Calculus

Hochschule Bonn-Rhein-Seig

- Divin and Santosh

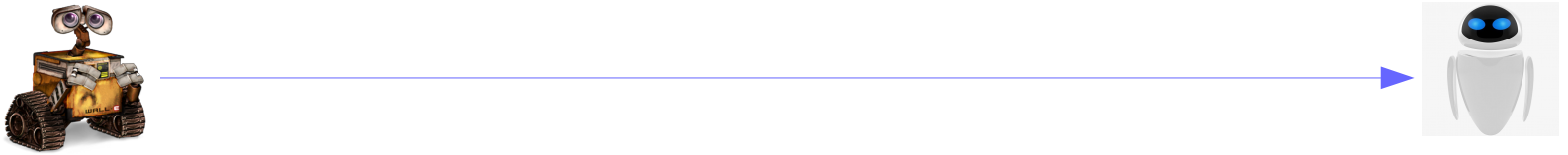
Where is Calculus applied?

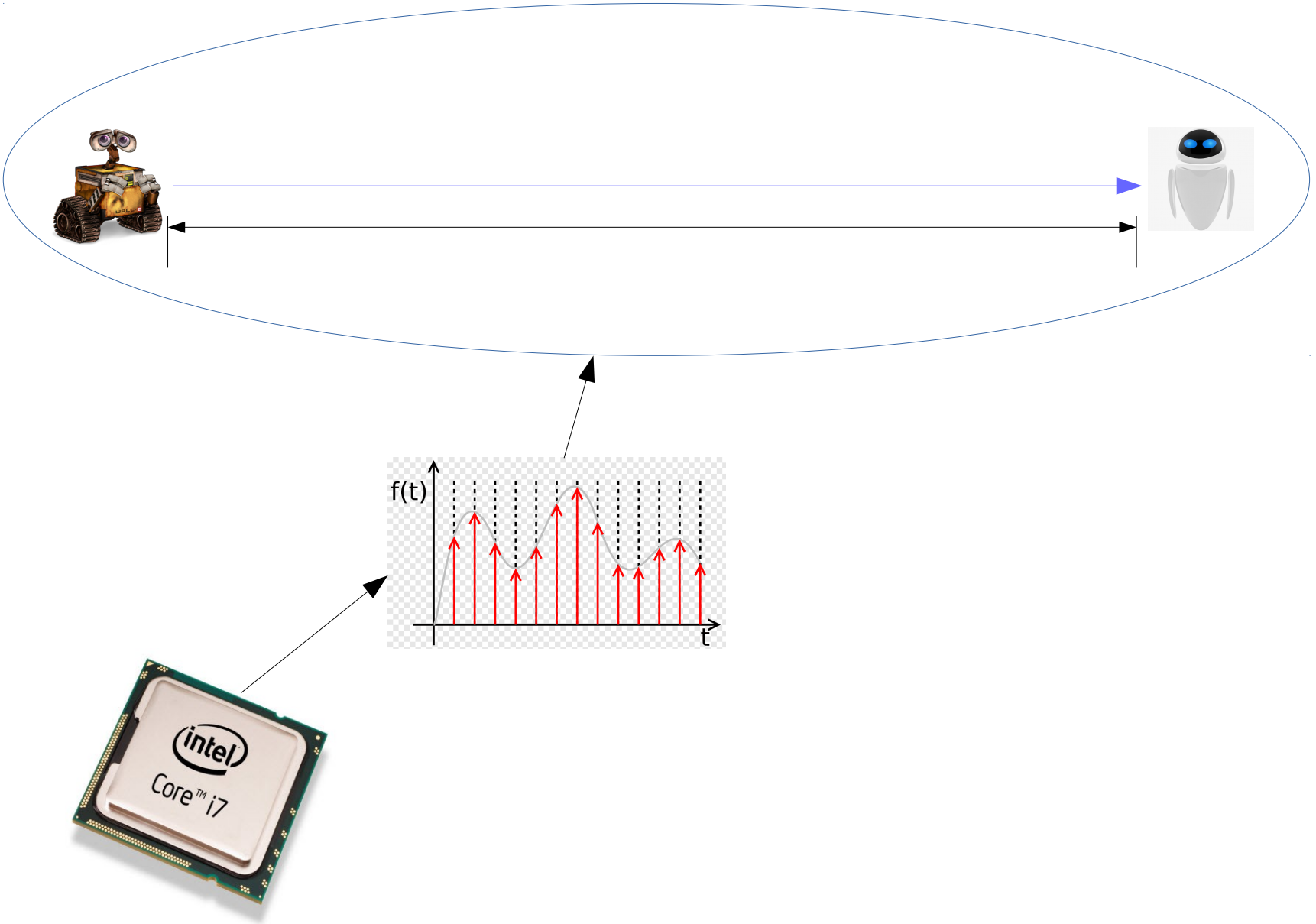
- Robotics (Kinematics)
- Neural Networks
- Dynamic System Modeling (Control System)

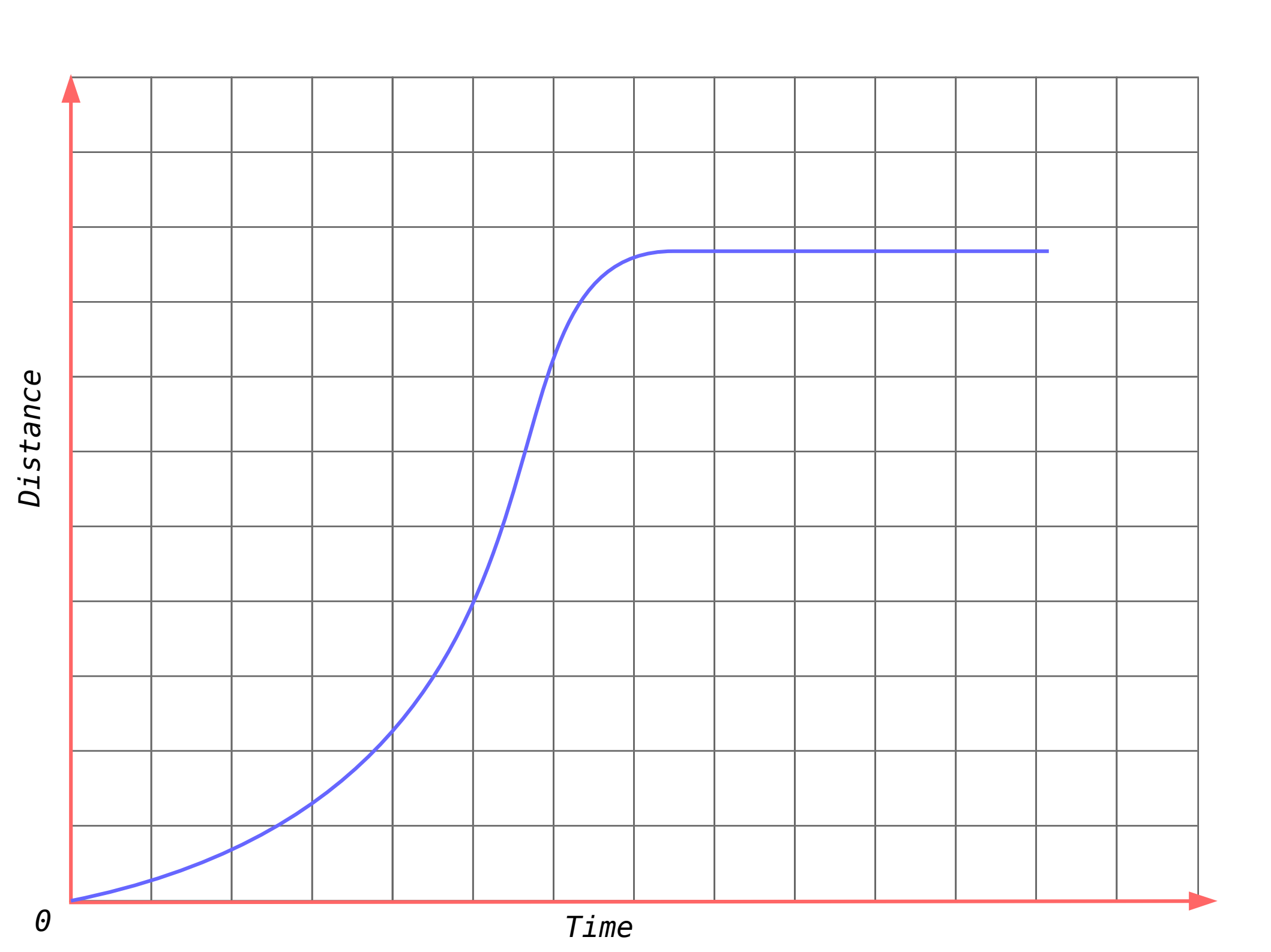
Derivatives

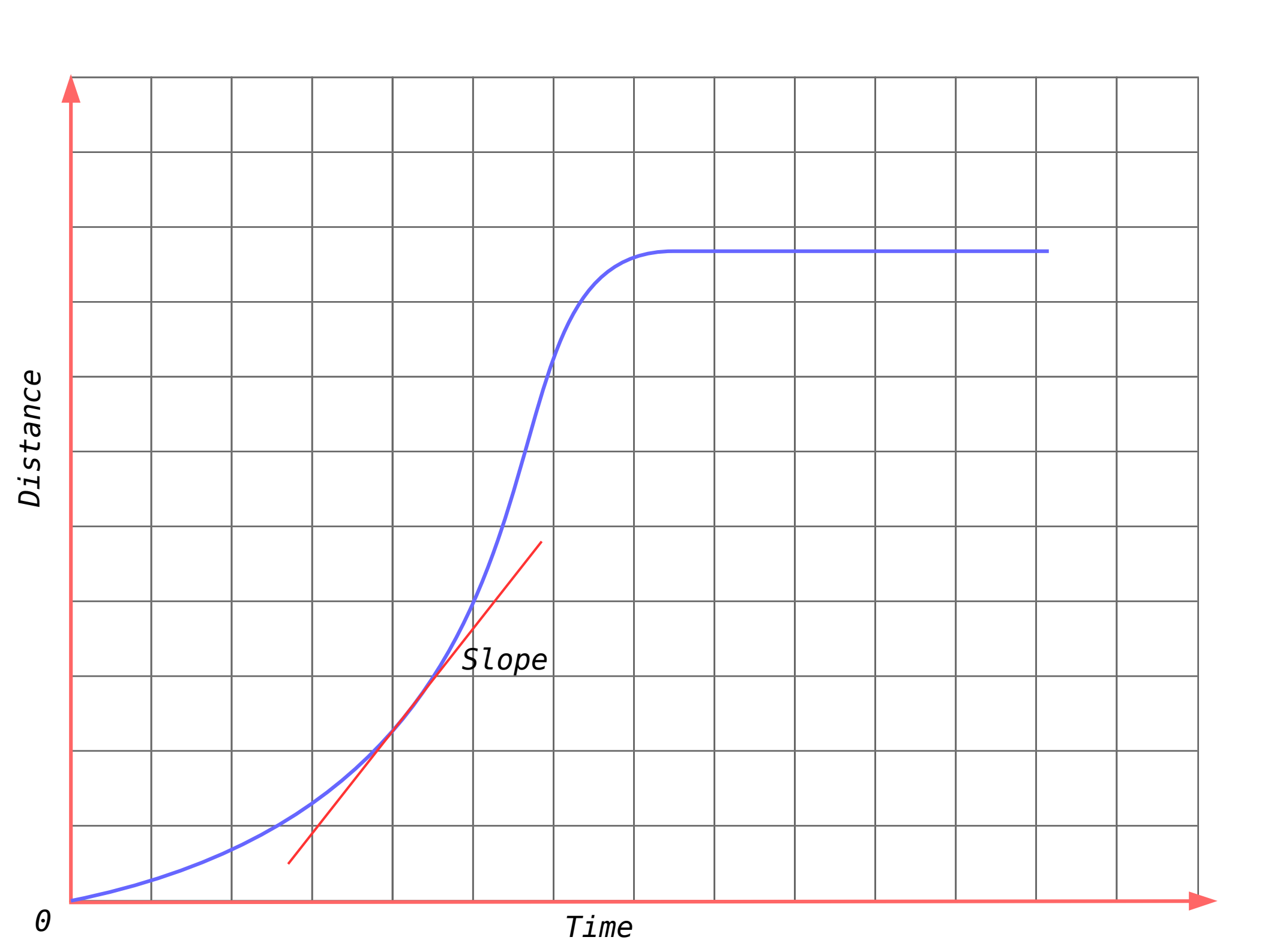
Analog

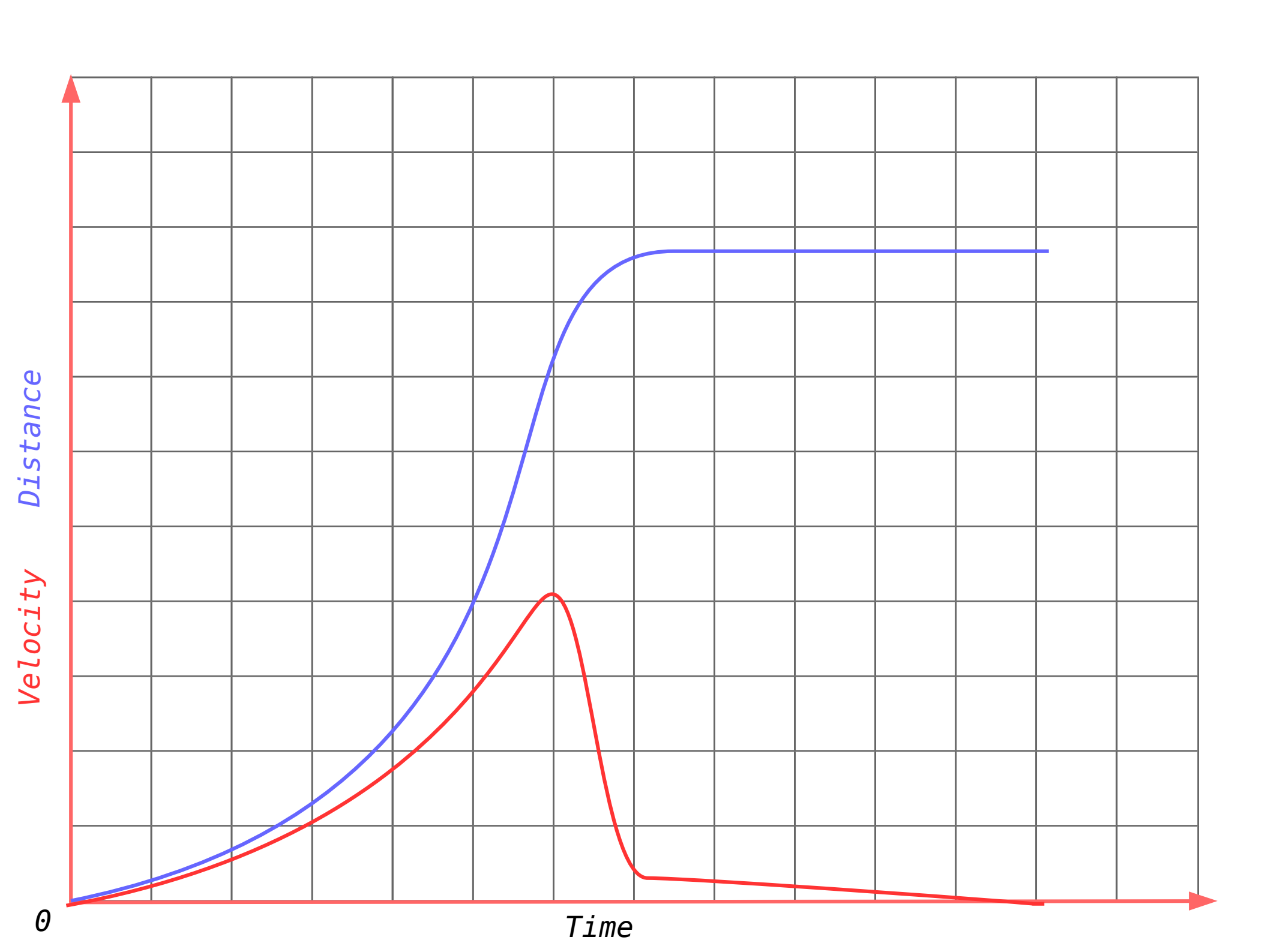
Digital

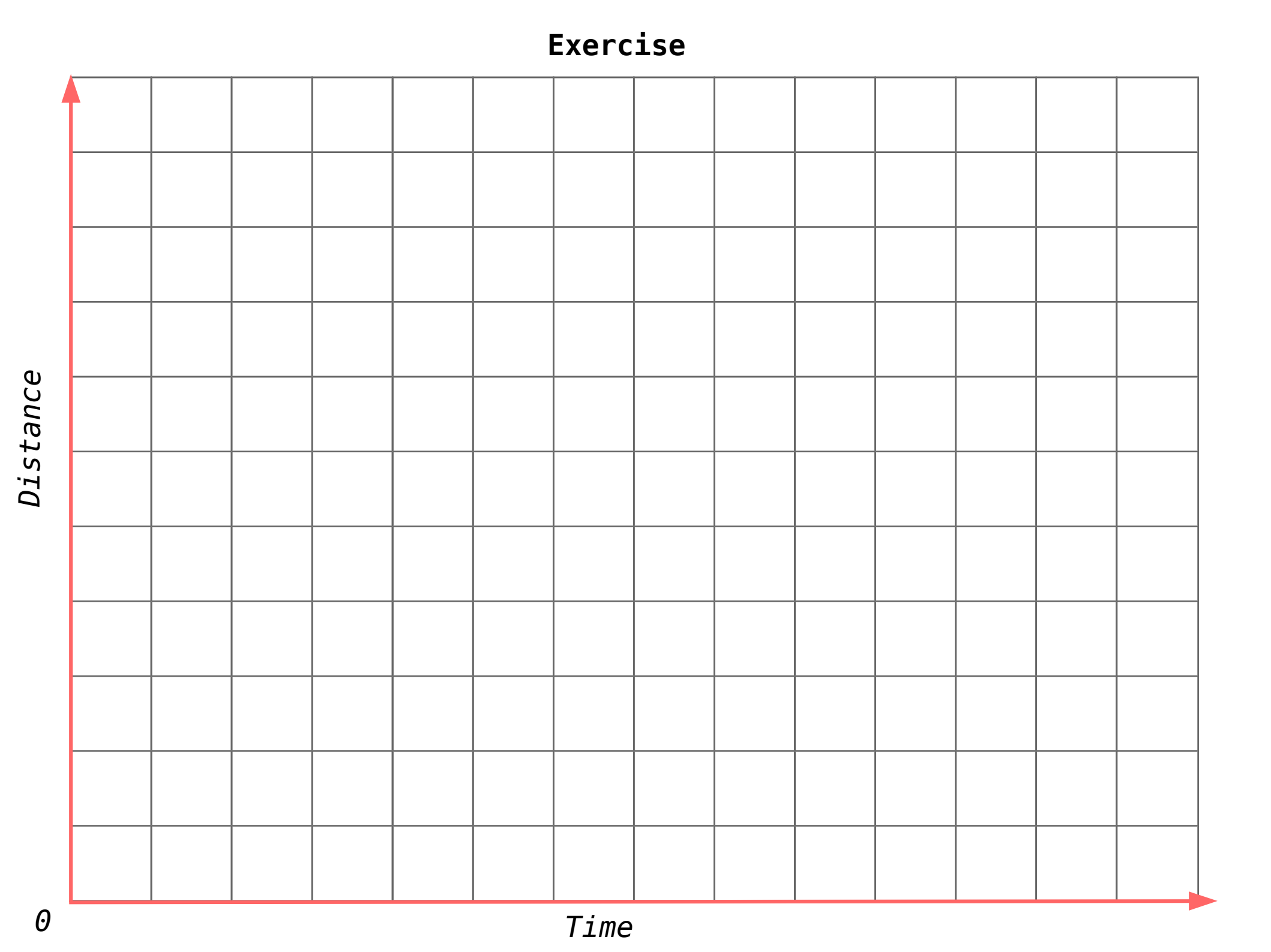


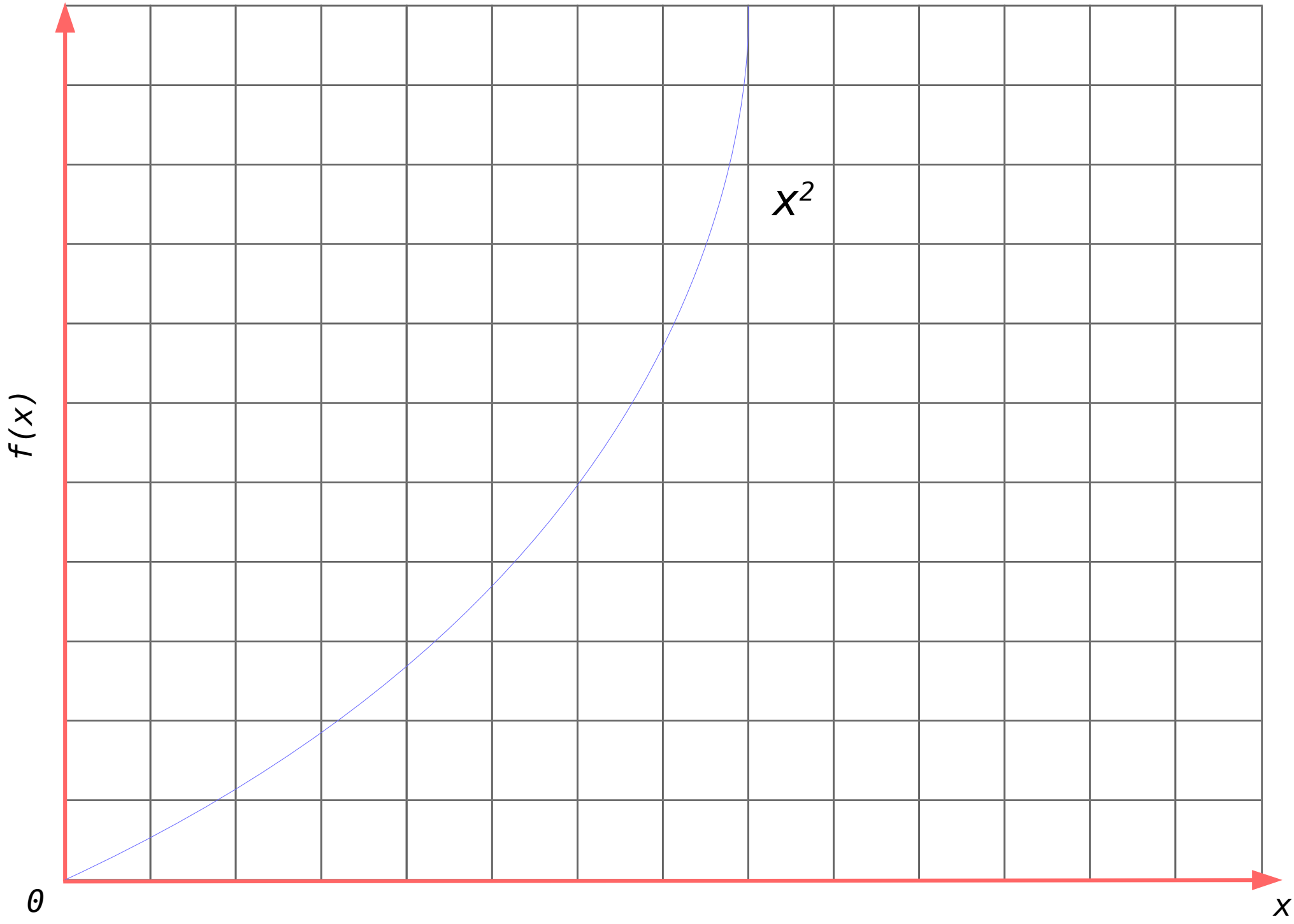

f(t)
t
intel
Core™ i7


Distance
0
Time


Distance
Slope
0
Time


Distance
Velocity
0
Time

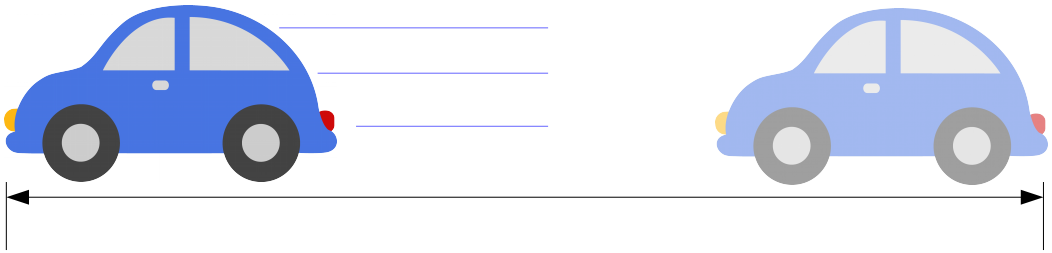

Exercise
Distance
0
Time

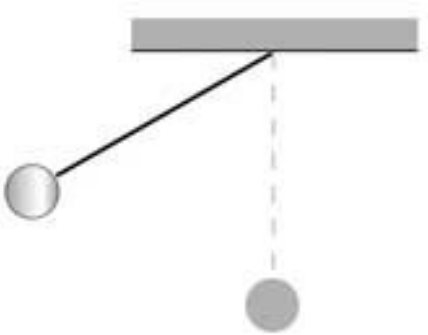

x^2
f(x)
0
x

Functions

- $f(x) = 2x^2 - x^3$
- $f(x) = sin(x)$
- $f(x) = e^x$

Application





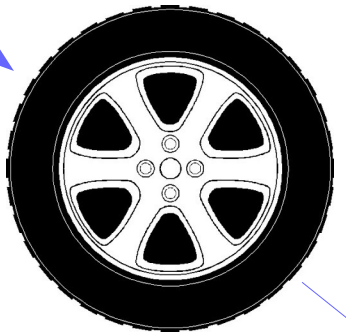
Chain Rule

Dependent Systems

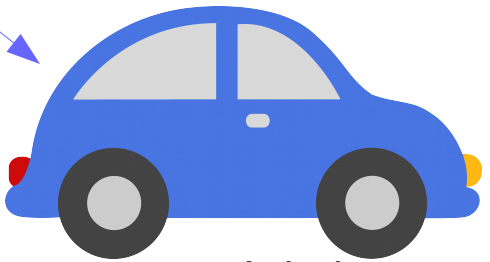
$u = f(x)$

$v = g(u)$

$w = h(v)$

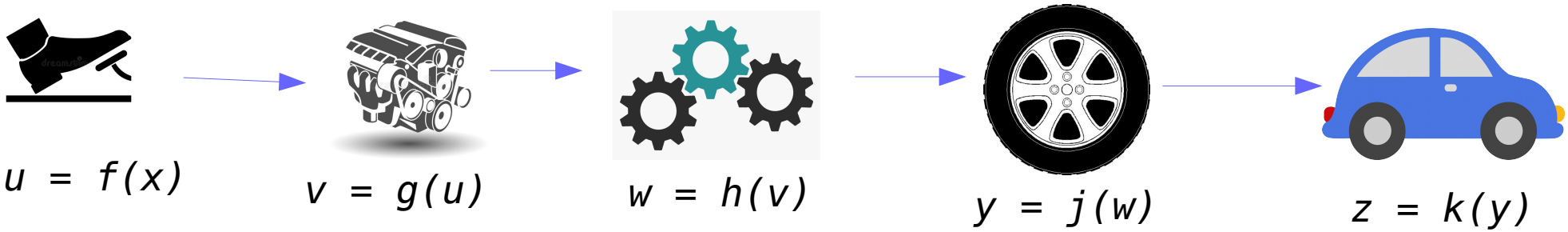


$y = j(w)$



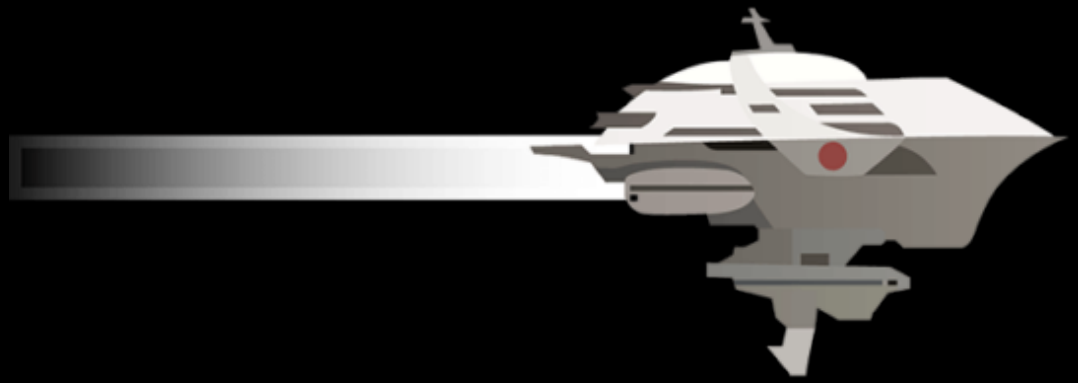
$z = k(y)$

Dependent Systems

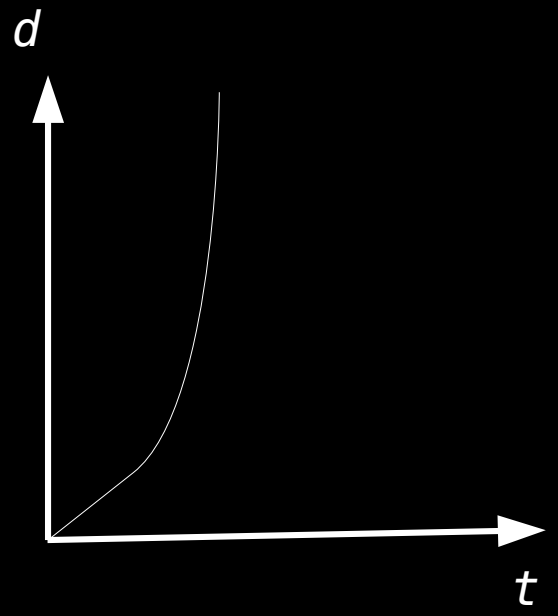


$$\frac{dz}{dx} = \frac{dz}{dy} * \frac{dy}{dw} * \frac{dw}{dv} * \frac{dv}{du} * \frac{du}{dx}$$

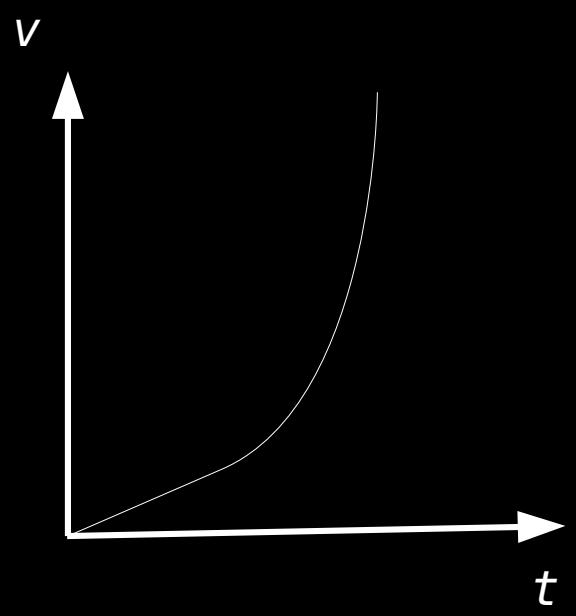
Higher Order Derivatives



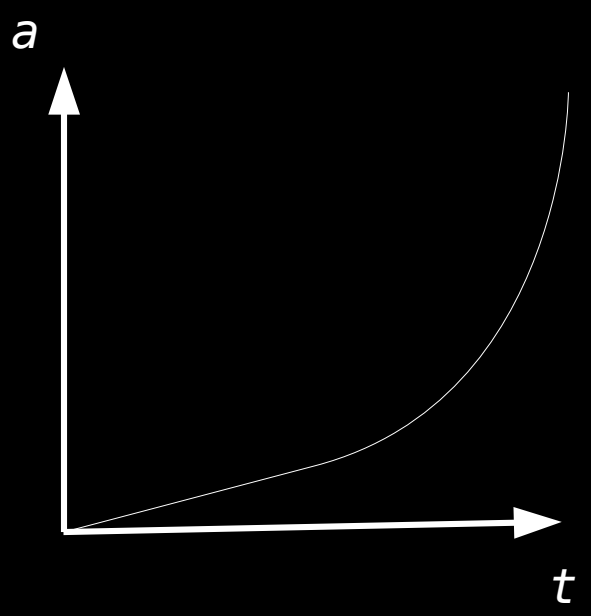
Warp Drive



$d = t^4$

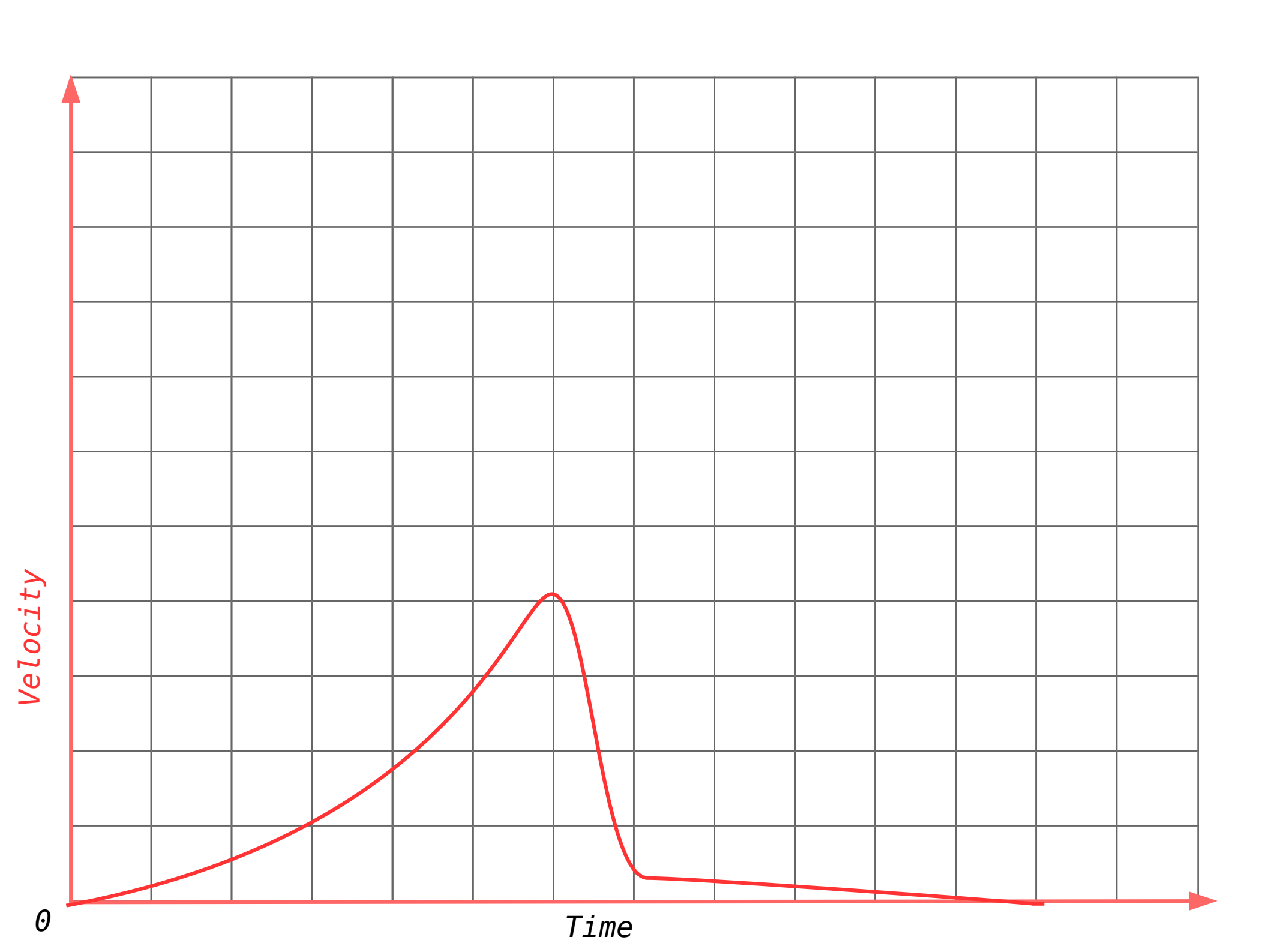


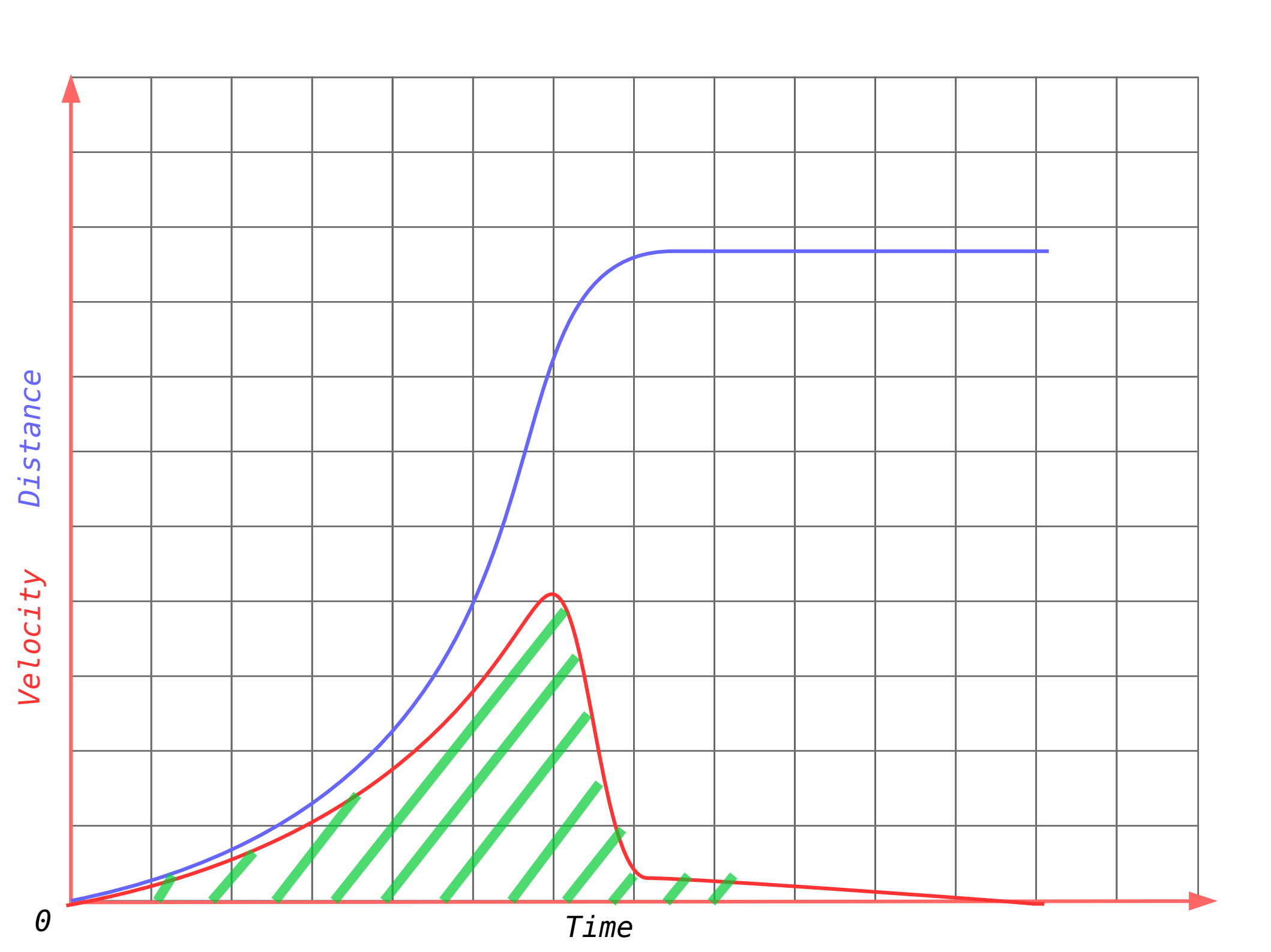
$v = 4t^3$



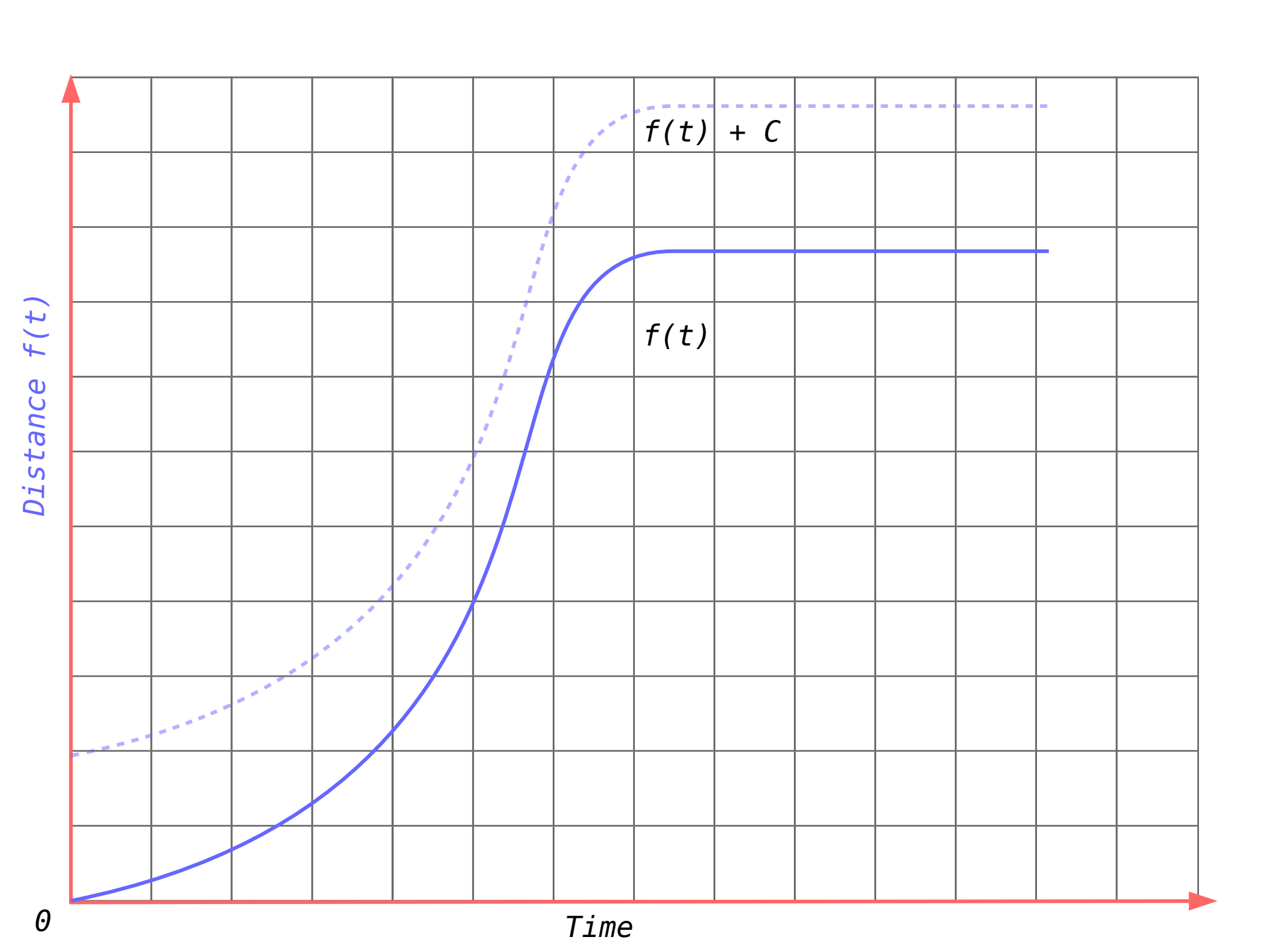
$a = 12t^2$

Integrals


Velocity
0
Time


Distance
Velocity
0
Time

Integrals Bounds


f(t) + C
f(t)
Distance f(t)
0
Time

Question