## IE 684 Lab 11: Optimization Algorithms Gradient Descent, Momentum, and NAG

#### Instructions

- Solve all problems independently. Seek help from instructors/TAs if needed.
- Use Python (NumPy, Matplotlib) for implementations.
- Submit separate notebooks for each exercise:
  - YOURROLLNUMBER\_IE684\_Lab05\_Ex1.ipynb
  - YOURROLLNUMBER\_IE684\_Lab05\_Ex2.ipynb
- Include LaTeX equations for explanations, plots for results, and comments on observations.
- Zip all files as YOURROLLNUMBER\_IE684\_Lab05.zip and upload to Moodle.

#### **Submission Guidelines**

- Include LaTeX equations for all derivations.
- Label plots clearly (title, axes, legend).
- Comment on observations (e.g., "NAG converges faster due to anticipatory updates").
- Penalties for incorrect naming conventions.

## Exercise 1: Mathematical Formulation (25 marks)

[R] Write the mathematical formulation for the following scenario to minimize the overall supply chain cost. There are two factories [P1, P2] which produce three products [PD1, PD2, PD3]. These products are transported from the factories to depots. There are five depots [D1, D2, D3, D4, D5] from where the products are delivered to ten customers [C1, C2, C3, C4, C5, C6, C7, C8, C9, C10]. While writing the formulation, the following parameters need to be considered:

- Production cost per product at factories.
- Transportion cost for factory to depot.
- Transportion cost for depot to customer.
- Depot capacity.
- Demand at customer location.

## Exercise 2: Gradient Descent Variants (25 marks)

Consider the function:

$$f(\mathbf{x}) = 3x_1^2 + 2x_1x_2 + 3x_2^2 - 4x_1 - 4x_2$$

#### 1. Theoretical Analysis (5 marks)

- Find the minimizer  $\mathbf{x}^*$ , minimum value  $f(\mathbf{x}^*)$ , and confirm if it's a global minimum.
- Compute the Hessian  $\nabla^2 f(\mathbf{x})$ . Is  $f(\mathbf{x})$  convex? Justify.

#### 2. Implementation (10 marks)

- Implement Gradient Descent (GD) with fixed step size  $\eta = 0.1$ . Use  $\mathbf{x}_0 = (5, 5)$ ,  $\tau = 10^{-6}$ .
- Plot  $\log(\|\mathbf{x}_k \mathbf{x}^*\|_2)$  vs. iterations. Comment on convergence rate.
- Repeat for  $\eta \in \{0.01, 0.05, 0.2\}$ . Plot all trajectories on the same graph. Compare results.

#### 3. Momentum and NAG (10 marks)

- Implement Momentum GD ( $\beta = 0.9$ ) and NAG ( $\beta = 0.9$ ) with  $\eta = 0.1$ .
- Plot  $\log(|f(\mathbf{x}_k) f(\mathbf{x}^*)|)$  for GD, Momentum, NAG. Compare convergence.
- Vary  $\beta \in \{0.5, 0.9, 0.99\}$ . Plot error vs. iterations for each  $\beta$ . Analyze the effect of momentum.

#### Algorithm 1 Gradient Descent with Momentum

**Require:** Initial point  $\mathbf{x}_0$ , step size  $\eta$ , momentum  $\beta$ , tolerance  $\tau$ 

- 1: Initialize  $\mathbf{v}_0 = 0, k = 0$
- 2: while  $\|\nabla f(\mathbf{x}_k)\|_2 > \tau$  do
- 3:  $\mathbf{v}_{k+1} = \beta \mathbf{v}_k \eta \nabla f(\mathbf{x}_k)$
- 4:  $\mathbf{x}_{k+1} = \mathbf{x}_k + \mathbf{v}_{k+1}$
- 5: k = k + 1
- 6: end whilereturn  $\mathbf{x}_k$

#### Algorithm 2 Nesterov Accelerated Gradient (NAG)

**Require:** Initial point  $\mathbf{x}_0$ , step size  $\eta$ , momentum  $\beta$ , tolerance  $\tau$ 

- 1: Initialize  $\mathbf{v}_0 = 0, k = 0$
- 2: while  $\|\nabla f(\mathbf{x}_k)\|_2 > \tau$  do
- 3:  $\mathbf{y}_k = \mathbf{x}_k + \beta \mathbf{v}_k$
- 4:  $\mathbf{v}_{k+1} = \beta \mathbf{v}_k \eta \nabla f(\mathbf{y}_k)$
- 5:  $\mathbf{x}_{k+1} = \mathbf{x}_k + \mathbf{v}_{k+1}$
- 6: k = k + 1
- 7: end whilereturn  $\mathbf{x}_k$

## Exercise 3: Comparative Analysis (25 marks)

Consider the Rosenbrock function:

$$f(\mathbf{x}) = 100(x_2 - x_1^2)^2 + (1 - x_1)^2$$

#### 1. GD vs. Momentum vs. NAG (15 marks)

- Implement GD ( $\eta = 0.001$ ), Momentum GD ( $\eta = 0.001, \beta = 0.9$ ), and NAG ( $\eta = 0.001, \beta = 0.9$ ).
- Use  $\mathbf{x}_0 = (-1.5, 2), \tau = 10^{-6}$ . Plot trajectories on contour plots.
- Record iterations to convergence. Tabulate results and explain differences.

#### 2. Step Size Sensitivity (10 marks)

- For GD, Momentum, NAG, test  $\eta \in \{0.0001, 0.001, 0.01, 0.1\}.$
- Plot final error vs.  $\eta$ . Identify "optimal"  $\eta$  for each method.
- Discuss trade-offs (speed vs. stability).

# Exercise 4: Difference between the GD with Momentum and NAG

[R] Explain the difference between the Gradient Descent with Momentum and Nesterov Accelerated Gradient (NAG)

### Reading Material

Click the link for finding the supplimentary material.