# SYMMETRIC MATRICES AND QUADRATIC FORMS

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$$\lambda = 8$$
:  $\mathbf{v}_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$ ;  $\lambda = 6$ :  $\mathbf{v}_2 = \begin{bmatrix} -1 \\ -1 \\ 2 \end{bmatrix}$ ;  $\lambda = 3$ :  $\mathbf{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ 

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$$\mathbf{u}_{1} = \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix}, \quad \mathbf{u}_{2} = \begin{bmatrix} -1/\sqrt{6} \\ -1/\sqrt{6} \\ 2/\sqrt{6} \end{bmatrix}, \quad \mathbf{u}_{3} = \begin{bmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix}$$

$$P = \begin{bmatrix} -1/\sqrt{2} & -1/\sqrt{6} & 1/\sqrt{3} \\ 1/\sqrt{2} & -1/\sqrt{6} & 1/\sqrt{3} \\ 0 & 2/\sqrt{6} & 1/\sqrt{3} \end{bmatrix}, \quad D = \begin{bmatrix} 8 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

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**PROOF** Let  $\mathbf{v}_1$  and  $\mathbf{v}_2$  be eigenvectors that correspond to distinct eigenvalues, say,  $\lambda_1$  and  $\lambda_2$ . To show that  $\mathbf{v}_1 \cdot \mathbf{v}_2 = 0$ , compute

$$\lambda_1 \mathbf{v}_1 \cdot \mathbf{v}_2 = (\lambda_1 \mathbf{v}_1)^T \mathbf{v}_2 = (A \mathbf{v}_1)^T \mathbf{v}_2 = (\mathbf{v}_1^T A^T) \mathbf{v}_2 = \mathbf{v}_1^T (A \mathbf{v}_2) = \mathbf{v}_1^T (\lambda_2 \mathbf{v}_2)$$
$$= \lambda_2 \mathbf{v}_1^T \mathbf{v}_2 = \lambda_2 \mathbf{v}_1 \cdot \mathbf{v}_2$$

$$\mathbf{v}_1 \cdot \mathbf{v}_2 = 0$$

An n\* n matrix A is said to be **orthogonally diagonalizable if there** are an orthogonal matrix P and a diagonal matrix D such that

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An  $n \times n$  matrix A is orthogonally diagonalizable if and only if A is a symmetric matrix.

The set of eigenvalues of a matrix A is sometimes called the *spectrum* of A

#### The Spectral Theorem for Symmetric Matrices

An  $n \times n$  symmetric matrix A has the following properties:

- a. A has n real eigenvalues, counting multiplicities.
- b. The dimension of the eigenspace for each eigenvalue  $\lambda$  equals the multiplicity of  $\lambda$  as a root of the characteristic equation.
- c. The eigenspaces are mutually orthogonal, in the sense that eigenvectors corresponding to different eigenvalues are orthogonal.
- d. A is orthogonally diagonalizable.

**EXAMPLE 3** Orthogonally diagonalize the matrix  $A = \begin{bmatrix} 3 & -2 & 4 \\ -2 & 6 & 2 \\ 4 & 2 & 3 \end{bmatrix}$ , whose

characteristic equation is

$$0 = -\lambda^3 + 12\lambda^2 - 21\lambda - 98 = -(\lambda - 7)^2(\lambda + 2)$$

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$$\lambda = 7$$
:  $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ ,  $\mathbf{v}_2 = \begin{bmatrix} -1/2 \\ 1 \\ 0 \end{bmatrix}$ ;  $\lambda = -2$ :  $\mathbf{v}_3 = \begin{bmatrix} -1 \\ -1/2 \\ 1 \end{bmatrix}$ 

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$$\mathbf{u}_{1} = \begin{bmatrix} 1/\sqrt{2} \\ 0 \\ 1/\sqrt{2} \end{bmatrix}, \quad \mathbf{u}_{2} = \begin{bmatrix} -1/\sqrt{18} \\ 4/\sqrt{18} \\ 1/\sqrt{18} \end{bmatrix} \qquad \mathbf{u}_{3} = \frac{1}{\|2\mathbf{v}_{3}\|} 2\mathbf{v}_{3} = \frac{1}{3} \begin{bmatrix} -2 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -2/3 \\ -1/3 \\ 2/3 \end{bmatrix}$$

$$P = \begin{bmatrix} \mathbf{u}_1 & \mathbf{u}_2 & \mathbf{u}_3 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{18} & -2/3 \\ 0 & 4/\sqrt{18} & -1/3 \\ 1/\sqrt{2} & 1/\sqrt{18} & 2/3 \end{bmatrix}, \quad D = \begin{bmatrix} 7 & 0 & 0 \\ 0 & 7 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$

# Spectral Decomposition

#### spectral decomposition of A

$$A = PDP^{T} = \begin{bmatrix} \mathbf{u}_1 & \cdots & \mathbf{u}_n \end{bmatrix} \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} \begin{bmatrix} \mathbf{u}_1^T \\ \vdots \\ \mathbf{u}_n^T \end{bmatrix}$$

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$$= \begin{bmatrix} \lambda_{1}\mathbf{u}_{1} & \cdots & \lambda_{n}\mathbf{u}_{n} \end{bmatrix} \begin{bmatrix} \mathbf{u}_{1}^{T} \\ \vdots \\ \mathbf{u}_{n}^{T} \end{bmatrix}$$

$$A = \lambda_1 \mathbf{u}_1 \mathbf{u}_1^T + \lambda_2 \mathbf{u}_2 \mathbf{u}_2^T + \dots + \lambda_n \mathbf{u}_n \mathbf{u}_n^T$$

an  $n \times n$  matrix of rank 1

# QUADRATIC FORM

## Quadratic form

A quadratic form on  $\mathbb{R}^n$  is a function Q defined on  $\mathbb{R}^n$  whose value at a vector  $\mathbf{x}$  in  $\mathbb{R}^n$  can be computed by an expression of the form  $Q(\mathbf{x}) = \mathbf{x}^T A \mathbf{x}$ , where A is an  $n \times n$  symmetric matrix.

$$Q(\mathbf{x}) = \mathbf{x}^T I \mathbf{x} = \|\mathbf{x}\|^2$$

**EXAMPLE 1** Let  $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ . Compute  $\mathbf{x}^T A \mathbf{x}$  for the following matrices:

a. 
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b. There are two -2 entries in A. Watch how they enter the calculations. The (1, 2)-entry in A is in boldface type.

$$\mathbf{x}^{T} A \mathbf{x} = \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 3 & -2 \\ -2 & 7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 3x_1 - 2x_2 \\ -2x_1 + 7x_2 \end{bmatrix}$$

$$= x_1 (3x_1 - 2x_2) + x_2 (-2x_1 + 7x_2)$$

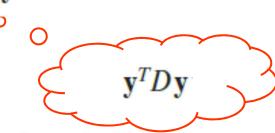
$$= 3x_1^2 - 2x_1x_2 - 2x_2x_1 + 7x_2^2$$

$$= 3x_1^2 - 4x_1x_2 + 7x_2^2$$

#### Change of Variable in a Quadratic Form

$$\mathbf{x} = P\mathbf{y}, \quad \mathbf{y} = P^{-1}\mathbf{x}$$

$$\mathbf{x}^T A \mathbf{x} = (P \mathbf{y})^T A (P \mathbf{y}) = \mathbf{y}^T P^T A P \mathbf{y} = \mathbf{y}^T (P^T A P) \mathbf{y}$$



there is an orthogonal matrix P such that  $P^{T}AP$  is a diagonal matrix D

**EXAMPLE 4** Make a change of variable that transforms the quadratic form in Example 3 into a quadratic form with no cross-product term.

**SOLUTION** The matrix of the quadratic form in Example 3 is

$$A = \begin{bmatrix} 1 & -4 \\ -4 & -5 \end{bmatrix}$$

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The first step is to orthogonally diagonalize A. Its eigenvalues turn out to be  $\lambda = 3$  and  $\lambda = -7$ . Associated unit eigenvectors are

$$\lambda = 3: \begin{bmatrix} 2/\sqrt{5} \\ -1/\sqrt{5} \end{bmatrix}; \qquad \lambda = -7: \begin{bmatrix} 1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix}$$

$$P = \begin{bmatrix} 2/\sqrt{5} & 1/\sqrt{5} \\ -1/\sqrt{5} & 2/\sqrt{5} \end{bmatrix}, \qquad D = \begin{bmatrix} 3 & 0 \\ 0 & -7 \end{bmatrix}$$

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## Quadratic form

#### The Principal Axes Theorem

Let A be an  $n \times n$  symmetric matrix. Then there is an orthogonal change of variable,  $\mathbf{x} = P\mathbf{y}$ , that transforms the quadratic form  $\mathbf{x}^T A \mathbf{x}$  into a quadratic form  $\mathbf{y}^T D \mathbf{y}$  with no cross-product term.

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The columns of P in the theorem are called the **principal axes** of the quadratic form  $\mathbf{x}_{\tau}A\mathbf{x}$ .

# Classifying quadratic forms

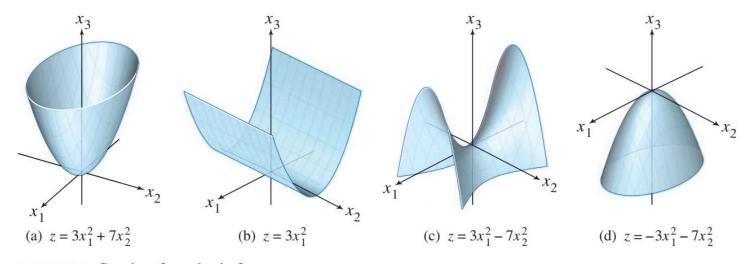


FIGURE 4 Graphs of quadratic forms.

$$(x_1, x_2, z)$$
 where  $z = Q(\mathbf{x})$ 

# Classifying Quadratic Forms

#### A quadratic form Q is:

- a. **positive definite** if  $Q(\mathbf{x}) > 0$  for all  $\mathbf{x} \neq \mathbf{0}$ ,
- b. **negative definite** if  $Q(\mathbf{x}) < 0$  for all  $\mathbf{x} \neq \mathbf{0}$ ,
- c. **indefinite** if  $Q(\mathbf{x})$  assumes both positive and negative values.

Also, Q is said to be **positive semidefinite** if  $Q(\mathbf{x}) \ge 0$  for all  $\mathbf{x}$ , and to be **negative semidefinite** if  $Q(\mathbf{x}) \le 0$  for all  $\mathbf{x}$ .

## Classifying Quadratic Forms

#### **Quadratic Forms and Eigenvalues**

Let A be an  $n \times n$  symmetric matrix. Then a quadratic form  $\mathbf{x}^T A \mathbf{x}$  is:

- a. positive definite if and only if the eigenvalues of A are all positive,
- b. negative definite if and only if the eigenvalues of A are all negative, or
- c. indefinite if and only if A has both positive and negative eigenvalues.

## Proof

**PROOF** By the Principal Axes Theorem, there exists an orthogonal change of variable  $\mathbf{x} = P\mathbf{y}$  such that

$$Q(\mathbf{x}) = \mathbf{x}^T A \mathbf{x} = \mathbf{y}^T D \mathbf{y} = \lambda_1 y_1^2 + \lambda_2 y_2^2 + \dots + \lambda_n y_n^2$$

**positive definite matrix** A is a *symmetric* matrix for which the quadratic form **x**<sub>⊤</sub>A**x** is positive definite

# CONSTRAINED OPTIMIZATION

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Engineers, economists, scientists, and mathematicians often need to find the maximum or minimum value of a quadratic form Q(x) for x in some specified set.

$$\|\mathbf{x}\| = 1, \quad \|\mathbf{x}\|^2 = 1, \quad \mathbf{x}^T \mathbf{x} = 1$$

$$x_1^2 + x_2^2 + \dots + x_n^2 = 1$$

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When a quadratic form Q has no cross-product terms, it is easy to find the maximum and minimum of  $Q(\mathbf{x})$  for  $\mathbf{x}^T\mathbf{x} = 1$ .

# example

**EXAMPLE 1** Find the maximum and minimum values of  $Q(\mathbf{x}) = 9x_1^2 + 4x_2^2 + 3x_3^2$  subject to the constraint  $\mathbf{x}^T\mathbf{x} = 1$ .

$$Q(\mathbf{x}) = 9x_1^2 + 4x_2^2 + 3x_3^2$$

$$\leq 9x_1^2 + 9x_2^2 + 9x_3^2$$

$$= 9(x_1^2 + x_2^2 + x_3^2)$$

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$$Q(\mathbf{x}) \ge 3x_1^2 + 3x_2^2 + 3x_3^2 = 3(x_1^2 + x_2^2 + x_3^2) = 3$$

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Let A be a symmetric matrix, and define m and M as in (2). Then M is the greatest eigenvalue  $\lambda_1$  of A and m is the least eigenvalue of A. The value of  $\mathbf{x}^T A \mathbf{x}$  is M when  $\mathbf{x}$  is a unit eigenvector  $\mathbf{u}_1$  corresponding to M. The value of  $\mathbf{x}^T A \mathbf{x}$  is m when  $\mathbf{x}$  is a unit eigenvector corresponding to m.

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PROOF Orthogonally diagonalize 
$$A$$
 as  $PDP^{-1}$ . We know that  $\mathbf{x}^T A \mathbf{x} = \mathbf{y}^T D \mathbf{y}$  when  $\mathbf{x} = P \mathbf{y}$   $\|\mathbf{x}\| = \|P\mathbf{y}\| = \|\mathbf{y}\|$  for all  $\mathbf{y}$ 

To simplify notation, suppose that A is a  $3 \times 3$  matrix with eigenvalues  $a \ge b \ge c$ .

$$D = \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix} \qquad \mathbf{y}^T D \mathbf{y} = ay_1^2 + by_2^2 + cy_3^2 \le ay_1^2 + ay_2^2 + ay_3^2$$
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$$\mathbf{x} = P\mathbf{e}_1 = \begin{bmatrix} \mathbf{u}_1 & \mathbf{u}_2 & \mathbf{u}_3 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \mathbf{u}_1$$

**EXAMPLE 3** Let  $A = \begin{bmatrix} 3 & 2 & 1 \\ 2 & 3 & 1 \\ 1 & 1 & 4 \end{bmatrix}$ . Find the maximum value of the quadratic

 $\begin{bmatrix} 1 & 1 & 4 \end{bmatrix}$  form  $\mathbf{x}^T A \mathbf{x}$  subject to the constraint  $\mathbf{x}^T \mathbf{x} = 1$ , and find a unit vector at which this maximum value is attained.

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form  $\mathbf{x}^T A \mathbf{x}$  subject to the constraint  $\mathbf{x}^T \mathbf{x} = 1$ , and find a unit vector at which this maximum value is attained.

$$0 = -\lambda^3 + 10\lambda^2 - 27\lambda + 18 = -(\lambda - 6)(\lambda - 3)(\lambda - 1)$$

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}. \text{ Set } \mathbf{u}_1 = \begin{bmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix}.$$

Let A,  $\lambda_1$ , and  $\mathbf{u}_1$  be as in Theorem 6. Then the maximum value of  $\mathbf{x}^T A \mathbf{x}$  subject to the constraints

$$\mathbf{x}^T \mathbf{x} = 1, \quad \mathbf{x}^T \mathbf{u}_1 = 0$$

is the second greatest eigenvalue,  $\lambda_2$ , and this maximum is attained when **x** is an eigenvector  $\mathbf{u}_2$  corresponding to  $\lambda_2$ .

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Let A be a symmetric  $n \times n$  matrix with an orthogonal diagonalization  $A = PDP^{-1}$ , where the entries on the diagonal of D are arranged so that  $\lambda_1 \ge \lambda_2 \ge \cdots \ge \lambda_n$  and where the columns of P are corresponding unit eigenvectors  $\mathbf{u}_1, \ldots, \mathbf{u}_n$ . Then for  $k = 2, \ldots, n$ , the maximum value of  $\mathbf{x}^T A \mathbf{x}$  subject to the constraints

$$\mathbf{x}^T\mathbf{x} = 1, \quad \mathbf{x}^T\mathbf{u}_1 = 0, \quad \dots, \quad \mathbf{x}^T\mathbf{u}_{k-1} = 0$$

is the eigenvalue  $\lambda_k$ , and this maximum is attained at  $\mathbf{x} = \mathbf{u}_k$ .

# SINGULAR VALUE DECOMPOSITION

#### Introduction

Example

$$A = \begin{bmatrix} 4 & 11 & 14 \\ 8 & 7 & -2 \end{bmatrix} \qquad \mathbf{X} \mapsto A\mathbf{X}$$

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 ${\bf x}$  at which the length  $\|{\bf A}{\bf x}\|$  is maximized, and compute this maximum length  $\|{\bf x}\|=1$ 

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$$\mathbf{x} \mapsto A\mathbf{x}$$

 $\mathbf{x}$  at which the length  $\|A\mathbf{x}\|$  is maximized, and compute this maximum length  $\|\mathbf{x}\| = 1$ 

$$\|A\mathbf{x}\|^2 = (A\mathbf{x})^T (A\mathbf{x}) = \mathbf{x}^T A^T A \mathbf{x} = \mathbf{x}^T (A^T A) \mathbf{x}$$

the greatest eigenvalue  $\lambda_1$  of  $A^TA$ 

$$A^{T}A = \begin{bmatrix} 4 & 8 \\ 11 & 7 \\ 14 & -2 \end{bmatrix} \begin{bmatrix} 4 & 11 & 14 \\ 8 & 7 & -2 \end{bmatrix} = \begin{bmatrix} 80 & 100 & 40 \\ 100 & 170 & 140 \\ 40 & 140 & 200 \end{bmatrix} \quad \lambda_{1} = 360, \lambda_{2} = 90, \text{ and } \lambda_{3} = 0$$

$$\mathbf{v}_1 = \begin{bmatrix} 1/3 \\ 2/3 \\ 2/3 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} -2/3 \\ -1/3 \\ 2/3 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 2/3 \\ -2/3 \\ 1/3 \end{bmatrix}$$

For  $\|\mathbf{x}\| = 1$ , the maximum value of  $\|A\mathbf{x}\|$  is  $\|A\mathbf{v}_1\| = \sqrt{360} = 6\sqrt{10}$ .

Let A be an  $m \times n$  matrix. Then  $A^TA$  is symmetric and can be orthogonally diagonalized. Let  $\{\mathbf{v}_1, \ldots, \mathbf{v}_n\}$  be an orthonormal basis for  $\mathbb{R}^n$  consisting of eigenvectors of  $A^TA$ , and let  $\lambda_1, \ldots, \lambda_n$  be the associated eigenvalues of  $A^TA$ . Then, for  $1 \le i \le n$ ,

$$\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_n \geq 0$$

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eigenvalues of  $A^{T}A$  are all nonnegative

The **singular values** of A are the square roots of the eigenvalues of  $A^TA$ , denoted by  $\sigma_1, \ldots, \sigma_n$ , and they are arranged in decreasing order. That is,  $\sigma_i = \sqrt{\lambda_i}$  for  $1 \le i \le n$ .

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$$\begin{aligned} ||A\mathbf{v}_i||^2 &= (A\mathbf{v}_i)^T A \mathbf{v}_i = \mathbf{v}_i^T A^T A \mathbf{v}_i \\ &= \mathbf{v}_i^T (\lambda_i \mathbf{v}_i) & \text{Since } \mathbf{v}_i \text{ is an eigenvector of } A^T A \\ &= \lambda_i & \text{Since } \mathbf{v}_i \text{ is a unit vector} \end{aligned}$$

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the singular values of A are the lengths of the vectors  $A\mathbf{v}_1,\dots,A\mathbf{v}_n$ 

#### Theorem

#### THEOREM 9

Suppose  $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  is an orthonormal basis of  $\mathbb{R}^n$  consisting of eigenvectors of  $A^TA$ , arranged so that the corresponding eigenvalues of  $A^TA$  satisfy  $\lambda_1 \ge \dots \ge \lambda_n$ , and suppose A has r nonzero singular values. Then  $\{A\mathbf{v}_1, \dots, A\mathbf{v}_r\}$  is an orthogonal basis for Col A, and rank A = r.

$$(A\mathbf{v}_i)^T(A\mathbf{v}_j) = \mathbf{v}_i^T A^T A \mathbf{v}_j = \mathbf{v}_i^T (\lambda_j \mathbf{v}_j) = 0$$

$$\mathbf{y} = A\mathbf{x} \qquad \mathbf{x} = c_1\mathbf{v}_1 + \dots + c_n\mathbf{v}_n$$

$$\mathbf{y} = A\mathbf{x} = c_1 A\mathbf{v}_1 + \dots + c_r A\mathbf{v}_r + c_{r+1} A\mathbf{v}_{r+1} + \dots + c_n A\mathbf{v}_n$$
$$= c_1 A\mathbf{v}_1 + \dots + c_r A\mathbf{v}_r + 0 + \dots + 0$$

#### SVD

#### THEOREM 10

#### The Singular Value Decomposition

Let A be an  $m \times n$  matrix with rank r. Then there exists an  $m \times n$  matrix  $\Sigma$  as in (3) for which the diagonal entries in D are the first r singular values of A,  $\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_r > 0$ , and there exist an  $m \times m$  orthogonal matrix U and an  $n \times n$  orthogonal matrix V such that

$$A = U \Sigma V^T$$

$$\Sigma = \begin{bmatrix} D & 0 \\ 0 & 0 \end{bmatrix} - m - r \text{ rows}$$

$$\uparrow \quad n - r \text{ columns}$$

matrices U and V are not uniquely determined by A, but the diagonal entries of D are necessarily the singular values of A

columns of U left singular vectors of A columns of V right singular vectors of A

# proof

**PROOF** Let  $\lambda_i$  and  $\mathbf{v}_i$  be as in Theorem 9, so that  $\{A\mathbf{v}_1, \dots, A\mathbf{v}_r\}$  is an orthogonal basis for Col A. Normalize each  $A\mathbf{v}_i$  to obtain an orthonormal basis  $\{\mathbf{u}_1, \dots, \mathbf{u}_r\}$ , where

$$\mathbf{u}_i = \frac{1}{\|A\mathbf{v}_i\|} A\mathbf{v}_i = \frac{1}{\sigma_i} A\mathbf{v}_i \qquad A\mathbf{v}_i = \sigma_i \mathbf{u}_i$$

extend  $\{\mathbf{u}_1,\ldots,\mathbf{u}_r\}$  to an orthonormal basis  $\{\mathbf{u}_1,\ldots,\mathbf{u}_m\}$  of  $\mathbb{R}^m$ 

$$U = [\mathbf{u}_1 \ \mathbf{u}_2 \ \cdots \ \mathbf{u}_m]$$
 and  $V = [\mathbf{v}_1 \ \mathbf{v}_2 \ \cdots \ \mathbf{v}_n]$ 

$$AV = [A\mathbf{v}_1 \quad \cdots \quad A\mathbf{v}_r \quad \mathbf{0} \quad \cdots \quad \mathbf{0}] = [\sigma_1\mathbf{u}_1 \quad \cdots \quad \sigma_r\mathbf{u}_r \quad \mathbf{0} \quad \cdots \quad \mathbf{0}]$$

# proof

$$AV = \begin{bmatrix} A\mathbf{v}_1 & \cdots & A\mathbf{v}_r & \mathbf{0} & \cdots & \mathbf{0} \end{bmatrix} = \begin{bmatrix} \sigma_1\mathbf{u}_1 & \cdots & \sigma_r\mathbf{u}_r & \mathbf{0} & \cdots & \mathbf{0} \end{bmatrix}$$

$$U\Sigma V^T = AVV^T = A.$$

$$A = \begin{bmatrix} 4 & 11 & 14 \\ 8 & 7 & -2 \end{bmatrix}$$

$$A = \begin{bmatrix} 4 & 11 & 14 \\ 8 & 7 & -2 \end{bmatrix} \qquad V = \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 & \mathbf{v}_3 \end{bmatrix} = \begin{bmatrix} 1/3 & -2/3 & 2/3 \\ 2/3 & -1/3 & -2/3 \\ 2/3 & 2/3 & 1/3 \end{bmatrix}$$

$$\sigma_1 = 6\sqrt{10}, \quad \sigma_2 = 3\sqrt{10}, \quad \sigma_3 = 0$$

$$D = \begin{bmatrix} 6\sqrt{10} & 0\\ 0 & 3\sqrt{10} \end{bmatrix}$$

$$\Sigma = \begin{bmatrix} D & 0 \end{bmatrix} = \begin{bmatrix} 6\sqrt{10} & 0 & 0 \\ 0 & 3\sqrt{10} & 0 \end{bmatrix}$$

$$\mathbf{u}_{1} = \frac{1}{\sigma_{1}} A \mathbf{v}_{1} = \frac{1}{6\sqrt{10}} \begin{bmatrix} 18 \\ 6 \end{bmatrix} = \begin{bmatrix} 3/\sqrt{10} \\ 1/\sqrt{10} \end{bmatrix}$$

$$\mathbf{u}_{2} = \frac{1}{\sigma_{2}} A \mathbf{v}_{2} = \frac{1}{3\sqrt{10}} \begin{bmatrix} 3 \\ -9 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{10} \\ -3/\sqrt{10} \end{bmatrix}$$

$$A = \begin{bmatrix} 3/\sqrt{10} & 1/\sqrt{10} \\ 1/\sqrt{10} & -3/\sqrt{10} \end{bmatrix} \begin{bmatrix} 6\sqrt{10} & 0 & 0 \\ 0 & 3\sqrt{10} & 0 \end{bmatrix} \begin{bmatrix} 1/3 & 2/3 & 2/3 \\ -2/3 & -1/3 & 2/3 \\ 2/3 & -2/3 & 1/3 \end{bmatrix}$$

$$\uparrow \qquad \qquad \uparrow \qquad \qquad \uparrow$$

$$U \qquad \qquad \Sigma \qquad \qquad \downarrow^{T}$$

Find a singular value decomposition of 
$$A = \begin{bmatrix} 1 & -1 \\ -2 & 2 \\ 2 & -2 \end{bmatrix}$$
  $A^TA = \begin{bmatrix} 9 & -9 \\ -9 & 9 \end{bmatrix}$ 

eigenvalues of  $A^{T}A$  are 18 and 0

$$\sigma_1 = \sqrt{18} = 3\sqrt{2}$$
 and  $\sigma_2 = 0$ 

$$\mathbf{v}_1 = \begin{bmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$

$$\mathbf{v}_1 = \begin{bmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$

$$A\mathbf{v}_1 = \begin{bmatrix} 2/\sqrt{2} \\ -4/\sqrt{2} \\ 4/\sqrt{2} \end{bmatrix}, \quad A\mathbf{v}_2 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \qquad \mathbf{u}_1 = \frac{1}{3\sqrt{2}}A\mathbf{v}_1 = \begin{bmatrix} 1/3 \\ -2/3 \\ 2/3 \end{bmatrix}$$

$$\Sigma = \begin{bmatrix} D & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 3\sqrt{2} & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\mathbf{v}_1 = \begin{bmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix} \qquad V = \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ -1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}$$

$$\mathbf{u}_1 = \frac{1}{3\sqrt{2}}A\mathbf{v}_1 = \begin{bmatrix} 1/3 \\ -2/3 \\ 2/3 \end{bmatrix}$$

$$\mathbf{u}_1^T \mathbf{x} = 0 \qquad x_1 - 2x_2 + 2x_3 = 0 \\ \mathbf{w}_1 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}, \quad \mathbf{w}_2 = \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}$$

Gram-Schmidt 
$$\mathbf{u}_2 = \begin{bmatrix} 2/\sqrt{5} \\ 1/\sqrt{5} \\ 0 \end{bmatrix}, \quad \mathbf{u}_3 = \begin{bmatrix} -2/\sqrt{45} \\ 4/\sqrt{45} \\ 5/\sqrt{45} \end{bmatrix}$$

# SVD for Image Compression

$$f_{ij}$$
 Where  $f_{ij} \equiv f(x_i, y_j)$ 

Redundancy exists in Images

Size of images

Compression

$$A = USV^{T} = \sum_{i=1}^{r} \sigma_{i} \mathbf{u}_{i} \mathbf{v}_{i}^{T}$$

$$A_{k} = \sigma_{1} \mathbf{u}_{1} \mathbf{v}_{1}^{T} + \sigma_{2} \mathbf{u}_{2} \mathbf{v}_{2}^{T} + \dots + \sigma_{k} \mathbf{u}_{k} \mathbf{v}_{k}^{T}$$

The total storage for  $A_k$  will be

$$k(m+n+1)$$

# SVD for Image Compression

$$C_R = m *n/(k (m + n + 1))$$

To measure the quality between original image A and the compressed image Ak, the measurement of Mean Square Error (MSE)

$$MSE = \frac{1}{mn} \sum_{y=1}^{m} \sum_{x=1}^{n} (f_A(x, y) - f_{A_k}(x, y))$$

C<sub>R</sub> MSE

Comp	(Quality)
5.03	108.11
3.35	63.15
2.51	40.39
2.01	27.22
1.68	15.64
1.26	9.07
1	

# Face Recognition: PCA (principle component analysis)

- •SVD approach treats a set of known faces as vectors in a subspace, called "face space"
- •Assume each face image has  $m \times n = M$  pixels
- •an  $M \times 1$  column vector  $\mathbf{fi}$
- •A training set, S with N number of face images of known individuals forms an  $M \times N$  matrix:

$$S = [\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_N]$$

$$\bar{\mathbf{f}} = \frac{1}{N} \sum_{i=1}^{N} \mathbf{f}_i$$

$$\mathbf{a}_i = \mathbf{f}_i - \bar{\mathbf{f}}_i, i = 1, 2, \dots N$$

$$A = [\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_N]$$

$$A = U \Sigma V^T$$

 $\{\mathbf{u}_1,\mathbf{u}_2,...,\mathbf{u}_r\}$  form an orthonormal basis for R(A)

# Face Recognition: PCA

$$\mathbf{x} \ (= [x_1, x_2, ..., x_r]^T)$$
 $\mathbf{x} = [\mathbf{u}_1, \mathbf{u}_2, ..., \mathbf{u}_r]^T (\mathbf{f} - \bar{\mathbf{f}})$ 

Minimize the distance

$$\varepsilon_i = \|\mathbf{x} - \mathbf{x}_i\|_2 = \left[ (\mathbf{x} - \mathbf{x}_i)^T (\mathbf{x} - \mathbf{x}_i) \right]^{1/2}$$

