

```
#include <stdlib.h>
#include <string.h>
#include <ctype.h>
```

```
#define MAXPAROLA 30
#define MAXRIGA 80
```

```
int main(int argc, char *argv[])
```

```
{
    int freq[MAXPAROLA]; /* vettore di contatori
    delle frequenze delle lunghezze delle parole */
    char riga[MAXRIGA];
    int i, inizio, lunghezza;
    FILE * f;
```

```
    for(i=0; i<MAXPAROLA; i++)
        freq[i]=0;
```

```
    if(argc != 2)
```

```
    {
        fprintf(stderr, "ERRORE: serve un parametro con il nome del file\n");
        exit(1);
    }
```

```
    f = fopen(argv[1], "rt");
    if(f==NULL)
```

```
    {
        fprintf(stderr, "ERRORE: impossibile aprire il file %s\n", argv[1]);
        exit(1);
    }
```

```
    while( fgets( riga, MAXRIGA, f ) != NULL )
```

Interrupts

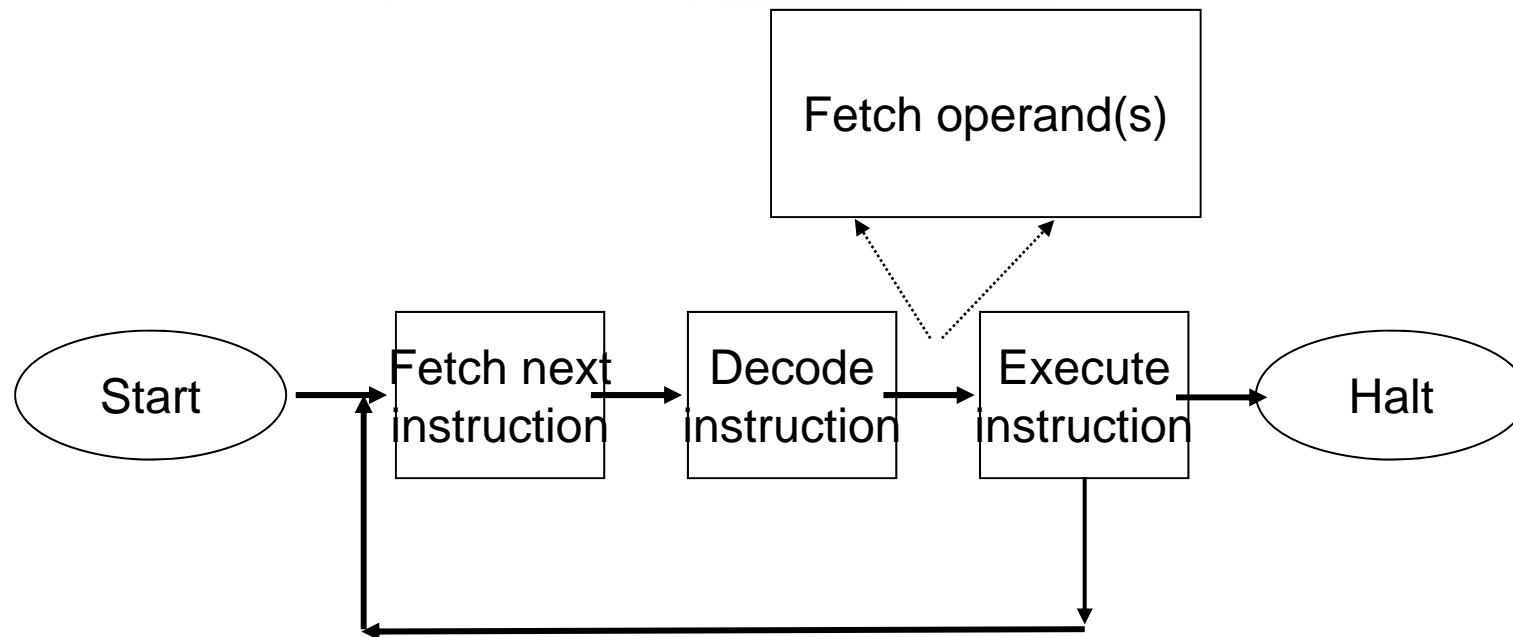
Interrupts

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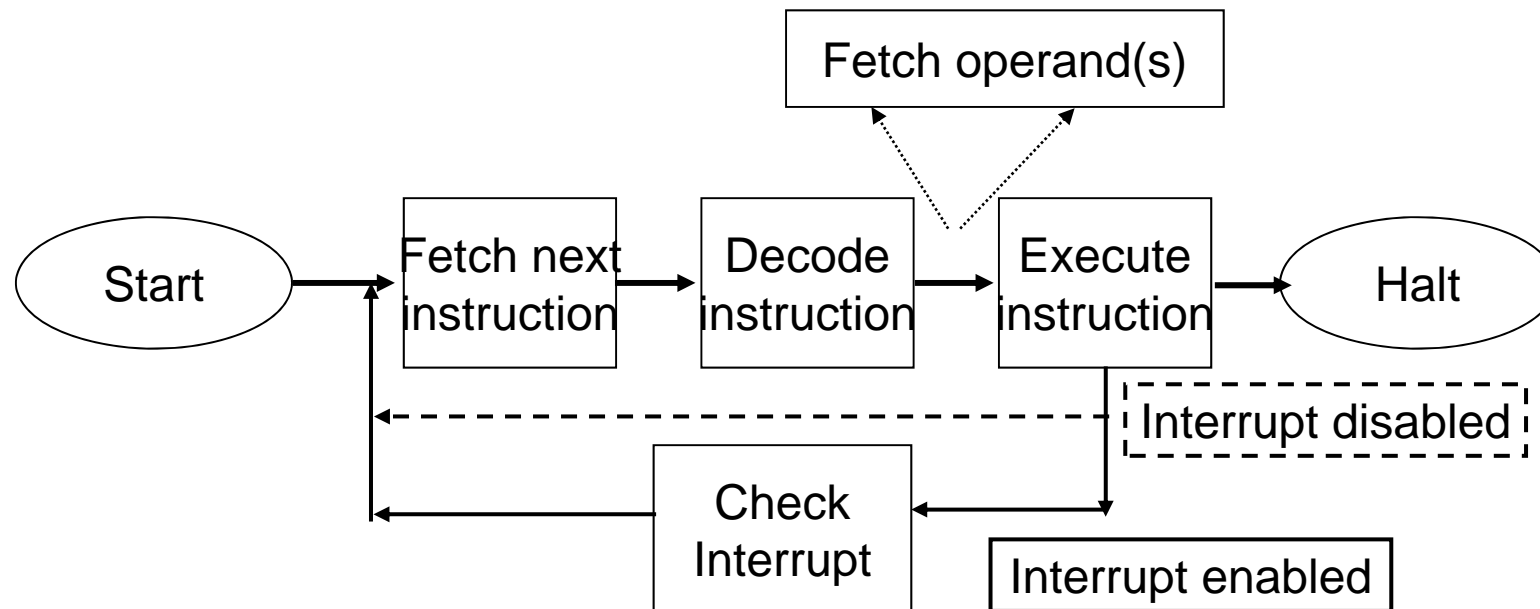
Instruction cycle



Interrupts

- ❖ **Interrupt** is a signal to the CPU generated by hardware or by software indicating an event that needs immediate attention
- ❖ **Interrupts** are generated by **timers** and **devices**
 - are **asynchronous**, i.e., they are generated at unpredictable times, or during the execution of any program instruction

Instruction cycle with interrupt



Interrupts

- ❖ An interrupt signal makes the control flow of a CPU to be moved from the current executing code to an **interrupt handler routine** that executes another code before returning to the original code.
- ❖ It is implemented by
 - **saving** the current value of the program counter (PC) and status (PSW) registers into a **stack**, so that the interrupted code can **restart from the next instruction**
 - **loading** in the PC register the address of the routine corresponding to the specific interrupt

Program Status Word

- ❖ The **PSW** contains
 - **condition** codes
 - interrupt enable/disable flags
 - kernel/user mode flag
 - ...

Interrupt Vector

| | | |
|--|---------|-------------------------|
| Interrupt Handler | 116 | int_h_10() |
| | | |
| | 108 | |
| | 164 | iret |
| • • • | | • • • |
| <div>main</div> <div><div>10</div></div> | 20000 | |
| | • | |
| | 20064 | |
| | 20068 | |
| | • | |
| | 23000 | |
| • • • | | • • • |
| Stack | 52540 | main PSW |
| | 52544 | 20068 |
| | 52548 | |
| | | |

| Memory | Address | Content |
|------------------|---------|-------------------|
| Interrupt vector | 6 | |
| | 10 | 116 |
| | 14 | PSW of int_h_10() |
| | 16 | |
| | | |

| | |
|-----|----------|
| PC | 20068 |
| SP | 52548 |
| PSW | main PSW |

Issues

- ❖ An interrupt needs fast processing, that can be obtained splitting the task in two phases
 - Urgent or critical operations (e.g., get a keyboard code)
 - Operations that can be delayed (e.g., manage the code according to its meaning)
- ❖ Nested interrupt processing
- ❖ Processing of critical regions with disabled interrupts

Enable/Disable Interrupt (Intel)

- ❖ Each interrupt is identified by a **number** between **0 e 255**, which Intel calls **vector**
 - ❖ The assembler instructions
 - **disable** interrupt **cli**
 - **enable** interrupt **sti**
- manage bit **IF** of the register **eflags**, which is tested in AND with masking

Interrupt management

- ❖ **Disable interrupts** while an interrupt is being processed
 - Processor ignores any new interrupt request signals
 - Interrupts remain pending until the processor enables interrupts
 - After interrupt handler routine completes, the processor checks for additional interrupts
- ❖ Higher priority interrupts cause lower-priority interrupts to wait.
 - Causes a lower-priority interrupt handler to be interrupted

Exceptions

- ❖ **Exception** differ from interrupts because they are **synchronous**
 - Program errors
 - System call (**int** or **sysenter** instructions)
 - Page faults
 - Fault conditions

Exceptions

❖ **Exception** are divided in 3 groups depending of the value of register **eip**, which is saved into the stack when the CPU raises an exception

➤ **Faults**

- The fault condition can be corrected and the process **can restart from the same instruction**

➤ **Traps**

- Used mainly for supporting debug

➤ **Abort**

- The error condition is such that it is impossible to decide which value **eip** should have

Exceptions examples

❖ Program Errors:

- divisions by zero
- illegal instruction
- memory parity error
- . . .

❖ Protection violations

- memory violation

Exceptions examples

```
#include <stdio.h>
int i, j, *pk; // global variables initialized to 0
int main(){
    scanf("%d", &i);
    j=2;
    j = j / i;    // possible division by 0 exception
    printf("%d\n", j);
    // Correct program
    pk = &i; // pk set to the address of variable i
    scanf("%d", pk);
    printf("i contains: %d %d\n", i, *pk);
    // Program generates here a memory violation exception
    pk = 0;
    scanf("%d", pk); // tries to write where pk points to,
                    // a memory location out of user domain
    printf("i contains: %d %d\n", i, *pk);
    return 0;
}
```

Programmed exceptions

- ❖ A programmed exception occurs because a specific instruction is executed
 - **int** or **int3**
 - **into** (check for overflow)
 - **bound** (check on address bound)
- ❖ Programmed exceptions, or software interrupts, allow
 - implementing **system calls**
 - signal events to the debugger