Mechanics II

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Q. 1

Let S be the frame in which the particle's velocity and acceleration is \vec{u} and \vec{a} respectively. Let S' be the instantaneously co-moving frame in which the particle's acceleration is \vec{a}_0 . Let a_{\parallel} and a_{\perp} be the acceleration components along the particle's velocity \vec{u} and perpendicular to the particle's velocity \vec{u} respectively w.r.t an observer in frame S. Similarly let $a_{\parallel,0}$ and $a_{\perp,0}$ be the components of acceleration \vec{a}_0 along the particle's velocity \vec{u} and perpendicular to the particle's velocity \vec{u} respectively w.r.t an observer in frame S'. The angle between vectors \vec{u} and \vec{a} is θ .

The acceleration components in the two frames are related by the following equations:

$$a'_{x} = \frac{a_{x}}{\left[\gamma(1 - \frac{u_{x}v}{c^{2}})\right]^{3}} , \quad a'_{y} = \frac{a_{y}}{\left[\gamma(1 - \frac{u_{x}v}{c^{2}})\right]^{2}} + \frac{u_{y}va_{x}}{c^{2}\gamma^{2}(1 - \frac{u_{x}v}{c^{2}})^{3}}$$

Since S' is an ICF and we are taking acceleration components along the direction of particle's velocity and perpendicular to particle's velocity in S frame, we have, $a'_x = a_{\parallel,0}$, $a_x = a_{\parallel} = acos\theta$, $\gamma = \gamma_u$, $u_x = v = u$, $a'_y = a_{\perp,0}$, $a_y = a_{\perp} = asin\theta$, $u_y = 0$. Substituting these in the above equations, we get:

$$a_{\parallel,0} = \frac{a cos \theta}{[\gamma_u (1 - \frac{u^2}{c^2})]^3} \ , \quad \ a_{\perp,0} = \frac{a sin \theta}{[\gamma_u (1 - \frac{u^2}{c^2})]^2}$$

where $\gamma_u = \frac{1}{\sqrt{1 - \frac{u^2}{c^2}}}$. On Simplifying, we get:

$$a_{\parallel,0} = \gamma_u^3 a cos\theta$$
, $a_{\perp,0} = \gamma_u^2 a sin\theta$

The magnitude of \vec{a}_0 is given by:

$$a_0 = \sqrt{(a_{\parallel,0})^2 + (a_{\perp,0})^2} = \gamma_u^2 \sqrt{\gamma_u^2 \cos^2\theta + \sin^2\theta} \ a = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \sqrt{(a_{\parallel,0})^2 + (a_{\perp,0})^2} = \gamma_u^2 \sqrt{\gamma_u^2 \cos^2\theta + \sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta + (1 - \beta_u^2)\sin^2\theta} \ a_0 = \gamma_u^3 \sqrt{\cos^2\theta} \ a_0$$

where $\beta_u = \frac{u}{c}$. Since $\cos^2\theta + \sin^2\theta = 1$, the above equation could be simplified as:

$$a_0 = \gamma_u^3 \sqrt{\cos^2\theta + \sin^2\theta - \beta_u^2 \sin^2\theta} \ a = \gamma_u^3 \sqrt{1 - \beta_u^2 \sin^2\theta} \ a$$

Hence Proved.

Q. 2

Let \tilde{X} and \tilde{X}' be the space-time coordinates for observer S and S' respectively. Given that $\tilde{X} \to \tilde{X}' = L\tilde{X}$ where Lorentz Transformation matrix L is given as:

$$L = \frac{1}{64} \begin{pmatrix} 125 & -48 & -60 & 75 \\ -75 & 80 & 36 & -45 \\ -60 & 0 & 80 & -36 \\ 48 & 0 & 0 & 80 \end{pmatrix}$$

With respect to observer S, the 4-covector A_{μ} is given as:

$$A_{\mu} = \begin{pmatrix} 5\\1\\-2\\0 \end{pmatrix}$$

Let the 4-covector w.r.t. observer S' be A'_{μ} . The 4-vector in a particular frame is related to the 4-covector in the same frame by $A^{\mu} = \eta A_{\mu}$ where Minkowski Metric η is given as:

$$\eta = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

Therefore, w.r.t. observer S, the 4-vector A^{μ} is given by:

$$A^{\mu} = \begin{pmatrix} 5 \\ -1 \\ 2 \\ 0 \end{pmatrix}$$

Since 4-vectors transforms the same way as coordinates do, we have $A^{\mu} \to A'^{\mu} = LA^{\mu}$, where A'^{μ} is the 4-vector w.r.t. observer S'.

$$\implies A'^{\mu} = \frac{1}{64} \begin{pmatrix} 125 & -48 & -60 & 75 \\ -75 & 80 & 36 & -45 \\ -60 & 0 & 80 & -36 \\ 48 & 0 & 0 & 80 \end{pmatrix} A^{\mu} = \frac{1}{64} \begin{pmatrix} 125 & -48 & -60 & 75 \\ -75 & 80 & 36 & -45 \\ -60 & 0 & 80 & -36 \\ 48 & 0 & 0 & 80 \end{pmatrix} \begin{pmatrix} 5 \\ -1 \\ 2 \\ 0 \end{pmatrix}$$

Since $A'^{\mu} = \eta A'_{\mu}$, we have:

$$\eta A'_{\mu} = \frac{1}{64} \begin{pmatrix} 125 & -48 & -60 & 75 \\ -75 & 80 & 36 & -45 \\ -60 & 0 & 80 & -36 \\ 48 & 0 & 0 & 80 \end{pmatrix} \begin{pmatrix} 5 \\ -1 \\ 2 \\ 0 \end{pmatrix}$$

Now, pre-multiplying both side by η^{-1} and noting that $\eta^{-1} = \eta$, we have:

$$A'_{\mu} = \frac{1}{64} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 125 & -48 & -60 & 75 \\ -75 & 80 & 36 & -45 \\ -60 & 0 & 80 & -36 \\ 48 & 0 & 0 & 80 \end{pmatrix} \begin{pmatrix} 5 \\ -1 \\ 2 \\ 0 \end{pmatrix}$$

$$\implies A'_{\mu} = \frac{1}{64} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 553 \\ -383 \\ -140 \\ 240 \end{pmatrix}$$

$$\implies A'_{\mu} = \frac{1}{64} \begin{pmatrix} 553 \\ 383 \\ 140 \\ -240 \end{pmatrix}$$

Hence the components of the 4-covector as measured by observer S' are given by A'_{μ} .

Q. 3 Part(a)

A Lorentz transformation matrix L obeys:

$$L^T \eta L = \eta \tag{1}$$

Since L_1 and L_2 are given to be Lorentz transformation matrices, we have:

$$L_1^T \eta L_1 = \eta \tag{2}$$

$$L_2^T \eta L_2 = \eta \tag{3}$$

Now we substitute L_1L_2 in place of L in L.H.S of Eqn(1) and compute it to check if it is a Lorentz transformation matrix. Therefore we have:

$$(L_1 L_2)^T \eta(L_1 L_2) = L_2^T L_1^T \eta L_1 L_2 \tag{4}$$

Using Eqn(2), R.H.S of Eqn(4) can be written as:

$$(L_1 L_2)^T \eta(L_1 L_2) = L_2^T \eta L_2 \tag{5}$$

Using Eqn(3), R.H.S of Eqn(5) can be written as:

$$(L_1 L_2)^T \eta(L_1 L_2) = \eta (6)$$

From Eqn(1), Eqn(2), Eqn(3) and Eqn(6), we conclude that if L_1 and L_2 are Lorentz Transformation matrices then L_1L_2 is also a Lorentz Transformation matrix.

Hence Proved.

Part(b)

Given that:

$$\det(L_1) = 1, \ \det(L_2) = 1$$
 (7)

Applying determinant on both sides of Eqn(6), we get:

$$\det((L_1L_2)^T \eta L_1L_2) = \det(\eta) \tag{8}$$

$$\implies \det((L_1L_2)^T)\det(\eta)\det(L_1L_2) = \det(\eta)$$

Since $\det((L_1L_2)^T) = \det(L_1L_2)$ and $\det(\eta) \neq 0$, we have from the above Equation:

$$(\det(L_1L_2))^2 = 1 \implies \det(L_1L_2) = \pm 1 \implies \det(L_1)\det(L_2) = \pm 1 \tag{9}$$

Using Eqn(7) in Eqn(9) we neglect negative value.

$$\implies \det(L_1)\det(L_2) = +1 \implies \det(L_1L_2) = +1$$

Hence proved.

Part(c)

We first prove some identities which we would be using for our proof. Let L be a general Lorentz Transformation matrix. Then we have:

$$\eta = (L)^T \eta(L) \tag{10}$$

Writing Eqn(10) in component form, we have:

$$\eta_{\mu\nu} = \sum_{\rho,\sigma} (L)_{\mu\rho}^T \eta_{\rho\sigma}(L)_{\sigma\nu} = \eta_{\rho\sigma} \Lambda^{\rho}_{\ \mu} \Lambda^{\sigma}_{\ \nu} \tag{11}$$

where we have used the fact that $(L)_{\mu\rho}^T=(L)_{\rho\mu}$. Note that $\eta_{\rho\sigma}=0$ for all $\rho\neq\sigma$ and $\rho,\sigma\in\{0,1,2,3\}$. Taking the 00-th element of $\eta_{\mu\nu}=\eta_{\rho\sigma}\Lambda^{\rho}{}_{\mu}\Lambda^{\sigma}{}_{\nu}$, we get:

$$1 = \eta_{00} = \eta_{\rho\sigma} \Lambda^{\rho}{}_{0} \Lambda^{\sigma}{}_{0} = (\Lambda^{0}{}_{0})^{2} - (\Lambda^{1}{}_{1})^{2} - (\Lambda^{2}{}_{2})^{2} - (\Lambda^{3}{}_{3})^{2}$$

$$\implies (\Lambda^{1}{}_{1})^{2} + (\Lambda^{2}{}_{2})^{2} + (\Lambda^{3}{}_{3})^{2} = (\Lambda^{0}{}_{0})^{2} - 1$$
(12)

We would be using Eqn(12) for our proof later.

Let us define $A = L_1L_2$. Accordingly, we use notation such that A^{μ}_{ν} , $(L_1)^{\mu}_{\nu}$ and $(L_2)^{\mu}_{\nu}$ denotes the $\mu - th$ row, $\nu - th$ column element of A, L_1 and L_2 respectively where $\mu, \nu \in \{0, 1, 2, 3\}$.

We define:

$$\vec{l_1} = \begin{pmatrix} (L_1)^0_1 \\ (L_1)^0_2 \\ (L_1)^0_3 \end{pmatrix}, \quad \vec{l_2} = \begin{pmatrix} (L_2)^1_0 \\ (L_2)^2_0 \\ (L_2)^3_0 \end{pmatrix}$$
(13)

Therefore we have:

$$A^{0}{}_{0} = (L_{1})^{0}{}_{0}(L_{2})^{0}{}_{0} + \vec{l_{1}}.\vec{l_{2}}$$

$$\implies A^{0}{}_{0} \ge (L_{1})^{0}{}_{0}(L_{2})^{0}{}_{0} - |\vec{l_{1}}.\vec{l_{2}}|$$
(14)

Now using Eqn(12) we can calculate the norm of $\vec{l_1}$ and $\vec{l_2}$ as follows:

$$\|\vec{l_1}\| = \sqrt{((L_1)^1_1)^2 + ((L_1)^2_2)^2 + ((L_1)^3_3)^2} = \sqrt{((L_1)^0_0)^2 - 1}$$
(15)

$$\|\vec{l_2}\| = \sqrt{((L_2)^1_1)^2 + ((L_2)^2_2)^2 + ((L_2)^3_3)^2} = \sqrt{((L_2)^0_0)^2 - 1}$$
(16)

Now using Cauchy-Schwarz inequality, we have:

$$|\vec{l_1}.\vec{l_2}| \le ||\vec{l_1}|| ||\vec{l_2}|| \tag{17}$$

Substituting Eqn(17) in Eqn(14), we get:

$$A^{0}_{0} \ge (L_{1})^{0}_{0}(L_{2})^{0}_{0} - \|\vec{l_{1}}\| \|\vec{l_{2}}\|$$

$$\tag{18}$$

Since it is given that $(L_1)^0_0 > 1$ and $(L_2)^0_0 > 1$, we use the inequality, $\sqrt{x^2 - 1} > x - 1 \ \forall x > 1$ in Eqn(15) and Eqn(16) to get:

$$\|\vec{l_1}\| > (L_1)^0_0 - 1 \tag{19}$$

$$\|\vec{l_2}\| > (L_2)^0_0 - 1 \tag{20}$$

Note that $(L_1)^0_0 - 1 > 0$ and $(L_2)^0_0 - 1 > 0$. Multiplying Eqn(19) and Eqn(20), we get:

$$\|\vec{l_1}\| \|\vec{l_2}\| > ((L_1)^0_0 - 1)((L_2)^0_0 - 1)$$
(21)

$$\implies \|\vec{l_1}\| \|\vec{l_2}\| > (L_1)^0_0 (L_2)^0_0 - (L_1)^0_0 - (L_2)^0_0 + 1 \tag{22}$$

Substituting Eqn(22) in Eqn(18), we get:

$$A^{0}_{0} > (L_{1})^{0}_{0}(L_{2})^{0}_{0} - [(L_{1})^{0}_{0}(L_{2})^{0}_{0} - (L_{1})^{0}_{0} - (L_{2})^{0}_{0} + 1]$$
(23)

$$\implies A^{0}_{0} > (L_{1})^{0}_{0} + (L_{2})^{0}_{0} - 1 \tag{24}$$

Since $(L_1)^0_0 > 1$ and $(L_2)^0_0 > 1$, Eqn(24) becomes:

$$A^0_0 > 2 - 1$$

$$\implies A^0_0 > 1$$

Therefore if Lorentz transformation matrices L_1 and L_2 have 0-0 components greater than 1 then L_1L_2 also has 0-0 component greater than 1.

Hence proved.

Remark:

Here I prove one non-standard inequality which I simply stated while solving Q. 3 Part(c). The inequality was:

$$\sqrt{x^2 - 1} > x - 1 \quad \forall x > 1 \tag{25}$$

Proof(by contradiction):

Let us assume that Eqn(25) is not true. Then $\exists x > 1$ such that following holds:

$$\sqrt{x^2 - 1} \le x - 1 \tag{26}$$

Since x > 1, both L.H.S and R.H.S of Eqn(26) are positive. On squaring Eqn(26), we get:

$$x^{2} - 1 \le x^{2} + 1 - 2x$$

$$\implies -2 \le -2x$$

$$\implies x < 1$$

which is a contradiction to our assumption that $\exists x > 1$ such that Eqn(26) holds. Hence our initial assumption was wrong and thus the inequality written as Eqn(25) holds.

Hence proved.