## Vision

Linus Berglund<sup>1</sup>, Johannes Edenholm<sup>1</sup>, Hugo Frost<sup>1</sup>, Hamza Kadric<sup>1</sup>, Johan Svennungsson<sup>2</sup>, Rikard Teodorsson<sup>2</sup>, Timmy Truong<sup>1</sup>, Arvid Wiklund<sup>1</sup> och Karl Ängermark<sup>1</sup>

<sup>1</sup>DAT255 - Software Engineering Project, högskoleingenjörsprogrammet i datateknik, Chalmers tekniska högskola <sup>2</sup>DAT255 - Software Engineering Project, civilingenjörsprogrammet i informationsteknik, Chalmers tekniska högskola

September 8, 2017

## Vision

We want to create a software solution to further assist in the development of autonomous vehicle functionality. The platooning MOPED is an autonomous vehicle. We have the opportunity to work alongside other groups, exploring how vehicles with different software interacts. The final goal is to achieve a level of sophistication where the MOPED can participate in a platooning line of vehicles. This is a unique opportunity because of the scope and resources available.