

```
#include <stdlib.h>
#include <string.h>
#include <ctype.h>
```

```
#define MAXPAROLA 30
#define MAXRIGA 80
```

```
int main(int argc, char *argv[])
```

```
{
    int freq[MAXPAROLA]; /* vettore di contatori
delle frequenze delle lunghezze delle parole */
    char riga[MAXRIGA];
    int i, inizio, lunghezza;
    FILE * f;
```

```
    for(i=0; i<MAXPAROLA; i++)
        freq[i]=0;
```

```
    if(argc != 2)
```

```
    {
        fprintf(stderr, "ERRORE: serve un parametro con il nome del file\n");
        exit(1);
    }
```

```
    f = fopen(argv[1], "rt");
    if(f==NULL)
```

```
    {
        fprintf(stderr, "ERRORE: impossibile aprire il file %s\n", argv[1]);
        exit(1);
    }
```

```
    while( fgets( riga, MAXRIGA, f ) != NULL )
```

Interrupts

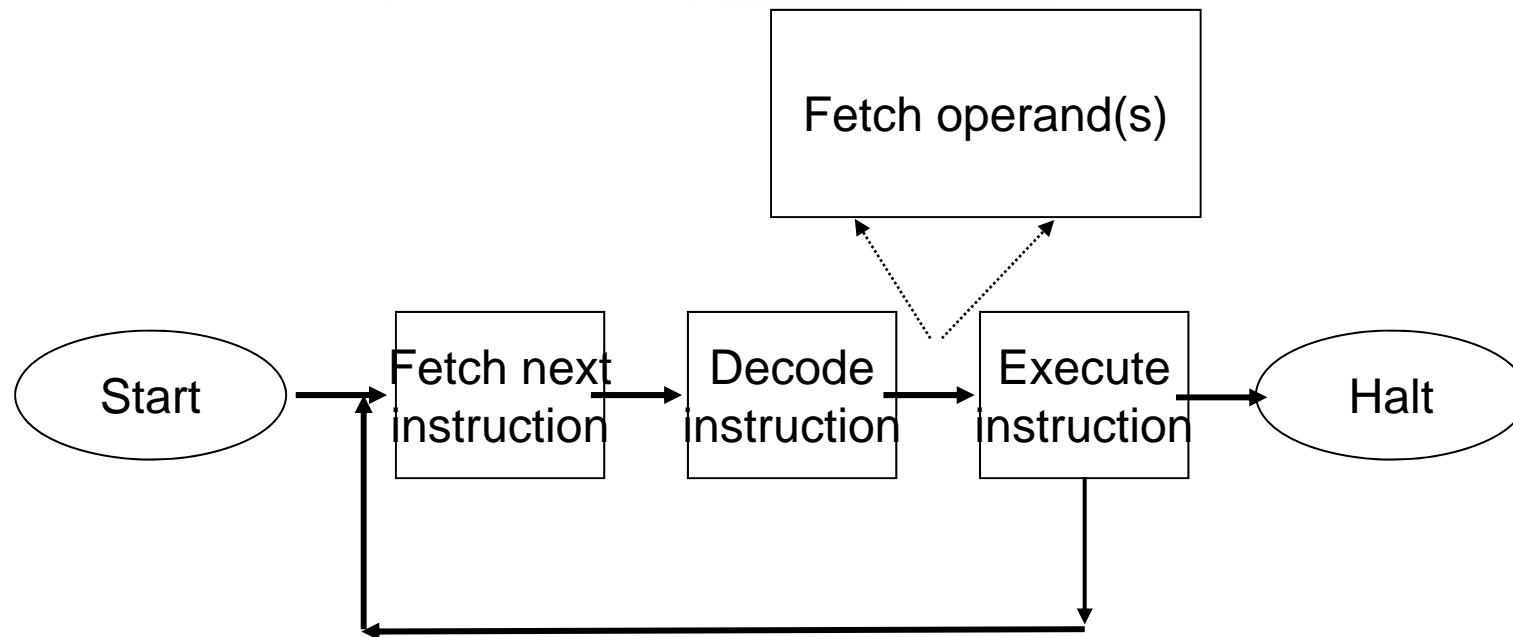
Interrupts

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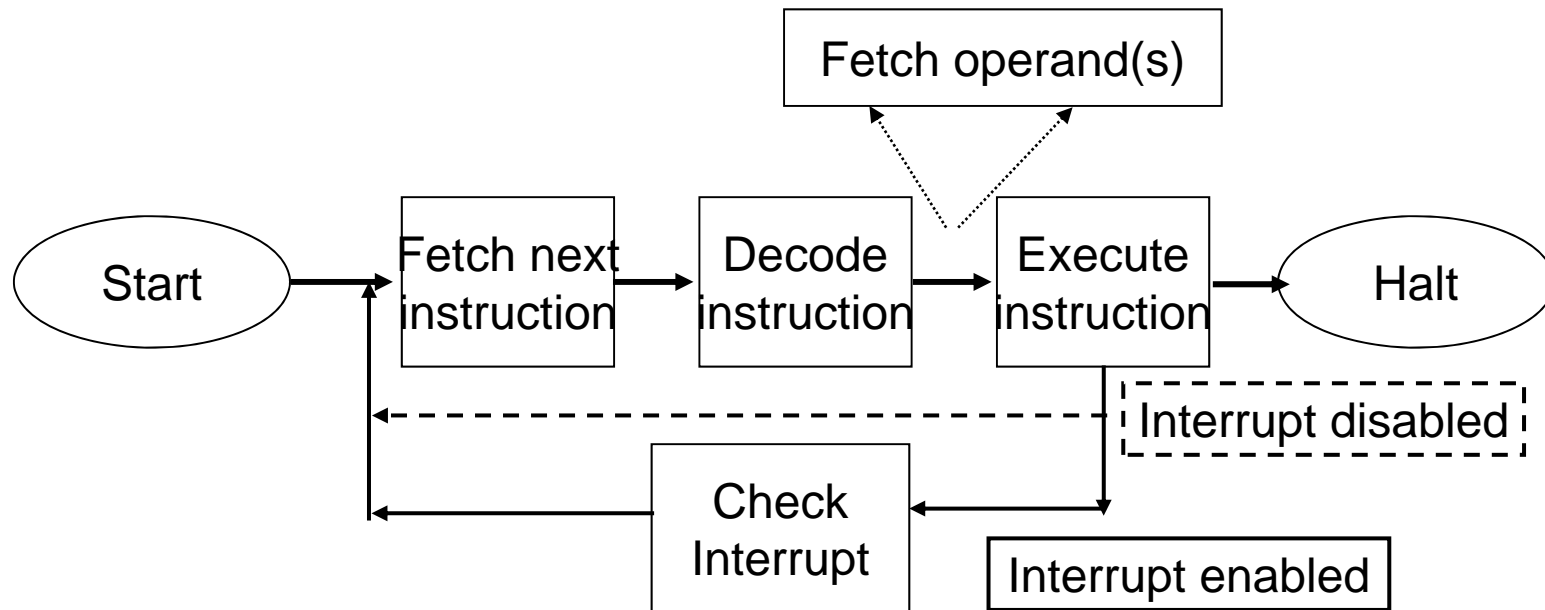
Instruction cycle



Interrupts

- ❖ **Interrupt** is a signal to the CPU generated by hardware or by software indicating an event that needs immediate attention
- ❖ **Interrupts** are generated by timers and devices
 - are **asynchronous**, i.e., they are generated at unpredictable times, or during the execution of any program instruction

Instruction cycle with interrupt



Interrupts

- ❖ An interrupt signal makes the control flow of a CPU to be moved from the current executing code to an interrupt handler routine that executes another code before returning to the original code.
- ❖ It is implemented by
 - saving the current value of the program counter (PC) and status (PSW) registers into a stack, so that the interrupted code can **restart from the next instruction**
 - loading in the PC register the address of the routine corresponding to the specific interrupt

Program Status Word

- ❖ The PSW contains
 - condition codes
 - interrupt enable/disable flags
 - kernel/user mode flag
 - ...

Interrupt Vector

Interrupt Handler	116	int_h_10()
	
	108	
	164	iret
..... • • •	 • • •
<div>main</div> <div><div>10</div></div>	20000	
 •	
	20064	
	20068	
 •	
	23000	
..... • • •	 • • •
Stack	52540	main PSW
	52544	20068
	52548	
	

Memory	Address	Content
Interrupt vector	6	
	10	116
	14	PSW of int_h_10()
	16	

PC	20068
SP	52548
PSW	main PSW

Issues

- ❖ An interrupt needs fast processing, that can be obtained splitting the task in two phases
 - Urgent or critical operations (e.g., get a keyboard code)
 - Operations that can be delayed (e.g., manage the code according to its meaning)
- ❖ Nested interrupt processing
- ❖ Processing of critical regions with disabled interrupts

Enable/Disable Interrupt (Intel)

- ❖ Each interrupt is identified by a number between 0 e 255, which Intel calls **vector**
 - ❖ The assembler instructions
 - disable interrupt **cli**
 - enable interrupt **sti**
- manage bit **IF** of the register **eflags**, which is tested in AND with masking

Interrupt management

- ❖ Disable interrupts while an interrupt is being processed
 - Processor ignores any new interrupt request signals
 - Interrupts remain pending until the processor enables interrupts
 - After interrupt handler routine completes, the processor checks for additional interrupts
- ❖ Higher priority interrupts cause lower-priority interrupts to wait.
 - Causes a lower-priority interrupt handler to be interrupted

Exceptions

- ❖ **Exception** differ from interrupts because they are **synchronous**
 - Program errors
 - System call (**int** or **sysenter** instructions)
 - Page faults
 - Fault conditions

Exceptions

❖ **Exception** are divided in 3 groups depending of the value of register **eip**, which is saved into the stack when the CPU raises an exception

➤ **Faults**

- The fault condition can be corrected and the process **can restart from the same instruction**

➤ **Traps**

- Used mainly for supporting debug

➤ **Abort**

- The error condition is such that it is impossible to decide which value **eip** should have

Exceptions examples

❖ Program Errors:

- divisions by zero
- illegal instruction
- memory parity error
- . . .

❖ Protection violations

- memory violation

Exceptions examples

```
#include <stdio.h>
int i, j, *pk; // global variables initialized to 0
int main(){
    scanf("%d", &i);
    j=2;
    j = j / i;    // possible division by 0 exception
    printf("%d\n", j);
    // Correct program
    pk = &i; // pk set to the address of variable i
    scanf("%d", pk);
    printf("i contains: %d %d\n", i, *pk);
    // Program generates here a memory violation exception
    pk = 0;
    scanf("%d", pk); // tries to write where pk points to,
                    // a memory location out of user domain
    printf("i contains: %d %d\n", i, *pk);
    return 0;
}
```

Programmed exceptions

- ❖ A programmed exception occurs because a specific instruction is executed
 - **int** or **int3**
 - **into** (check for overflow)
 - **bound** (check on address bound)
- ❖ Programmed exceptions, or software interrupts, allow
 - implementing **system calls**
 - signal events to the debugger