

Q1

- (a) We can see that the surface S , is defined implicitly $f(x, y, z) = 0$ where $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ is continuously differentiable (as it is a polynomial). Thus, we can see that as $(a, b, c) = (1, 2, 1)$ is a surface point, the tangent plane is given by:

$$\begin{aligned} 0 &= \frac{\partial f}{\partial x}(a, b, c)(x - a) + \frac{\partial f}{\partial y}(a, b, c)(y - b) + \frac{\partial f}{\partial z}(a, b, c)(z - c) \\ &= 2a(x - a) + 4b(y - b) - 10c(z - c) \\ &= 2(x - 1) + 8(y - 2) - 10(z - 1) \\ &= 2x + 8y - 10z - 8 \end{aligned}$$

- (b) MATLAB code for producing plot:

```
syms x y z
f = x.^2 + 2*y.^2 - 5*z.^2 - 4; % Implicit eq for surface
x0 = [1;2;1]; % Point for tangent plane

% Implicit function for tangent plane
t = subs(jacobian(f, [x, y, z]), [x, y, z], x0.').*([x;y;z]-x0);

% Shadding and colouring
colormap(bone); lighting gouraud; shading interp;
fimplicit3(f); % Plot implicit surface
hold on % Overlay both surfaces
fimplicit3(t); % Plot the x0 tangent plane (Twice for colouring trick)
fimplicit3(t, "FaceColor", [0.9, 0.1, 0.1], "FaceAlpha", 0.5);

% Label the plot
xlabel('x'); ylabel('y'); zlabel('z');
title("Surface x^2 + 2y^2 - 5z^2 = 4 with [1 2 1]^T tangent plane")
view([-238.75 6.89])
```

Resulting plot shown in Figure 1.

- (c) We are considering a surface defined by a function $f(x, y, z) = 0$, evaluating $f(0, 0, 1) = -9 \neq 0$, thus the point does not lie on the surface, and it does not make sense to ask for the tangent plane at this point.

We could still use f to find a plane at this point from the partial derivatives of f , however, this plane is not determined by the surface, it is determined by the choice of implicit function f , any plane passing through this point could match this definition by choosing a different f that gives the same surface.

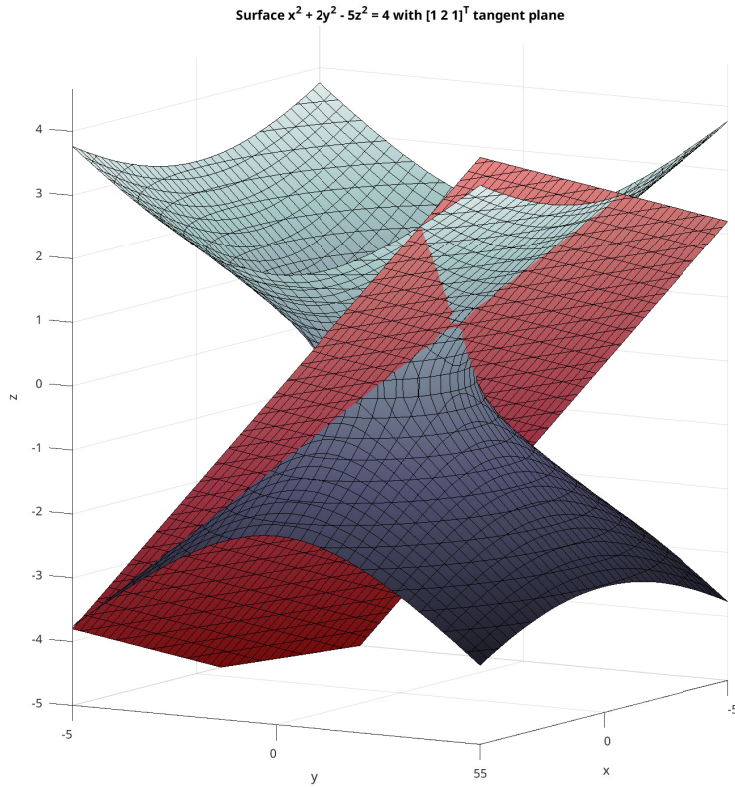


Figure 1: Plot of the tangent plane for the point $[1, 2, 1]^T$ for the surface implicitly defined by $x^2 + 2y^2 - 5z^2 = 4$

Q2

(a) Consider the function $\zeta : \begin{bmatrix} u \\ v \end{bmatrix} \mapsto \begin{bmatrix} x \\ y \end{bmatrix}$. From the definitions given we know:

$$\zeta : \begin{bmatrix} u \\ v \end{bmatrix} \mapsto \begin{bmatrix} ve^u \\ ve^{-u} \end{bmatrix}$$

Thus we find that:

$$D\zeta = \left[\begin{array}{c|c} \frac{\partial \zeta}{\partial u} & \frac{\partial \zeta}{\partial v} \end{array} \right] = \begin{bmatrix} ve^u & e^u \\ -ve^{-u} & e^{-u} \end{bmatrix}$$

The columns of $D\zeta$ give us a moving frame of basis vectors, which we normalise to give unit vectors:

$$e_u = \frac{\begin{bmatrix} ve^u \\ -ve^{-u} \end{bmatrix}}{\sqrt{v^2 e^{2u} + v^2 e^{-2u}}} = \frac{\begin{bmatrix} e^u \\ -e^{-u} \end{bmatrix}}{\sqrt{e^{2u} + e^{-2u}}} = \begin{bmatrix} \sqrt{\frac{e^{2u}}{e^{2u} + e^{-2u}}} \\ -\sqrt{\frac{e^{-2u}}{e^{2u} + e^{-2u}}} \end{bmatrix} = \begin{bmatrix} \sqrt{\frac{1}{e^{2u} + e^{-2u}}} \\ -\sqrt{\frac{1}{e^{2u} + e^{-2u}}} \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{1 + e^{-4u}}} \\ \frac{-1}{\sqrt{1 + e^{4u}}} \end{bmatrix}$$

$$e_v = \frac{\begin{bmatrix} e^u \\ e^{-u} \end{bmatrix}}{\sqrt{e^{2u} + e^{-2u}}} = \begin{bmatrix} \sqrt{\frac{e^{2u}}{e^{2u} + e^{-2u}}} \\ \sqrt{\frac{e^{-2u}}{e^{2u} + e^{-2u}}} \end{bmatrix} = \begin{bmatrix} \sqrt{\frac{1}{e^{2u} + e^{-2u}}} \\ \sqrt{\frac{1}{e^{2u} + e^{-2u}}} \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{1 + e^{-4u}}} \\ \frac{1}{\sqrt{1 + e^{4u}}} \end{bmatrix}$$

(b) See that:

$$\mathbf{e}_u + \mathbf{e}_v = \begin{bmatrix} \frac{1}{\sqrt{1+e^{-4u}}} \\ \frac{-1}{\sqrt{1+e^{4u}}} \end{bmatrix} + \begin{bmatrix} \frac{1}{\sqrt{1+e^{-4u}}} \\ \frac{1}{\sqrt{1+e^{4u}}} \end{bmatrix} = \begin{bmatrix} \frac{2}{\sqrt{1+e^{-4u}}} \\ \frac{1-1}{\sqrt{1+e^{4u}}} \end{bmatrix} = \begin{bmatrix} \frac{2}{\sqrt{1+e^{-4u}}} \\ 0 \end{bmatrix} = \frac{2}{\sqrt{1+e^{-4u}}} \mathbf{e}_x$$

Now for $\mathbf{e}_u - \mathbf{e}_v$ we see that:

$$\mathbf{e}_u - \mathbf{e}_v = \begin{bmatrix} \frac{1}{\sqrt{1+e^{-4u}}} \\ \frac{-1}{\sqrt{1+e^{4u}}} \end{bmatrix} - \begin{bmatrix} \frac{1}{\sqrt{1+e^{-4u}}} \\ \frac{1}{\sqrt{1+e^{4u}}} \end{bmatrix} = \begin{bmatrix} \frac{0}{\sqrt{1+e^{-4u}}} \\ \frac{-1-1}{\sqrt{1+e^{4u}}} \end{bmatrix} = \begin{bmatrix} 0 \\ \frac{-2}{\sqrt{1+e^{4u}}} \end{bmatrix} = \frac{-2}{\sqrt{1+e^{4u}}} \mathbf{e}_y$$

(c) We find the partial derivatives of the unit vectors:

$$\begin{aligned} \frac{\partial \mathbf{e}_u}{\partial u} &= \frac{\partial}{\partial u} \begin{bmatrix} \frac{1}{\sqrt{1+e^{-4u}}} \\ \frac{-1}{\sqrt{1+e^{4u}}} \end{bmatrix} \\ &= \begin{bmatrix} \frac{\partial}{\partial u} (1+e^{-4u})^{-\frac{1}{2}} \\ -\frac{\partial}{\partial u} (1+e^{4u})^{-\frac{1}{2}} \end{bmatrix} \\ &= \begin{bmatrix} \frac{-1}{2} (1+e^{-4u})^{-\frac{3}{2}} (0-4e^{-4u}) \\ -\frac{-1}{2} (1+e^{4u})^{-\frac{3}{2}} (0+4e^{4u}) \end{bmatrix} \\ &= 2 \begin{bmatrix} e^{-4u} (1+e^{-4u})^{-\frac{3}{2}} \\ e^{4u} (1+e^{4u})^{-\frac{3}{2}} \end{bmatrix} \\ &= \frac{e^{-4u}}{1+e^{-4u}} (\mathbf{e}_u + \mathbf{e}_v) - \frac{e^{4u}}{1+e^{4u}} (\mathbf{e}_u - \mathbf{e}_v) \\ &= \frac{\mathbf{e}_u + \mathbf{e}_v}{1+e^{4u}} - \frac{\mathbf{e}_u - \mathbf{e}_v}{1+e^{-4u}} \\ \\ \frac{\partial \mathbf{e}_u}{\partial v} &= \frac{\partial}{\partial v} \begin{bmatrix} \frac{1}{\sqrt{1+e^{-4u}}} \\ \frac{-1}{\sqrt{1+e^{4u}}} \end{bmatrix} = 0 \\ \\ \frac{\partial \mathbf{e}_v}{\partial u} &= \frac{\partial}{\partial u} \begin{bmatrix} \frac{1}{\sqrt{1+e^{-4u}}} \\ \frac{1}{\sqrt{1+e^{4u}}} \end{bmatrix} \\ &= 2 \begin{bmatrix} e^{-4u} (1+e^{-4u})^{-\frac{3}{2}} \\ -e^{4u} (1+e^{4u})^{-\frac{3}{2}} \end{bmatrix} \\ &= \frac{e^{-4u}}{1+e^{-4u}} (\mathbf{e}_u + \mathbf{e}_v) + \frac{e^{4u}}{1+e^{4u}} (\mathbf{e}_u - \mathbf{e}_v) \\ &= \frac{\mathbf{e}_u + \mathbf{e}_v}{1+e^{4u}} + \frac{\mathbf{e}_u - \mathbf{e}_v}{1+e^{-4u}} \\ \\ \frac{\partial \mathbf{e}_v}{\partial v} &= \frac{\partial}{\partial v} \begin{bmatrix} \frac{1}{\sqrt{1+e^{-4u}}} \\ \frac{1}{\sqrt{1+e^{4u}}} \end{bmatrix} = 0 \end{aligned}$$

Finding the velocity in terms of $\mathbf{e}_u, \mathbf{e}_v$:

$$\begin{aligned} \mathbf{R}'(t) &= \frac{d\mathbf{R}(t)}{dt} \\ &= \frac{d}{dt} [u(t) \cdot \mathbf{e}_u(u(t), v(t))] + \frac{d}{dt} [v(t) \cdot \mathbf{e}_v(u(t), v(t))] \\ &= \left[u'(t) \mathbf{e}_u + u(t) \cdot \frac{d}{dt} [\mathbf{e}_u(u(t), v(t))] \right] + \left[v'(t) \mathbf{e}_v + v(t) \cdot \frac{d}{dt} [\mathbf{e}_v(u(t), v(t))] \right] \\ &= \left[u'(t) \mathbf{e}_u + u(t) \cdot \left[u'(t) \cdot \frac{\partial \mathbf{e}_u}{\partial u} + v'(t) \cdot \frac{\partial \mathbf{e}_u}{\partial v} \right] \right] + \left[v'(t) \mathbf{e}_v + v(t) \cdot \left[u'(t) \cdot \frac{\partial \mathbf{e}_v}{\partial u} + v'(t) \cdot \frac{\partial \mathbf{e}_v}{\partial v} \right] \right] \\ &= u' \mathbf{e}_u + uu' \left(\frac{\mathbf{e}_u + \mathbf{e}_v}{1+e^{4u}} - \frac{\mathbf{e}_u - \mathbf{e}_v}{1+e^{-4u}} \right) + v' \mathbf{e}_v + vv' \left(\frac{\mathbf{e}_u + \mathbf{e}_v}{1+e^{4u}} + \frac{\mathbf{e}_u - \mathbf{e}_v}{1+e^{-4u}} \right) \end{aligned}$$

Q3

(a) First we choose α, β such for $t \in [0, \frac{\pi}{2}]$:

$$\begin{aligned} 4 &= (\alpha \cos t)^2 + 2(\beta \sin t)^2 \\ &= \alpha^2 \cos^2 t + 2\beta^2 \sin^2 t \end{aligned}$$

See that by choosing $\alpha = 2$ and $\beta = \sqrt{2}$, the equation is satisfied for all $t \in [0, \frac{\pi}{2}]$:

$$\begin{aligned} 4 &= 2^2 \cos^2 t + 2(\sqrt{2})^2 \sin^2 t \\ &= 4(\cos^2 t + \sin^2 t) \\ &= 4 \end{aligned}$$

Thus $\{r(t) : t \in [0, \frac{\pi}{2}]\} \subseteq \{(x, y) \in \mathbb{R}^2 : x^2 + 2y^2 = 4 \wedge x, y \geq 0\}$.

(b) The mass of the wire will be given by:

$$m = \int_0^{\frac{\pi}{2}} \rho(r(t)) \|r'(t)\| dt$$

Where:

$$\begin{aligned} \rho(t) &= (\alpha \cos t)(\beta \sin t) \\ r'(t) &= \begin{bmatrix} -\alpha \sin t \\ \beta \cos t \end{bmatrix} \\ \|r'(t)\| &= \sqrt{\alpha^2 \sin^2 t + \beta^2 \cos^2 t} \\ &= \sqrt{4 \sin^2 t + 2 \cos^2 t} \end{aligned}$$

By substituting values, then applying the identity $\sin^2 \theta + \cos^2 \theta = 1$ and pulling the constants out of the integral:

$$\begin{aligned} m &= \int_0^{\frac{\pi}{2}} [2\sqrt{2} \sin t \cos t] \sqrt{4 \sin^2 t + 2 \cos^2 t} dt \\ &= 4 \int_0^{\frac{\pi}{2}} [\sin t \cos t] \sqrt{\sin^2 t + 1} dt \end{aligned}$$

Now we use u-substitution with $u(t) = \sin^2 t + 1$, hence $\frac{du}{dt} = 2 \sin t \cos t$, therefore $dt = \frac{du}{2 \sin t \cos t}$. Thus:

$$\begin{aligned} m &= 4 \int_{u(0)}^{u(\frac{\pi}{2})} [\sin t \cos t] \sqrt{u} \frac{du}{2 \sin t \cos t} \\ &= 2 \int_{u(0)}^{u(\frac{\pi}{2})} \sqrt{u} du \\ &= 2 \int_1^2 \sqrt{u} du \\ &= 2 \left[\frac{2}{3} u^{\frac{3}{2}} - \frac{2}{3} 1^{\frac{3}{2}} \right] \\ &= \frac{8\sqrt{2} - 4}{3} \end{aligned}$$