

## TOPIC 2A

# DATA STRUCTURES: HEAPS

# DATA STRUCTURES

Data structures are used for organizing data in memory.

Algorithms and Data structure go hand in hand

- Without appropriate data structures algorithms would be slow
- Without algorithms data cannot be manipulated

Data Structures defined by their operations

- For **dynamic sets**: Insert, Delete, Search, Minimum, Maximum, Predecessor (in a sorted list), Successor (in a sorted list)
- More complicated operations for complex data types

Abstract Data Type (ADT)

- Operations that can be performed on the data structure and the complexities of the operations
- Example: Heaps

Data Structure

- The implementation of the ADT, depends on the language, the platform, etc.
- Example: Heaps implemented as arrays

# DESCRIBING A DATA STRUCTURE

## API (Application Programming Interface):

- Functions provided by the data structure and their complexities

## Invariants

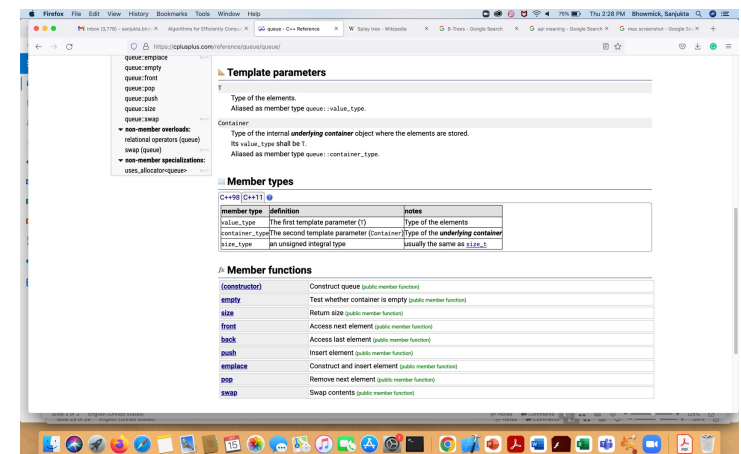
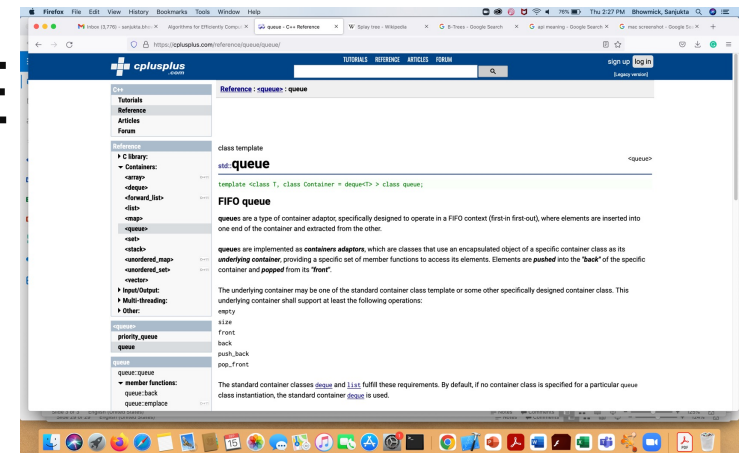
- Properties that hold true during the lifetime of the data structure

## Data Model

- How is the data stored; list, array, etc.

## Algorithms

- Algorithms to support the API functions



# PRIORITY QUEUES

Given a dynamic data set, enable access to element with highest priority

- Queue: First in First out (Priority: highest time stamp)
- Stack: Last in First out (Priority: lowest time stamp)
- Used in scheduling, shortest paths, efficient routing, etc.

More general: heaps

- Max heap: Element with highest value
- Min heap: Element with lowest value

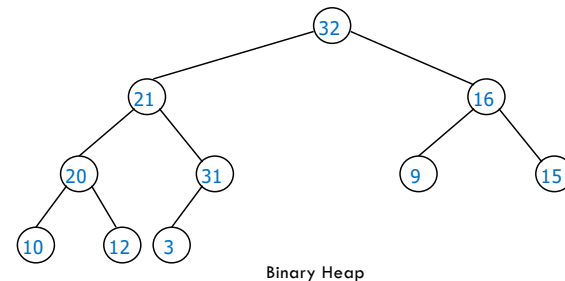
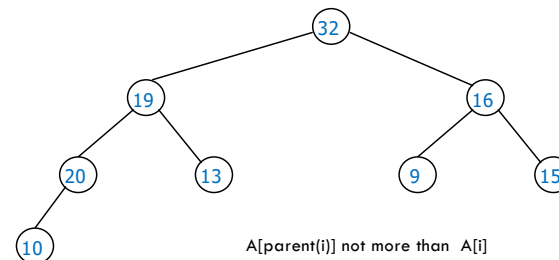
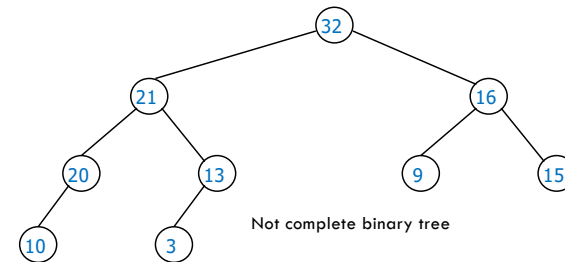
Operations

- Top: remove element with highest priority from top
- Peek: check what is the element with the highest priority
- Insert: insert an element, along with its priority
- Delete: remove an element
- Update: update the priority of an element

# BINARY HEAP

## Invariant Properties

- Is a complete binary tree
  - Every level except possibly the last is filled and the leaves are as far left as possible (fill from left to right)
  - What is the benefit ?
- For a maxheap: every node  $i$  other than the root,  $A[\text{parent}(i)] > A[i]$ 
  - Parents are greater than children
  - Reverse if minheap
  - What does that imply about the root ?

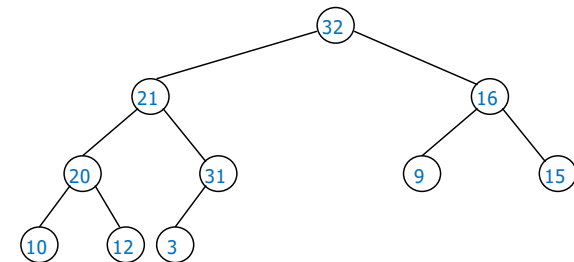


# BINARY HEAP

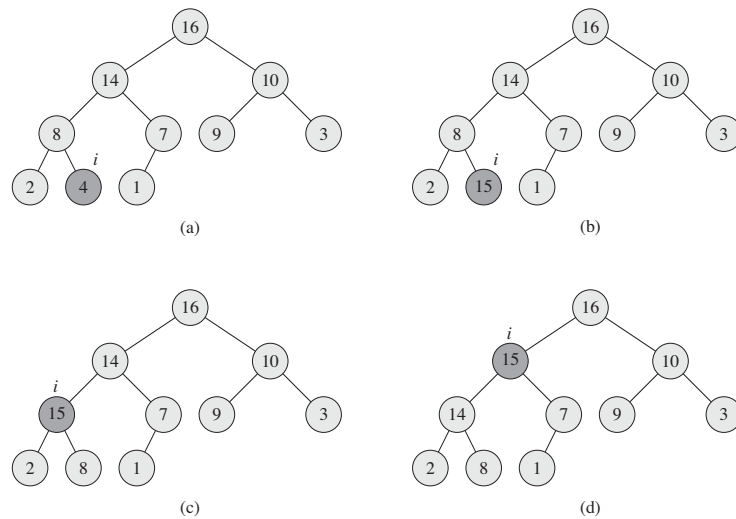
For any element in array position  $i$ , the left child is in position  $2i$ , the right child is in the cell after the left child ( $2i+1$ ), and the parent is in position  $\lfloor i/2 \rfloor$

The operations required to traverse the tree are extremely simple and very fast on most computers.

32	21	16	20	31	9	15	10	12	3
1	2	3	4	5	6	7	8	9	10



# UPDATING—INCREASE KEY



Complexity:  $O(\log n)$

**Figure 6.5** The operation of HEAP-INCREASE-KEY. **(a)** The max-heap of Figure 6.4(a) with a node whose index is  $i$  heavily shaded. **(b)** This node has its key increased to 15. **(c)** After one iteration of the **while** loop of lines 4–6, the node and its parent have exchanged keys, and the index  $i$  moves up to the parent. **(d)** The max-heap after one more iteration of the **while** loop. At this point,  $A[\text{PARENT}(i)] \geq A[i]$ . The max-heap property now holds and the procedure terminates.

# BUILD HEAP

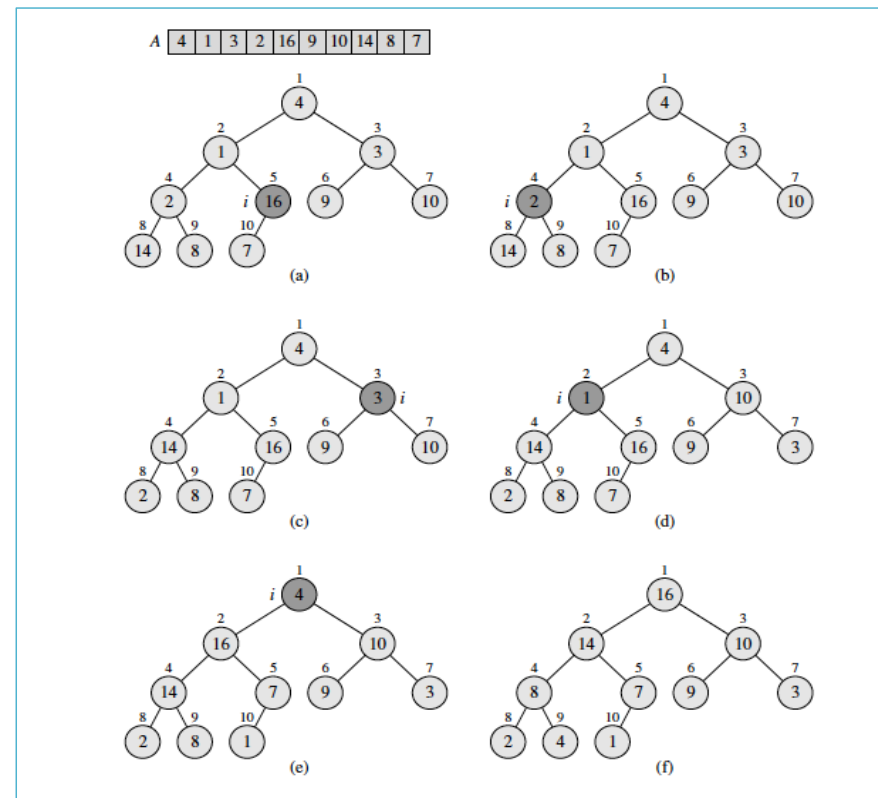
Fill the heap in order the numbers appear in the array A

For  $i = \text{length}[A]/2$  to 1

- Start with the rightmost nonleaf node to root
- Percolate down until heap property is achieved

$A[\text{parent}[i]] > A[i]$

Max Heap





# COMPLEXITY OF BUILDING HEAP

To build the heap, we have to heapify  $n$  elements

Each element takes  $O(\log n)$  time = height of the tree

What is the total time to build the heap

- $n * O(\log n) = O(n \log n)$
- However, by creating a max heap we can only know the element with the maximum value
- We could have had the information in  $O(n)$  time by just going through the array
- Why is build heap more expensive ?

## TIGHTER BUILD-HEAP TIME

Each node does not traverse any more than its height.

There are at most  $\lceil n/2^{h+1} \rceil$  nodes at height  $h$ .

Therefore total number of traversals

$$\sum_{h=0}^{\lceil \lg n \rceil} \left\lceil \frac{n}{2^{h+1}} \right\rceil O(h) = O\left(n \sum_{h=0}^{\lceil \lg n \rceil} \frac{h}{2^h}\right)$$

## Tighter Build-Heap Time

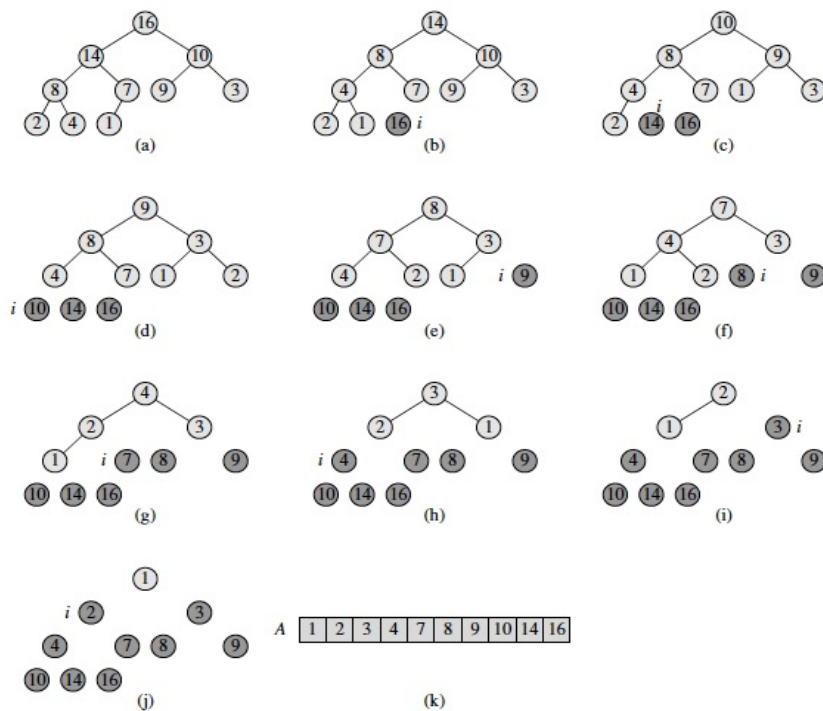
Geometric Series  $\sum_{k=0}^n x^k = \frac{x^{n+1} - 1}{x - 1}$ .

If  $x < 1$  and  $n$  tends to  $\infty$   $\sum_{k=0}^{\infty} x^k = \frac{1}{1 - x}$ .

Taking the derivative on each side  $\sum_{k=0}^{\infty} kx^k = \frac{x}{(1 - x)^2}$

Set  $x = 1/2$  to compute bound on build heap to be  $O(n)$

# HEAPSORT



HEAPSORT(A)

```

1 BUILD-MAX-HEAP(A)
2 for i ← length[A] downto 2
3   do exchange A[1] ↔ A[i]
4   heap-size[A] ← heap-size[A] - 1
5   MAX-HEAPIFY(A, 1)

```

Replace element to be deleted  
by the last in array.

Delete the last element

Update heap to maintain heap  
property

Deleting elements takes  $O(\log n)$

Heapsort = Deleting  $n$  elements

$O(\log(n)) + \log(n-1) + \dots + 1 = O(\log n!) = O(n \log n)$

# COMPLEXITIES OF HEAP OPERATIONS

Top :  $O(1)$

Peak:  $O(1)$

Insert:  $O(\log h)$ , worst case  $O(\log n)$

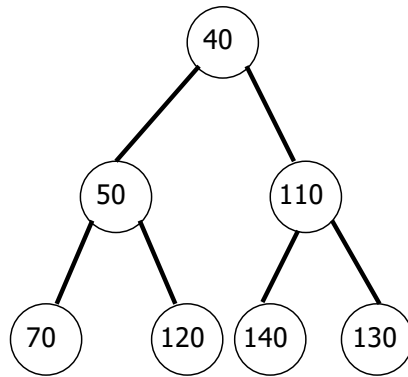
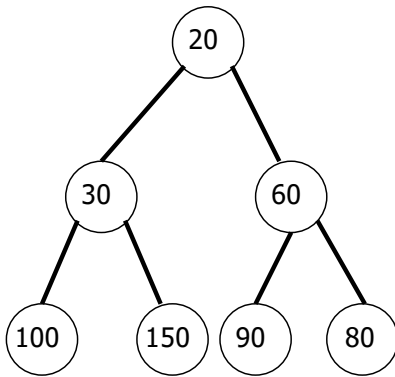
Delete:  $O(\log h)$ , worst case  $O(\log n)$

Update:  $O(\log h)$ , worst case  $O(\log n)$

How do we combine two heaps ?

Can we do Insert and Update in  $O(1)$  ?

# MERGING TWO HEAPS



If we concatenate the arrays and recreate the heap  $O(m+n)$

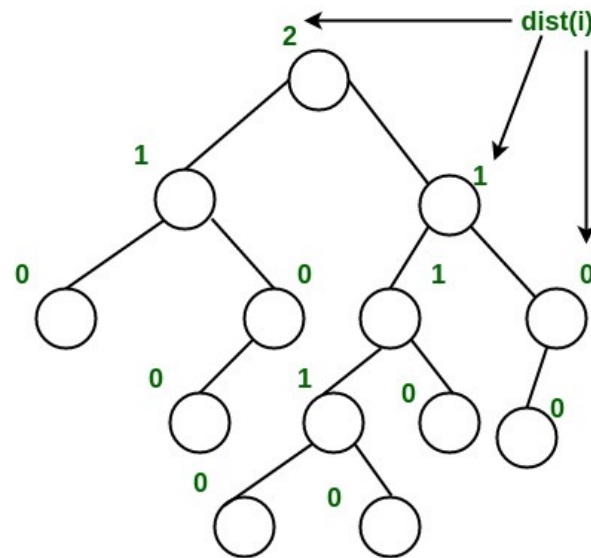
If smaller heap has  $n$  elements, and we just insert these elements, then total cost is  $O(n)$

Can we do better ?

## LEFTIST HEAP

A leftist heap is a binary heap where

- Element of highest priority (max/min) is at top
- $\text{Left}(S\_value) \geq \text{Right}(S\_value)$
- $S\_value = \text{distance to leaf}$
- $S\_value \text{ of leaf} = 0$
- $S\_value \text{ of node with one child} = 0$



**Node:**

data	
dist	
L	R

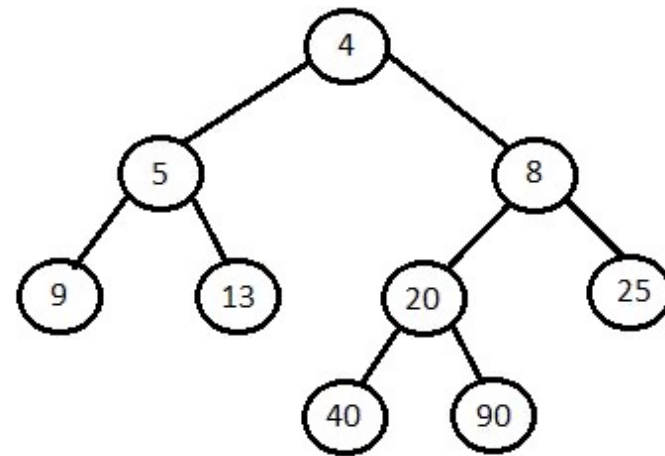
Image from <https://www.geeksforgeeks.org/leftist-tree-leftist-heap/>

# BUILDING LEFTIST HEAP

Insert new node as rightmost leaf

Check if  $S\_value$  criteria is maintained

Otherwise swap the left and right subtrees to maintain the criteria



<https://www.cs.usfca.edu/~galles/visualization/LeftistHeap.html>

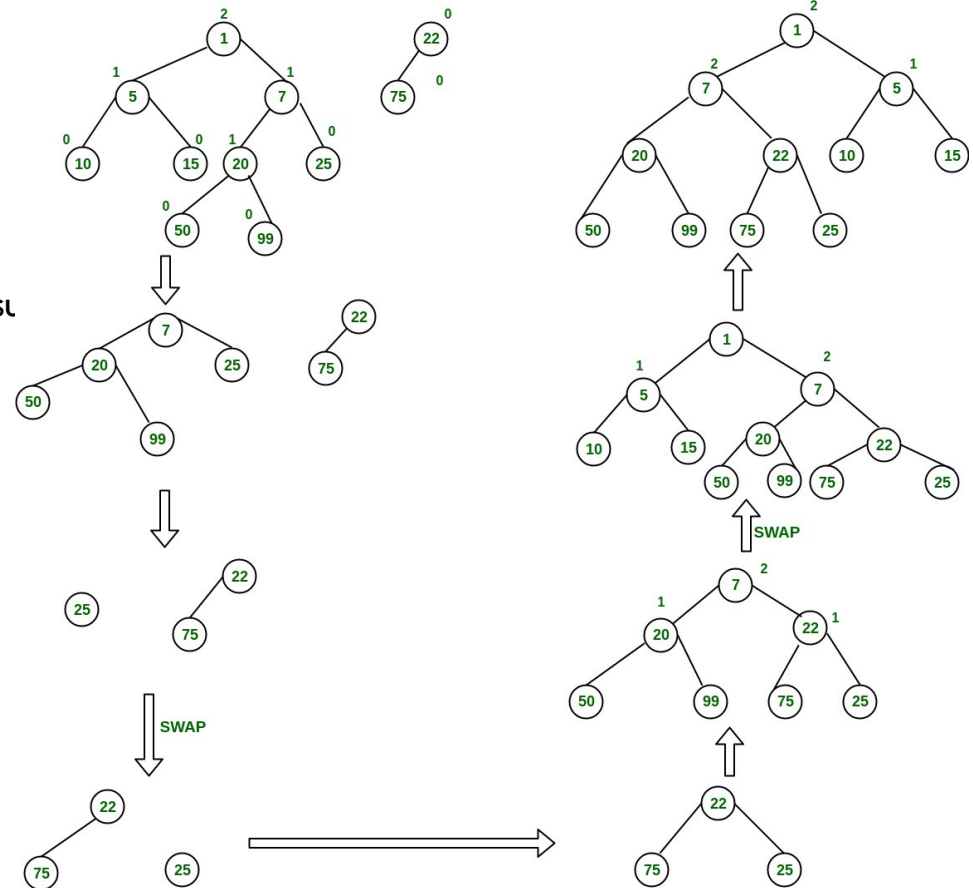
Image from <https://iq.opengenus.org/leftist-heap/>



# MERGING LEFTIST HEAPS

Merge(H1, H2)

- If H1 or H2 contains one node, insert as usual
  - If  $\text{root}(H1) < \text{root}(H2)$ 
    - $\text{right\_subtree}(H1) = \text{new\_H2}$
    - $H2 = \text{new\_H1}$
  - Else
    - $\text{right\_subtree}(H2) = \text{new\_H2}$
    - $H1 = \text{new\_H1}$
- Swap to maintain S\_value criteria as needed
- Merge(new\_H1, new\_H2)



# DELETION

Remove Root

This will create two trees

Merge them

Complexity of Insertion (one element), Deletion (one element) and Merging (smallest tree has  $n$  elements) are all  $O(\log n)$

Why do we get  $O(\log n)$ , given that the tree is not balanced ?

# PROPERTY OF LEFTIST HEAP

Given a heap with  $n$  elements, the shortest path from root to a leaf is  $O(\log n)$

- Since  $\text{Right}(S\_value) \leq \text{Left}(S\_value)$ ; therefore one of the shortest path will to the rightmost leaf
- Let the  $\text{Right}(S\_value)$  of root be  $x$
- That means there are at least  $x$  nodes from root to leaf.
- Since nodes without two children have  $S\_value$  0, therefore all nodes with  $S\_value > 1$  in the path will have two children.
- Thus there are at least  $2^x - 1$  nodes
- $2^x - 1 \leq n$  ( $n$  is total number of nodes)
- $x \leq O(\log(n))$

Since we are prioritizing new insertions in the right subtree, therefore complexity is  $O(\log n)$

# BINOMIAL QUEUES

Binomial queues support all three operations (insertion, deleteMin, and merge) in  $O(\log N)$  worst-case time per operation, but insertions take constant time on average.

# BINOMIAL QUEUE STRUCTURE

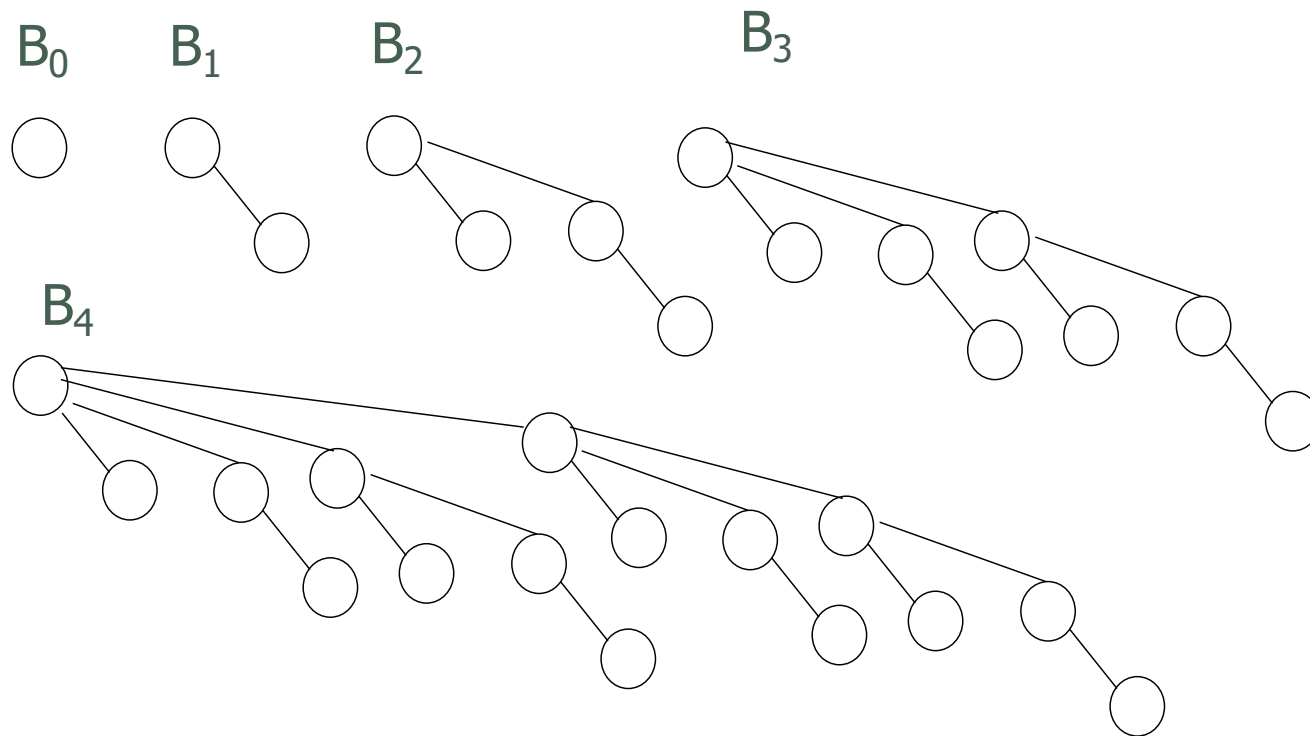
Binomial queue is not a heap-ordered tree but rather a collection of heap-ordered trees, known as a forest.

Each of the heap-ordered trees is of a constrained form known as a binomial tree.

## HOW TO CONSTRUCT A BINOMIAL TREE?

1. A binomial tree  $B_0$  of height 0 is a one-node tree;
2. A binomial tree,  $B_k$ , of height  $k$  is formed by attaching a binomial tree,  $B_{k-1}$ , to the root of another binomial tree,  $B_{k-1}$ .

# BINOMIAL TREES $B_0, B_1, B_2, \dots$



# PROPERTIES

A binomial tree,  $B_k$ , consists of a root with children  $B_0, B_1, \dots, B_{k-1}$ .

The height of a binomial tree,  $B_k$ , is  $k$ .

Binomial trees of height  $k$  have exactly  $2^k$  nodes.

The number of nodes at depth  $d$  is the binomial coefficient (root has depth 0 and height  $k$ )

- $= k! / ((k-d)! \cdot d!).$



# PRIORITY QUEUE USING BINOMIAL TREES

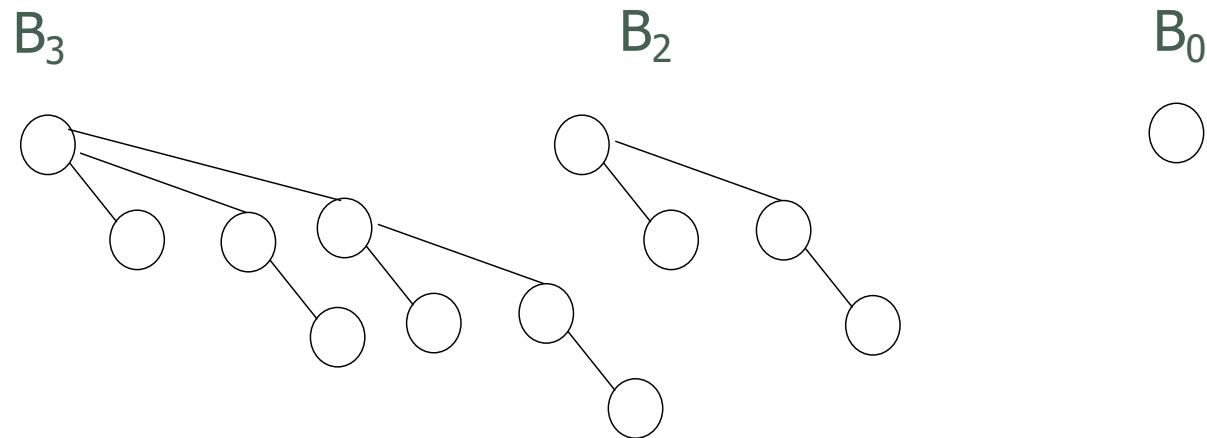
Impose heap order on the binomial trees

Allow **at most one** binomial tree of any height

Then, we can **uniquely** represent a priority queue of any size by a collection of binomial trees.

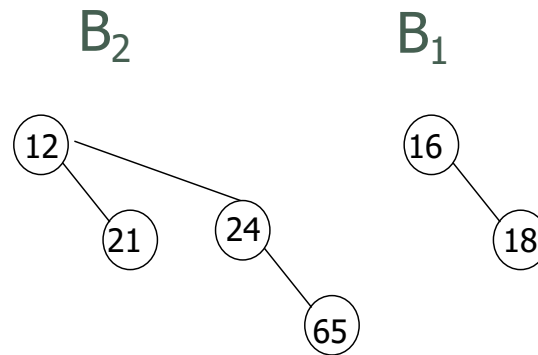
HOW ?

# A PRIORITY QUEUE OF SIZE 13



$$13 = 1101$$

## A PRIORITY QUEUE OF SIZE 6



$$6 = 110$$

# BINOMIAL QUEUE OPERATIONS

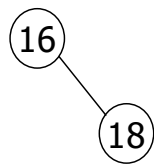
Find the minimum element:  $O(\log N)$

- The minimum element can be found by scanning the roots of all the trees. Since there are at most  $\log N$  different trees, the minimum can be found in  $O(\log N)$  time.

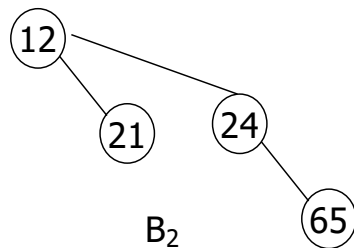
We can maintain knowledge of the minimum and perform the operation in  $O(1)$  time.

# MERGING TWO BINOMIAL QUEUES

$H_1$ :



$B_1$

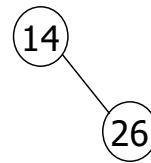


$B_2$

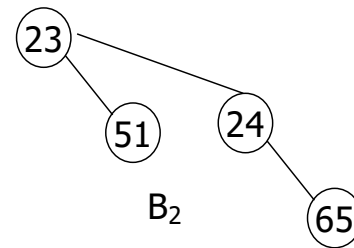
$H_2$ :



$B_0$



$B_1$

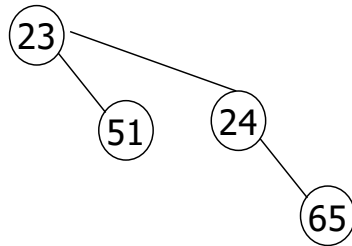


$B_2$

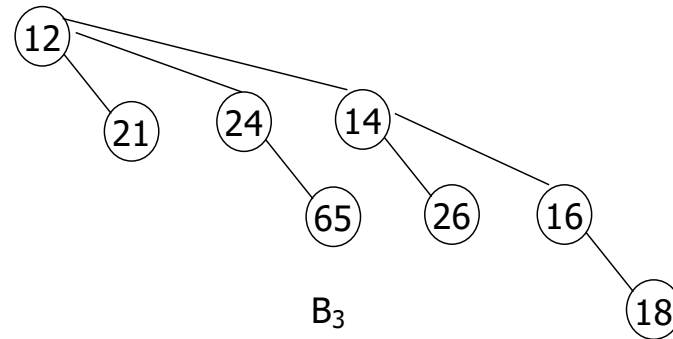
$H_3$ :



$B_0$



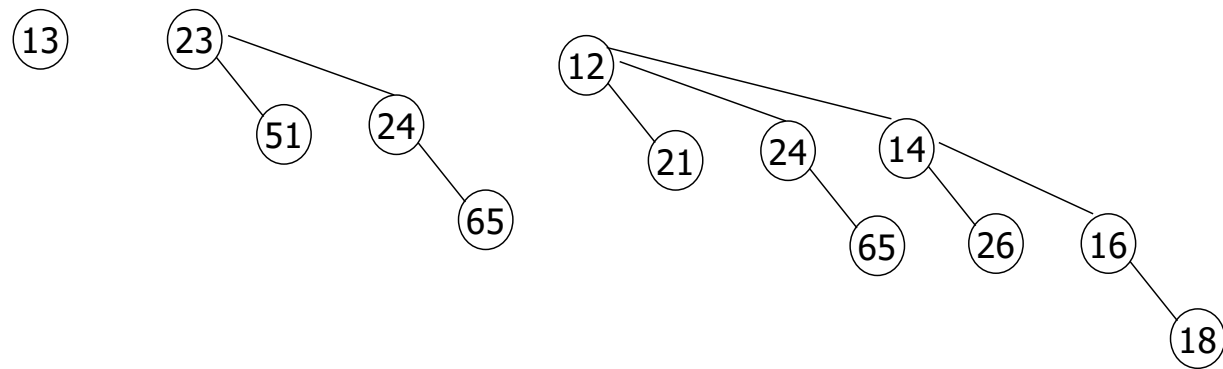
$B_2$



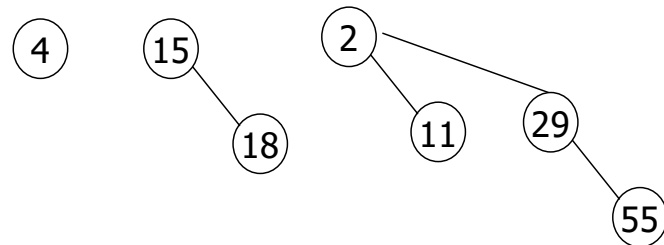
$B_3$

## EXERCISE: MERGING TWO BINOMIAL QUEUES

$H_1$ :



$H_2$ :



## COMPLEXITY ON MERGE

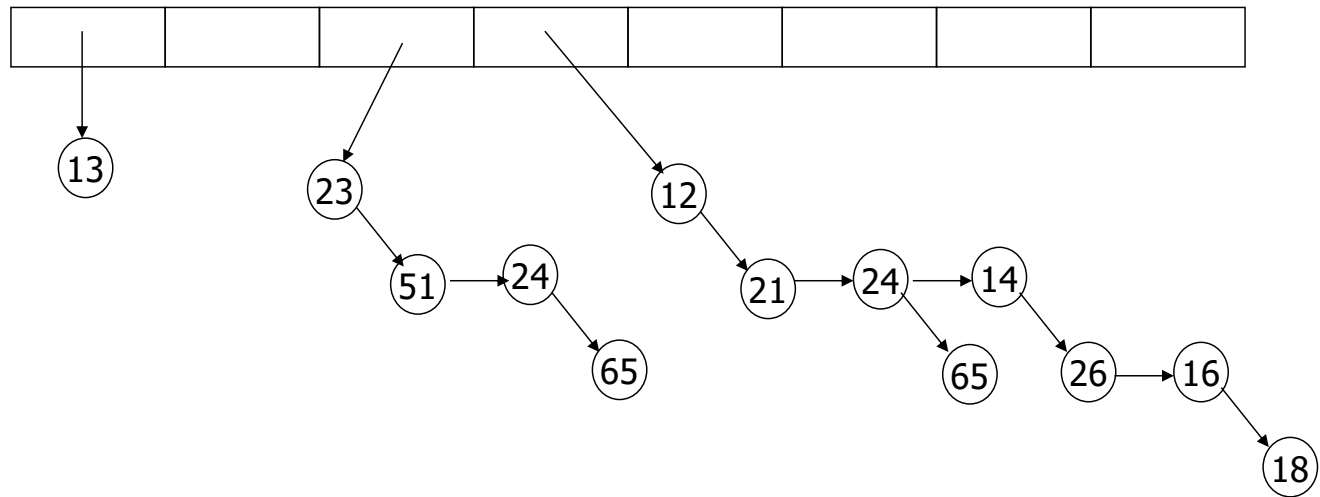
Merging two binomial trees takes constant time.

There are  $O(\log N)$  binomial trees.

So merge two binomial queues take  $O(\log N)$  time in the worst case.

To make this operation efficient, we need to keep the trees in the binomial queue sorted by height.

# REPRESENTATION OF BINOMIAL QUEUE





# INSERTION

Insertion is just a special case of merging: create a one-node tree and perform a merge.

Worst case:  $O(\log N)$

Averagely:  $O(1)$

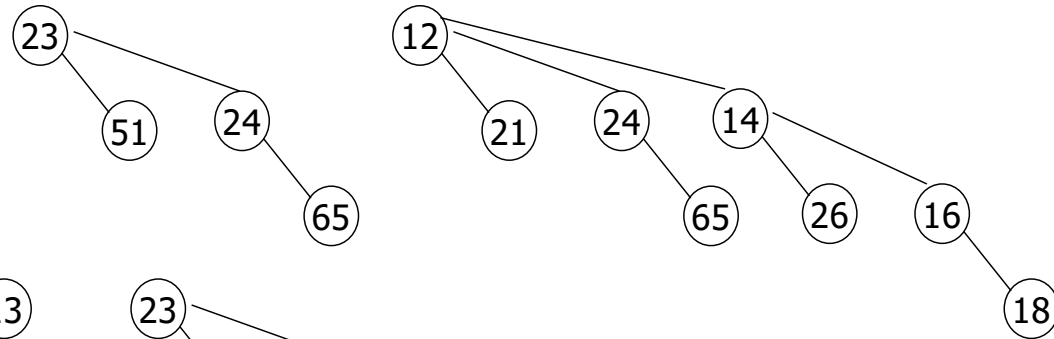
Performing  $N$  inserts on an initially empty binomial queue will take  $O(N)$  worst-case time

## DELETEMIN

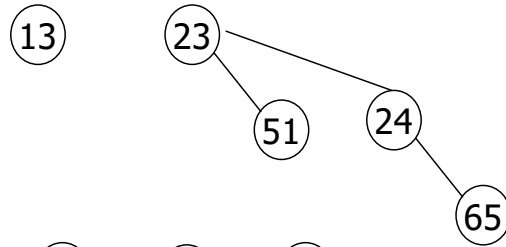
1. Find the binomial tree with the smallest root. Let this tree be  $B_k$ , and let the original binomial queue be  $H$ .
2. Remove the binomial tree  $B_k$  from  $H$ , and form a new binomial queue  $H'$ .
3. Remove the root of  $B_k$ , create binomial trees  $B_0, B_1, \dots, B_{k-1}$ , and form another new binomial queue  $H''$ .
4. Merge  $H'$  and  $H''$ .

# DELETMIN OPERATION

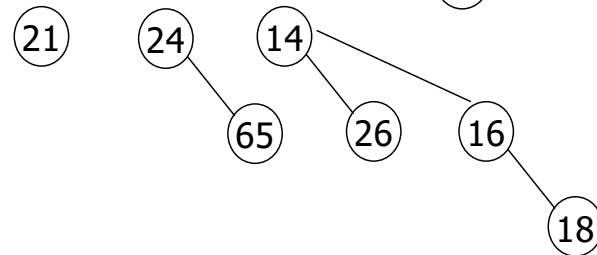
H<sub>3</sub>: 13



H':



H'':



Merge H' and H''.

## COMPLEXITY ON DELETEMIN

It takes  $O(\log N)$  time to find the tree containing the minimum element.

Constant time to create the queues  $H'$  and  $H''$ .

Merging these two queues takes  $O(\log N)$  time.

Entirely  $O(\log N)$  time

# SUMMARY

Binary Heaps: Find minimum is constant; Insertion, Delete in  $O(\log N)$ ; Merge is  $O(n+m)$

Leftist heaps: Merge is  $O(\log n)$ . Not balanced

Binomial Heap: Insertion is constant on average. A forest of multiple binomial trees

Other types of heaps:

D-way heaps, Fibonacci heaps, etc.