```c
/*
 * main.c
 *
 * Created: 21/02/2023 10:20:03 PM
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 */
#define F_CPU 1000000
#include <avr/io.h>
#include <util/delay.h>

#define get_bit(reg,bitnum) ((reg & (1<<bitnum))>>bitnum)
int main() {
    float duty_cycle = 0;

    DDRA=0b11110000; // Set the first 2 pins of PORTA as inputs to read push buttons
    DDRB=0b11111111; // Set Pin3 (OC0) in Port B as output
    DDRD=0b11111111;

    TCCR0=0b01110101; // Configure TCCR0 as explained in the article
    OCR0=255; // Set OCR0 to 255 for initial duty cycle = 0 and the motor is not rotating
    while(1) {
        if ((get_bit(PINA,0) == 1)) {
            // Place your code here (Increase the duty cycle)
            if(duty_cycle < 1.0) {
                duty_cycle += 0.1;
            }
            else
                duty_cycle = 1;
        }
        if ((get_bit(PINA,1) == 1)) {
            // Place your code here (Decrease the duty cycle)
            if(duty_cycle > 0) {
                duty_cycle -= 0.1;
            }
            else
                duty_cycle = 0;
        }
        if ((get_bit(PINA,2) == 1)) {
            PORTD = 1;
        }
        if ((get_bit(PINA,3) == 1)) {
            PORTD = 2;
        }
        // Place your code here (Apply the change in duty cycle to OCR0)
        OCR0 = 255 - 255*duty_cycle; // d = (255-OCR0)/255  // 255 - d*255
        _delay_ms(250);
    }
    return 0;
}
```