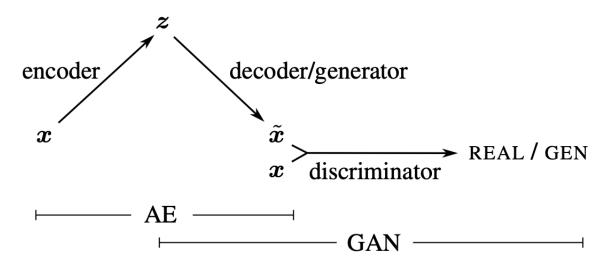
# Learning a Probabilistic Latent Space of Object Shapes via 3D Generative-Adversarial Modeling

3D - VAE - GAN

## Report



Dataset: IKEA Dataset, SUN Database

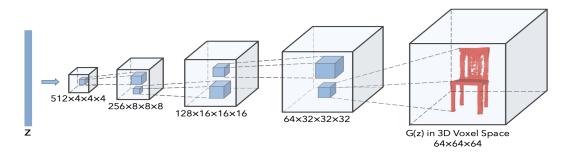
Pytorch Code: <a href="https://github.com/rimchang/3DGAN-Pytorch">https://github.com/rimchang/3DGAN-Pytorch</a>

Paper: https://arxiv.org/pdf/1610.07584.pdf

Key points to note:

### **Encoder**

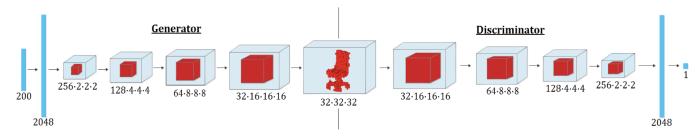
- The encoder is the part where we convert the image to a 200 D vector which is our latent space
- To do this we use 5 convolution layers with BN and ReLU in between



#### Generator

- The generator uses the latent space vector to generate the 3D model
- It contains 5 ConvTranspose3D layers with BN and ReLU in between the layers

#### **Discriminator**



- The discriminator takes the 3D Volume as input and predicts whether the 3D object is real or fake(generated model)
- The architecture of the Discriminator is the mirror of the generator model except there is a sigmoid layer attached at the end

#### **Loss Function**

$$L = L_{3 ext{D-GAN}} + lpha_1 L_{ ext{KL}} + lpha_2 L_{ ext{recon}}$$
 $L_{3 ext{D-GAN}} = \log D(x) + \log(1 - D(G(z)))$ 
 $L_{ ext{KL}} = D_{ ext{KL}}(q(z|y) \mid\mid p(z)),$ 
 $L_{ ext{recon}} = ||G(E(y)) - x||_2,$ 

- x is a 3D shape from the training set, y is its corresponding 2D image, and q(z|y) is the variational distribution of the latent representation z
- The loss function consists of three parts: an object reconstruction loss L<sub>Recon</sub>, a cross-entropy loss L<sub>3D-GAN</sub> for 3D-GAN, and a KL divergence loss L<sub>KL</sub> to restrict the distribution of the output of the encoder
- The Kullback-Leibler Divergence score, or KL divergence score, quantifies how much one probability distribution differs from another probability distribution
- So we use the KL Divergence score so that we can bring the q(z|y) as close to p(z). Basically, we want q(z|y) to represent a Gaussian distribution.