

```
#include <stdlib.h>
#include <string.h>
#include <ctype.h>
```

```
#define MAXPAROLA 30
#define MAXRIGA 80
```

```
int main(int argc, char *argv[])
```

```
{
    int freq[MAXPAROLA]; /* vettore di contatori
delle frequenze delle lunghezze delle parole */
    char riga[MAXRIGA];
    int i, inizio, lunghezza;
    FILE * f;
```

```
    for(i=0; i<MAXPAROLA; i++)
        freq[i]=0;
```

```
    if(argc != 2)
```

```
    {
        fprintf(stderr, "ERRORE: serve un parametro con il nome del file\n");
        exit(1);
    }
```

```
    f = fopen(argv[1], "r");
    if(f==NULL)
```

```
    {
        fprintf(stderr, "ERRORE: impossibile aprire il file %s\n", argv[1]);
        exit(1);
    }
```

```
    while( fgets( riga, MAXRIGA, f ) != NULL )
```

Deadlock

Definition and modeling

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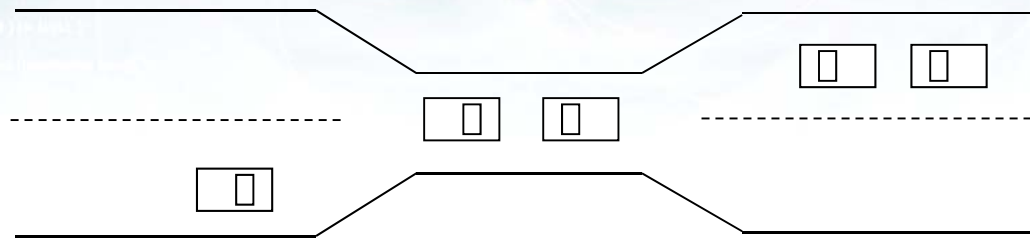
The Deadlock Problem

- ❖ A set of blocked processes each holding a resource and waiting to acquire a resource held by another process in the set.
 - Example: P_1 and P_2 each hold one tape drive and each needs another one.
 - Solution with 2 semaphores A and B, initialized to 1

P_1
wait (A)
wait (B)

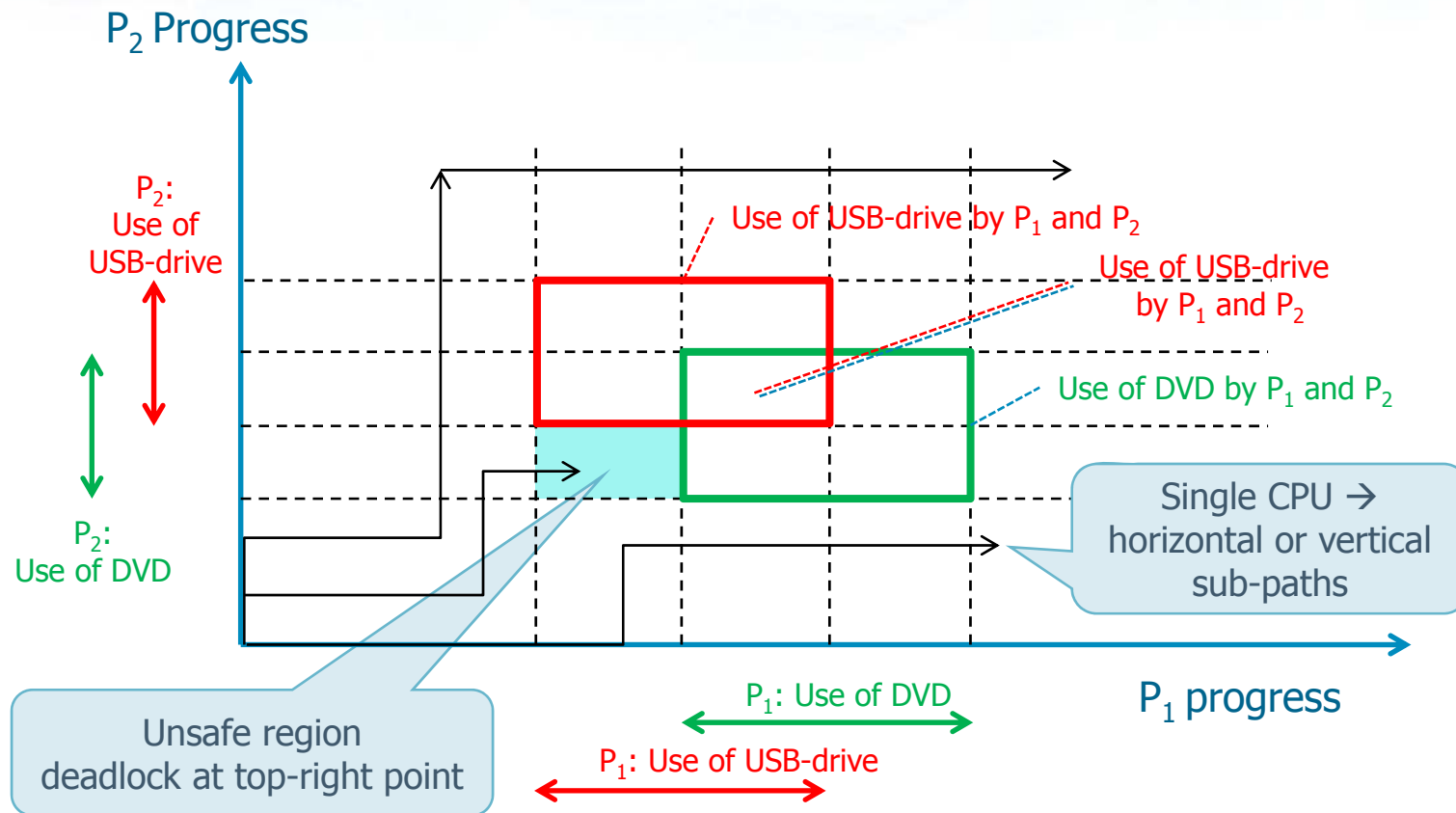
P_2
wait(B)
wait(A)

Bridge Crossing Example

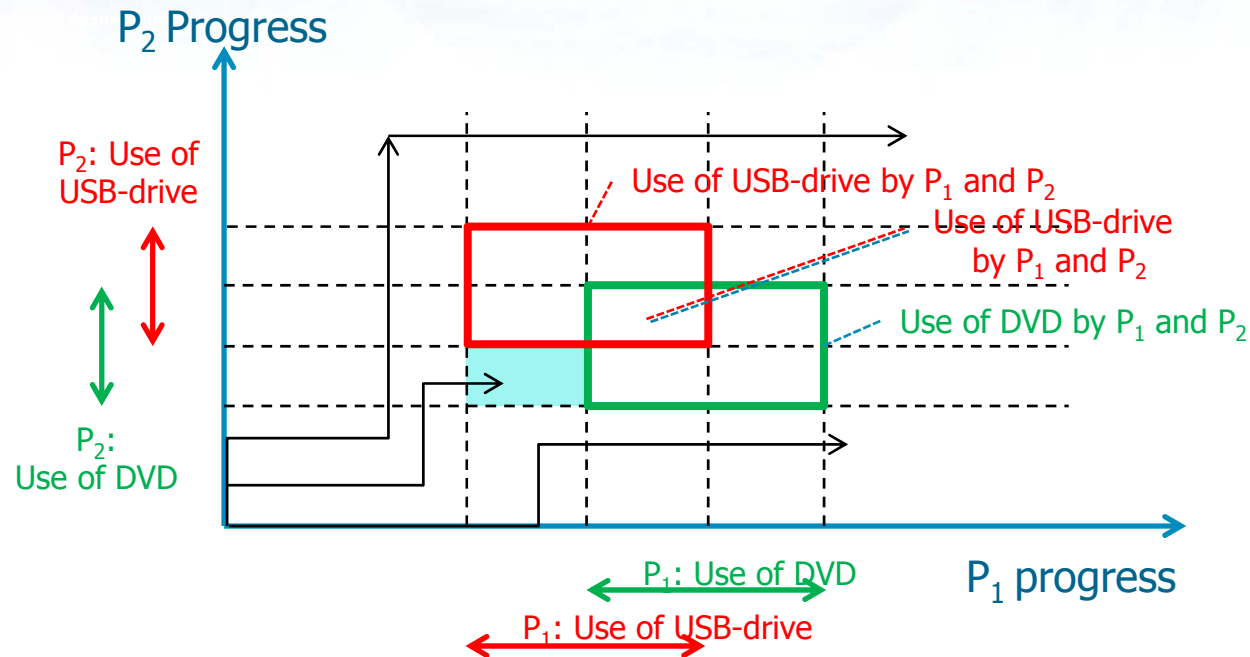


- ❖ Traffic on the bridge possible only in one direction.
- ❖ Each of the two sections of the bridge can be viewed as a resource.
- ❖ If a deadlock occurs, it can be resolved if one car rolls back preempting resource it occupies.
- ❖ Several cars may have to roll backup if the bridge has place for several cars, and a deadlock occurs.
- ❖ Starvation is possible.

Joint progress of two processes



Joint progress of two processes



- Prevention: forbid the **existence** of an unsafe state
- Avoidance : forbid the **entrance** into an unsafe state
- Recovery: forbid the **residence** into an unsafe state

Deadlock

❖ Deadlock

- A process requires a not available resource, and enter in a waiting state forever
- The deadlock consists of
 - A set of processes that wait the occurrence of an event that can only be caused by another process of the same set

❖ Deadlock implies starvation not vice-versa

- The starvation of a process implies that it waits indefinitely, but the other processes can proceed, not being deadlocked
- All processes in deadlock are also in starvation

Necessary conditions for occurrence of a deadlock

Conditions	Description
Mutual exclusion	Only one process at a time can use a resource
Hold and wait	A process holding at least one resource is allowed to wait for acquiring additional resources held by other processes
No preemption	A resource can be released only voluntarily by the process holding it, not preempted by the system.
Circular wait	A set of waiting processes $\{P_1, P_2, \dots, P_n\}$ such that P_1 is waiting for a resource that is held by P_2 , P_2 is waiting for a resource that is held by P_3 , ..., and P_n is waiting for a resource that is held by P_1

Summary

- ❖ Modeling techniques
- ❖ Management strategies

- Ignore

Ignore the problem assuming the probability of a deadlock in the system is very low

- Method used by many operating systems, including Windows and Unix
- Less appropriate if concurrency and complexity of the system increase

- A priori

- Prevention
- Avoidance

In case of **possibility** of deadlock

- A posteriori

- Detect
- Recovery

In case of deadlock

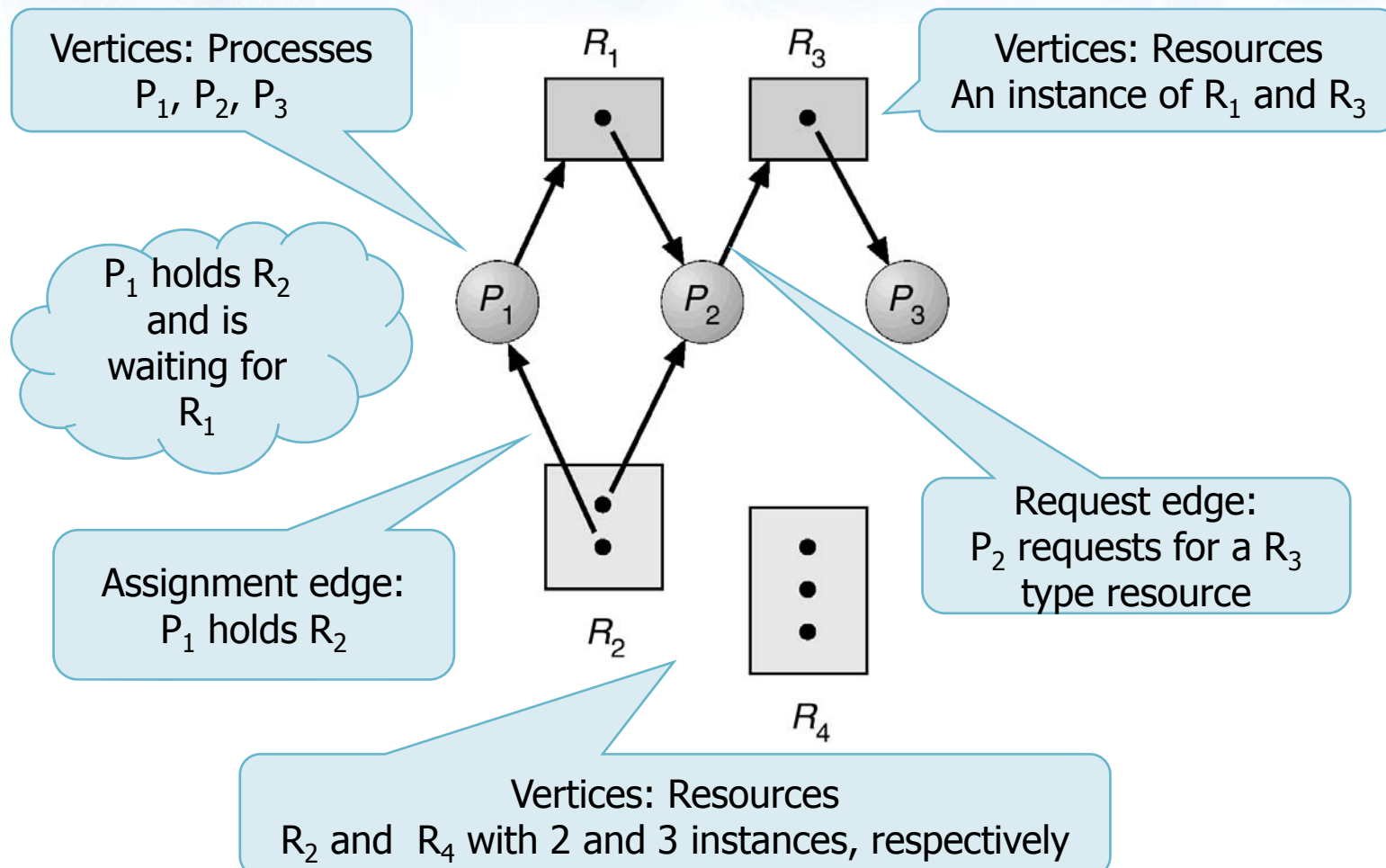
Modeling

- ❖ **Resource-Allocation Graph $G = (V, E)$**
 - Allows deadlock description and analysis
- ❖ The set of vertices V is composed of processes and resources
 - Process set $P = \{P_1, P_2, \dots, P_n\}$
 - Each process accesses a resource via a standard protocol consisting of
 - Request
 - Utilization
 - Release

Modeling

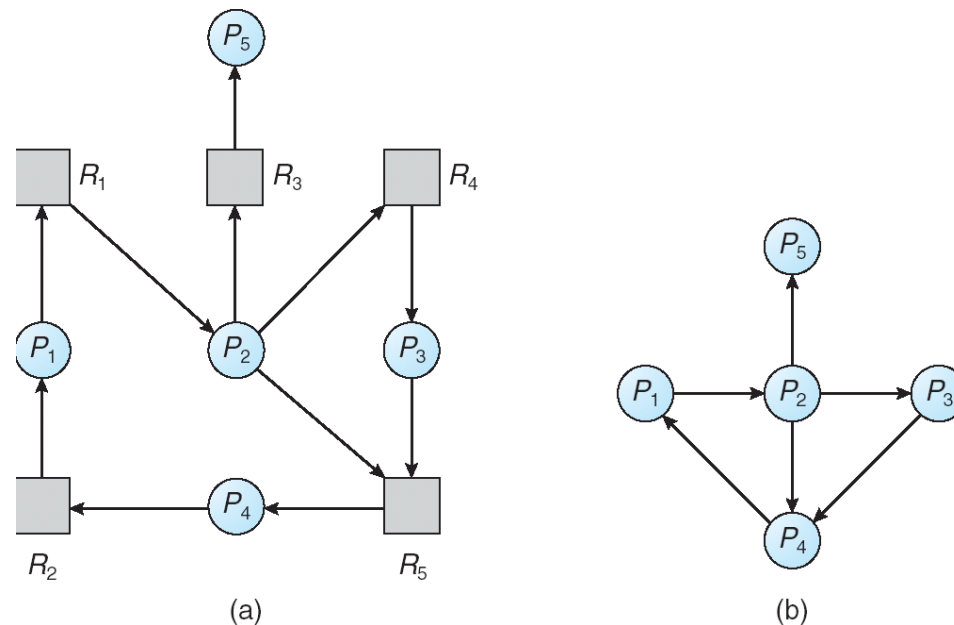
- System resource set $R = \{R_1, R_2, \dots, R_m\}$
 - The resources are divided into classes (types)
 - Each resource type R_i has W_i instances
 - All instances of a class are **identical**: any instance satisfies a demand for that type of resource
- ❖ The set of edges E is composed of
 - Request edges
 - $P_i \rightarrow R_j$, i.e., from a process to a resource type
 - Assignment edge
 - $R_{jk} \rightarrow P_i$, i.e., from a resource to a process

Modeling



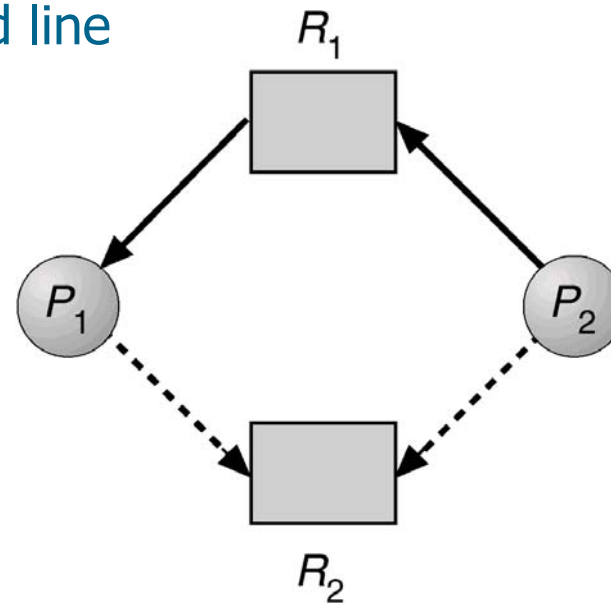
Modeling

- ❖ A **resource-allocation** graph can be sometime simplified in a **wait-for graph** by
 - deleting the resource vertices
 - creating the edges between the remaining vertices



Modeling

- ❖ Sometimes it is useful to extend the resource-allocation graph to a **claim graph** by
 - adding a claim edge: $P_i - - \rightarrow R_j$, indicates that process P_i can ask resource R_j in the future
 - It is represented by dashed line



Detection and recovery techniques

- ❖ The system is allowed to enter in a deadlock state, but
 - **Deadlock detection**
 - The system performs a deadlock detection algorithm
 - **Recovery form deadlock**
 - If deadlock has been detected a recovery action is performed

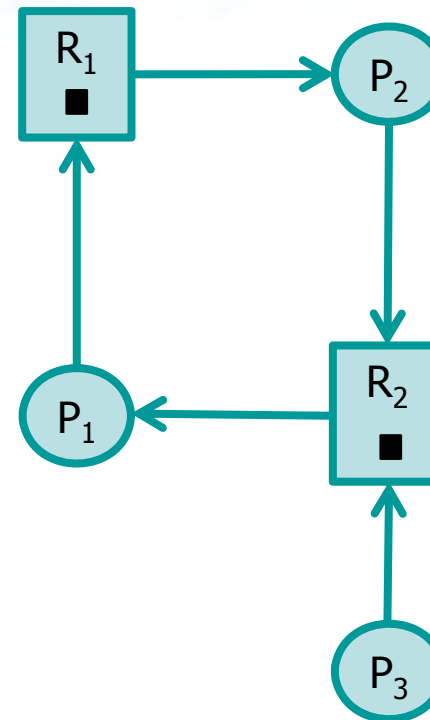
Detection: strategies

- ❖ Given an allocation graph deadlock can be detected by checking for cycles
 - If the graph contains no cycles, then there is no deadlock
 - If the graph contains one or more cycles then
 - Deadlock exist if each type of resource has a single instance
 - Deadlock is possible if there are several instances per resource type
 - The presence of cycles is necessary but not sufficient in the case of multiple instances per resource type

For multiple instances see the Banker's Algorithm

Example

- ❖ Processes
 - P_1, P_2, P_3
- ❖ Resources
 - R_1 and R_2 with a single instance
- ❖ A cycle exists
- ❖ Deadlock
 - P_1 waits for P_2
 - P_2 waits for P_1



Example

❖ Processes

- P_1, P_2, P_3, P_4

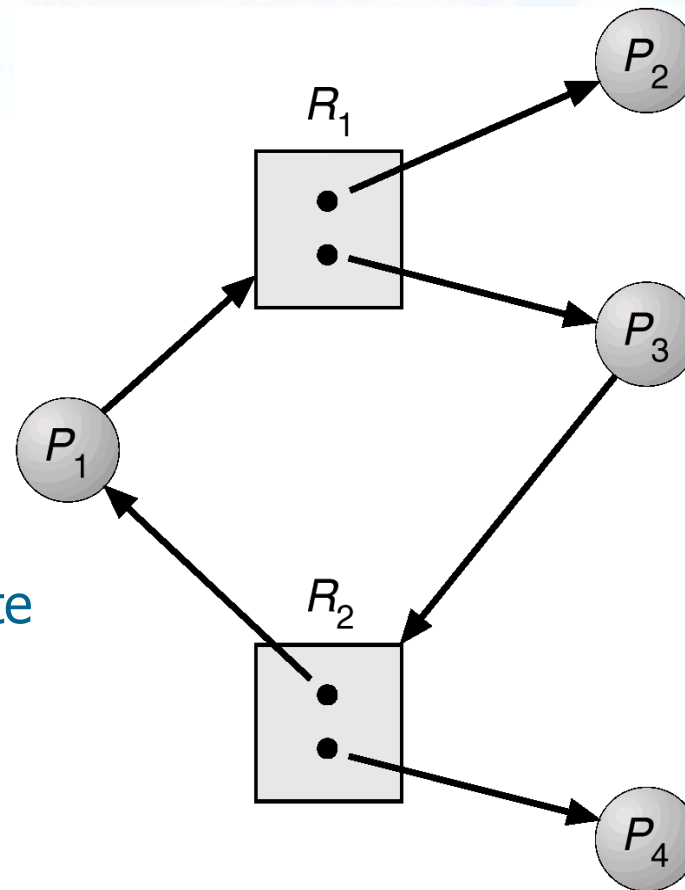
❖ Resources

- R_1 and R_2 with two instances

❖ A cycle exists

❖ No deadlock

- P_2 and P_4 can terminate
- P_1 can acquire R_1 and terminate
- P_3 can acquire R_2 and terminate



Example

❖ Processes

- P_1, P_2, P_3

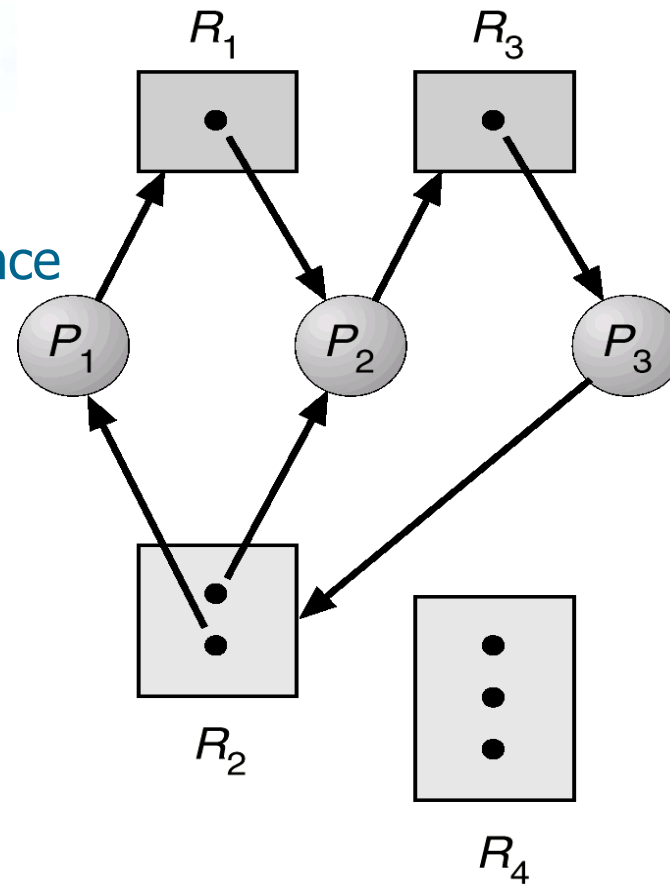
❖ Resources

- R_1 and R_3 with an instance
- R_2 with two instances
- R_4 with three instances

❖ Two cycles exist

❖ Deadlock

- P_1 waits for R_1
- P_2 waits for R_3
- P_3 waits for R_2



Detection: costs

- ❖ Detection phase has the high computational cost of finding a cycle in the graph
 - *An algorithm to detect a cycle in a graph requires $O(n^2)$ operations, where n is the number processes.*
- ❖ When detection is performed?
 - Every time a process makes a request not immediately satisfied
 - At fixed time intervals, e.g., every 30 minutes
 - At variable intervals of time, e.g., when the CPU usage falls below a given threshold

Recovery

- ❖ Different strategies are possible for deadlock recovery
 - Terminate all deadlocked processes
 - Terminate a process at a time among the ones in deadlock
 - Select a victim process, re-check the deadlock condition, and possibly iterate
 - Select a deadlocked process and
 - preempt the resources it holds, imposing a rollback, re-check the deadlock condition, and possibly iterate

Recovery

Strategy	Description
Terminate all deadlocked processes	<ul style="list-style-type: none">• Complexity: low, but easy to cause inconsistencies on databases• Cost: much higher than it might be strictly necessary
Terminate a process at a time among the ones in deadlock	<ul style="list-style-type: none">• Complexity: high, since it is necessary to select the victims with objective criteria (priority, current and future execution time, number of held resources, etc.)• Cost: high, after each termination must re-check the deadlock condition
Preempt the resources of a deadlocked process at a time	<ul style="list-style-type: none">• Complexity: rollback is necessary to return the selected process to a safe state• Cost: the victim process selection must aim at minimizing the preemption cost

Conclusions

- ❖ Detection and recovery operations are
 - logically complex
 - computationally expensive
- ❖ In any case, if a process requires many resources, starvation may occur
 - The same process is repeatedly chosen as the victim, incurring repeated rollbacks
 - To avoid starvation the victim selection algorithm should take into account the number of a process rollbacks