## Example

**Theorem 0.1.** Let A be an embedded n-manifold with boundary  $\partial A$ . Let v be a direction such that  $h_v^A:A\to\mathbb{R}$  is a Morse function. Let the interval decomposition of the k-dimensional extended persistent homology of  $h_v^{\partial A}:\partial A\to\mathbb{R}$  be

$$\mathrm{XPH}_k\left(\partial A, h_v\right) = \bigoplus_{[b_i, d_i) \in S_X} \mathcal{I}_{[b_i, d_i)}.$$

Let  $J_A^k$  be the subset of intervals  $[b_i, d_i)$  such that  $b_i = (h_v(p), \text{ ord})$  for some  $p \in \text{Crit}(h_v^A, (k, +1))$ , or  $b_i = (h_v(p), \text{ rel })$  for some  $p \in \text{Crit}(h_v^A, (n-k-1, -1))$ . Then

$$\mathrm{XPH}_{k}\left(A,h_{v}\right) = \bigoplus_{[b_{i},d_{i}) \in J_{A}^{k}} \mathcal{I}_{[b_{i},d_{i})}.$$

For simplicity, we will classify all possible critical points.

**Definition 0.1.** For a given vertex, we have  $3 \times 2$  possibilities for critical points.



**Figure 1:** Index= (0,-)



Figure 2: Index= (0,-)

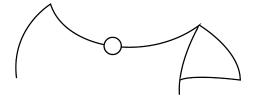


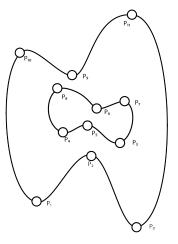
Figure 3: Index= (0,-)

It is well known that the homology groups of the torus are:

- 1.  $H_0(T) = \mathbb{Z}$
- 2.  $H_1(T) = \mathbb{Z} \oplus \mathbb{Z}$
- 3.  $H_2(T) = \mathbb{Z}$

As for the solid torus:

- 1.  $H_0(T) = \mathbb{Z}$
- 2.  $H_1(T) = \mathbb{Z}$
- 3.  $H_2(T) = 0$



**Figure 4:** Illustration of multiheaded attention. The two highlighted attention heads have learned to associate "it" with different parts of the sentence.

**Example 1.** Consider Figure 1. And we will compute  $XPH_0$ . We will also compare what is happening with the critical points with respect to both A and  $\partial A$ .

We will start with the boundary  $\partial A$  first.

- 1.  $P_0$  is a local minimum. It creates a connected component. It is actually the global minimum.
- 2.  $P_1$  is another local minimum. It creates another class in  $H_0$ .
- 3.  $P_2$  This is a saddle which joins the two connected components. So we pair  $(P_1, P_2)$ .
- 4.  $P_3$  This is a saddle which looks like a handle. This forms an essential class in  $H_1$ .
- 5.  $P_4$  adds another handle which forms another class in  $H_1$ .
- 6.  $P_5$  is a local maximum which joins two cycles, so we pair  $(P_4, P_5)$ .
- 7.  $P_6$  is a local minimum, which starts a class in  $H_0$ .
- 8.  $P_7$  is a saddle, which joins the component, so we pair  $(P_6, P_7)$ .
- 9.  $P_8$  is a saddle, which forms an essential class in  $H_1$ .
- 10.  $P_9$  is a saddle which looks like a handle, which forms a class in  $H_1$ .
- 11.  $P_{10}$  is a local maximum, which kills a class in  $H_1$ , so we pair  $(P_9, P_{10})$ .
- 12.  $P_{11}$  Is a global maximum, which creates a class in  $H_2$ .

Let us contrast this with the solid torus with boundary A.

- 1.  $P_0$  is a local minimum. It creates a connected component. It is actually the global minimum.
- 2.  $P_1$  is another local minimum. It creates another class in  $H_0$ .
- 3.  $P_2$  This is a saddle which joins the two connected components. So we pair  $(P_1, P_2)$ .
- 4.  $P_3$
- 5.  $P_4$

- 6.  $P_5$
- 7.  $P_6$
- 8.  $P_7$
- 9.  $P_8$
- 10.  $P_9$
- 11.  $P_{10}$
- 12.  $P_{11}$  Is a global maximum. Homology does not change.

 $P_3$  is where things start becoming different for the solid donut and for its boundary.



Figure 5: Handle

**Theorem 0.2.** Let  $A \subset \mathbb{R}^2$  be a 2-dimensional piecewise linear manifold with boundary  $X = \partial$ . Fix  $v \in S^1$ . The 0-dimensional persistent homology of  $h_v^X : X \to \mathbb{R}$  can be written as

$$\mathrm{PH}_{0}\left(X,h_{v}^{X}\right)=\oplus_{i=1}^{m}\mathcal{I}_{\left[h_{v}\left(y_{j_{i}}\right),d_{i}\right)}$$

where  $y_{j_1}, \dots y_{j_m}$  are the set of vertex representatives, and  $d_1, \dots d_m \in \mathbb{R} \cup \infty$ . Here we have only included intervals with positive length.

Let  $J^{\text{ord}}$  be the subset of  $\{1, 2, \dots m\}$  such that  $d_i$  is finite and  $y_{j_i}$  is (+) critical for  $h_v^A$ . Then

$$\operatorname{Ord}_{0}\left(A, h_{v}^{A}\right) = \bigoplus_{i \in J^{\operatorname{ord}}} \mathcal{I}_{\left[\left(h_{v}\left(y_{j_{i}}\right), \operatorname{ord}\right), \left(d_{i}, \operatorname{ord}\right)\right)}$$

Now let  $J^{\text{rel}}$  be the subset of  $\{1, 2, \dots m\}$  such that  $d_i$  is finite but  $y_i$  is not (+)-critical for  $h_{\cdot \cdot \cdot}^A$ .

$$\operatorname{Rel}_{1}\left(A, h_{v}^{A}\right) = \bigoplus_{i \in Jrel} \mathcal{I}_{\left[\left(d_{i}, \operatorname{rel}\right), \left(h_{v}\left(y_{j_{i}}\right), \operatorname{rel}\right)\right)}$$

**Theorem 0.3.** Let  $A \subset \mathbb{R}^3$  be a 3-dimensional piecewise linear manifold with boundary  $\partial A$ . Fix  $v \in S^1$ . The 0-dimensional persistent homology of  $h_v^X : X \to \mathbb{R}$  can be written as

$$\mathrm{PH}_{0}\left(X,h_{v}^{X}\right)=\oplus_{i=1}^{m}\mathcal{I}_{\left[h_{v}\left(y_{j_{i}}\right),d_{i}\right)}$$

where  $y_{j_1}, \dots y_{j_m}$  are the set of vertex representatives, and  $d_1, \dots d_m \in \mathbb{R} \cup \infty$ . Here we have only included intervals with positive length.

Let  $J^{\text{ord}}$  be the subset of  $\{1, 2, \dots m\}$  such that  $d_i$  is finite and  $y_{j_i}$  is (+)critical for  $h_v^A$ . Then

$$\operatorname{Ord}_{0}\left(A, h_{v}^{A}\right) = \bigoplus_{i \in J^{\operatorname{ord}}} \mathcal{I}_{\left[\left(h_{v}\left(y_{j_{i}}\right), \operatorname{ord}\right), \left(d_{i}, \operatorname{ord}\right)\right)}$$

Now let  $J^{\text{rel}}$  be the subset of  $\{1, 2, \dots m\}$  such that  $d_i$  is finite but  $y_i$  is not (+)-critical for  $h_n^A$ .

$$\operatorname{Rel}_{1}\left(A, h_{v}^{A}\right) = \bigoplus_{i \in Jrel} \mathcal{I}_{\left[\left(d_{i}, rel\right), \left(h_{v}\left(y_{j_{i}}\right), \ rel\ \right)\right)}$$

**Theorem 0.4.** Proposition 4.20. Let  $A \subset \mathbb{R}^n$  be an n-manifold with boundary  $X = \partial A$ . Let v be a direction such that  $h_v^A : A \to \mathbb{R}$  is a Morse function. Let  $\{X_1, \dots X_k\}$  be the interior boundary components of X and  $\{Y_1, \dots Y_l\}$  be the exterior boundary components of X. Then

$$\operatorname{Ess}_{0}(A, h_{v}) = \sum_{j=1}^{l} \mathcal{I}_{[(\min\{h_{v}(Y_{j})\}, \operatorname{ord}), (\max\{h_{v}(Y_{j})\}, \operatorname{rel}))}$$

and

$$\operatorname{Ess}_{n-1}(A, h_v) = \sum_{i=1}^{k} \mathcal{I}_{[(\max\{h_v(X_i)\}, \operatorname{ord}), (\min\{h_v(X_i)\}, \operatorname{rel}))}$$