

# **Operating Systems**

# **Synchronization Tools-Part2**

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# Hardware Support for Synchronization

# **Memory model**

 Memory model are the memory guarantees a computer architecture makes to application programs.

- IMC: Integrated Memory Controller
- The QPI is a point-to-point connection protocol developed by Intel to replace the front-side-bus (FSB).

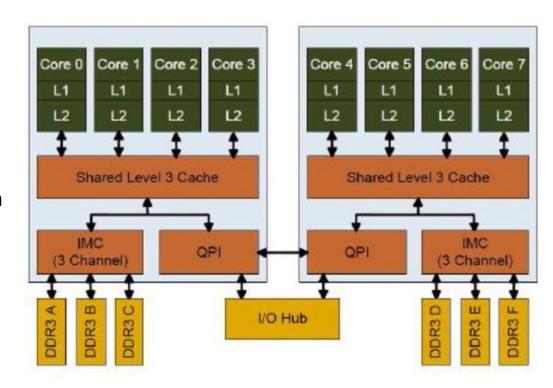


Fig. 2-1. Eight-core Processor cache hierarchy[1]

https://www.semanticscholar.org/paper/Multi-Core-Processor-Cache-Hierarchy-Design-Kumari-Charles/2d16258444e9935c8d56c855b17a2c8d2c212745



# Memory model (cont.)

Memory models may be either:

#### Strongly ordered

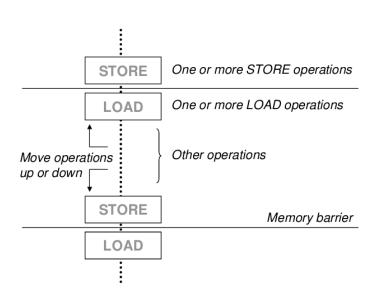
Memory modification of one processor is immediately visible to all other processors.

#### Weakly ordered

Memory modification of one processor may not be immediately visible to all other processors.

# Memory Barrier (cont.)

 A memory barrier is an instruction that forces any change in memory to be propagated (made visible) to all other processors.



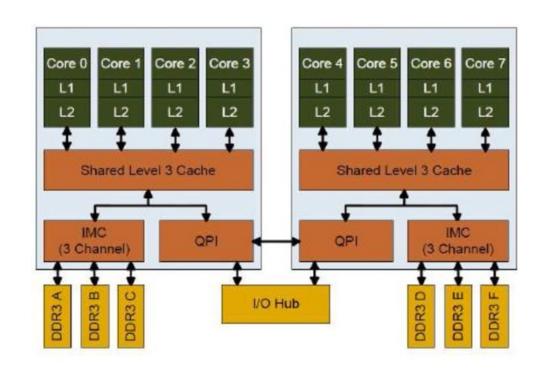


Fig. 2-1. Eight-core Processor cache hierarchy[1]



# **Memory Barrier Instructions**

• When a memory barrier instruction is performed, the system ensures that all loads and stores are completed before any subsequent load or store operations are performed.

Therefore, even if instructions were reordered, the memory barrier ensures that the store operations are completed in memory and visible to other *processors* before future load or store operations are performed.

# **Memory Barrier Example**

Returning to the example of slides 5-6

 We could add a memory barrier (as follows) to ensure Thread 1 outputs 100.

# Memory Barrier Example (cont.)

Thread 1 now performs

```
while (!flag)
memory_barrier();
print x
```

Thread 2 now performs

```
x = 100;
memory_barrier();
flag = true
```

- For Thread 1  $\rightarrow$  the value of flag is loaded before the value of x.
- For Thread 2  $\rightarrow$  the assignment to x occurs **before the assignment flag**.

## **Memory Barrier for Peterson's solution**

#### Where should we add memory barrier?

```
//P_0
                                      //P_1
                                      1. while (true) {
1. while (true) {
2.
   flag[0] = true;
                                      2. flag[1] = true;
3.
                                      3. turn = 0;
  turn = 1;
  while (flag[1] \&\& turn == 1);
                                      4. while (flag[0] && turn == 0);
4.
    /* critical section */
                                          /* critical section */
5.
     flag[0] = false;
                                            flag[1] = false;
    /* remainder section */
                                          /* remainder section */
                                      }
```

#### Memory Barrier for Peterson's solution (Cont.)

We could place a memory barrier between the first two assignment statements in the entry section to avoid the reordering of operations shown in the previous slide.

Note that memory barriers are considered very low-level operations and are typically only used by kernel developers when writing specialized code that ensures mutual exclusion.

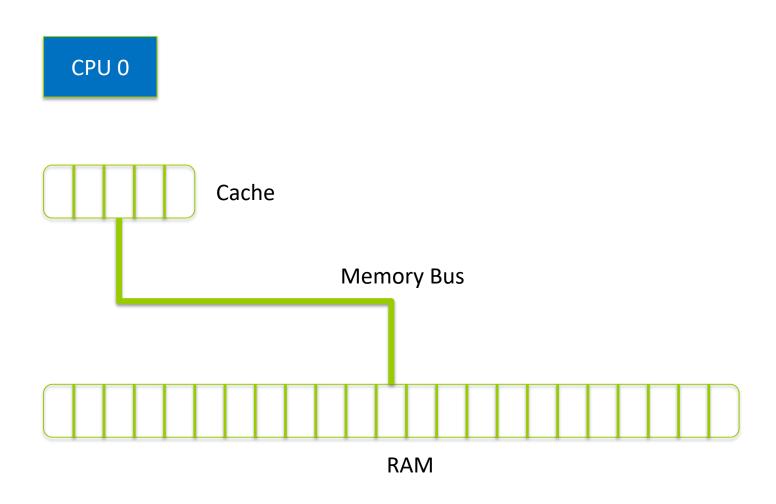


# Slides from Don Porter's Course

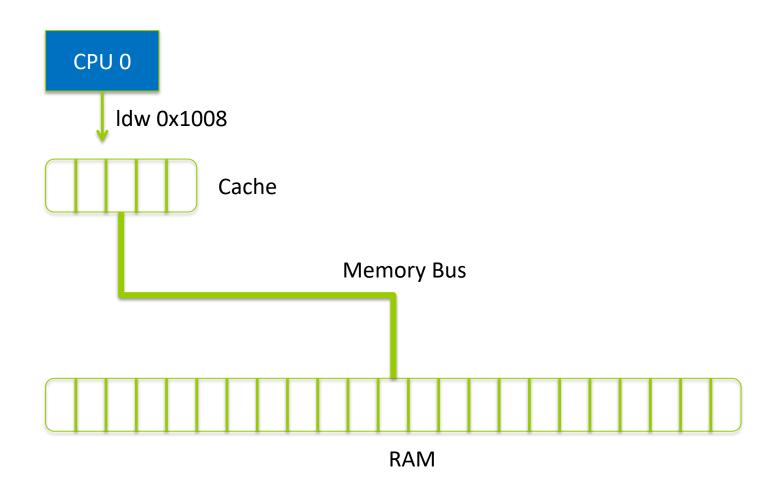
## **Cache line alignment**

Lines are the basic unit at which memory is cached

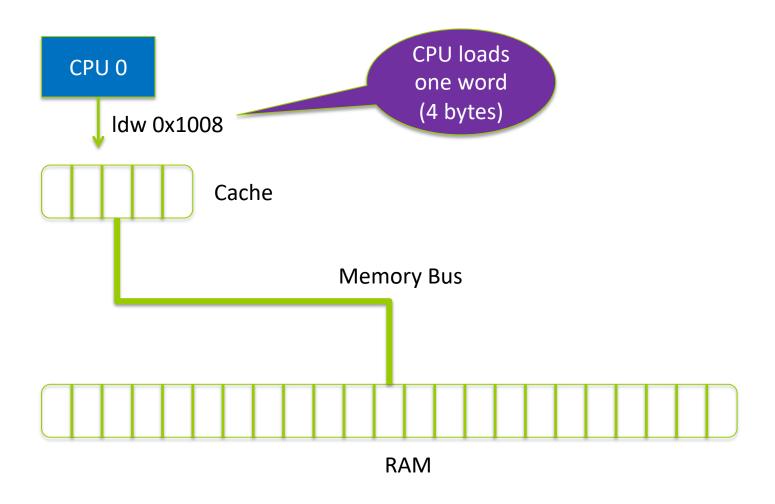
- Cache lines are bigger than words
  - Word: 32-bits or 64-bits
  - Cache line 64—128 bytes on most CPUs



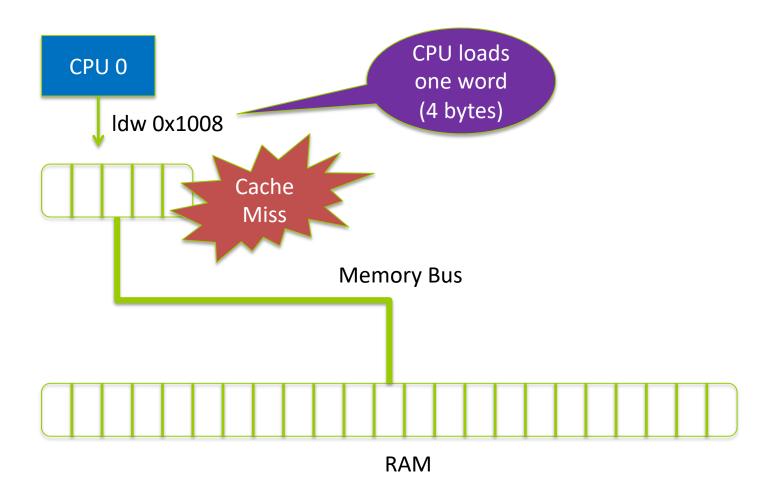




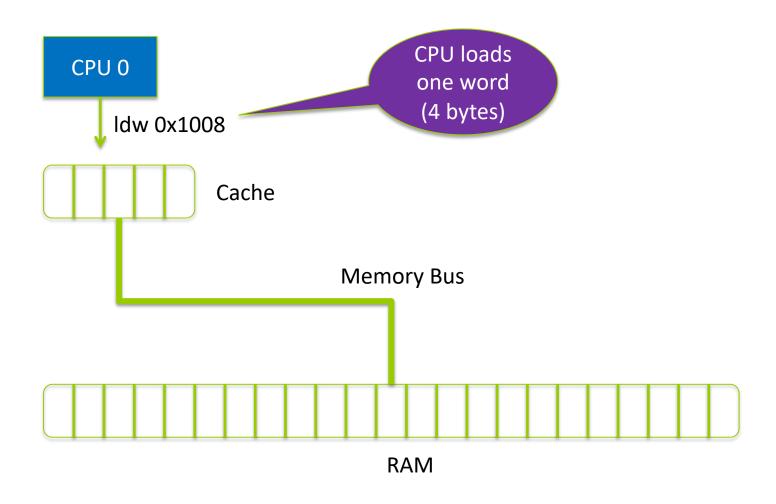




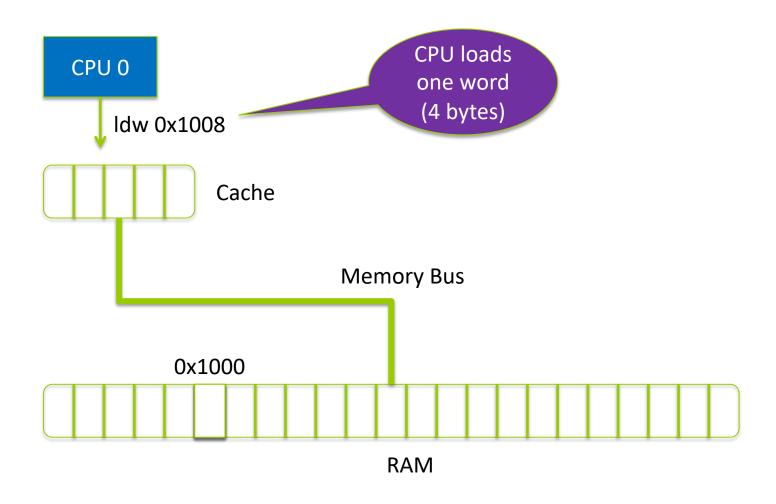




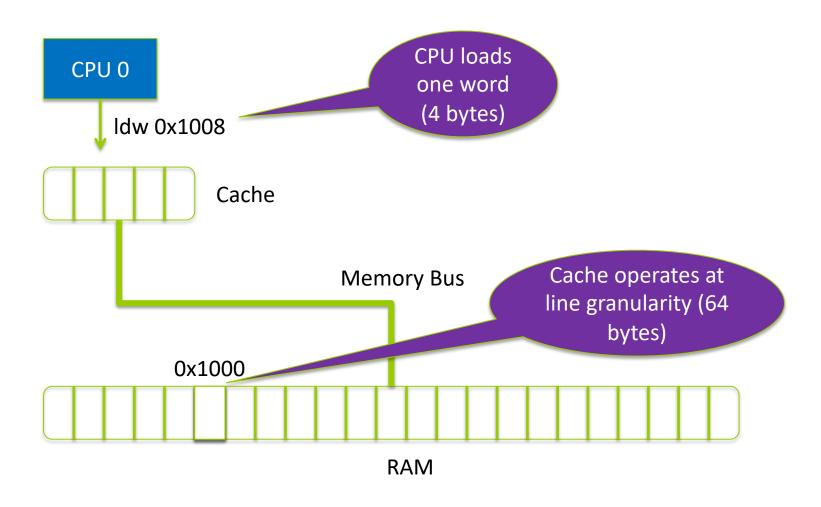




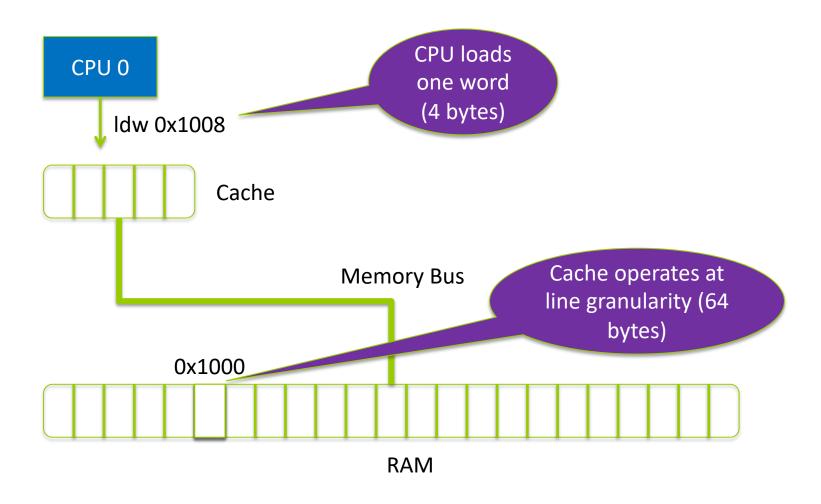




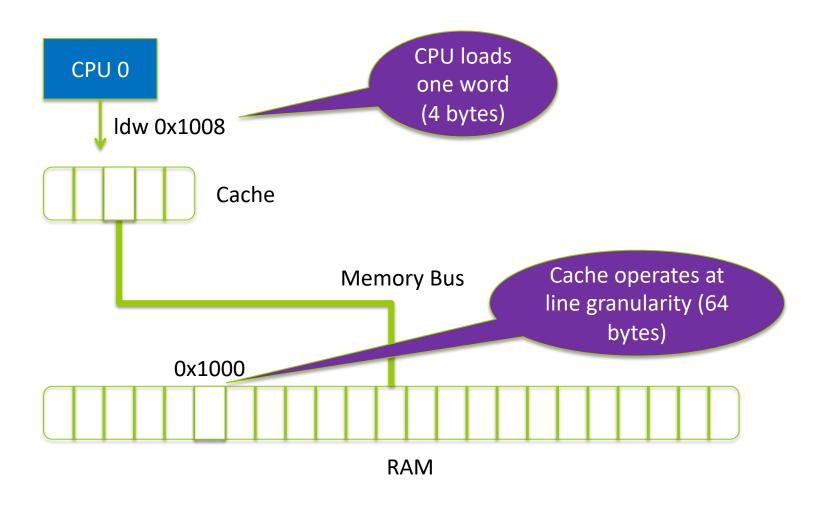








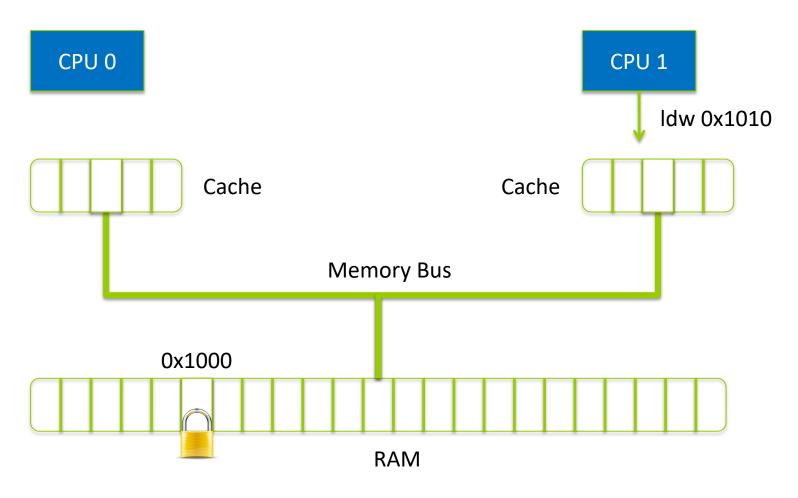






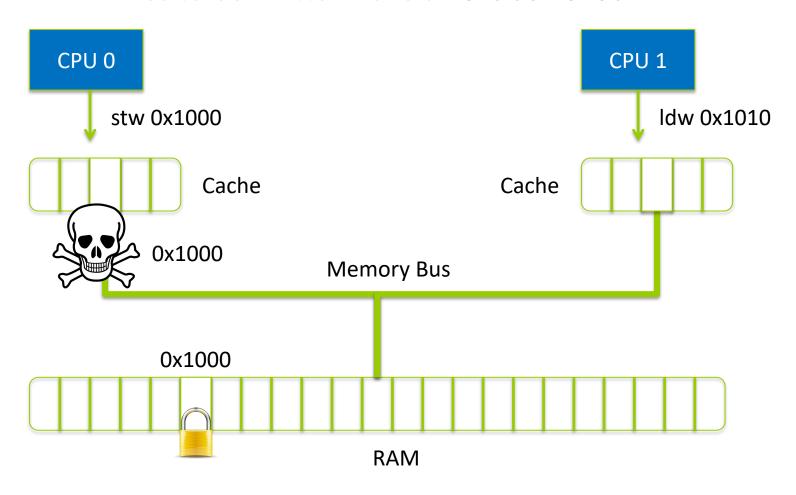
## **Cache Coherence (1)**

#### Lines shared for reading have a *shared lock*



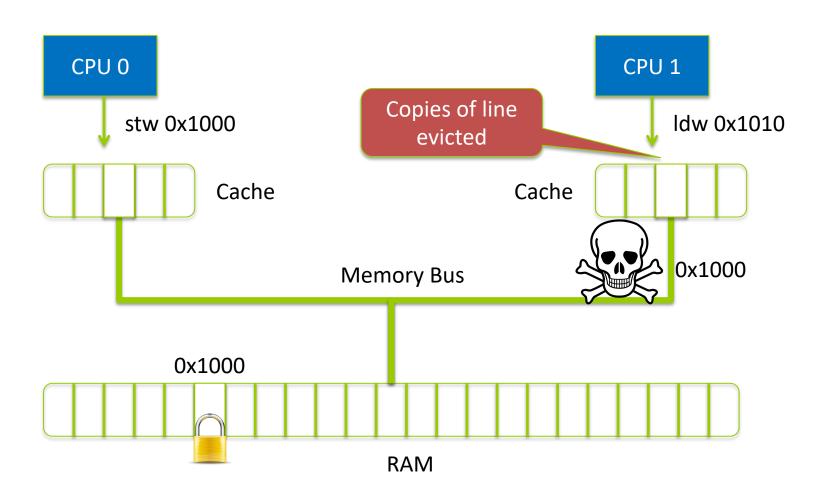


## **Cache Coherence (2)**





## **Cache Coherence (2)**



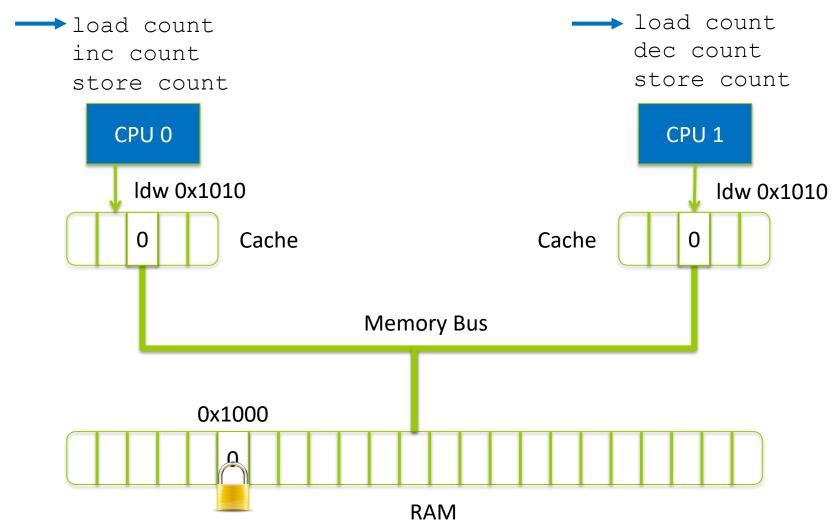


## Simple coherence model

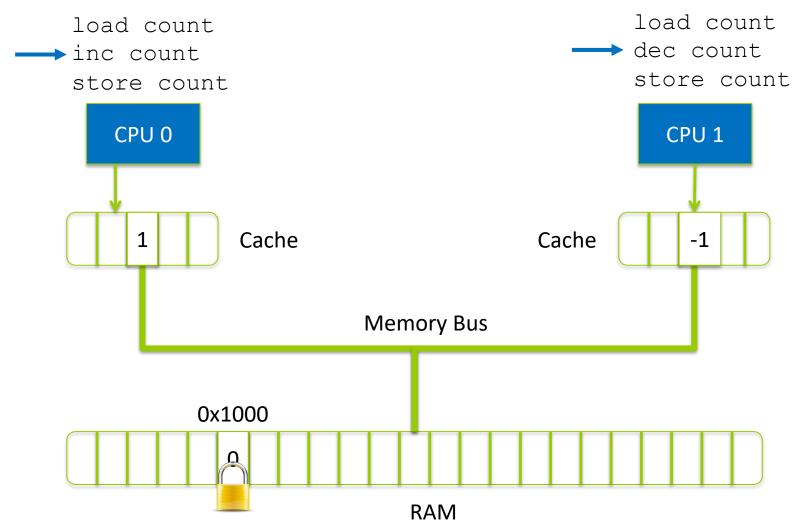
- When a memory region is cached, CPU automatically acquires a reader-writer lock on that region
  - Multiple CPUs can share a read lock
  - Write lock is exclusive

- Programmer can't control how long these locks are held
  - Ex: a store from a register holds the write lock long enough to perform the write; held from there until the next CPU wants it

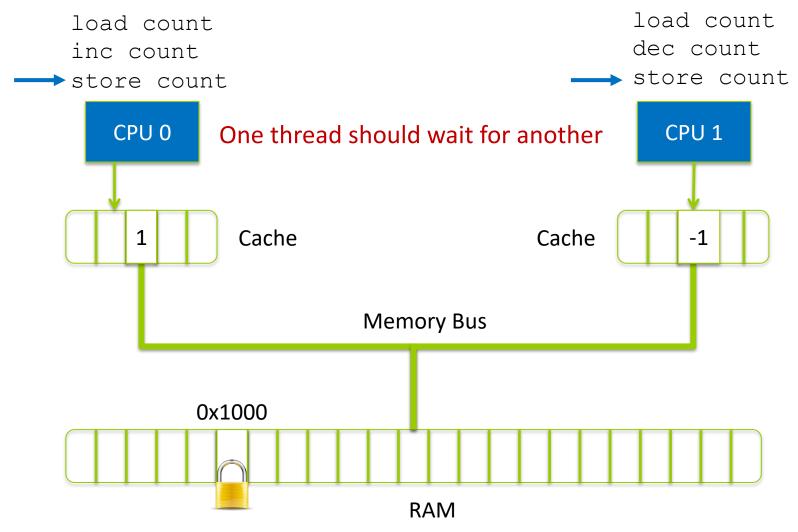
#### Lines shared for reading have a *shared lock*

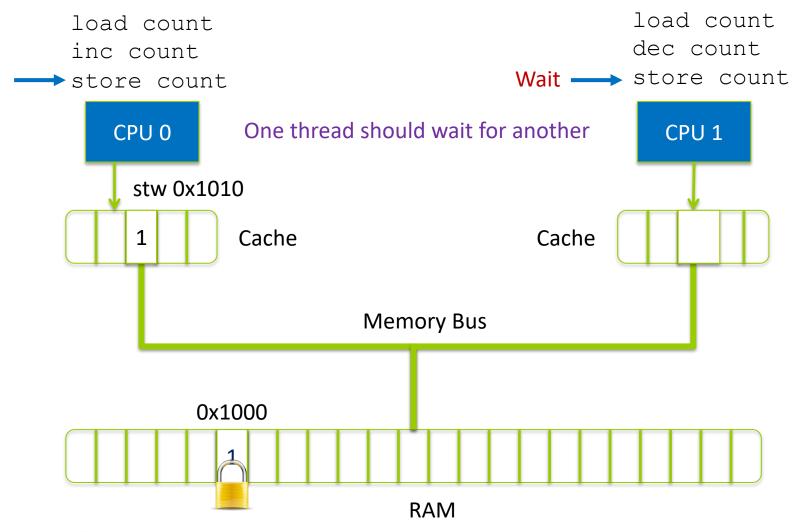


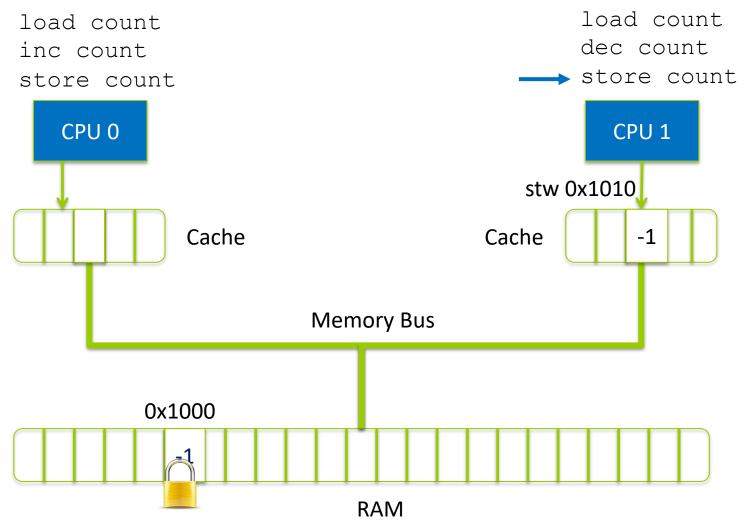












# **Back to HW supports for CS problem**

# **Synchronization Hardware Support**

- Many systems provide hardware support for implementing the critical section code.
- Uniprocessors could disable interrupts
  - Currently running code would execute without preemption
  - Generally, too inefficient on multiprocessor systems
    - Operating systems using this not broadly scalable.
- We will look at two forms of hardware support:
  - 1. Hardware instructions
  - 2. Atomic variables



#### **Hardware Instructions**

- Special hardware instructions that allow us to either test-and-modify the content of a word, or two swap the contents of two words atomically (uninterruptedly.)
  - Test-and-Set instruction
  - Compare-and-Swap instruction

# The test\_and\_set Instruction

Definition

```
boolean test_and_set (boolean *target)
{
    boolean rv = *target;
    *target = true;
    return rv:
}
```

- Properties
  - Executed atomically
  - Returns the original value of passed parameter
  - Set the new value of passed parameter to true



# Solution Using test\_and\_set()

Shared boolean variable lock, initialized to false

Does it solve the critical-section problem?

Requirement	Yes/No
Mutual Exclusion	
Progress	
Bounded waiting	

# The compare\_and\_swap Instruction

#### Definition

```
Int compare_and_swap(int *value, int expected, int new_value)
{
  int temp = *value;
  if (*value == expected)
     *value = new_value;
  return temp;
}
```

#### Properties

- Executed atomically
- Returns the original value of passed parameter value
- Set the variable value the value of the passed parameter new\_value but only if \*value == expected is true.



# Solution using compare\_and\_swap

Shared integer lock initialized to 0;

```
while (true) {
   while (compare_and_swap(&lock, 0, 1)!= 0);/*do nothing*/
   /* critical section */
   lock = 0;
   /* remainder section */
}
```

Does it solve the critical-section problem?

Requirement	Yes/No
Mutual Exclusion	
Progress	
Bounded waiting	

# Second solution using compare-and-swap

The common data structures are:

```
boolean waiting[n];
int lock;
```

- The elements in the waiting array are initialized to false
- Variable *lock* is initialized to 0.

#### Second solution using compare-and-swap

```
while (true) {
   waiting[i] = true;
   key = 1;
   while (waiting[i] && key == 1)
      key = compare and swap(\&lock, 0, 1);
   waiting[i] = false;
   /* critical section */
```



#### Second solution using compare-and-swap

```
while (true) {
   j = (i + 1) % n;
   while ((j != i) \&\& !waiting[j])
       j = (j + 1) % n;
                                              Yes/No?
                                Requirement
   if (j == i)
                             Mutual Exclusion
       lock = 0;
                             Progress
                             Bounded waiting
   else
      waiting[j] = false;
   /* remainder section */
```

# **Synchronization Hardware Support**

#### Hardware instructions

- test\_and\_set()
- Compare\_and\_swap()

#### Atomic variables

- We unfortunately do not have enough time to cover this
- Please read the related section in the reference book