

# Jason Liang McGrath

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## WORK EXPERIENCE

**Stangl Associates, Engineering Consulting Firm**, Amherst, MA

*March 2022-April 2023,*

*Mechanical Engineer*

*May 2019 - August 2019*

- Scanned plant equipment and surrounding infrastructure to be used in 3D modeling and understand any potential obstacles that would impede a client's project
- Modeled industrial equipment and buildings to understand and determine feasibility of client's project
- Modeled industrial equipment and infrastructure from manufacturing drawings
- Created drawings of modeled equipment and buildings to portray client's project to manufacturers
- Modified Ruby scripts to improve operation workflow in SketchUp

**EPIC Labs, Boston University**, Boston, MA

*June 2021 - December 2021*

*Lab Assistant*

- Trained students to use various equipment to ensure safe and productive machining practices
- Mentored students through CAD and CAM software to ensure machinability of their projects
- Cleaned and organized machine shop to encourage a safe and efficient working environment

## PROJECTS

**EMG controlled pneumatic glove**, Boston, MA

*September 2021 - December 2021*

Created pneumatically actuated glove assisting in finger flexion

- Programmed an electro-mechanical system to activate once an electromyography (EMG) sensor identified muscle activation
- Printed mold and cast pneumatic actuators used to assist finger flexion
- Programmed force sensors for user haptic feedback

**Wall mounted controller holder**, Boston, MA

*January 2021 - May 2021*

Developed wall mounted controller holder from ideation through EVT, DVT, and PVT

- Urethane casted dragon head, claws, and laser cut backplate
- Updated documents: Gantt chart, SOPs, BOM, FMEA, Specifications, Process, Tooling, and Quality test plan
- Outlined product packaging and mass production plan

**Assistive Knee Device**, Worcester, MA

*September 2019 - May 2020*

Designed motorized knee brace to aid users when climbing stairs addressing a range of constraints including compact, lightweight, and aesthetically pleasing

- Modeled knee brace in SolidWorks to optimize design
- Simulated brace undergoing external forces to identify design feasibility in SolidWorks FEA
- Manufactured a prototype using ESPRIT and Haas mini mill

## EDUCATION

**Boston University** Boston, MA

*January 2022*

Master of Science, Product Design and Manufacturing

*GPA 3.9/4.0*

**Worcester Polytechnic Institute** Worcester, MA

*May 2020*

Bachelor of Science, Mechanical Engineering

*GPA 3.7/4.0*

Minor: Robotics Engineering

Graduated, *Honors with Distinction*

**Relevant Coursework:** Advanced Product Design, Additive Manufacturing, Product Realization, Medical Robotics, Advanced CAD, Manufacturing Strategy, Automation and Manufacturing Methods (TA)

## TECHNICAL SKILLS

**Hardware:** Manual Mill, CNC Mill, Laser Cutter, Drill Press, Bandsaw, Hand tools, 3D Printing, Universal Robotics, Casting, Manual lathe, Arduino, Soldering

**Software:** SolidWorks, Creo, GibbsCAM, Esprit, C, MATLAB, Python, OnShape, SketchUp, Ruby