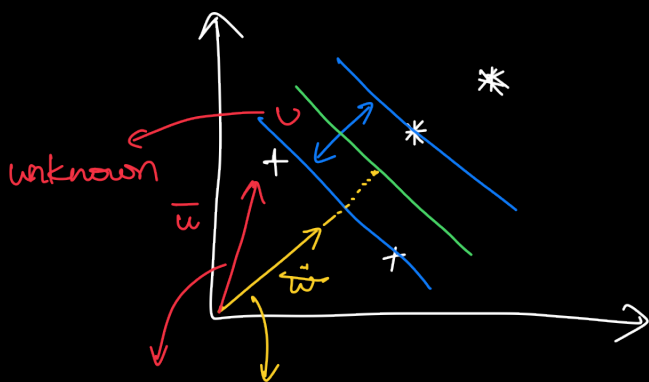


Support vector machine

Decision boundaries



vector pointing to unknown
vector which perpendicular to the median

Draw straight line

But How?

Draw wide as possible.

Now we don't know whether it is "*" or "+"

we project that vector down on the one that's \perp to the street.

$$\vec{w} \cdot \vec{u} \geq c \rightarrow \text{constant} \quad c = -b$$

DECISION
RULE

$\vec{w} \cdot \vec{u} + b \geq 0$ then it is "*"
 else it is "+"

But we don't which b to use and ①

which \vec{w} to use either.

because there can be multi \vec{w} which can be drawn from with many lengths.

adding addition constraints

$$\bar{w} \cdot \bar{x}_+ + b \geq 1$$

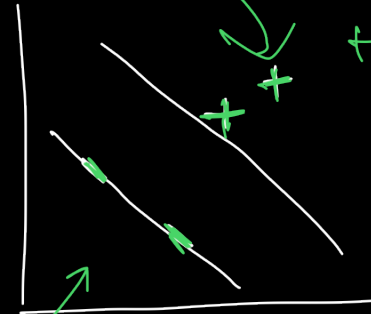
↓
positive samples

②

$$\bar{w} \cdot \bar{x}_- + b \leq -1$$

↓
negative samples

③



we introduce a term y_i for mathematical conversion -

y_i such that $y_i = +1$ for + samples.

$y_i = -1$ for - samples.

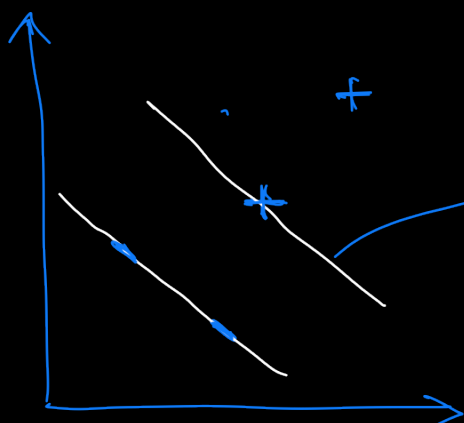
$$\textcircled{2} \Rightarrow y_i (\bar{x}_i \bar{w} + b) \geq 1$$

$$\textcircled{3} \Rightarrow y_i (\bar{x}_i \bar{w} + b) \geq 1$$

both become same equations.

⇓

$$y_i (\bar{w} \cdot \bar{x}_i + b) - 1 \geq 0$$

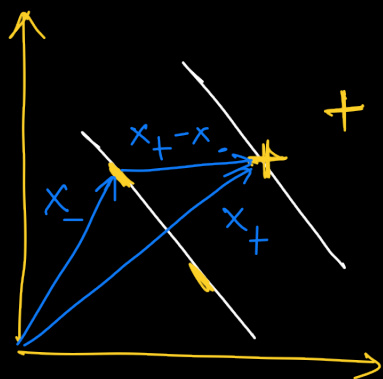


this line will be gutter

$$y_i (\bar{w} \bar{x}_i + b) - 1 = 0$$

(4)

Now to express the distance the gutter.



\bar{x}_+ = vector of x_+ in gutter

\bar{x}_- = vector of x_- in gutter

$$\text{width} = (\bar{x}_+ - \bar{x}_-) \cdot \frac{\bar{w}}{\|\bar{w}\|}$$

scalar

(5)

$$\textcircled{5} \Rightarrow \text{width} = \frac{\bar{\omega} \cdot \bar{x}_+ - \bar{\omega} \cdot \bar{x}_-}{\|\bar{\omega}\|}$$

$$\text{From } \textcircled{2} \Rightarrow +1 (\bar{\omega} \cdot \bar{x}_+ - b) - 1 = 0$$

$$\bar{\omega} \cdot \bar{x}_+ - b - 1 = 0$$

$$\boxed{\bar{\omega} \cdot \bar{x}_+ = b + 1}$$

$$\text{From } \textcircled{3} \Rightarrow -1 (\bar{\omega} \cdot \bar{x}_- - b) - 1 = 0$$

$$-\bar{\omega} \cdot \bar{x}_- + b - 1 = 0$$

$$\boxed{\bar{\omega} \cdot \bar{x}_- = b - 1}$$

Sub in $\textcircled{5}$

$$\text{width} = \frac{\cancel{b+1} - \cancel{b-1}}{\|\bar{\omega}\|}$$

$$\boxed{\text{width} = \frac{2}{\|\bar{\omega}\|}} \rightarrow \textcircled{6}$$

we need to maximize the line

$$\max \frac{2}{\|w\|}$$

So we need to $\max \frac{1}{\|w\|}$ or

~~min~~ $\|w\|$

or

↓

$\frac{1}{2} \|w\|^2$

→ But why $\frac{1}{2}$ and squared

⑦

for mathematical
convention

⑦ is an expression and ② & ③ are constraints and we need to find maximum.

If we need to find minima or maxima of a function subject to constraint then we have to use Lagrange multipliers.

$$L = \frac{1}{2} \|\omega\|^2 - \sum \alpha_i [y_i (\bar{\omega} \cdot \bar{x}_i + b) - 1]$$

expression \swarrow \searrow \downarrow \downarrow \downarrow
 summation of all constants \downarrow multipliers \downarrow constants

$$\frac{\partial L}{\partial \bar{\omega}} = \bar{\omega} - \sum \alpha_i y_i \bar{x}_i = 0$$

$$\Rightarrow \boxed{\bar{\omega} = \sum \alpha_i y_i \bar{x}_i} \rightarrow \textcircled{8}$$

$\bar{\omega}$ is the linear sum of all samples.

$$\frac{\partial L}{\partial b} = 0 - \sum \alpha_i y_i = 0$$

$$\Rightarrow \boxed{\sum \alpha_i y_i = 0} \rightarrow \textcircled{9}$$

Sub ⑧ & ⑨ in ④

$$L = \frac{1}{2} (\sum \alpha_i y_i \bar{x}_i) (\sum \alpha_j y_j \bar{x}_j) - (\sum \alpha_i y_i \bar{x}_i) (\sum \alpha_j y_j \bar{x}_j) - (\sum \alpha_i y_i b) - \sum \alpha_i$$

$$L = \frac{1}{2} (\sum \sum \alpha_i \alpha_j y_i y_j \bar{x}_i \bar{x}_j) - (\sum \sum \alpha_i \alpha_j y_i y_j \bar{x}_i \bar{x}_j) - b \sum \alpha_i y_i - \sum \alpha_i$$

$$L = \sum \alpha_i - \frac{1}{2} (\sum \sum \alpha_i \alpha_j y_i y_j \bar{x}_i \bar{x}_j)$$

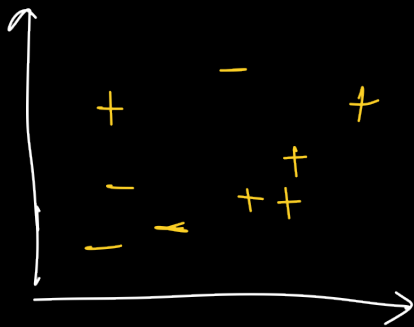
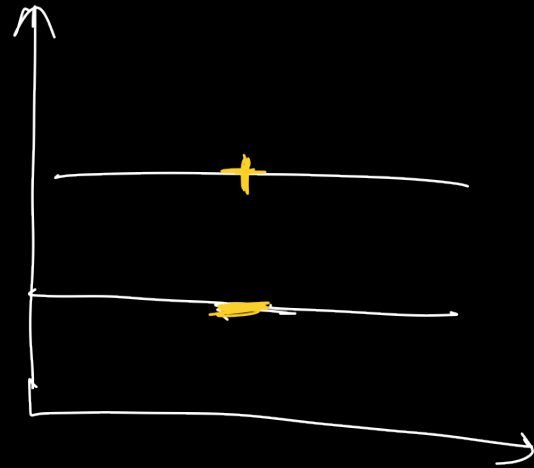
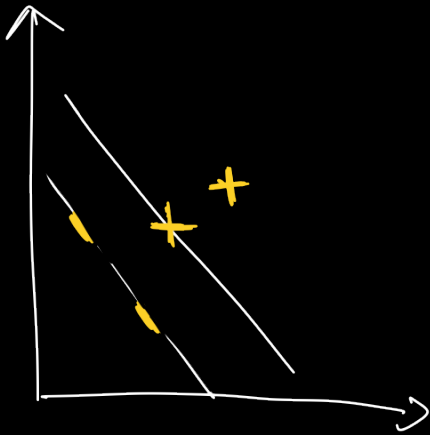
↓
We got this expression to get the dependences

optimization only depends on the dot product of \bar{x}_i and \bar{x}_j

$$\bar{w} \cdot \bar{u} + b \geq 0 \Rightarrow \sum \alpha_i y_i \boxed{\bar{x}_i \cdot \bar{u}} + b \geq 0$$

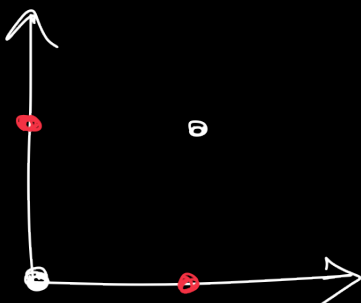
then +

depends on only
the dot
product



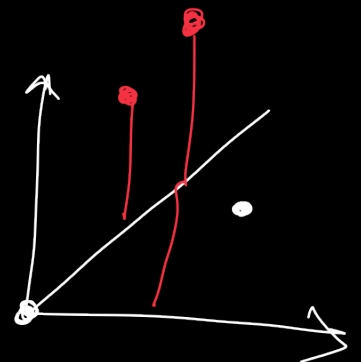
Now it get confused
because it is not
linearly inseparable.

But then



Suppose

transform
 \Rightarrow to
outer
space



$\phi(\bar{x}) \rightarrow$ is the transformation function.

and we also know the optimization only depends on the dot product of the sample vectors.

so, $\phi(\bar{x}_i) \cdot \phi(\bar{x}_j)$ to max.

and to recognize we need.

$$\phi(\bar{x}_i) \cdot \phi(\bar{u})$$

$$K(\bar{x}_i, \bar{x}_j) = \phi(\bar{x}_i) \cdot \phi(\bar{x}_j)$$

Kernel function.

popular kernels

① linear kernel

$$(\bar{u} \cdot \bar{v} + 1)^n$$

②

$$e^{-\frac{\|\bar{x}_i - \bar{x}_j\|}{\sigma}}$$

