

# G51FAI

# Fundamentals of AI

## *Neural Networks*



# What is a Neural Network

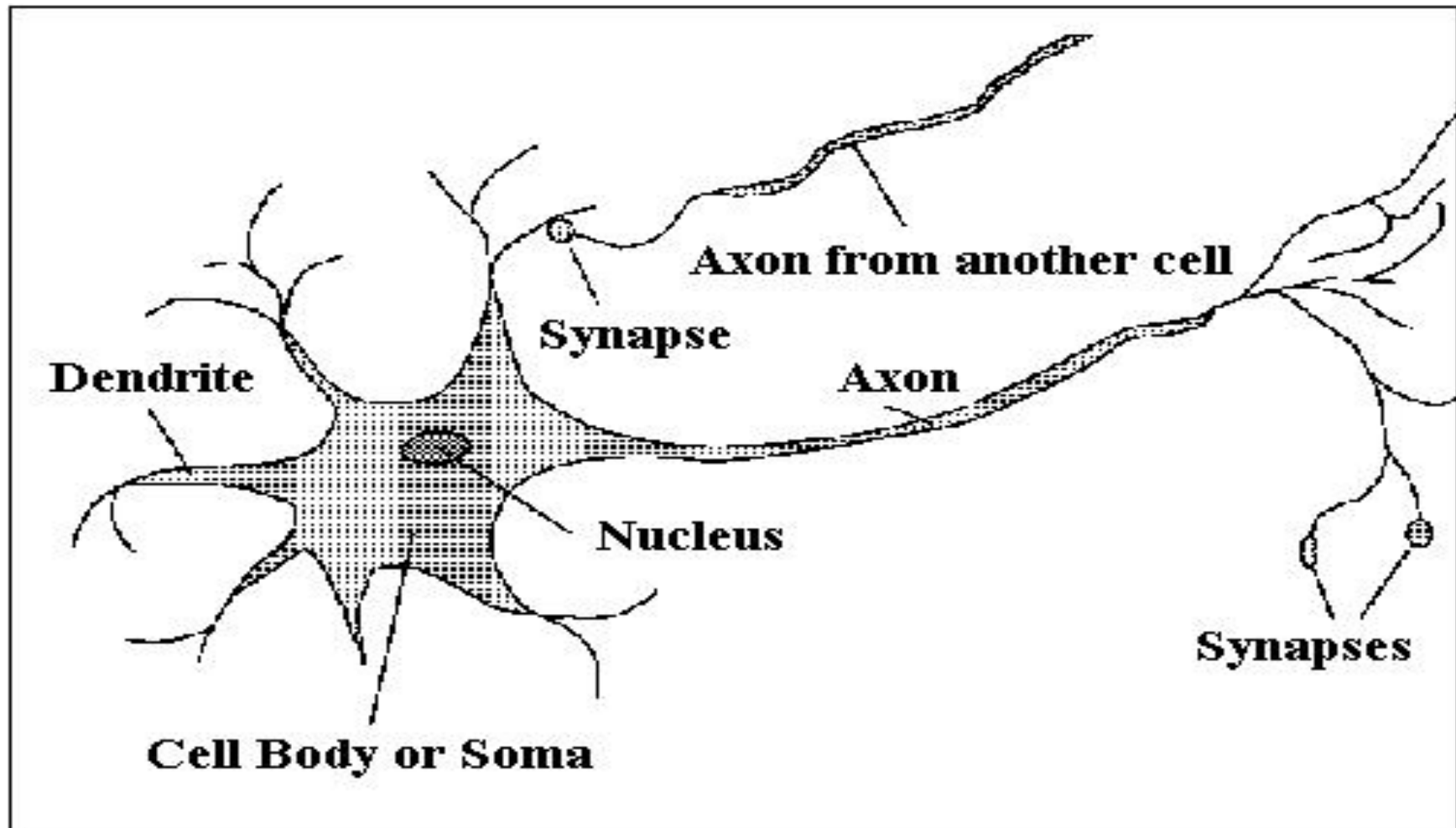
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## *Computers & Symbols versus Nets & Neurons* (Kevin Gurney)

- An interconnected assembly of simple processing elements, ***units or nodes***, whose functionality is loosely based on the animal neuron. The processing ability of the network is stored in the inter-unit connection strengths, or ***weights***, obtained by a process of adaptation to, or ***learning*** from, a set of training patterns.

# *Biological Neuron*

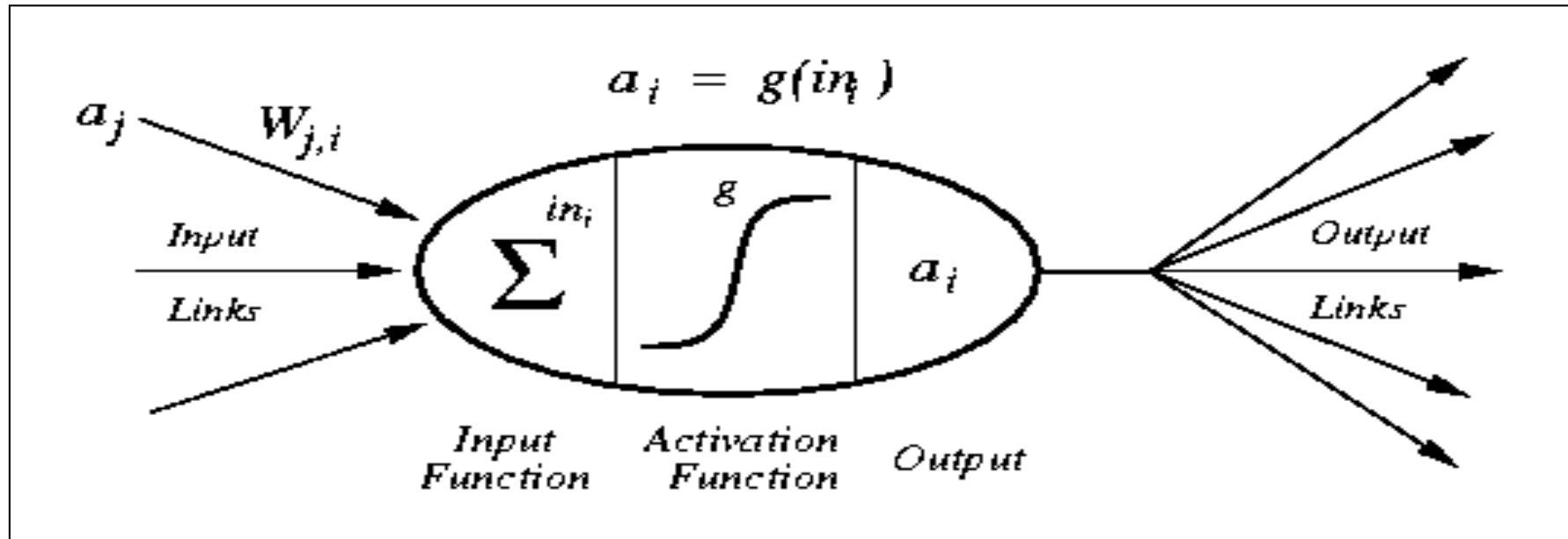
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# Biological Neural Networks

- We are born with about 100 billion neurons
- A neuron may connect to as many as 100,000 other neurons
- Signals “move” via complex electrochemical reactions
- The synapses release a chemical transmitter – the sum of which can cause a threshold to be reached – causing the neuron to “fire”
- Synapses can be inhibitory or excitatory

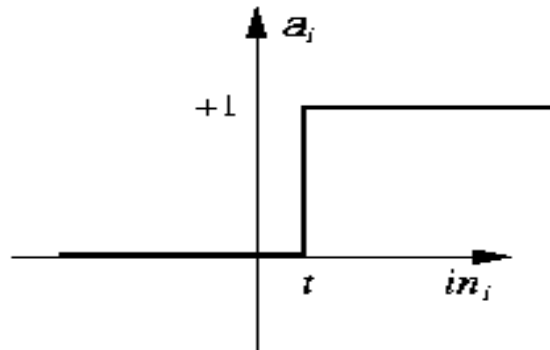
# Modeling a Neuron



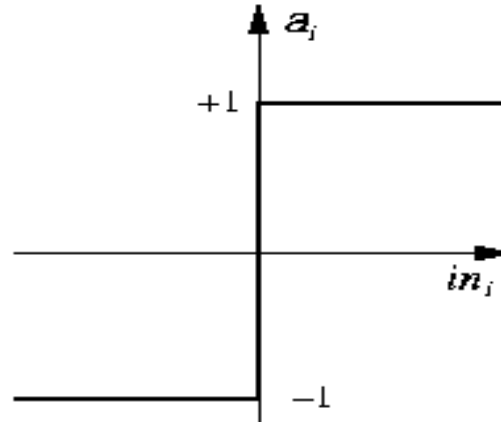
$$in_i = \sum_j W_{j,i} a_j$$

- $a_j$  : Activation value of unit j
- $w_{j,i}$  : Weight on the link from unit j to unit i
- $in_i$  : Weighted sum of inputs to unit i
- $a_i$  : Activation value of unit i
- $g$  : Activation function

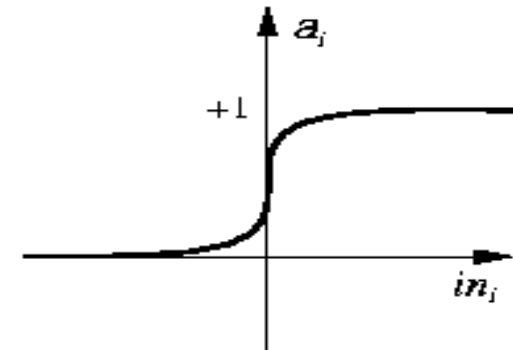
# Activation Functions



(a) Step function



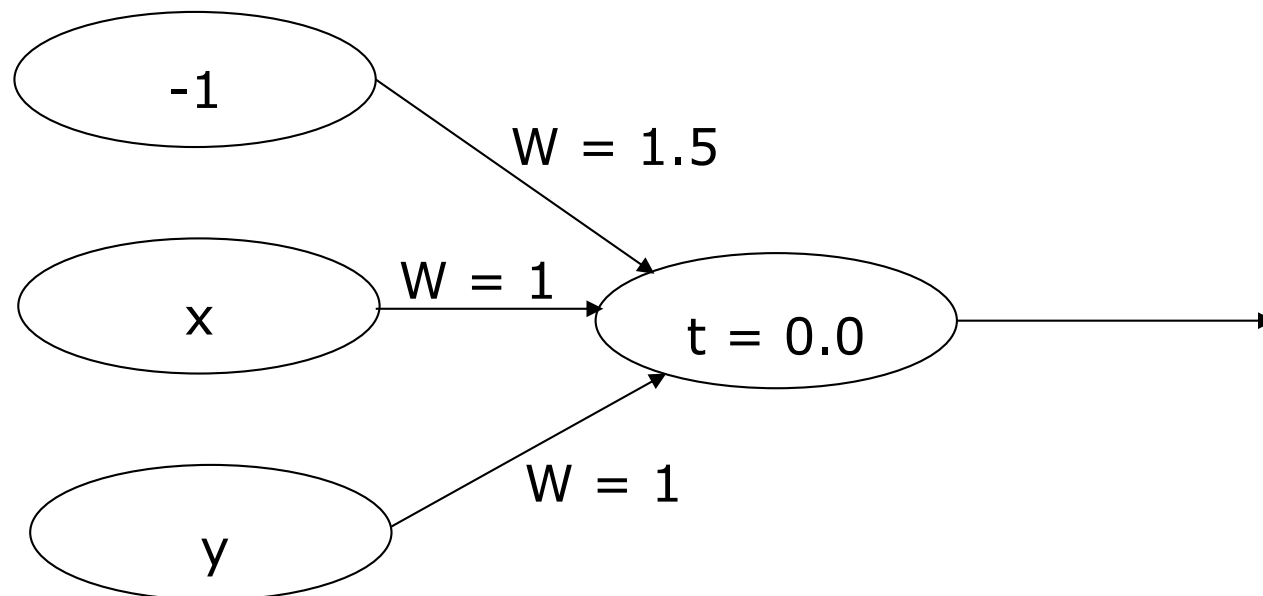
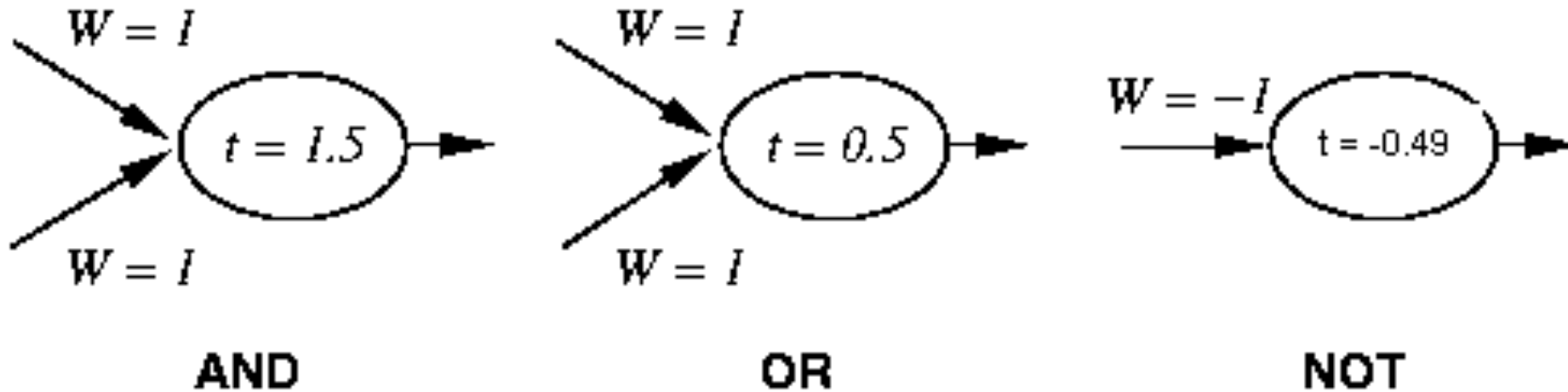
(b) Sign function



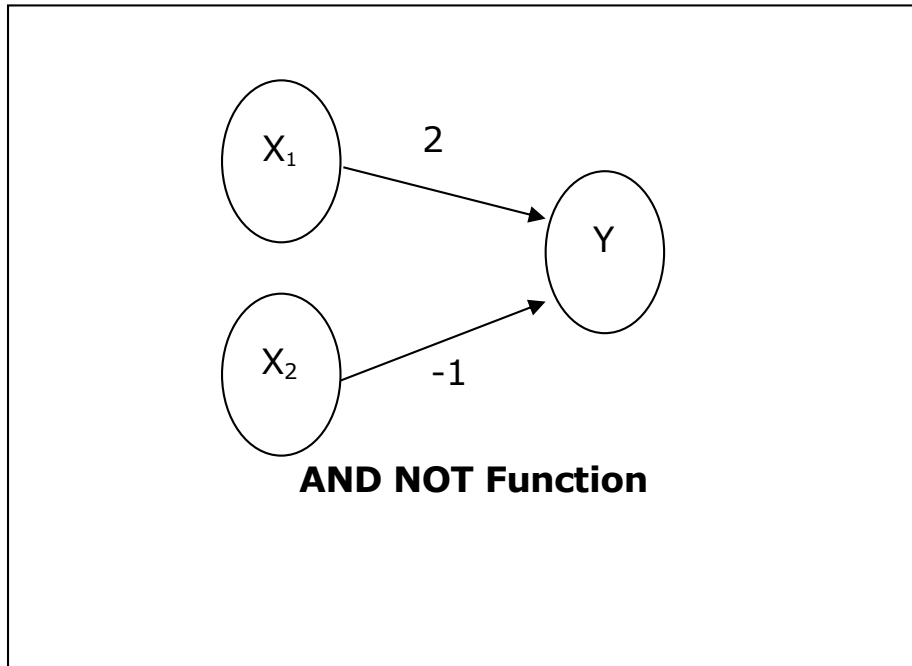
(c) Sigmoid function

- $\text{Step}_t(x) = 1$  if  $x \geq t$ , else 0
- $\text{Sign}(x) = +1$  if  $x \geq 0$ , else -1
- $\text{Sigmoid}(x) = 1/(1+e^{-x})$
- Identity Function

# Simple Networks



# Neural Networks – AND NOT

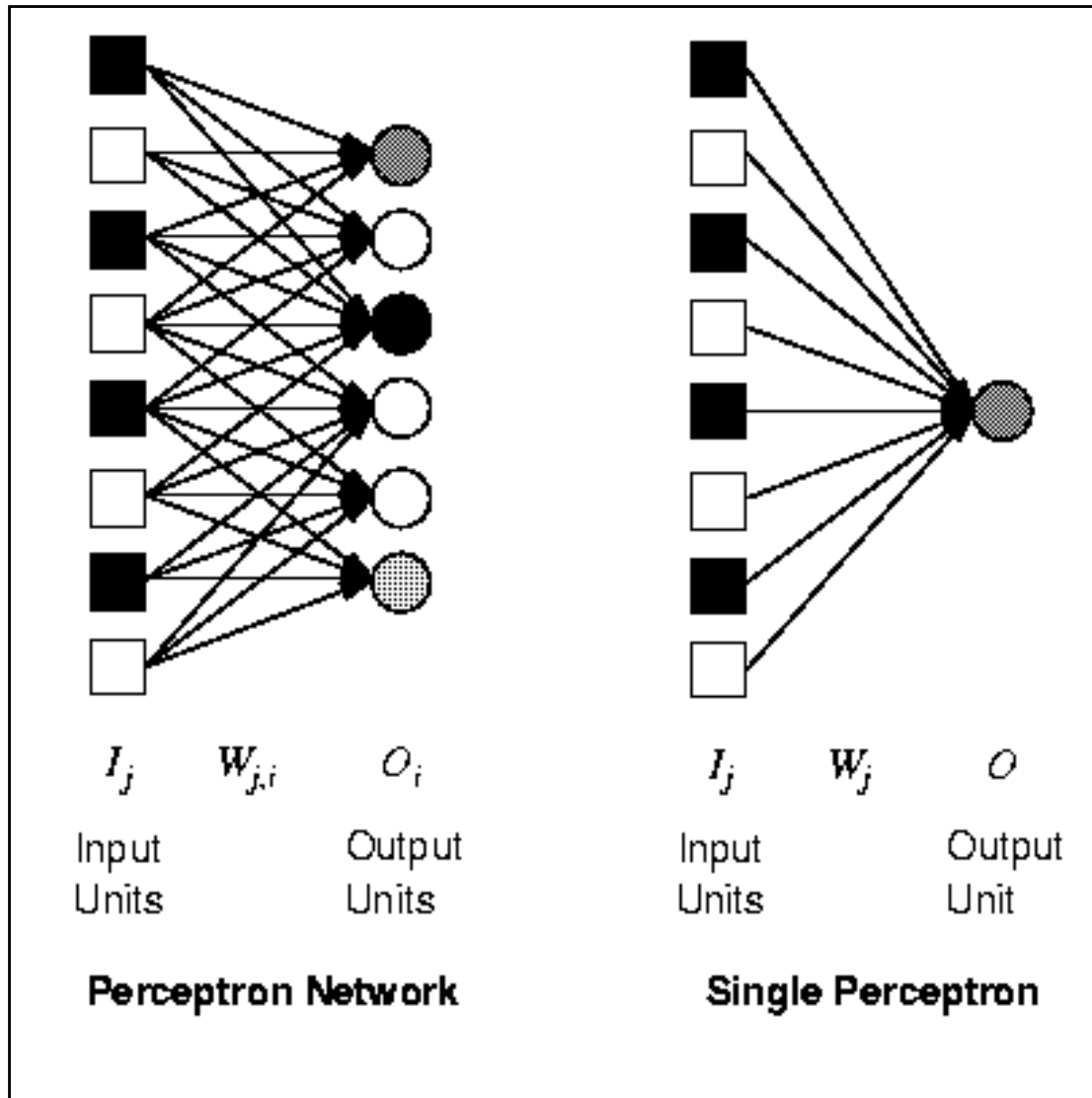


$\text{threshold}(Y) = 1.5$

AND NOT		
X1	X2	Y
1	1	0
1	0	1
0	1	0
0	0	0



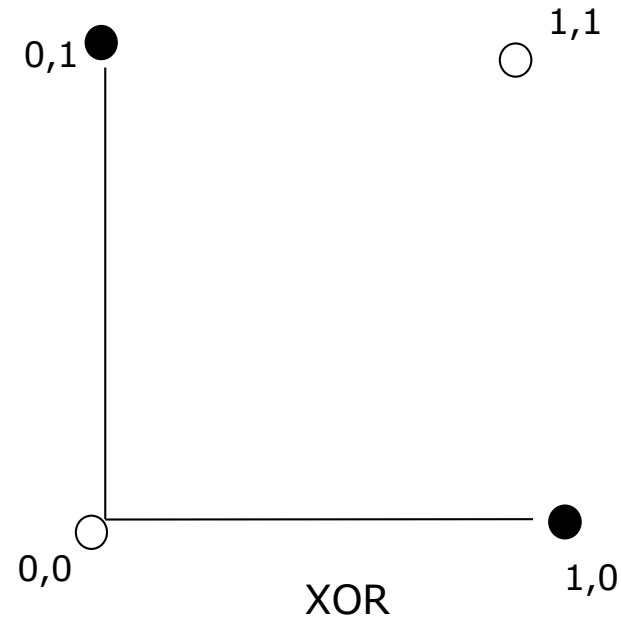
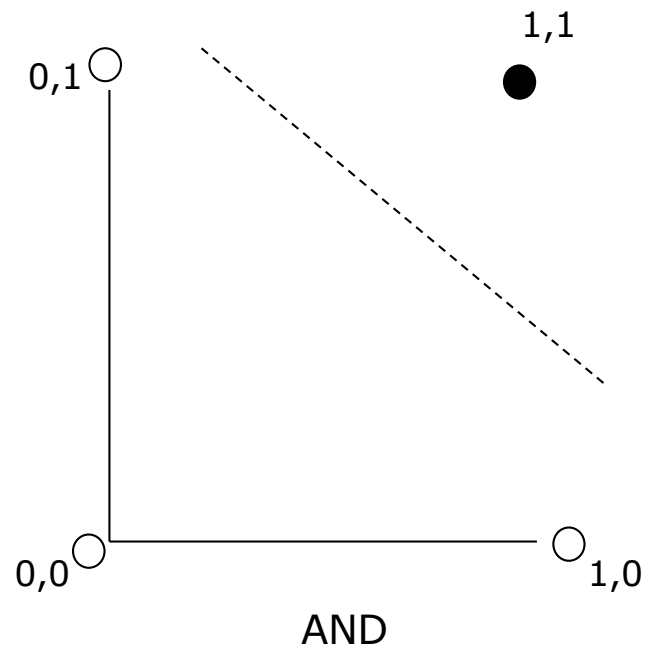
# Perceptron



- A single weight only affects one output so we can restrict our investigations to a model as shown on the right
- Notation can be simpler, i.e.

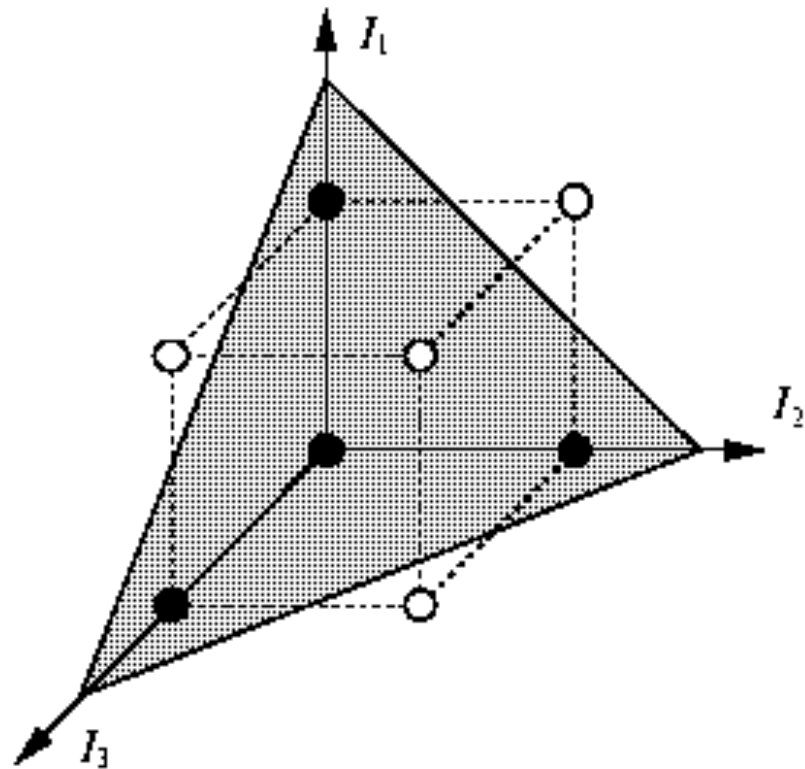
$$O = Step_0 \sum_j W_j I_j$$

# What can Perceptrons Represent?

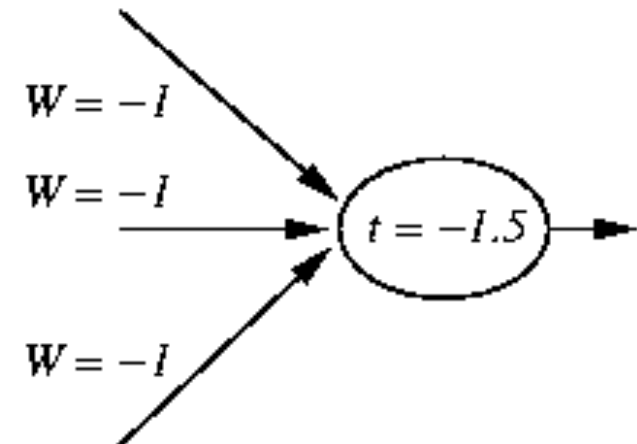


- Only functions which can be separated in this way (*linearly separable*) can be represented by a perceptron
- The dimensionality of function space is equal to the number of inputs, which will typically be higher than 2!
- Separation in this case is by a *hyperplane of* (dimensionality – 1)

# What can Perceptrons Represent?



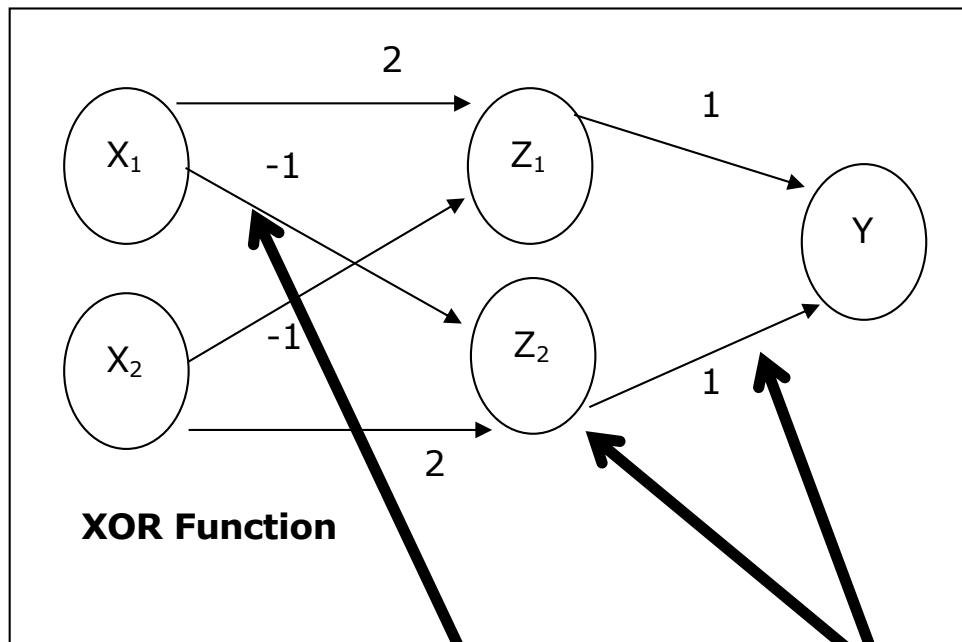
(a) Separating plane



(b) Weights and threshold

Linear Separability is also possible in more than 3 dimensions – but it is harder to visualise

# Neural Networks - XOR



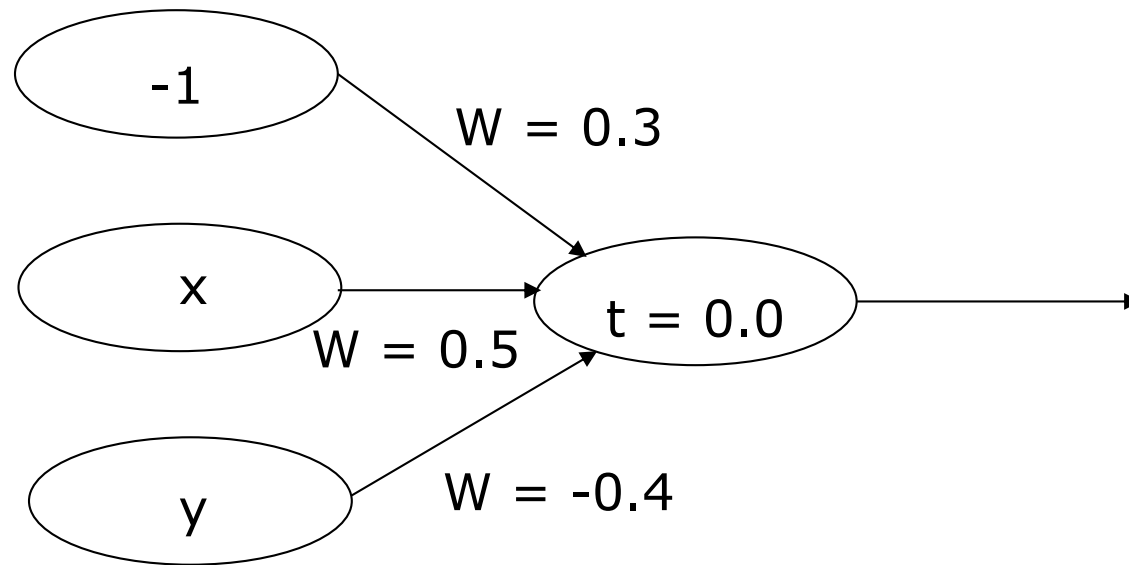
threshold (Z)

threshold(Y) = 1.5

XOR		
X1	X2	Y
1	1	0
1	0	1
0	1	1
0	0	0

$$X_1 \text{ XOR } X_2 = (X_1 \text{ AND NOT } X_2) \text{ OR } (X_2 \text{ AND NOT } X_1)$$

# Training a Perceptron



$I_1$	$I_2$	$I_3$	Summation	Output
-1	0	0	$(-1 * 0.3) + (0 * 0.5) + (0 * -0.4) = -0.3$	0
-1	0	1	$(-1 * 0.3) + (0 * 0.5) + (1 * -0.4) = -0.7$	0
-1	1	0	$(-1 * 0.3) + (1 * 0.5) + (0 * -0.4) = 0.2$	1
-1	1	1	$(-1 * 0.3) + (1 * 0.5) + (1 * -0.4) = -0.2$	0

# Learning

While epoch produces an error

**Present network with next inputs  
from epoch**

**Err = T – O**

**If |Err| > 0 then**

**$W_j = W_j + LR * I_j * Err$**

**End If**

End While

# Learning

**While epoch produces an error**

**Present network with next inputs  
from epoch**

**$Err = T - O$**

**If  $|Err| > 0$  then**

**$W_j = W_j + LR * I_j * Err$**

**End If**

**End While**

**Epoch** : Presentation of the entire training set to the neural network.

In the case of the AND function an epoch consists of four sets of inputs being presented to the network (i.e.  $[0,0]$ ,  $[0,1]$ ,  $[1,0]$ ,  $[1,1]$ )

# Learning

**While epoch produces an error**

**Present network with next inputs  
from epoch**

**Err = T - O**

**If |Err| > 0 then**

**$W_j = W_j + LR * I_j * Err$**

**End If**

**End While**

**Training Value, T** : When we are training a network we not only present it with the input but also with a value that we require the network to produce. For example, if we present the network with [1,1] for the AND function the training value will be 1

**Output from Neuron, O** : The output value from the neuron



# Learning

**While epoch produces an error**

**Present network with next inputs  
from epoch**

**$Err = T - O$**

**If  $|Err| > 0$  then**

**$W_j = W_j + LR * I_j * Err$**

**End If**

**End While**

**I<sub>j</sub>**: Inputs being presented to the neuron

**W<sub>j</sub>**: Weight from input neuron ( $I_j$ ) to the output neuron

**LR**: The learning rate. This dictates how quickly the network converges. It is set by a matter of experimentation. It is typically 0.1

**Error, Err**: It is the amount by which the value output by the network differs from the training value. For example, if we required the network to output 0 and it output a 1, then  $Err = -1$

# Example

- A perceptron with two inputs, is to learn the AND function below:

$x_1$	$x_2$	T
0	0	0
0	1	0
1	0	0
1	1	1

- Let  $\alpha=0.25$  be the learning rate, initial weights and threshold be 0, 0.4 and 0.3 respectively, T the training output and O the actual output, the weights and threshold should be adjusted as below:

$$\delta w_i = \alpha(T-O)I_i ; \quad \delta \theta = -\alpha(T-O)$$

where  $I_i$  is the input and is always equal to -1 for the threshold

# Perceptron Learning (1)

$w_1$	$w_2$	$\theta$	$x_1$	$x_2$	$a$	$O$	$T$	$\alpha(T-O)$	$\delta w_1$	$\delta w_2$	$\delta \theta$
0.0	0.4	0.3	0	0	0	0	0	0	0	0	0
0.0	0.4	0.3	0	1	0.4	1	0	-0.25	0	-0.25	0.25
0.0	0.15	0.55	1	0	0	0	0	0	0	0	0
0.0	0.15	0.55	1	1	0.15	0	1	0.25	0.25	0.25	-0.25
0.25	0.4	0.3	0	0	0	0	0	0	0	0	0
0.25	0.4	0.3	0	1	0.4	1	0	-0.25	0	-0.25	0.25
0.25	0.15	0.55	1	0	0.15	0	0	0	0	0	0
0.25	0.15	0.55	1	1	0.4	0	1	0.25	0.25	0.25	-0.25
0.5	0.4	0.3	0	0	0	0	0	0	0	0	0
0.5	0.4	0.3	0	1	0.4	1	0	-0.25	0	-0.25	0.25
0.5	0.15	0.55	1	0	0.5	0	0	0	0	0	0
0.5	0.15	0.55	1	1	0.65	1	1	0	0	0	0

# Perceptron Learning (2)

$w_1$	$w_2$	$\theta$	$x_1$	$x_2$	$a$	$O$	$T$	$\alpha(T-O)$	$\delta w_1$	$\delta w_2$	$\delta \theta$
0.5	0.15	0.55	0	0	0	0	0	0	0	0	0
0.5	0.15	0.55	0	1	0.15	0	0	0	0	0	0
0.5	0.15	0.55	1	0	0.5	0	0	0	0	0	0
0.5	0.15	0.55	1	1	0.65	1	1	0	0	0	0

$$a = \sum_i w_i x_i \quad \text{and} \quad \theta = \text{threshold}$$

# Building a Neural Network

There are many forms of neural networks. Most operate by passing neural 'activations' through a network of connected neurons.

1. "Select Structure": design the way that the neurons are interconnected

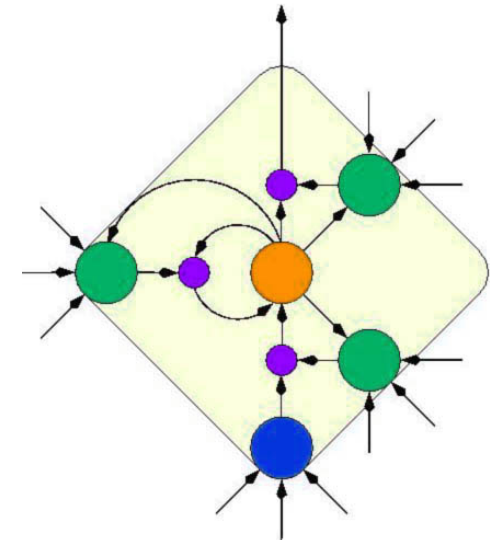
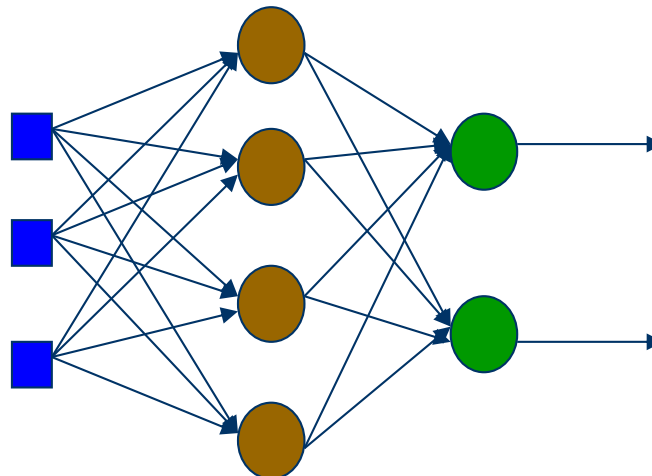
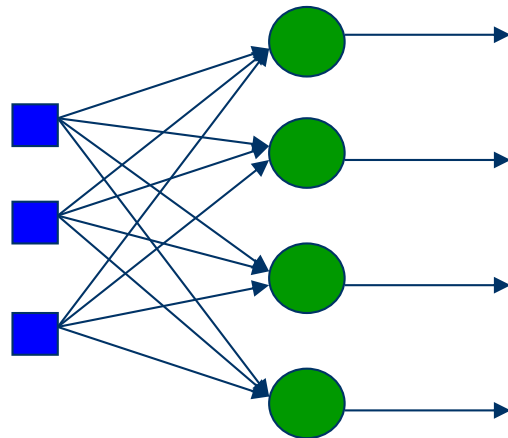
- three main classes of network architectures

- ❖ single-layer feed-forward

- ❖ multi-layer feed-forward

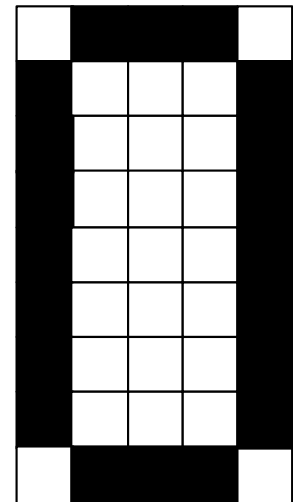
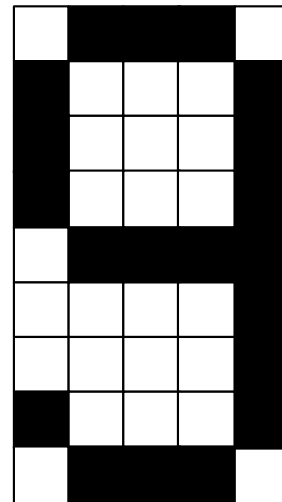
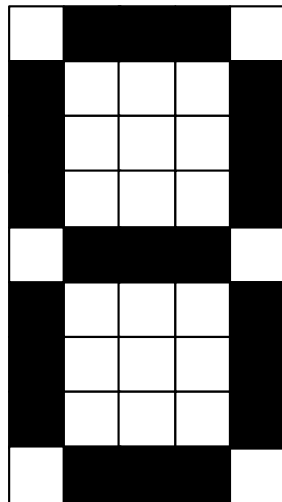
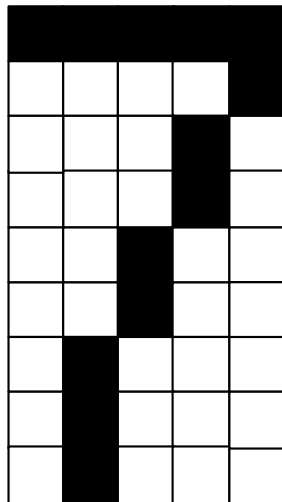
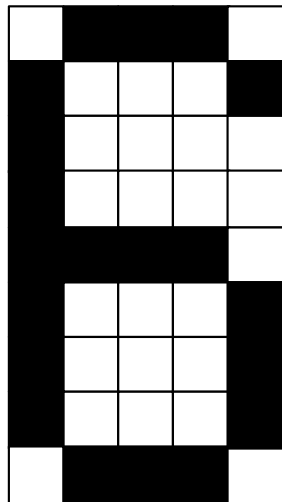
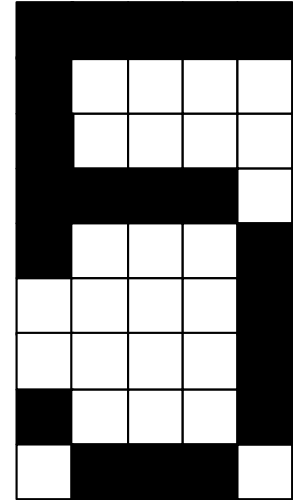
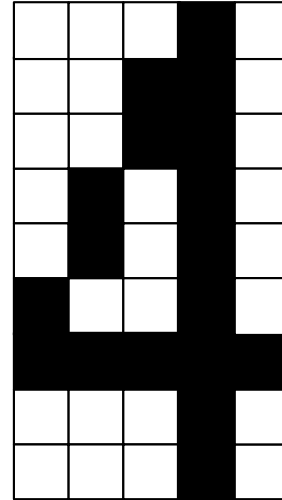
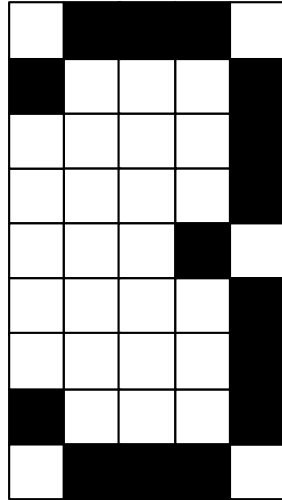
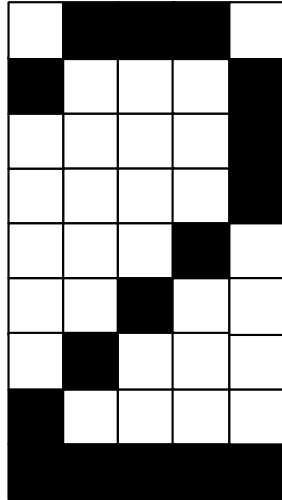
- ❖ recurrent

} neurons are organised  
in acyclic layers

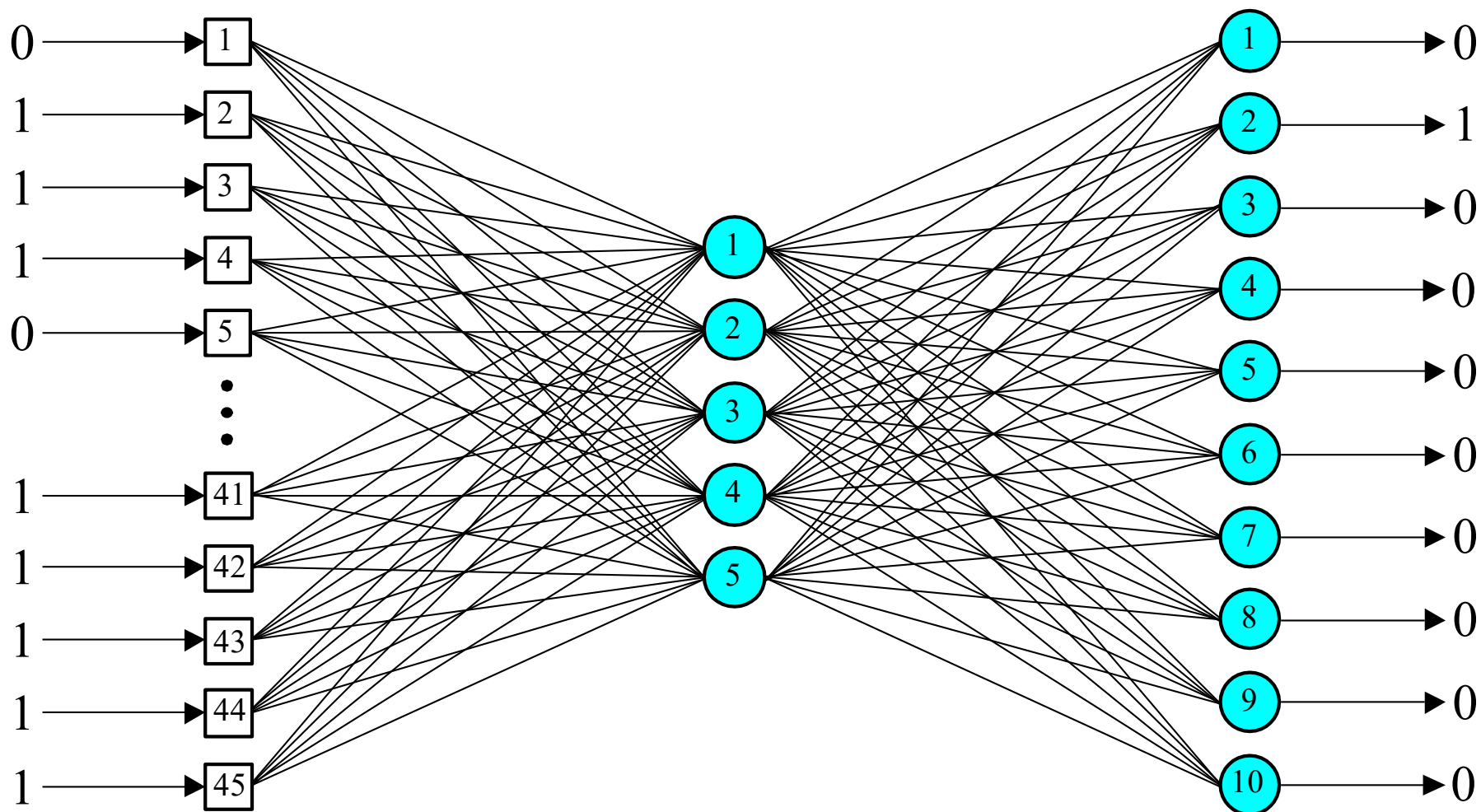


# Bit Maps for Digit Recognition

1	2	3	4	5
6	7	8	9	10
11	12	13	14	15
16	17	18	19	20
21	22	23	24	25
26	27	28	29	30
31	32	33	34	35
36	37	38	39	40
41	42	43	44	45

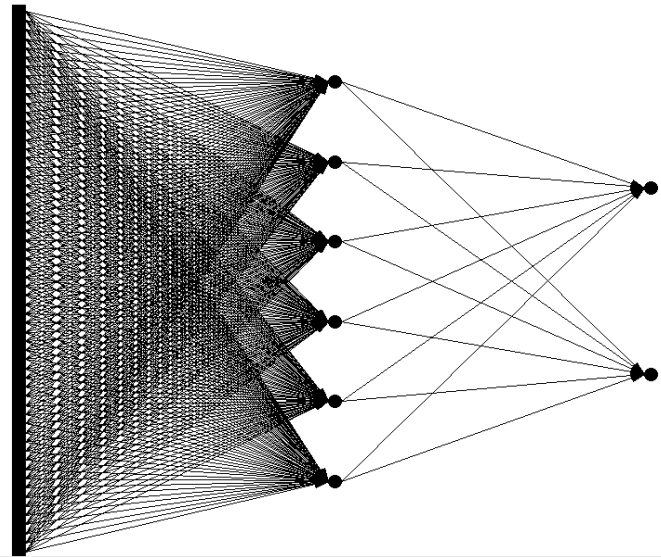
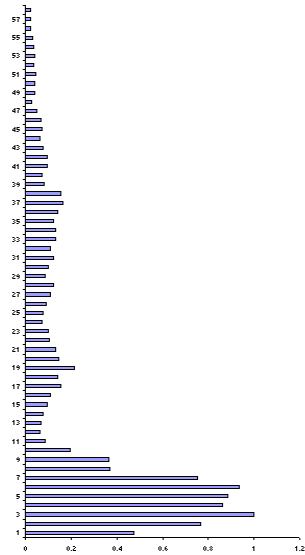


# Neural Network for Printed Digit Recognition



# Voice Recognition

Steve



0.01

0.99

Network  
Architecture

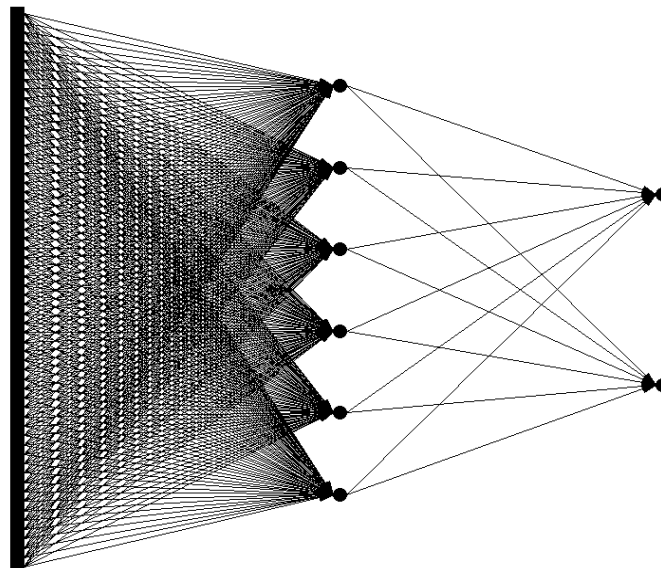
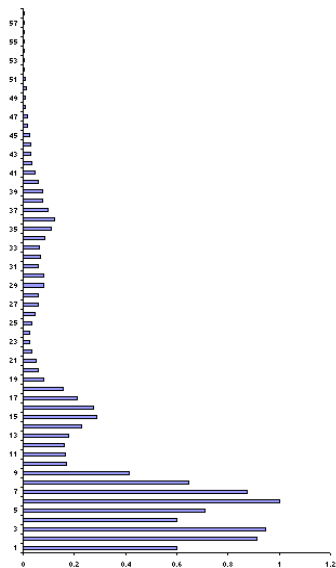
Feedforward Network

60 inputs (one for  
each frequency bin);

6 hidden;

2 output (0-1 for  
"Steve", 1-0 for  
"David")

David



0.99

0.01



# Summary of Neural Network

- Definitions
- Modelling Functions
  - weights
  - Activation functions
- Simple Networks
  - perceptron
- Network Architecture
- Learning Algorithm
  - delta rule

# Acknowledgements

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