

Q1

- (a) We can see that the surface S , is defined implicitly $f(x, y, z) = 0$ where $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ is continuously differentiable (as it is a polynomial). Thus, we can see that as $(a, b, c) = (1, 2, 1)$ is a surface point, the tangent plane is given by:

$$\begin{aligned} 0 &= \frac{\partial f}{\partial x}(a, b, c)(x - a) + \frac{\partial f}{\partial y}(a, b, c)(y - b) + \frac{\partial f}{\partial z}(a, b, c)(z - c) \\ &= 2a(x - a) + 4b(y - b) - 10c(z - c) \\ &= 2(x - 1) + 8(y - 2) - 10(z - 1) \\ &= 2x - 2 + 8y - 16 - 10z + 10 \\ &= 2x + 8y - 10z - 8 \end{aligned}$$

- (b) **MATLAB**

- (c) We are considering a surface defined by a function $f(x, y, z) = 0$,

Q2

- (a) Consider the function $\zeta : \begin{bmatrix} u \\ v \end{bmatrix} \mapsto \begin{bmatrix} x \\ y \end{bmatrix}$. From the definitions given we know:

$$\zeta : \begin{bmatrix} u \\ v \end{bmatrix} \mapsto \begin{bmatrix} ve^u \\ ve^{-u} \end{bmatrix}$$

Thus we find that:

$$D\zeta = \left[\begin{array}{c|c} \frac{\partial \zeta}{\partial u} & \frac{\partial \zeta}{\partial v} \end{array} \right] = \begin{bmatrix} ve^u & e^u \\ -ve^{-u} & e^{-u} \end{bmatrix}$$

The columns of $D\zeta$ give us a moving frame of basis vectors, which we normalise to give unit vectors:

$$\begin{aligned}
e_u &= \frac{\begin{bmatrix} ve^u \\ -ve^{-u} \end{bmatrix}}{\sqrt{v^2 e^{2u} + v^2 e^{-2u}}} \\
&= \frac{\begin{bmatrix} e^u \\ -e^{-u} \end{bmatrix}}{\sqrt{e^{2u} + e^{-2u}}} \\
&= \begin{bmatrix} \sqrt{\frac{e^{2u}}{e^{2u} + e^{-2u}}} \\ -\sqrt{\frac{e^{-2u}}{e^{2u} + e^{-2u}}} \end{bmatrix} \\
&= \begin{bmatrix} \sqrt{\frac{1}{\frac{e^{2u} + e^{-2u}}{e^{2u}}}} \\ -\sqrt{\frac{1}{\frac{e^{2u} + e^{-2u}}{e^{-2u}}}} \end{bmatrix} \\
&= \begin{bmatrix} \frac{1}{\sqrt{1 + e^{-4u}}} \\ \frac{-1}{\sqrt{1 + e^{4u}}} \end{bmatrix}
\end{aligned}$$

$$\begin{aligned}
e_v &= \frac{\begin{bmatrix} e^u \\ e^{-u} \end{bmatrix}}{\sqrt{e^{2u} + e^{-2u}}} \\
&= \begin{bmatrix} \sqrt{\frac{e^{2u}}{e^{2u} + e^{-2u}}} \\ \sqrt{\frac{e^{-2u}}{e^{2u} + e^{-2u}}} \end{bmatrix} \\
&= \begin{bmatrix} \sqrt{\frac{1}{\frac{e^{2u} + e^{-2u}}{e^{2u}}}} \\ \sqrt{\frac{1}{\frac{e^{2u} + e^{-2u}}{e^{-2u}}}} \end{bmatrix} \\
&= \begin{bmatrix} \frac{1}{\sqrt{1 + e^{-4u}}} \\ \frac{1}{\sqrt{1 + e^{4u}}} \end{bmatrix}
\end{aligned}$$

(b) See that:

$$\begin{aligned}
e_u + e_v &= \begin{bmatrix} \frac{1}{\sqrt{1 + e^{-4u}}} \\ \frac{-1}{\sqrt{1 + e^{4u}}} \end{bmatrix} + \begin{bmatrix} \frac{1}{\sqrt{1 + e^{-4u}}} \\ \frac{1}{\sqrt{1 + e^{4u}}} \end{bmatrix} \\
&= \begin{bmatrix} \frac{2}{\sqrt{1 + e^{-4u}}} \\ \frac{1-1}{\sqrt{1 + e^{4u}}} \end{bmatrix} \\
&= \begin{bmatrix} \frac{2}{\sqrt{1 + e^{-4u}}} \\ 0 \end{bmatrix} = \frac{2}{\sqrt{1 + e^{-4u}}} e_x
\end{aligned}$$

Now for $e_u - e_v$ we see that:

$$\begin{aligned}
e_u - e_v &= \begin{bmatrix} \frac{1}{\sqrt{1 + e^{-4u}}} \\ \frac{-1}{\sqrt{1 + e^{4u}}} \end{bmatrix} - \begin{bmatrix} \frac{1}{\sqrt{1 + e^{-4u}}} \\ \frac{1}{\sqrt{1 + e^{4u}}} \end{bmatrix} \\
&= \begin{bmatrix} \frac{0}{\sqrt{1 + e^{-4u}}} \\ \frac{-1-1}{\sqrt{1 + e^{4u}}} \end{bmatrix} \\
&= \begin{bmatrix} 0 \\ \frac{-2}{\sqrt{1 + e^{4u}}} \end{bmatrix} = \frac{-2}{\sqrt{1 + e^{4u}}} e_y
\end{aligned}$$

(c) We find the partial derivatives of the unit vectors:

$$\begin{aligned}
\frac{\partial e_u}{\partial u} &= \frac{\partial}{\partial u} \left[\frac{1}{\sqrt{1+e^{-4u}}} \right] \\
&= \left[\frac{\partial}{\partial u} (1+e^{-4u})^{-\frac{1}{2}} \right] \\
&= \left[\frac{-1}{2} (1+e^{-4u})^{-\frac{3}{2}} (0-4e^{-4u}) \right] \\
&= 2 \left[\frac{e^{-4u} (1+e^{-4u})^{-\frac{3}{2}}}{e^{4u} (1+e^{4u})^{-\frac{3}{2}}} \right]
\end{aligned}$$

$$\begin{aligned}
\frac{\partial e_v}{\partial u} &= \frac{\partial}{\partial u} \left[\frac{1}{\sqrt{1+e^{-4u}}} \right] \\
&= 2 \left[\frac{e^{-4u} (1+e^{-4u})^{-\frac{3}{2}}}{-e^{4u} (1+e^{4u})^{-\frac{3}{2}}} \right]
\end{aligned}$$

$$\begin{aligned}
\frac{\partial e_u}{\partial v} &= \frac{\partial}{\partial v} \left[\frac{1}{\sqrt{1+e^{-4u}}} \right] \\
&= 0
\end{aligned}$$

$$\begin{aligned}
\frac{\partial e_v}{\partial v} &= \frac{\partial}{\partial v} \left[\frac{1}{\sqrt{1+e^{-4u}}} \right] \\
&= 0
\end{aligned}$$

$$\begin{aligned}
R'(t) &= \frac{dR(t)}{dt} \\
&= \frac{d}{dt} [u(t) \cdot e_u(u(t), v(t))] + \frac{d}{dt} [v(t) \cdot e_v(u(t), v(t))] \\
&= \left[u'(t) e_u + u(t) \cdot \frac{d}{dt} [e_u(u(t), v(t))] \right] + \left[v'(t) e_v + v(t) \cdot \frac{d}{dt} [e_v(u(t), v(t))] \right] \\
&= \left[u'(t) e_u + u(t) \cdot \left[u'(t) \cdot \frac{\partial e_u}{\partial u} + v'(t) \cdot \frac{\partial e_u}{\partial v} \right] \right] + \left[v'(t) e_v + v(t) \cdot \left[u'(t) \cdot \frac{\partial e_v}{\partial u} + v'(t) \cdot \frac{\partial e_v}{\partial v} \right] \right]
\end{aligned}$$

e

Q3

(a) A

(b) The mass of the wire will be given by:

$$m = \int_0^{\frac{\pi}{2}} \rho(r(t)) dt$$