: Oscillation Time**

Environmental Control

Temperature: 25 °C  Inherit Set Point

Soak Time: 00:00:00 hh:mm:ss  Wait For Temperature

**Test Parameters**

Duration: 00:16:40 hh:mm:ss

Sampling interval: 10.0 s/pt

Strain %: 0.1 %

Single point

Frequency: 1.0 Hz

**Controlled Strain Advanced**

Controlled strain type: Non-iterative sampling

Initial stress

Torque: 1.0 uN.m

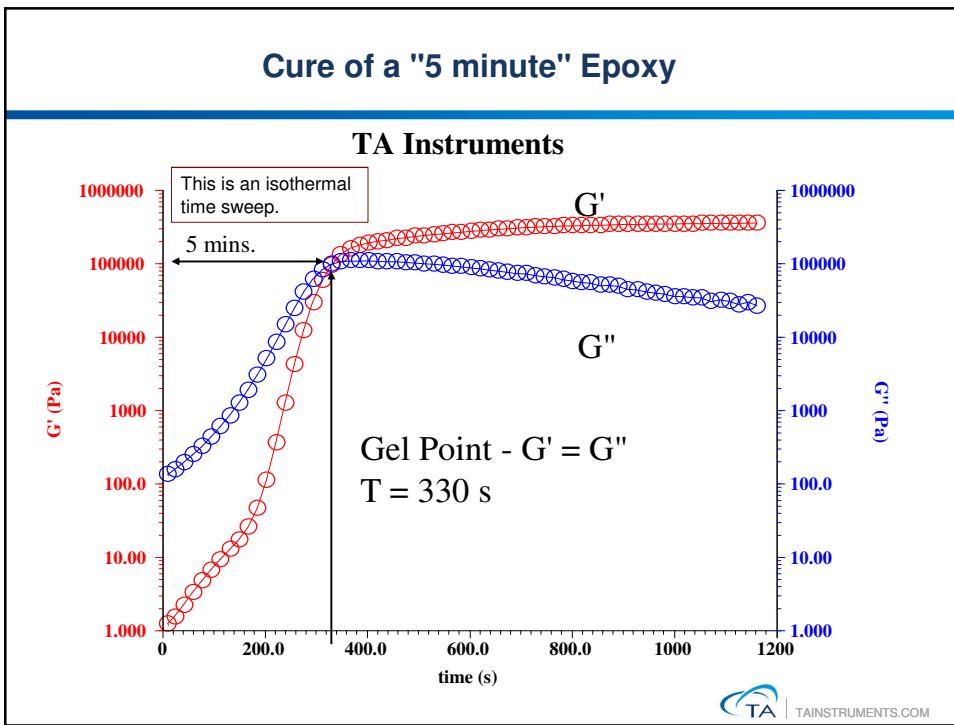
Lower torque limit: 1.0 uN.m

Number of tries: 4

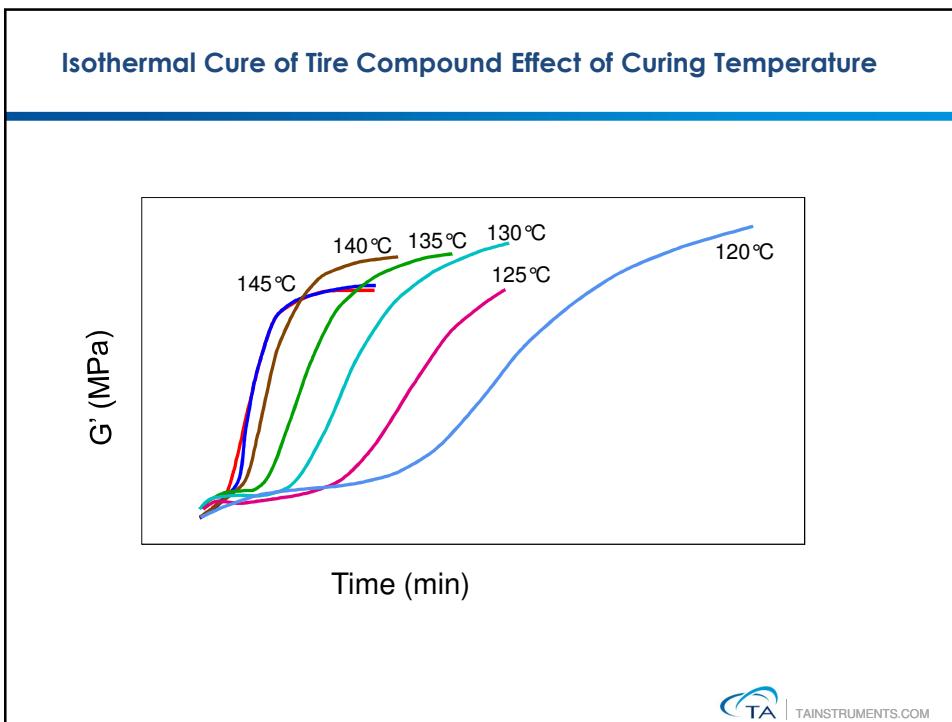
Initial tolerance: 0.5 %

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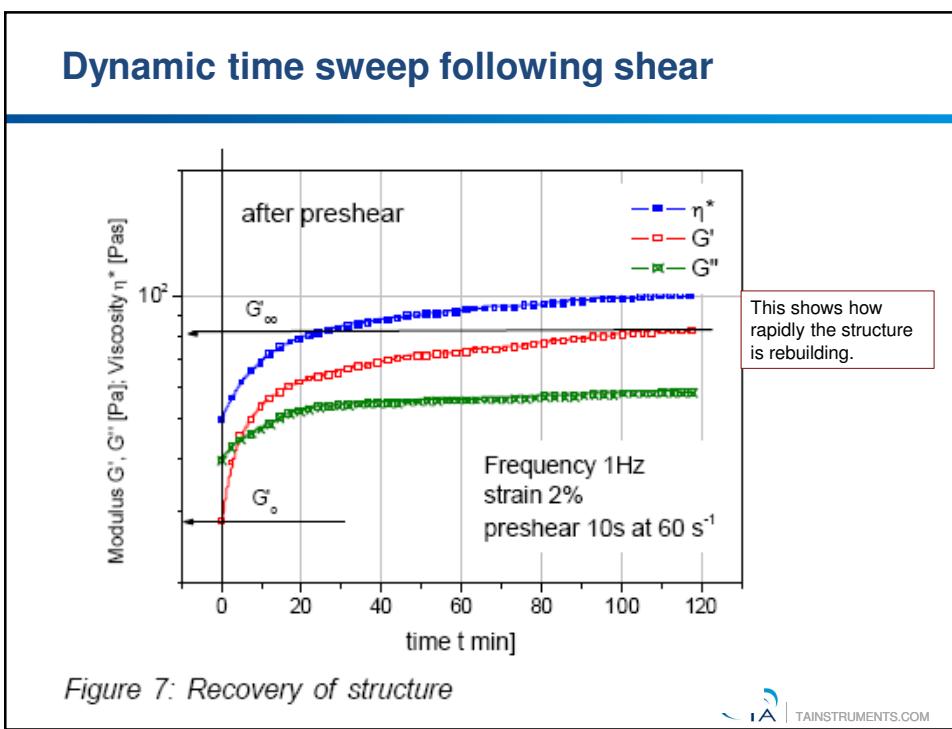
75



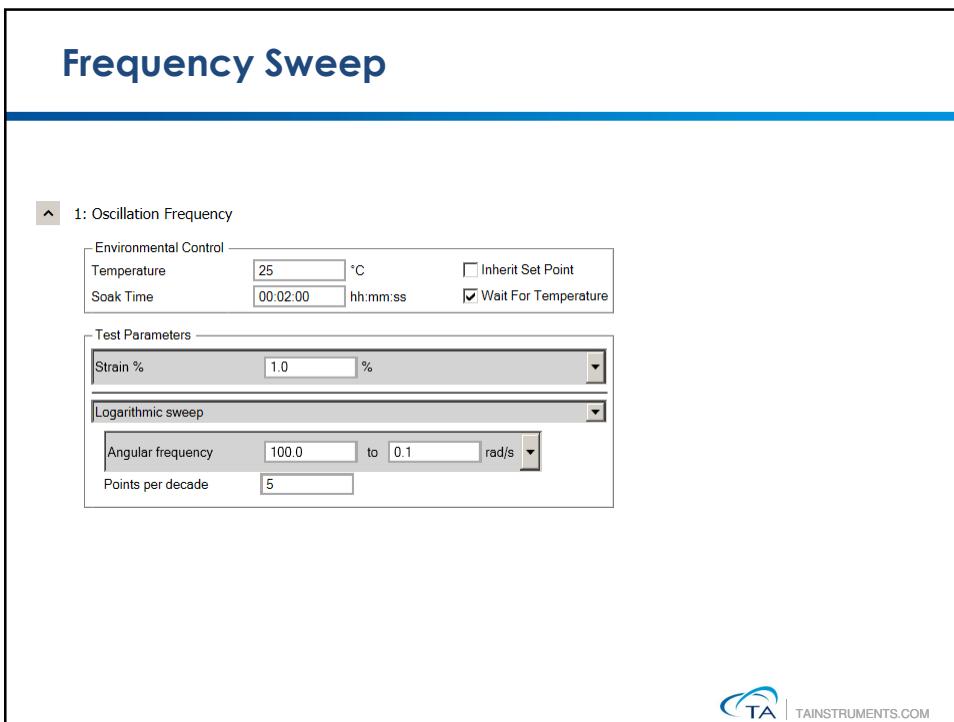
76



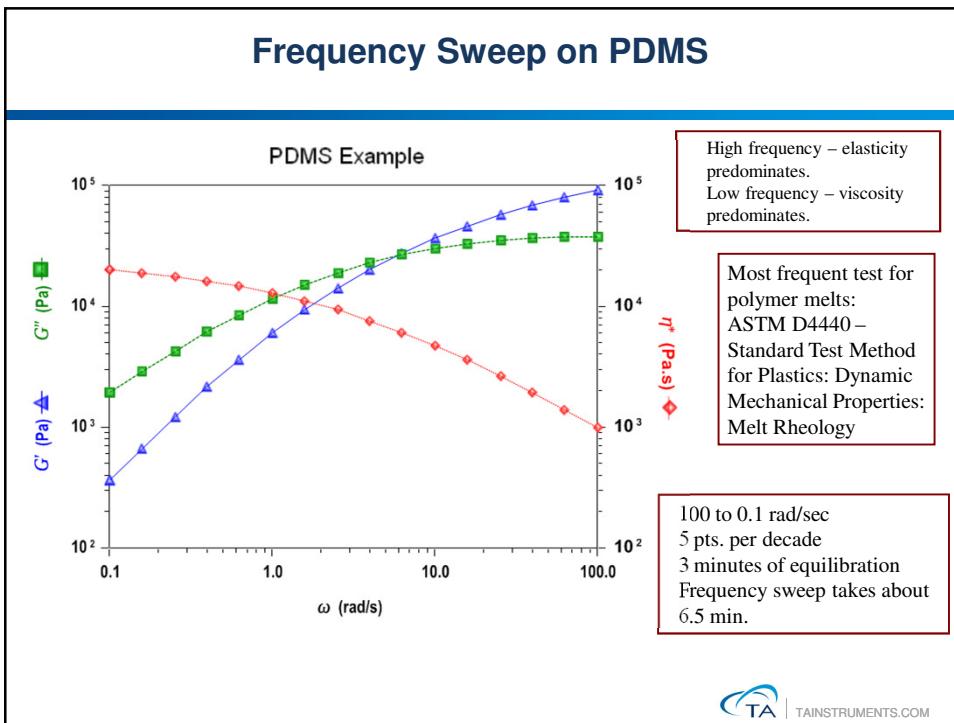
77



78



79

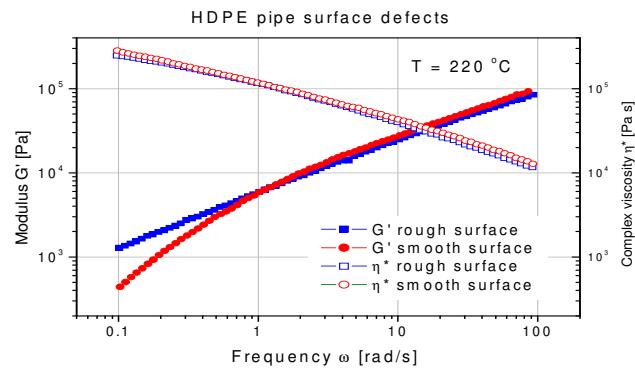


80

## Surface Defects during Pipe Extrusion

**Indicated by**  
Elasticity at  
low  
frequency

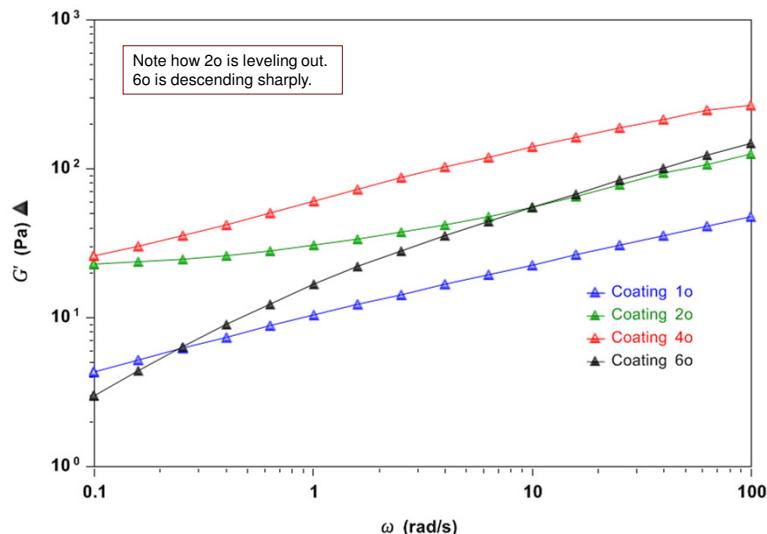
**Caused by**  
Broader  
MWD



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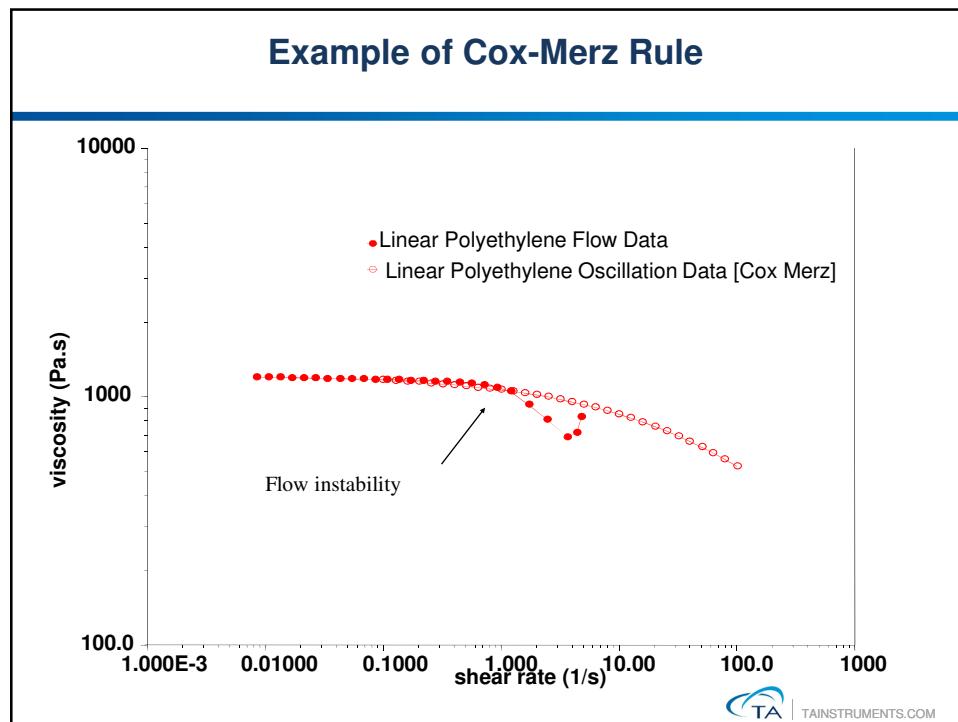
81

## Coatings Frequency Sweep

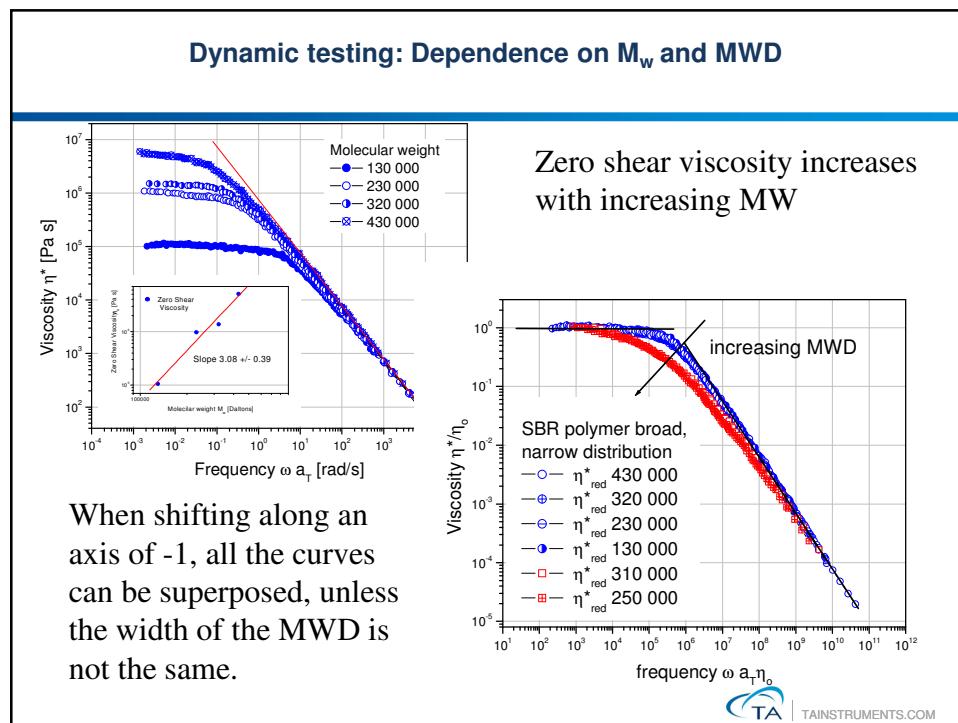


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82

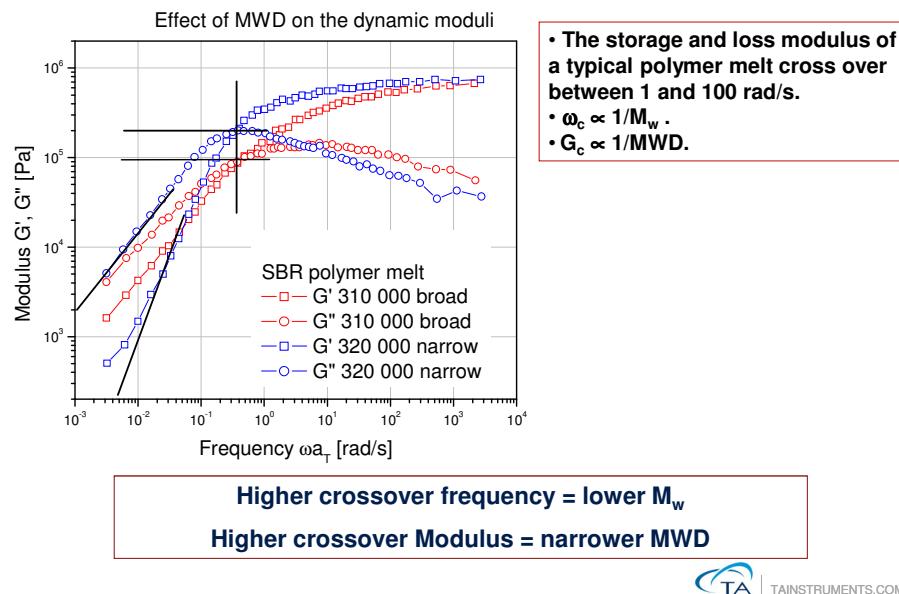


83



84

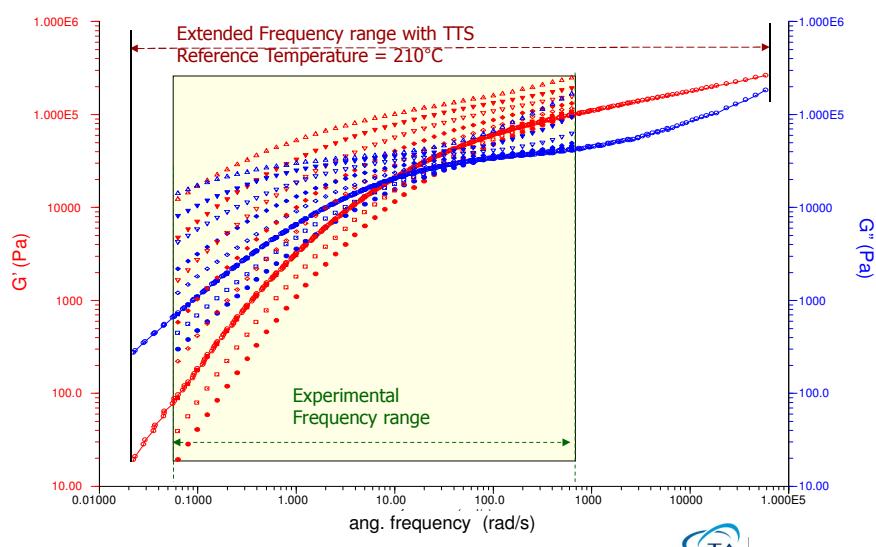
## MWD and Dynamic Moduli



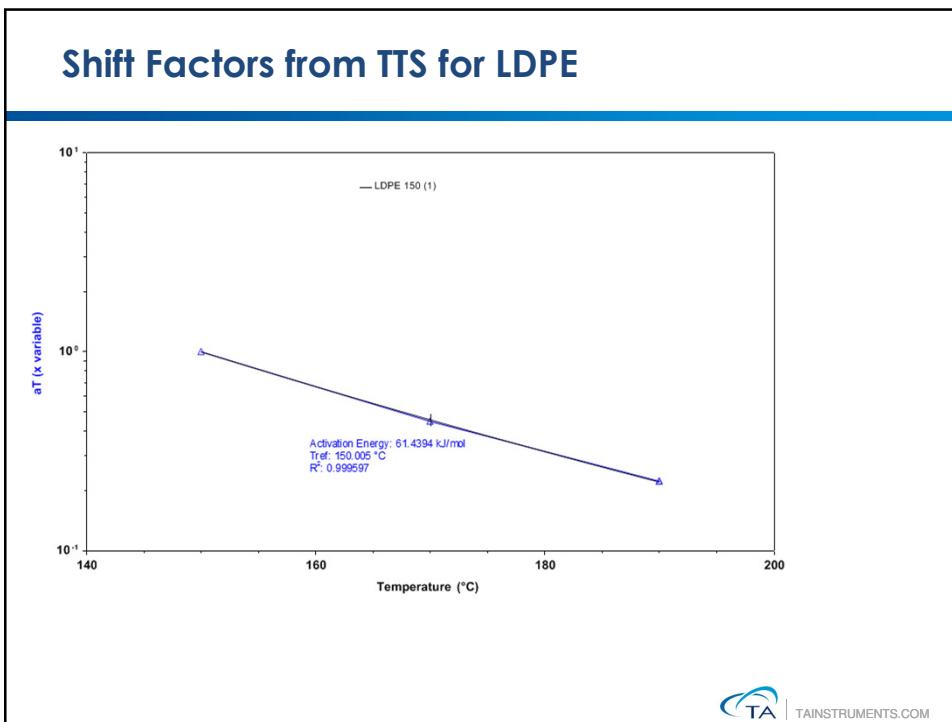
85

## ETC Application: TTS on Polymer Melt

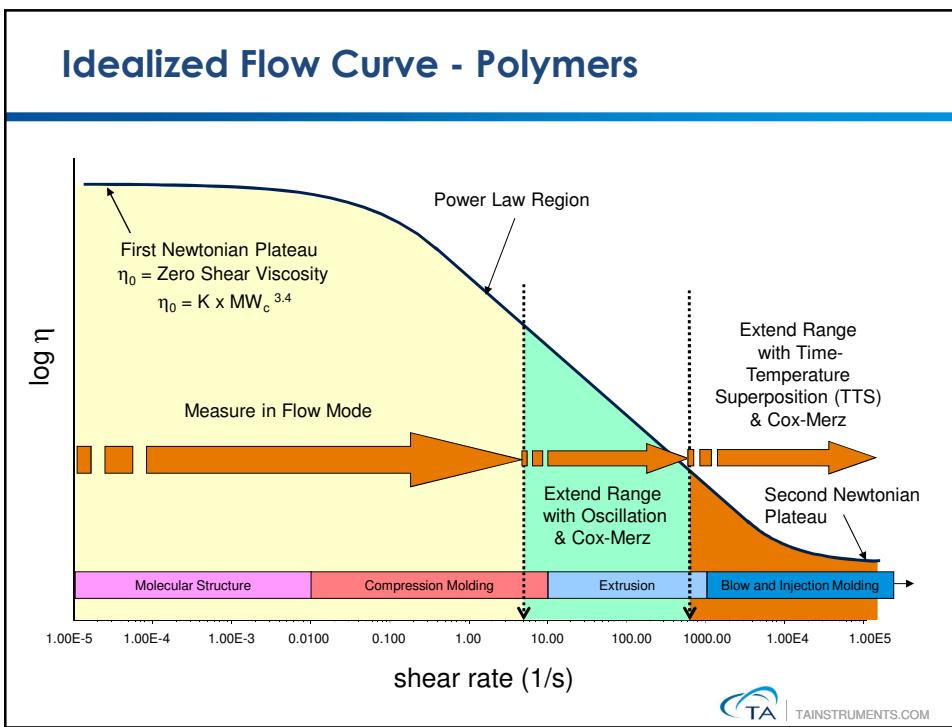
Polystyrene Frequency Sweeps from 160°C to 220°C



86

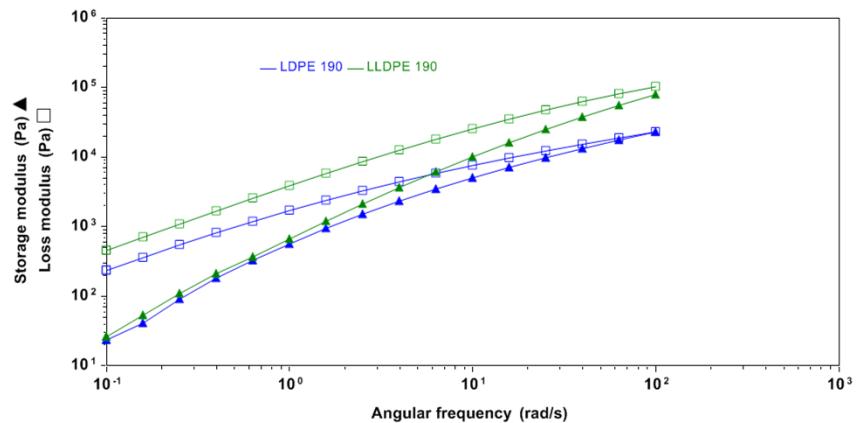


87



88

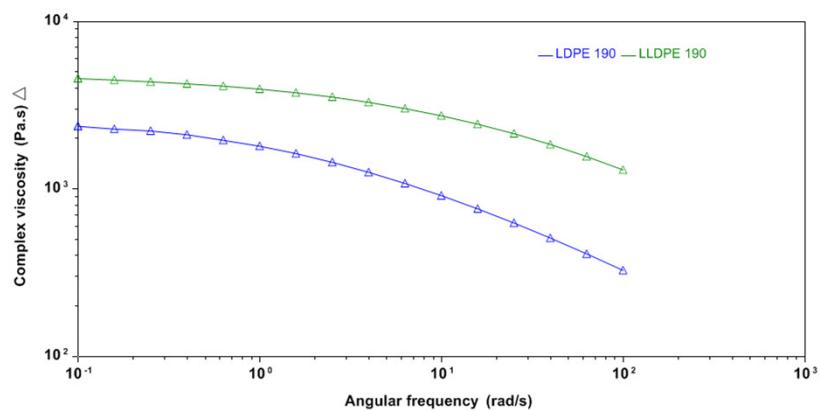
## Example: Dynamic Frequency Sweeps



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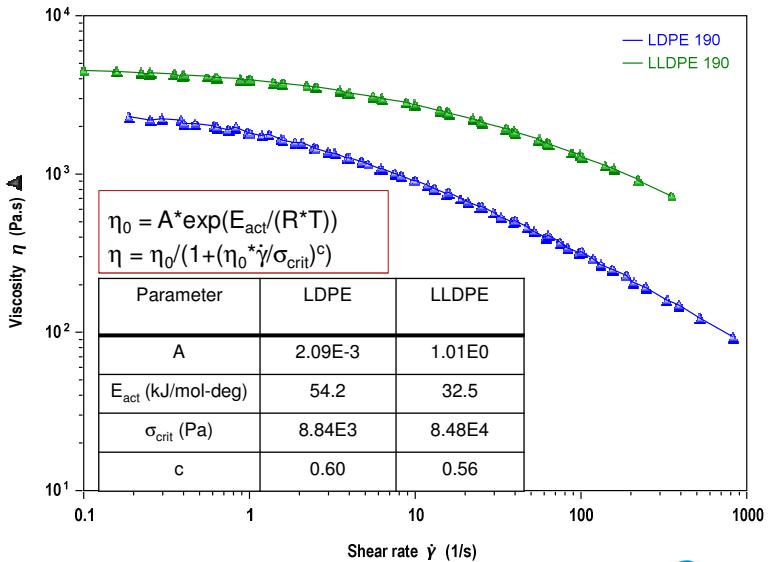
## Dynamic Frequency Sweeps



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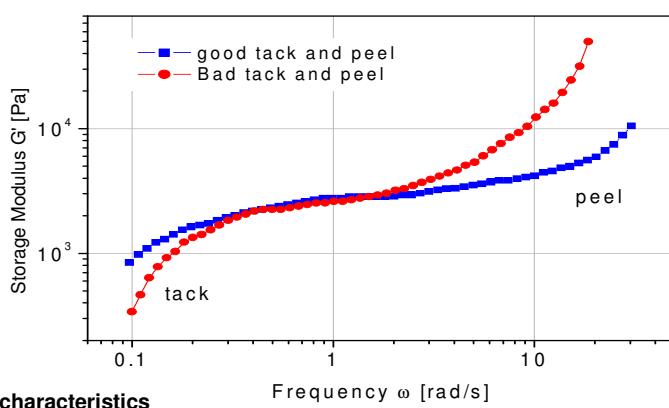
## Fitting Data to Williamson/Arrhenius Models



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## Tack and Peel of Adhesives

Tack and Peel performance of a PSA



**Desirable PSA characteristics**  
 Tack: high G' at low frequency  
 Peel: low G' at high frequency

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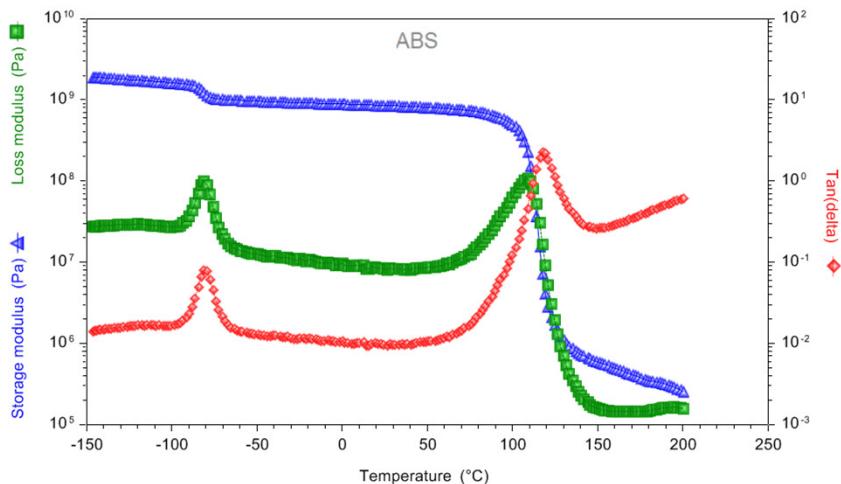
### Correlation of Rheological Parameters to Adhesive Properties

Property	Rheological Properties	Practical Adhesive Property
Tack	<ul style="list-style-type: none"> <li>Low <math>\tan \delta</math> and Low <math>G'</math></li> <li>Low Cross-links (<math>G'' &gt; G' @ \sim 1 \text{ Hz}</math>)</li> </ul>	High Tack
Shear Resistance	<ul style="list-style-type: none"> <li>High <math>G' @ &lt; 0.1 \text{ Hz}</math></li> <li>High Viscosity @ Low Shear Rates</li> </ul>	High Shear Resistance
Peel Strength	<ul style="list-style-type: none"> <li>High <math>G'' @ \sim 100 \text{ Hz}</math></li> </ul>	High Peel Strength
Cohesive Strength	<ul style="list-style-type: none"> <li>High <math>G'</math>, low <math>\tan \delta</math></li> </ul>	High Cohesive Strength
Adhesive Strength	<ul style="list-style-type: none"> <li>High <math>G''</math>, high <math>\tan \delta</math></li> </ul>	High Adhesion Strength with Surface

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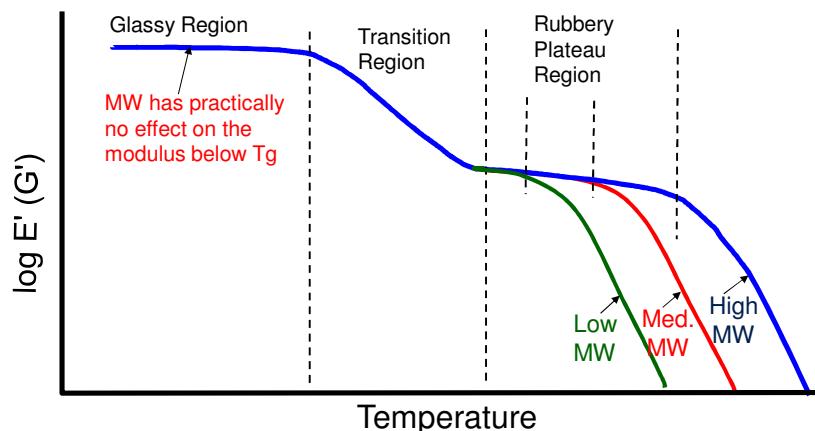
### Dynamic Temperature Ramp - Torsion



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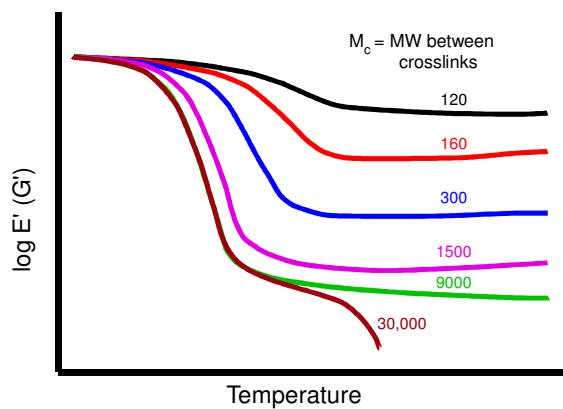
## Effect of Molecular Weight



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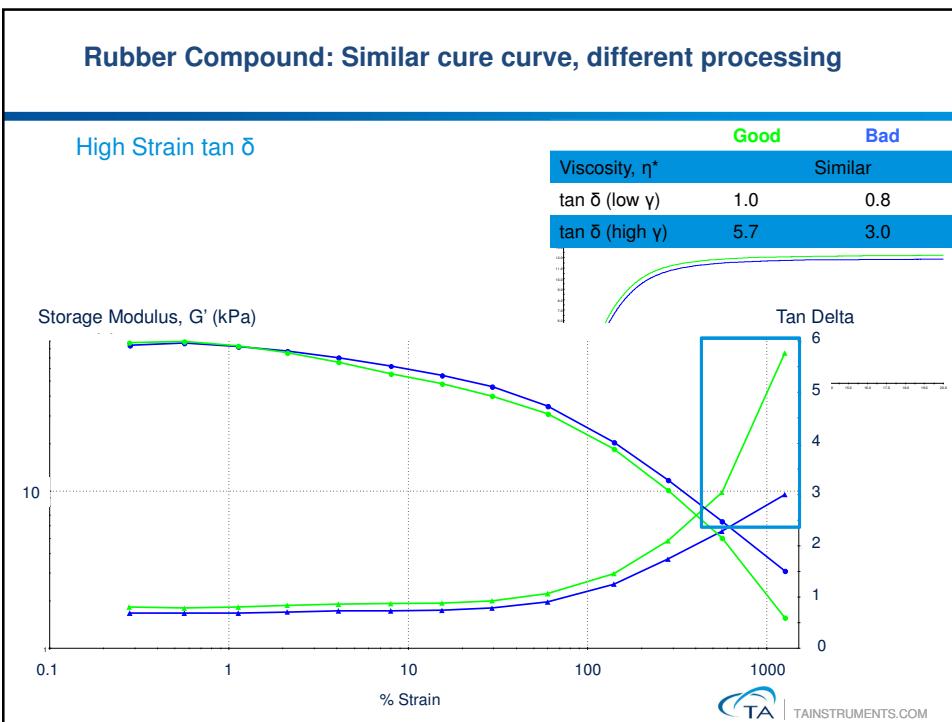
95

## Effect of Crosslinking

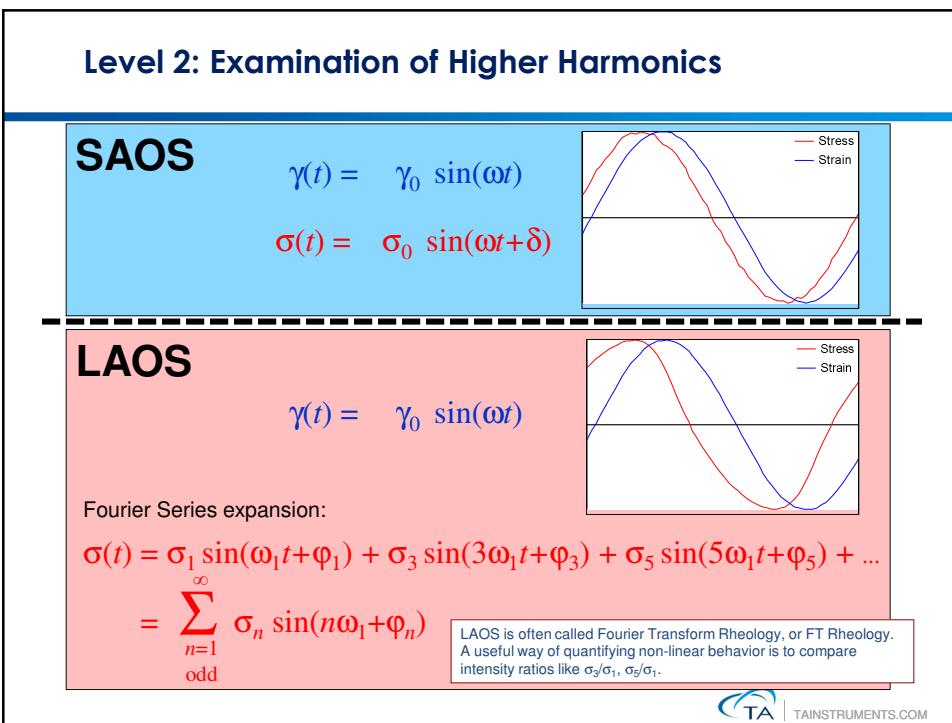


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96

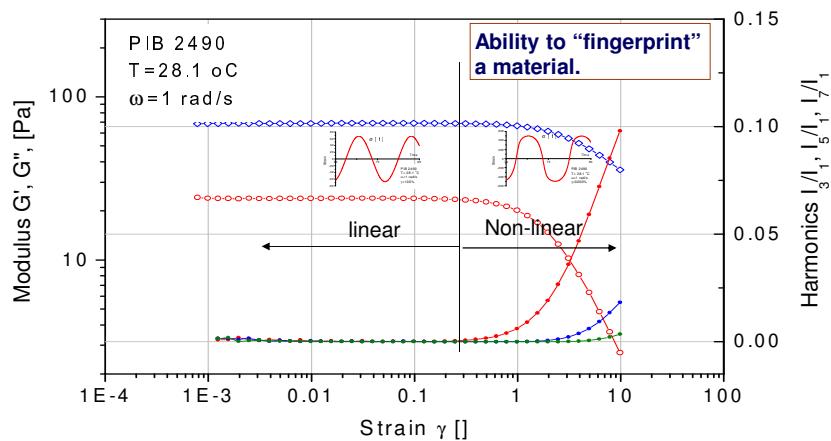


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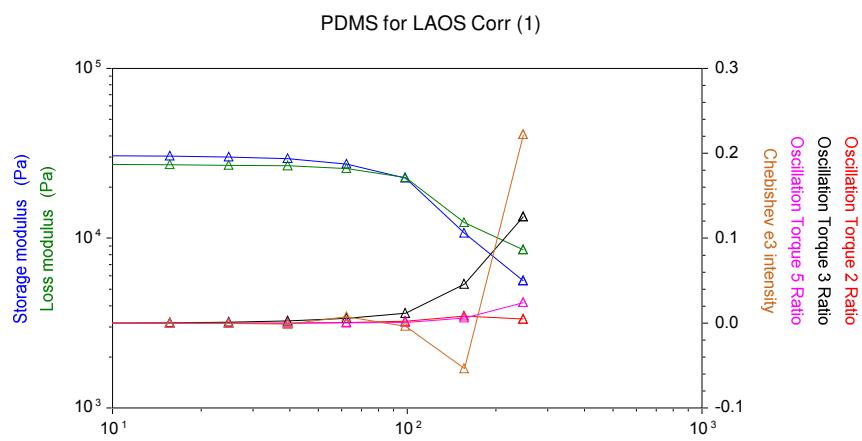
## Large Angle Oscillatory Shear: Higher Harmonics



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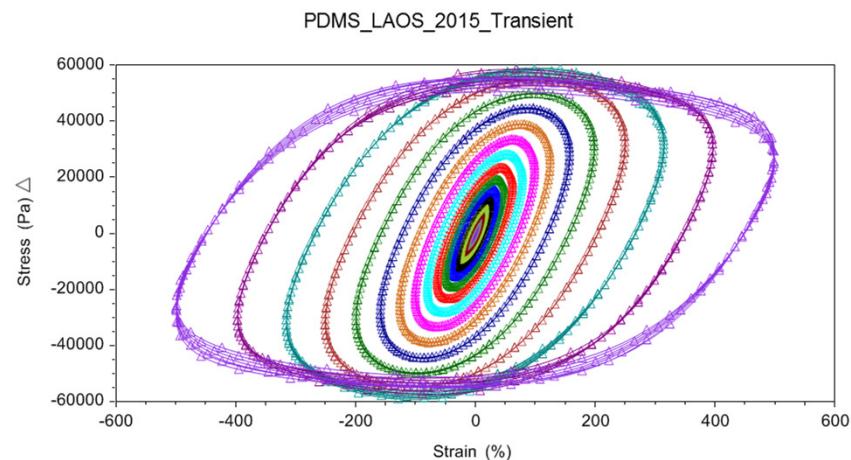
## LAOS on PDMS



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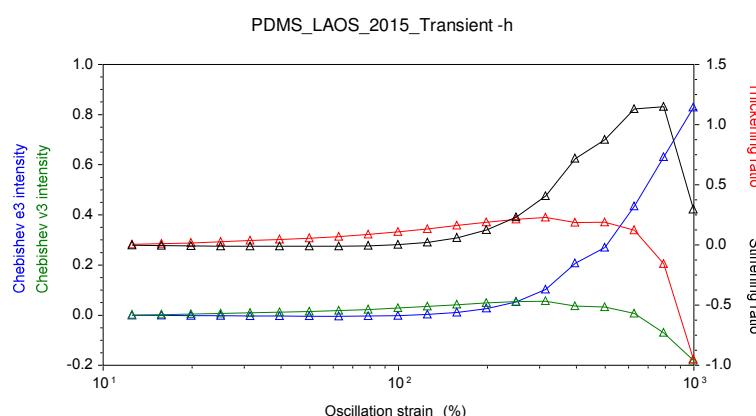
## LAOS with Transient Data Acquisition



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## LAOS with Transient Data Acquisition



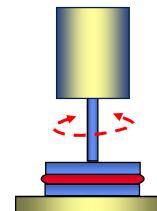
Transient data acquisition with ARES-G2 or DHR-2, DHR-3

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## Dynamic Testing

- Of all the tests performed on a rheometer, dynamic oscillatory testing is the most common. Typically, this is the most convenient way of getting a material's viscous and elastic nature.
- Dynamic Stress or Strain sweeps are useful for determining a dynamic yield point of a material and can suggest strains or stresses to use in subsequent tests, such as frequency sweeps or temperature ramps.
- Dynamic Frequency sweeps are the most useful tests for characterizing polymer melts and adhesives. They provide information on the molecular weight and molecular weight distribution of a material.
- Time temperature superposition can often be used to provide knowledge beyond the usual limits of 0.1 to 100 rad/sec.
- The rheometer can be used as a DMA to provide glass transition temperatures and thermal mechanical integrity.



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## THE RHEOMETERS

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## Five Important Rheometer Specifications

- Torque range
- Angular Resolution
- Angular Velocity Range
- Frequency Range
- Normal Force



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## TA Instruments Rotational Rheometers

Discovery HR Rheometer



Combined Motor and Transducer  
“Native Mode” = Force (Stress)

ARES-G2

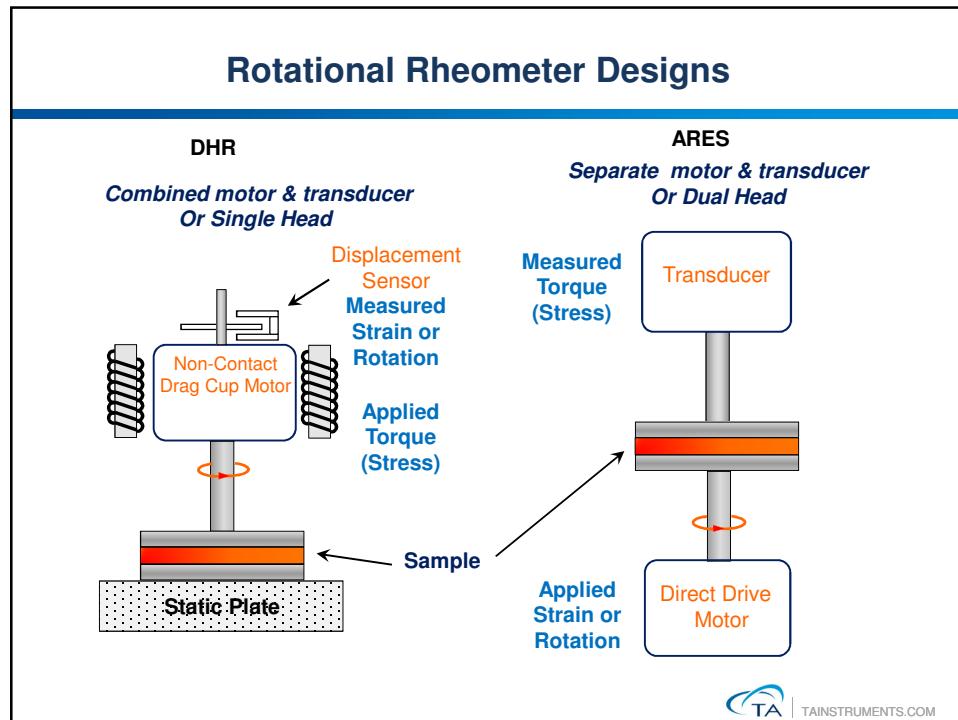


Separate Motor and Transducer  
“Native Mode” = Deformation/Deformation Rate  
(Strain/Shear Rate)

With computer feedback, the instruments can do both,  
deformation/deformation rate control and force control.



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## Discovery Hybrid Rheometer Specifications

Specification	HR-3	HR-2	HR-1
Bearing Type, Thrust	Magnetic	Magnetic	Magnetic
Bearing Type, Radial	Porous Carbon	Porous Carbon	Porous Carbon
Motor Design	Drag Cup	Drag Cup	Drag Cup
Minimum Torque (nN.m) Oscillation	0.5	2	10
Minimum Torque (nN.m) Steady Shear	5	10	20
Maximum Torque (mN.m)	200	200	150
Torque Resolution (nN.m)	0.05	0.1	0.1
Minimum Frequency (Hz)	1.0E-07	1.0E-07	1.0E-07
Maximum Frequency (Hz)	100	100	100
Minimum Angular Velocity (rad/s)	0	0	0
Maximum Angular Velocity (rad/s)	300	300	300
Displacement Transducer	Optical encoder	Optical encoder	Optical encoder
Optical Encoder Dual Reader	Standard	N/A	N/A
Displacement Resolution (nrad)	2	10	10
Step Time, Strain (ms)	15	15	15
Step Time, Rate (ms)	5	5	5
Normal/Axial Force Transducer	FRT	FRT	FRT
Maximum Normal Force (N)	50	50	50
Normal Force Sensitivity (N)	0.005	0.005	0.01
Normal Force Resolution (mN)	0.5	0.5	1

HR-1      HR-2      HR-3

**DHR - DMA mode (optional)**

Motor Control	FRT
Minimum Force (N) Oscillation	0.1
Maximum Axial Force (N)	50
Minimum Displacement (μm) Oscillation	1.0
Maximum Displacement (μm) Oscillation	100
Displacement Resolution (nm)	10
Axial Frequency Range (Hz)	$1 \times 10^{-5}$ to 16

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## DHR Instrument Model Features

All Discovery Hybrid Rheometers Feature:	Moving from HR-1 to HR-2 Adds:	Moving from HR-2 to HR-3 Adds:
<ul style="list-style-type: none"> <li>- Patented Ultra-low Inertia Drag-Cup Motor</li> <li>- Single-Thrust &amp; Dual-Radial Bearing Design</li> <li>- Patented Second Generation Magnetic Bearing</li> <li>- Nano-Torque Motor Control</li> <li>- High-Resolution Optical Encoder</li> <li>- Superior Stress and Strain Control</li> <li>- Force Rebalance Normal Force (FRT)</li> <li>- Patented Smart Swap Geometries</li> <li>- True Position Sensor (Patent Pending)</li> <li>- Ultra-low Compliance Single-Piece Frame</li> <li>- Heat and vibration Isolated Electronics Design</li> <li>- Smart Swap™ Temperature Systems</li> <li>- Superior Peltier Technology</li> <li>- Patented Heat Spreader Technology</li> <li>- Patented Active Temperature Control</li> <li>- Color Display</li> <li>- Capacitive Touch Keypad</li> <li>- TRIOS Software</li> <li>- Navigator Software</li> <li>- Electronic Bearing Lock</li> <li>- NIST Traceable Torque Calibration</li> </ul>	<ul style="list-style-type: none"> <li>- 5X better low torque in Oscillation</li> <li>- 2X better low torque in steady Shear</li> <li>- 25% Higher torque</li> <li>- 2X better NF Sensitivity</li> <li>- Direct Strain Oscillation</li> <li>- Fast data sampling</li> <li>- Transient Data Acquisition/LAOS</li> <li>- Stress Growth (Transient NF)</li> <li>- Access to UV Curing Options</li> <li>- Access to SALS Option</li> <li>- Access to Interfacial Options</li> </ul>	<ul style="list-style-type: none"> <li>- 4X better low torque in Oscillation</li> <li>- 2X better low torque in steady Shear</li> <li>- Optical Encoder Dual Reader (pat. Pend.)</li> <li>- 5X better angular resolution</li> <li>- 3X better phase angle resolution</li> <li>- No encoder drift</li> </ul>



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## ARES-G2 Rheometer Specifications

Force/Torque Rebalance Transducer (Sample Stress)	
Transducer Type	Force/Torque Rebalance
Transducer Torque Motor	Brushless DC
Transducer Normal/Axial Motor	Brushless DC
Minimum Torque ( $\mu$ N.m) Oscillation	0.05
Minimum Torque ( $\mu$ N.m) Steady Shear	0.1
Maximum Torque (mN.m)	200
Torque Resolution (nN.m)	1
Transducer Normal/Axial Force Range (N)	0.001 to 20
Transducer Bearing	Groove Compensated Air



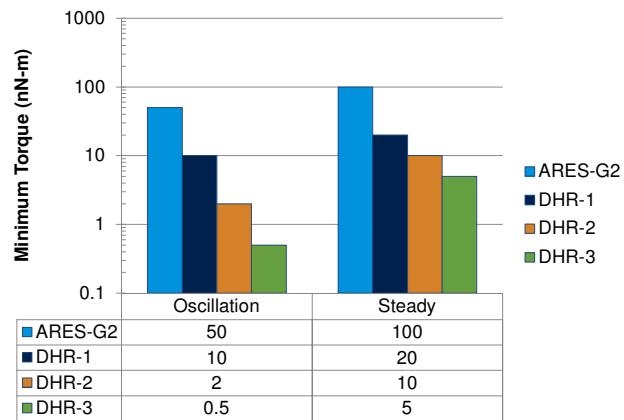
Driver Motor (Sample Deformation)	
Maximum Motor Torque (mN.m)	800
Motor Design	Brushless DC
Motor Bearing	Jeweled Air, Sapphire
Displacement Control/ Sensing	Optical Encoder
Strain Resolution ( $\mu$ rad)	0.04
Minimum Angular Displacement ( $\mu$ rad) Oscillation	1
Maximum Angular Displacement ( $\mu$ rad) Steady Shear	Unlimited
Angular Velocity Range (rad/s)	$1 \times 10^{-6}$ to 300
Angular Frequency Range (rad/s)	$1 \times 10^{-7}$ to 628
Step Change, Velocity (ms)	5
Step Change, Strain (ms)	10

Orthogonal Superposition (OSP) and DMA modes	
Motor Control	FRT
Minimum Transducer Force (N) Oscillation	0.001
Maximum Transducer Force (N)	20
Minimum Displacement ( $\mu$ m) Oscillation	0.5
Maximum Displacement ( $\mu$ m) Oscillation	50
Displacement Resolution (nm)	10
Axial Frequency Range (Hz)	$1 \times 10^{-5}$ to 16

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## Minimum Torque Specs



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## SELECTED ACCESSORIES

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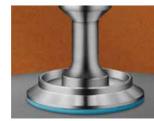
## DHR Accessories – Visual Display



Peltier Plate  
Temperature Systems



Advanced Peltier Plate



Dual Stage Peltier Plate



Upper Heated Plate for  
Peltier Plate



Peltier Concentric  
Cylinders



Electrically Heated  
Cylinder (EHC)



Pressure Cell



Electrically Heated  
Plates



Environmental Test  
Chamber



Relative Humidity  
Accessory



Modular Microscope  
(MMA)



Optical Plate

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updated list of  
accessories on our  
website,  
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## DHR Accessories – Visual Display



Small Angle Light  
Scattering



Interfacial Accessories



Tribo-Rheometry  
Accessory



Magneto-Rheology



Electro-Rheology



UV Curing Accessories



Dielectric Measurement



Immobilization Cell



Starch Pasting Cell



Dynamic Mechanical  
Analysis

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## ARES-G2 Accessories



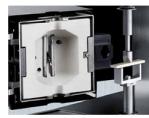
Forced Convection Oven  
(FCO)



Advanced Peltier  
System (APS)



Orthogonal  
Superposition & 2D-  
SAOS



Dynamic Mechanical  
Analysis (DMA)



UV Curing Accessory



Dielectric Thermal  
Analysis Accessory  
(DETA)



Extensional Viscosity  
Fixture (EVF)



Tribo-Rheometry  
Accessory



Air Chiller System



Cone and Partitioned  
Plate Accessory



Interfacial Rheology



Electrorheology (ER)  
Accessory

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## DMA Capabilities



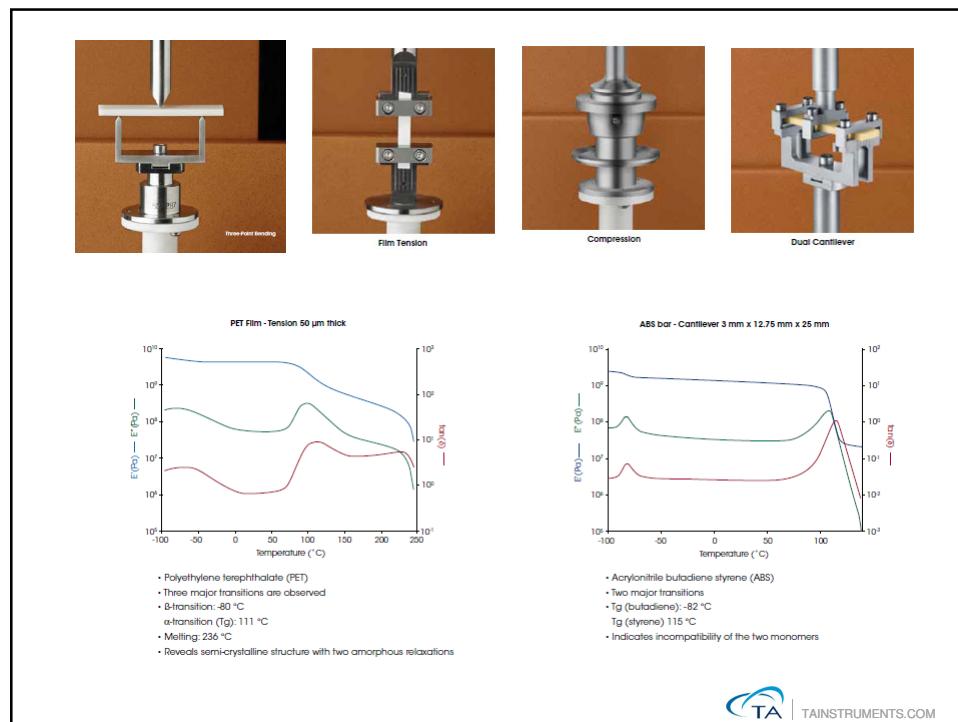
Motor Control	Force Rebalance Transducer
Minimum Force in Oscillation	0.1 N
Maximum Axial Force	50 N
Minimum Displacement in Oscillation	1 µm
Maximum Displacement in Oscillation	100 µm
Displacement Resolution	10 nm
Axial Frequency Range	1×10 <sup>-5</sup> to 16 Hz

- DHR Film/Fiber Tension Clamp Accessory kit
- DHR 3-Point Bending Clamp Accessory kit
- DHR Cantilever Bending Clamp Accessory kit

The DMA capabilities of the DHR and ARES-G2 are unique for commercial rheometers.

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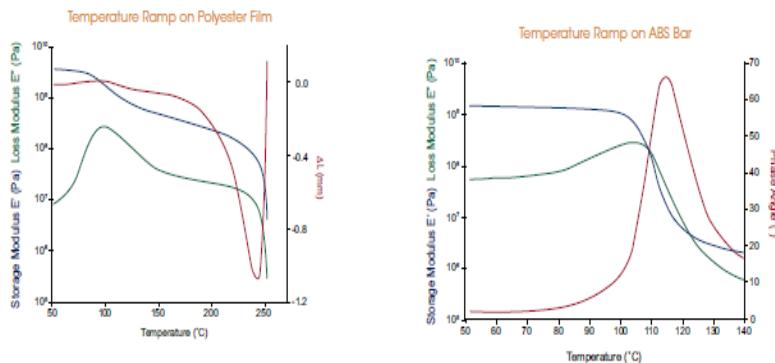


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## ARES-G2 DMA Testing



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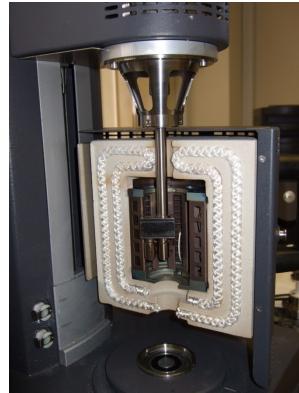
## DMA Specifications

	RSA G2	DMA 850	ARES G2 DMA	DHR DMA (optional)
Max Force	35N	18N	20N	50N
Min Force	0.0005N	0.0001N	0.001N	0.1N
Frequency Range	1e-5 to 628 rad/s (1.6e-6 to 100 Hz)	6.28e-3 to 1250 rad/s (0.001 to 200 Hz)	6.3e-5 to 100 rad/s (1.0e-5 to 16 Hz)	6.3e-5 to 100 rad/s (1.0e-5 to 16 Hz)
Dynamic Deformation Range	+/- 0.05 to 1,500μm	+/- 0.005 to 1e4 μm	+/- 1 to 50 μm	+/- 1 to 100 μm
Control Stress/Strain	Control Strain (SMT)	Control Stress (CMT)	Control Strain (CMT)	Control Stress (CMT)
Heating Rate	0.1°C to 60°C/min	0.1°C to 20°C/min	0.1°C to 60°C/min	0.1°C to 60°C/min
Cooling Rate	0.1°C to 60°C/min	0.1°C to 20°C/min	0.1°C to 60°C/min	0.1°C to 60°C/min

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## SER2 for DHR Rheometers

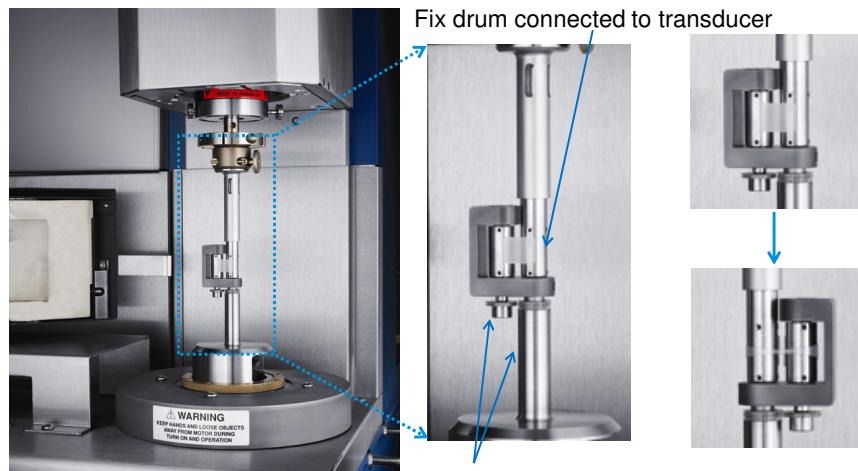


This is an interesting application of using the rotational rheometer to determine elongational viscosity

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## Extensional Viscosity Measurements



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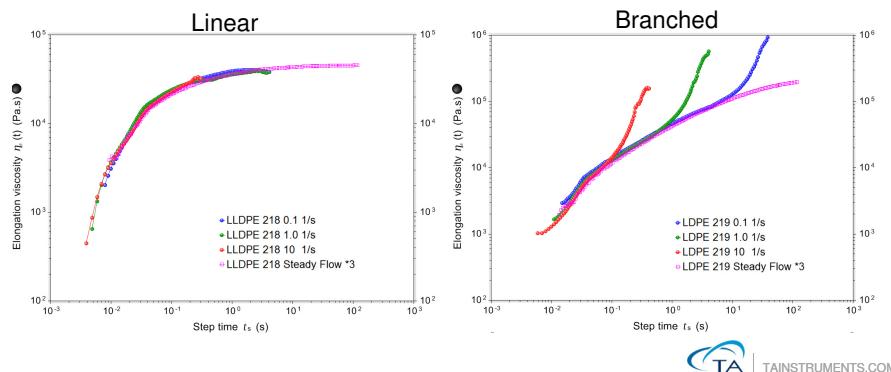
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## Extensional Viscosity

- Extensional rheology is very sensitive to polymer chain entanglement. Therefore it is sensitive to LCB
- The measured extensional viscosity is 3 times of steady shear viscosity

$$\eta_E = 3 \times \eta_0$$

- LCB polymer shows strain hardening effect



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## UV Light Guide Curing Accessory



- Collimated light and mirror assembly insure uniform irradiance across plate diameter
- Maximum intensity at plate 300 mW/cm<sup>2</sup>
- Broad range spectrum with main peak at 365 nm with wavelength filtering options
- Cover with nitrogen purge ports
- Optional disposable acrylic plates

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## UV LED Curing Accessory



- Mercury bulb alternative technology
- 365 nm wavelength with peak intensity of 150 mW/cm<sup>2</sup>
- 455 nm wavelength with peak intensity of 350 mW/cm<sup>2</sup>
- No intensity degradation over time
- Even intensity across plate diameter
- Compact and fully integrated design including power, intensity settings and trigger
- Cover with nitrogen purge ports
- Optional disposable Acrylic plates

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## UV Curing Procedure

▲ Procedure: Proposed UV cure test

1: Conditioning Options

Axial force adjustment

Mode	Active
<input checked="" type="radio"/> Tension	<input type="radio"/> Compression
Axial force	0.0 N
Sensitivity	0.2 N
<input type="checkbox"/> Compensate for stiffness changes	
<input type="button" value="Advanced"/>	

Auto strain adjustment

Mode	Disabled
------	----------

2: Conditioning UV Curing

UV Shutter Control

UV power level	25.0 %
Delay before UV shutter open	00:00:30 hh:mm:ss
UV shutter open time	00:00:10 hh:mm:ss

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## UV Curing Procedure

**3: Oscillation Time**

Environmental Control  
Temperature: 25 °C    Inherit Set Point  
Soak Time: 00:00:00 hh:mm:ss    Wait For Temperature

Test Parameters  
Duration: 00:00:25 hh:mm:ss  
Sampling interval: 5.0 s/pt  
Strain %: 10.0 %  
Single point  
Frequency: 10.0 Hz

**5: Oscillation Time**

Environmental Control  
Temperature: 25 °C    Inherit Set Point  
Soak Time: 00:00:00 hh:mm:ss    Wait For Temperature

Test Parameters  
Duration: 00:01:00 hh:mm:ss  
Sampling interval: 5.0 s/pt  
Strain %: 0.05 %  
Single point  
Frequency: 10.0 Hz

**4: Oscillation Fast Sampling**

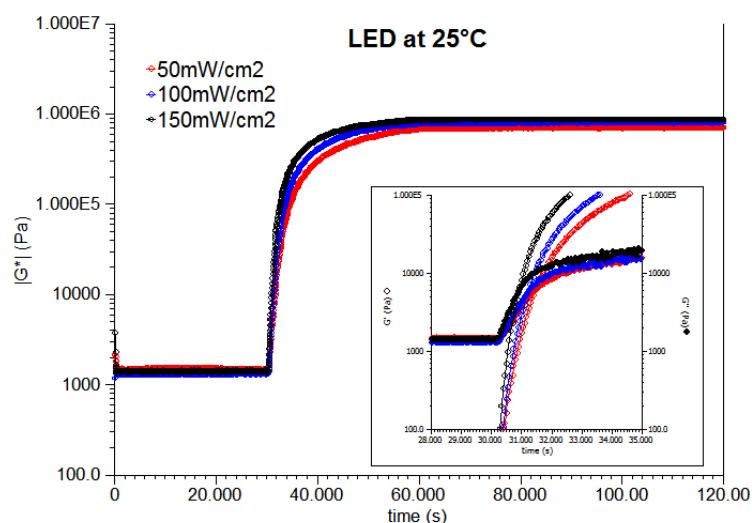
Environmental Control  
 Isothermal    Ramp  
Temperature: 25 °C    Inherit set point  
Soak time: 00:00:00 hh:mm:ss    Wait for temperature

Test Parameters  
Duration: 00:00:40 hh:mm:ss  
Sampling rate: 20.0 pts/s  
Strain %: 0.05 %  
Single point  
Frequency: 10.0 Hz

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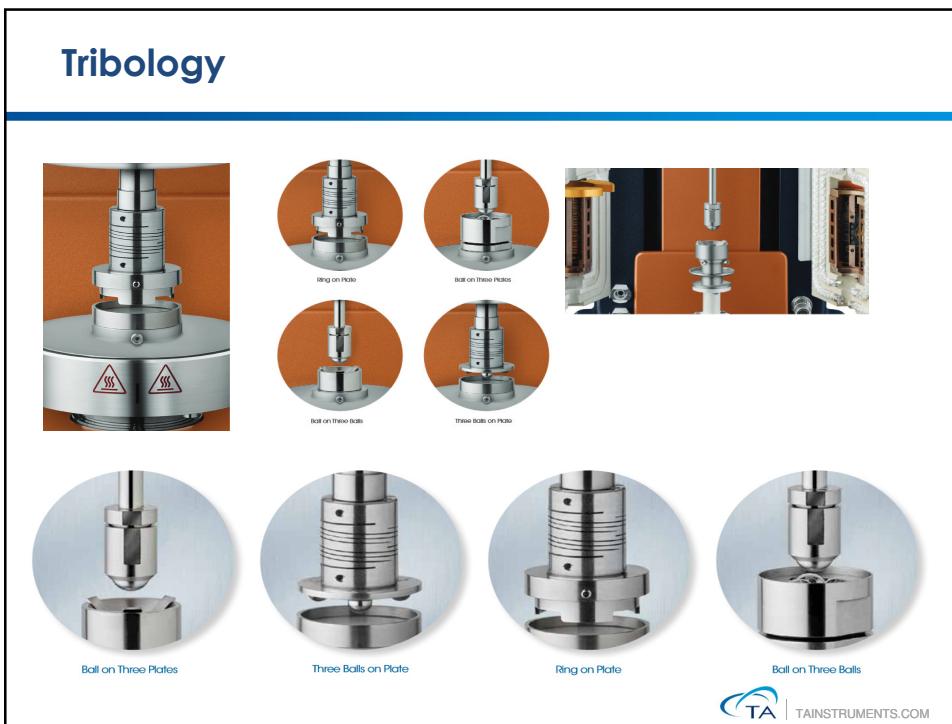
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## UV Cure Profile Changes with Intensity

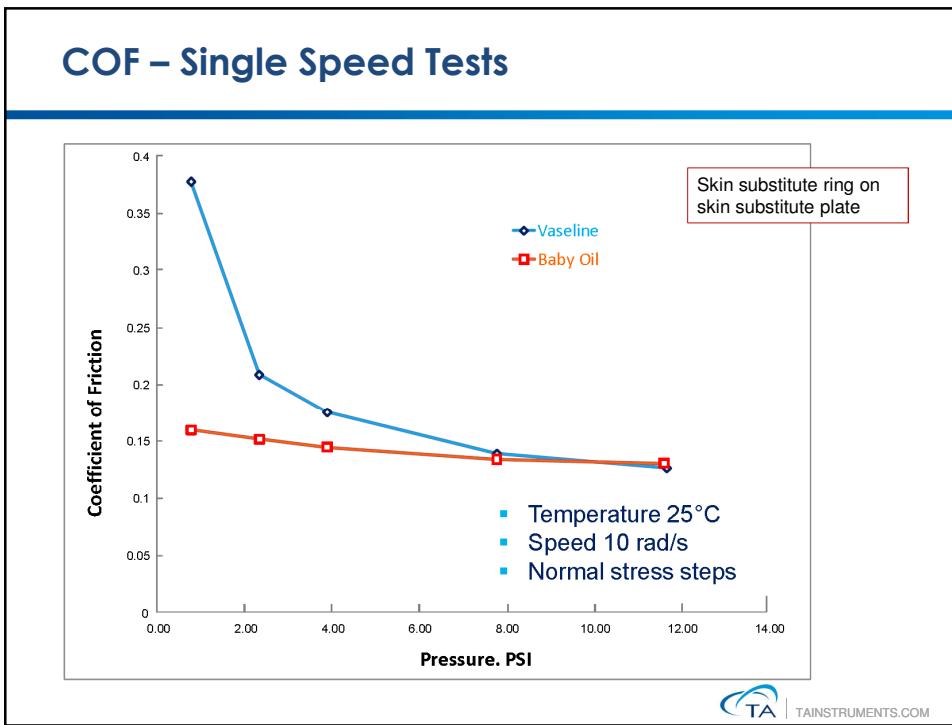


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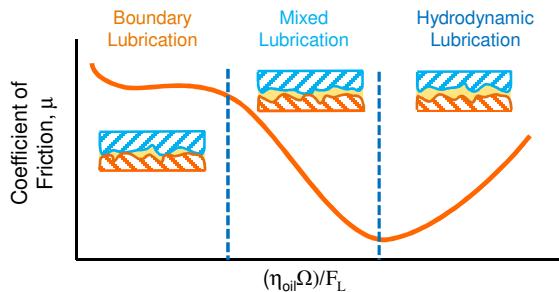


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## Tribology of Lubricated Systems



- In lubricated systems, the 'Stribeck curve' captures influence of lubricant viscosity( $\eta_{oil}$ ), rotational velocity ( $\Omega$ ) and contact load ( $F_L$ ) on  $\mu$
- At low loads, the two surfaces are separated by a thin fluid film (gap, d) with frictional effects arising from fluid drag (**Hydrodynamic Lubrication**)
- At higher loads, the gap becomes smaller and causes friction to go up (**Mixed Lubrication**)
- At extremely high loads, there is direct solid-solid contact between the surface asperities leading to very high friction (**Boundary Lubrication**)

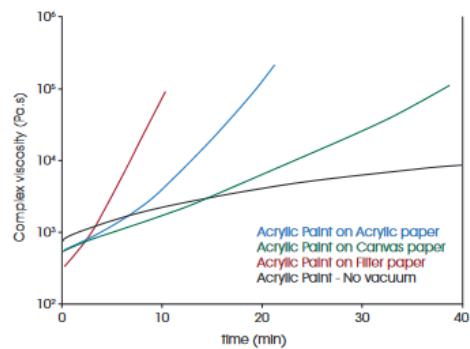
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## DHR Immobilization Cell

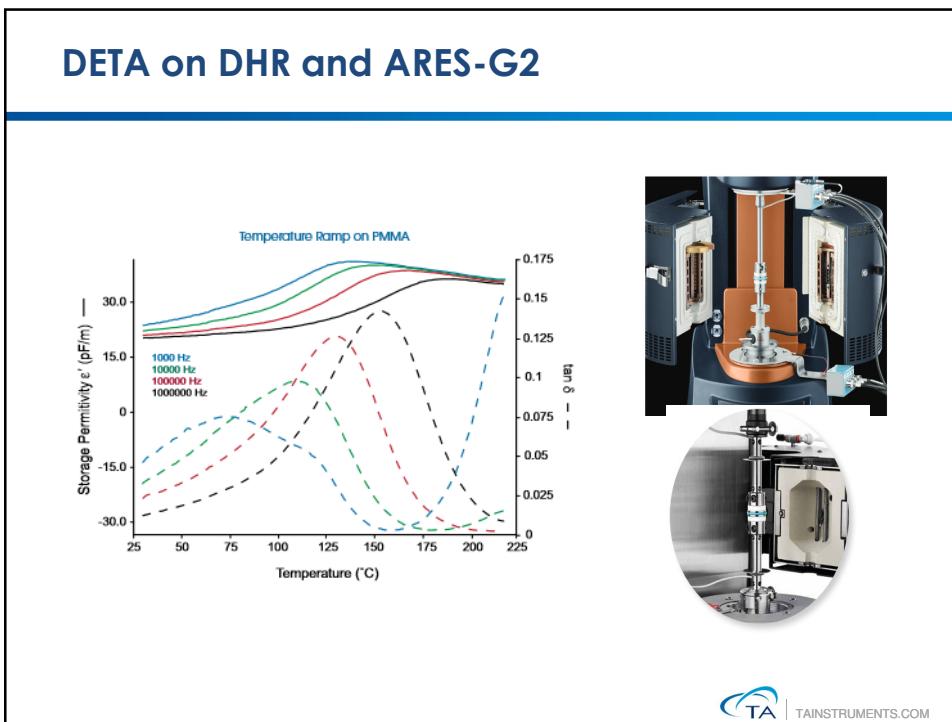


Acrylic Paint Drying

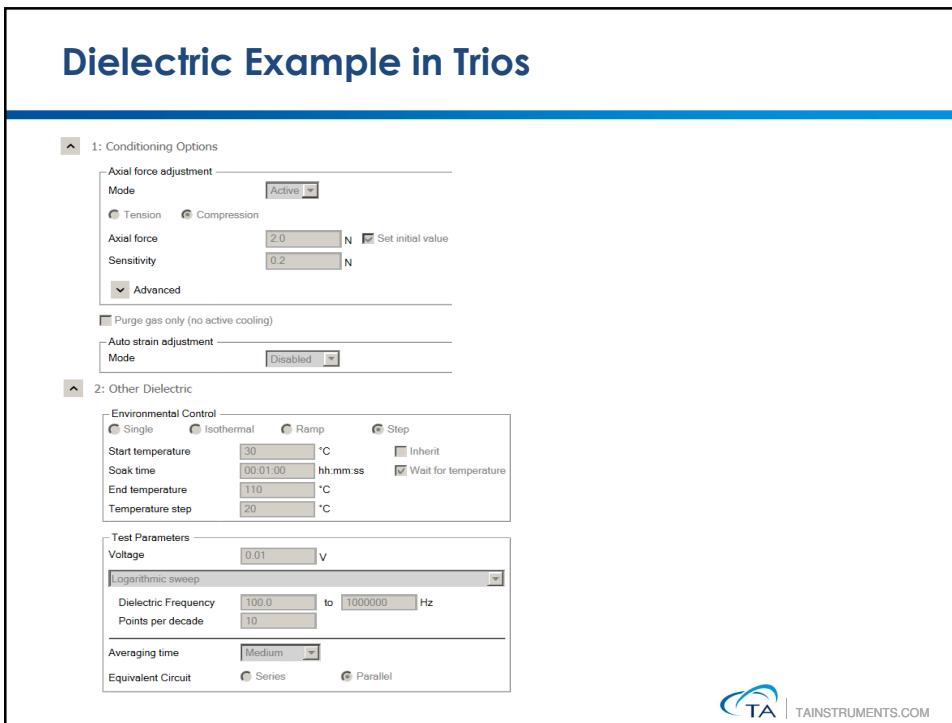


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## Interfacial Rheology

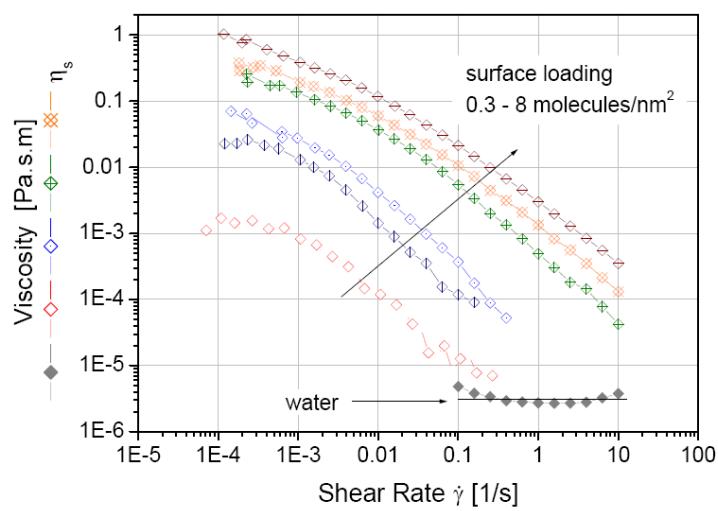


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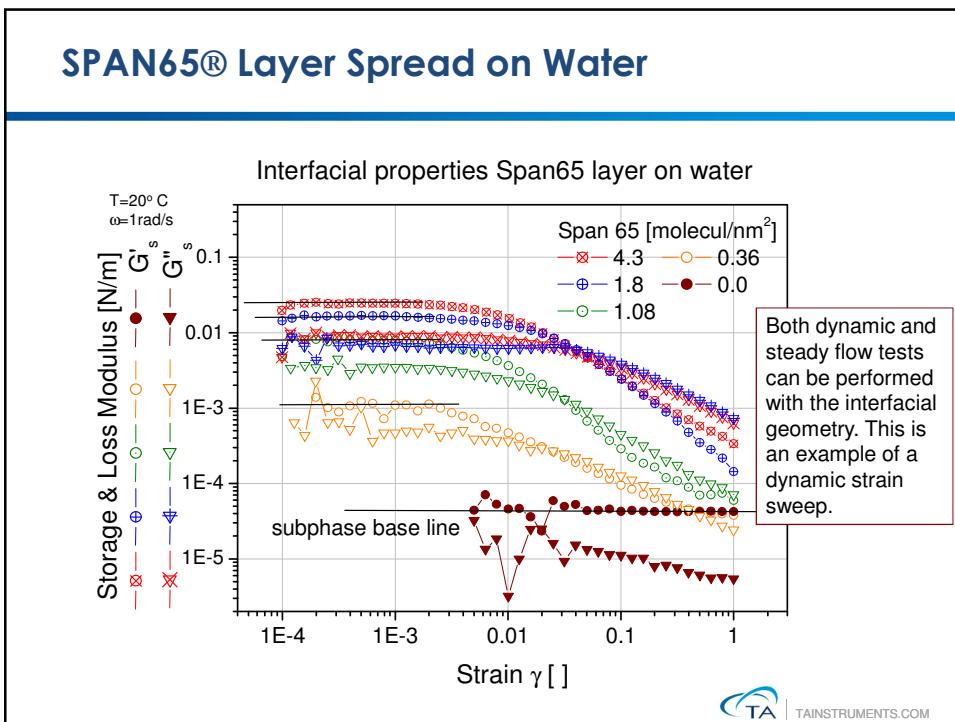
## Surface Concentration Effects on Interfacial Viscosity

Surface viscosity of Span 65 layer deposited on water

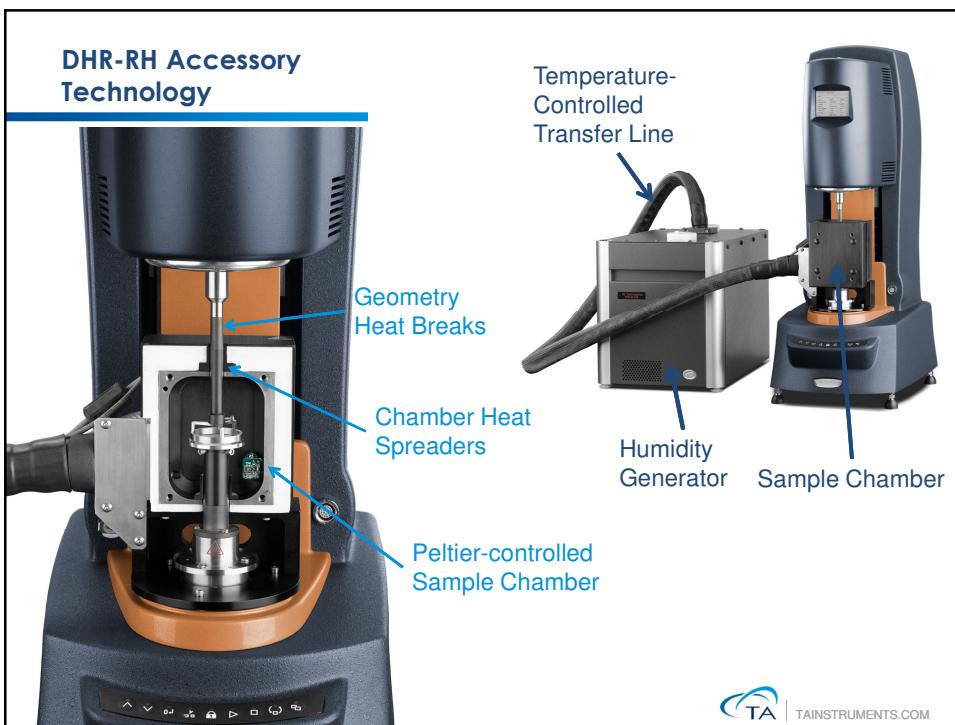


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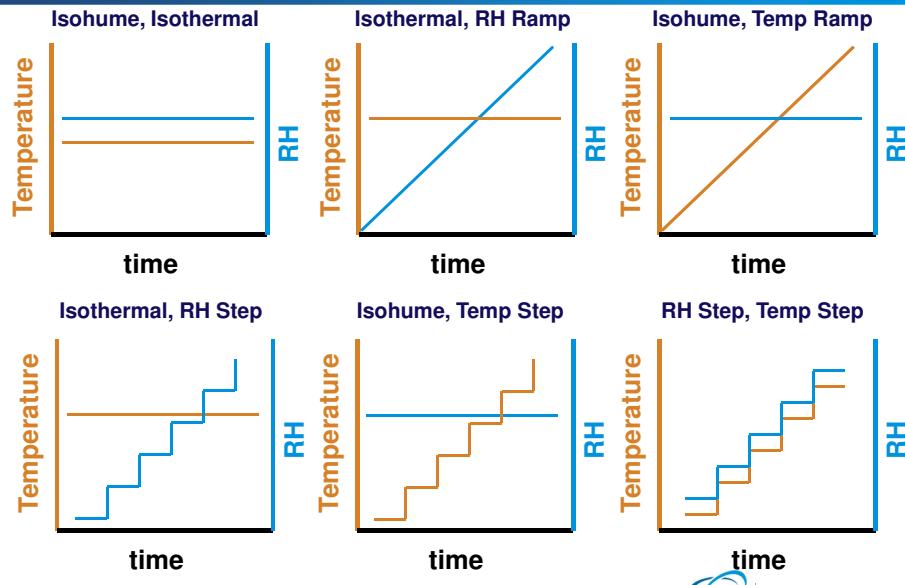


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## DMA-RH Experimental Options

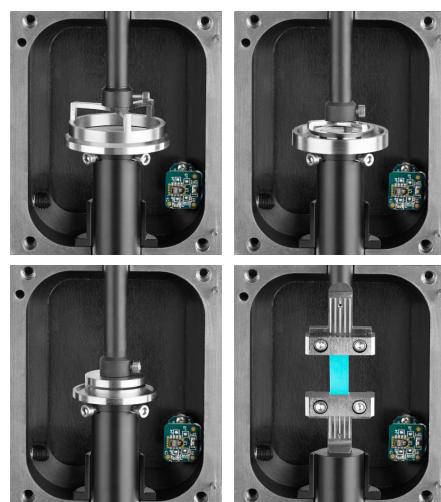


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## Test Geometries

- Wide variety of test geometries:
  - Standard parallel plate
  - Disposable parallel plate
  - Annular Ring
  - Surface Diffusion
  - Rectangular Torsion
- Innovative geometries for RH: true humidity-dependent rheology, not dominated by diffusion
- True Axial DMA:
  - Film Tension
  - Three-point Bending

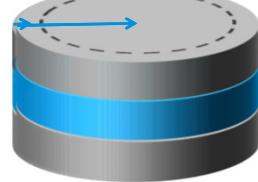


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## Annular Ring Geometry

Diffusion



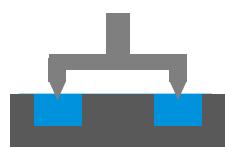
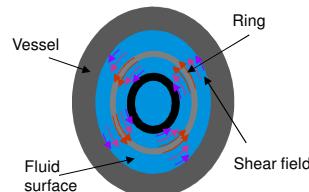
- Parallel plate: long diffusion length
- Remove center section
- Annular ring: short diffusion length
- Provides quantitative bulk rheology with less delay and gradients associated with diffusion



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## Surface Diffusion Geometry



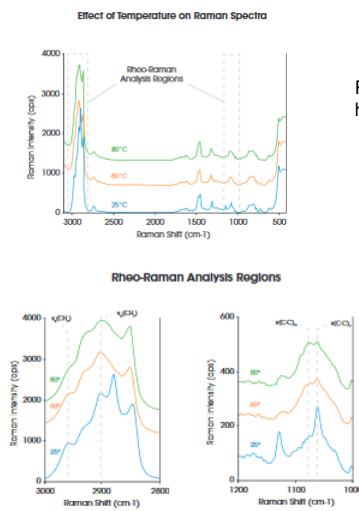
- Surface rheological properties and process kinetics
- Very simple sample loading
- Ideal for:
  - Fast evolving systems
  - Samples with shallow interaction depth
  - Drying, curing...



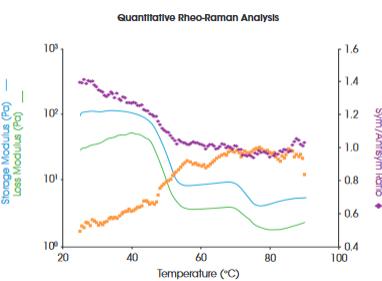
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## Rheo-Raman Accessory



Rheo-Raman on a hand lotion



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## Need Some Assistance?

- Instrument Manuals
- Help Feature in Trios
- TA Instruments website
- TA Instruments Rheology Helpline
  - [rsupport@tainstruments.com](mailto:rsupport@tainstruments.com)

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## DHR Quick Start Guide

**DHR Temperature Control Systems**

Peltier Plate -40 to 200 °C  
Concentric Cylinder -20 to 150 °C  
Upper Heated Plate (UHP) -30 to 150 °C  
Electrically Heated Plate (EHP) -70 to 400 °C  
Environmental Test Chamber (ETC) -160 to 600 °C

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### TRIOS QuickStart Guide – Basic Data Analysis Applications in Rheology

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