7 SUPPLEMENT TO "ESTIMATING GRAPHLETS VIA LIFTING"

7.1 **Proof of Prop. 3.1.**

PROOF. Let ϕ_i be as defined in (12), (13). For both estimators, because of the form of (5) and (6), if a single term ϕ_i is unbiased then \hat{N}_m is as well. Let us begin with $\hat{N}_{O,m}$, by considering a draw from the lifting process, $A = [v_1, \ldots, v_k]$ which induces the k-subgraph, G|A. By the definition of $\tilde{\pi}$,

$$\mathbb{E}\left(\phi_{O,1}\right) = \sum_{A \in V_G^k} \tilde{\pi}(A) \left(\frac{\mathbb{1}(T(A) \sim H_m)}{\operatorname{co}(T(A))\tilde{\pi}(A)}\right)$$
$$= \sum_{T \in \mathcal{V}_k} \sum_{A \in V_G^k: T(A) = T} \frac{\mathbb{1}(T \sim H_m)}{\operatorname{co}(T)} = \sum_{T \in \mathcal{V}_k} \mathbb{1}(T \sim H_m) = N_m.$$

Hence, the $\hat{N}_{O,m}$ is unbiased. Consider the shotgun estimator, $\hat{N}_{S,m}$,

$$\mathbb{E}\left(\phi_{S,1}\right) = \sum_{B \in V_G^{k-1}} \tilde{\pi}(B) \sum_{u \in \mathcal{N}_{\upsilon}(B)} \left(\frac{\mathbb{1}(G|B \cup \{u\} \sim H_m)}{\operatorname{co}(H_m)\tilde{\pi}(B)}\right)$$

$$= \sum_{T \in \mathcal{V}_k} \sum_{B \in V_G^{k-1}} \mathbb{1}(G|B \cup \{u\} = T, u \in \mathcal{N}_{\upsilon}(B)) \frac{\mathbb{1}(T \sim H_m)}{\operatorname{co}(T)}$$

$$= \sum_{T \in \mathcal{V}_k} \mathbb{1}(T \sim H_m) = N_m.$$

Hence, the shotgun estimator is unbiased as well.

7.2 Proof of Theorem 4.1.

We can bound the variance in (11) by the second moment, which is bounded by,

$$\mathbb{E}\phi_1^2 \leq \mathbb{E}\phi_1 \max \phi_1 = N_m(G) \max \phi_1$$
.

Seeking to control the the maximum of ϕ_1 , we see that,

$$\max_{T} \frac{1}{\pi_{U}(T)} \leq \max_{A} \frac{1}{|\text{co}(T)|\tilde{\pi}(A)} \leq \max_{T} \frac{\prod_{r=1}^{k-1} (d_{1} + \ldots + d_{r})}{|\text{co}(H_{m})| \pi_{1}(d_{1})},$$

$$\max_{B} \frac{|\mathcal{N}_{v}(B)|}{|\operatorname{co}(H_{m})|\tilde{\pi}(B)} \leq \max \frac{\prod_{r=1}^{k-1} (d_{1} + \ldots + d_{r})}{|\operatorname{co}(H_{m})|\pi_{1}(d_{1})}.$$

Thus, we can construct a bound on $V_m^{\perp}(\phi_1)$.

7.3 Proof of Theorem 4.4

Let ϕ_i be as defined in (12), (13) or (14). Given two starting vertices v_i and v_j of the lifting process, notice that random variables $\phi_i|v_i$ and $\phi_j|v_j$ are independent. Therefore

$$\mathbb{E}(\phi_{i}\phi_{i+1})) = \mathbb{E}_{\pi_{1}(v_{i})\times\pi_{1}(v_{i+1})}\mathbb{E}(\phi_{i}\phi_{i+1}|v_{i},v_{i+1}) = \\ \mathbb{E}_{\pi_{1}(v_{i})\times\pi_{1}(v_{i+1})}(\mathbb{E}(\phi_{i}|v_{i})\mathbb{E}(\phi_{i+1}|v_{i+1})).$$

Using the equation above, we can bound the covariance of ϕ_i and ϕ_{i+1} with basic inequalities:

$$\begin{split} |\text{Cov}\,(\phi_i,\phi_{i+1})| &\leq \\ \sum_{x_1,x_2 \in V_G} \mathbb{E}(\phi_i|v_i = &x_1) \mathbb{E}\left(\phi_{i+1}|v_{i+1} = x_2\right) \\ & |\mathbb{P}(v_i = x_1,v_{i+1} = x_2) - \pi_1(x_1)\pi_1(x_2)| \leq \\ \max_{x_2 \in V_G} \mathbb{E}(\phi_{i+1}|v_{i+1} = x_2) \sum_{x_1} \mathbb{E}\left(\phi_i|v_i = x_1\right) \\ \max_{x_1} \sum_{x_2} |\mathbb{P}(v_i = x_1,v_{i+1} = x_2) - \pi(x_1)\pi(x_2)| &= \\ 2\gamma_{G_V}(h) \max_{x_2} \mathbb{E}\left(\phi_{i+1}|v_{i+1} = x_2\right) \sum_{x_2} \mathbb{E}\left(\phi_i|v_i = x_1\right), \end{split}$$

where $\gamma_{G_V}(h)$ is the mixing coefficient from (18) for the random walk on vertices. Next, estimate factors from the RHS as follows:

$$\sum_{x} \mathbb{E}\left(\phi|v=x\right) \le \max_{x} \frac{1}{\pi(x)} \sum_{x} \mathbb{E}\left(\phi|v=x\right) \pi(x) \le 2|E_{G}|N_{m}(G). \quad (21)$$

For $\max_x \mathbb{E}(\phi|v=x)$, consider the expressions for ϕ from (12), (13) or (14).

Using notation $D = \prod_{r=2}^{k-1} (\Delta_1 + \ldots + \Delta_r)$, for the Ordered Lift estimator,

$$\max_{x} \mathbb{E}\left(\phi_{O} \middle| v = x\right) \leq \max_{x} \sum_{A} \frac{\mathbb{P}(A \middle| v = x)}{\tilde{\pi}(A)} \leq$$

$$\max_{x} \frac{\left|\{A \middle| A[1] = x\}\right|}{\pi(x)} \leq 2|E_{G}|D.$$

For the Shotgun Lift estimator,

$$\max_{x} \mathbb{E}(\phi_{S}|v=x) \le \max_{x} \sum_{B} |\mathcal{N}_{v}(B)| \frac{\mathbb{P}(B|v=x)}{\tilde{\pi}(B)} \le$$

$$\max_{x} \frac{|\mathcal{N}_{v}(B)||\{B \mid B[1]=x\}|}{\pi(x)} \le 2|E_{G}|D,$$

For the Unordered Lift estimator,

$$\begin{split} \max_x \mathbb{E}\left(\phi_U \middle| v = x\right) &\leq \max_x \sum_T \frac{\mathbb{P}(T \middle| v = x)}{\pi_U(T)} \leq \\ \max_x \frac{\left|\left\{T \middle| x \in V_T\right\}\right|}{\pi(x)} &\leq 2|E_G|D. \end{split}$$

Combining the results, we get the desired bound.