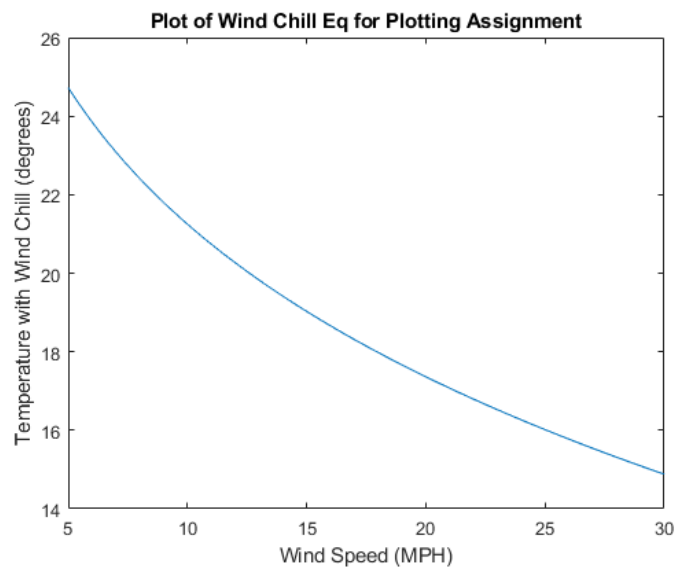


**Problem 1.**

(a) [1pt] Vectors: -5.9167

(b) [1pt] Plotting:



(c) [1pt] For Loops:

```
1 x = ones(20,1); %sets up vector and initializes first value to 1
2 for i = 2:20
3     x(i) = (x(i-1)/2)+2; %iterates as desired
4 end
```

(d) [1pt] Solving ODEs (a): 245.96

(e) [1pt] Solving ODEs (b):  $S = 13.89$   $I = 10.24$   $R = 975.86$

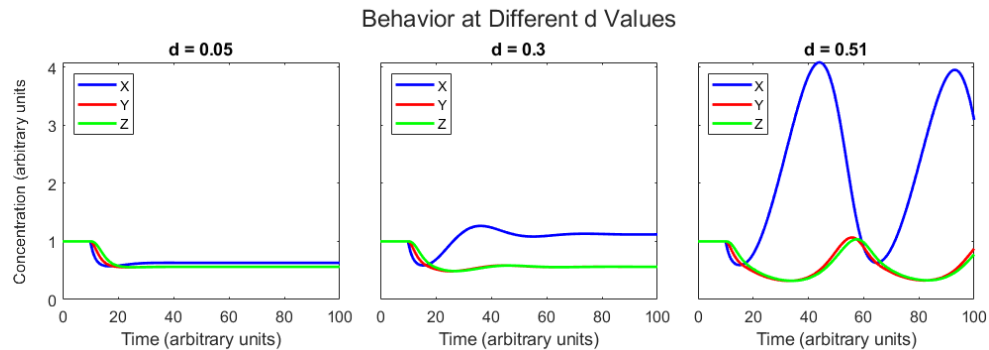
**Problem 2.**

(a) [1pt] `tSol` has 40 elements. Using `linspace(0,30,61)`, `tSol` then has 61 elements.

(b) [1pt] At time = 5 (the 11th element of `ySol`),  $X = 1$   $Y = 1$   $Z = 1$ , or the initial conditions. At time = 30,  $X = 0.5625$   $Y = 0.5625$   $Z = 0.5626$ .

### Problem 3.

- (a) [2pts] The plots look the same because with  $d = 0$ , the population of Z has no effect on TF. No product is moving through the feedback pathway, so the pathway proceeds as before.
- (b) [1pts] Selecting several values for  $d$ , the following plots were created.



These plots show the variable activity of the system under different  $d$  values. It is difficult to see the stability of the oscillations in the far right plot. Breaking the x-axis in a matlab plot is not something I know how to do off the top of my head, so I have included the following plot to demonstrate that the oscillations stabilize after 1500 time units or so.

