

6. Detection

Statistical Signal Processing

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6.1 Neyman-Pearson detectors

Binary hypothesis testing

- A hypothesis is a statement about the distribution of a measurement $\mathbf{y} \in \mathcal{Y}$, coded by a parameter $\boldsymbol{\theta} \in \boldsymbol{\Theta}$ that indexes the pdf $f_{\boldsymbol{\theta}}(\mathbf{y})$. The value of $\boldsymbol{\theta}$ **modulates** the distribution of the measurement (e.g., through the mean or covariance matrix).
- In **binary hypothesis testing** there are two competing hypotheses, H_0 (the **null hypothesis**) and H_1 (the **alternative**).
- Each of the hypotheses may be
 - **simple**, in which case the pdf of the measurement is $f_{\boldsymbol{\theta}_i}(\mathbf{y})$ under hypothesis H_i
 - **composite**, in which case the distribution of the measurement is $f_{\boldsymbol{\theta}}(\mathbf{y}), \boldsymbol{\theta} \in \boldsymbol{\Theta}_i$, under hypothesis H_i
- There are two main lines of development for detection theory:
 - **Neyman-Pearson**: frequentist theory that assigns no prior probabilities to competing models (we will study only Neyman-Pearson detectors)
 - **Bayes**: assigns prior probabilities to competing models; assigns costs to incorrect decisions, and then minimizes average cost

A binary test of H_1 vs. H_0 is a **test statistic**, or **threshold detector** $\phi : \mathcal{Y} \rightarrow \{0, 1\}$ of the form

$$\phi(\mathbf{y}) = \begin{cases} 1, & \mathbf{y} \in \mathcal{Y}_1 \\ 0, & \mathbf{y} \in \mathcal{Y}_0 \end{cases}$$

Two types of errors:

- **Missed detection:** Classify a measurement drawn from the pdf $f_{\theta}(\mathbf{y}), \theta \in \Theta_1$, as a measurement drawn from the pdf $f_{\theta}(\mathbf{y}), \theta \in \Theta_0$
- **False alarm:** Classify a measurement drawn from the pdf $f_{\theta}(\mathbf{y}), \theta \in \Theta_0$, as a measurement drawn from the pdf $f_{\theta}(\mathbf{y}), \theta \in \Theta_1$

For simple hypothesis and alternative the **detection probability** (power) P_D and the **false alarm probability** (size) P_F of a test are defined as

$$P_D = P_{\theta_1}(\phi = 1) = E_{\theta_1}[\phi]$$

$$P_F = P_{\theta_0}(\phi = 1) = E_{\theta_0}[\phi]$$

The subscripts θ_i denote probability and expectation under pdf $f_{\theta_i}(\mathbf{y})$.

Neyman-Pearson (NP) detector

Among all competing binary tests ϕ' of a simple alternative vs. a simple hypothesis, with probability of false alarm less than or equal to α , none has larger detection probability than the **likelihood ratio test**

$$\phi(\mathbf{y}) = \begin{cases} 1, & \ell(\mathbf{y}) > \eta \\ \gamma, & \ell(\mathbf{y}) = \eta \\ 0, & \ell(\mathbf{y}) < \eta. \end{cases}$$

In this equation, $0 \leq \ell(\mathbf{y}) < \infty$ is the *likelihood ratio*

$$\ell(\mathbf{y}) = \frac{f_{\theta_1}(\mathbf{y})}{f_{\theta_0}(\mathbf{y})}$$

and the threshold parameters (η, γ) are chosen to meet the constraint on false alarm probability $P_{\theta_0}[\ell(\mathbf{y}) > \eta] + \gamma P_{\theta_0}[\ell(\mathbf{y}) = \eta] = \alpha$. When $\phi(\mathbf{y}) = \gamma$, then select H_1 with probability γ , and H_0 with probability $1 - \gamma$.

The test function ϕ , given its likelihood ratio ℓ , is 0 if $\ell < \eta$, γ if $\ell = \eta$, and 1 if $\ell > \eta$, independently of θ . Thus, the likelihood ratio statistic is a **sufficient statistic** for testing H_1 vs. H_0 .

Fisher-Neyman factorization theorem

We call a statistic $\mathbf{t}(\mathbf{y})$ **sufficient** if the pdf $f_{\theta}(\mathbf{y})$ may be factored as $f_{\theta}(\mathbf{y}) = a(\mathbf{y})q_{\theta}(\mathbf{t})$.

In this case the likelihood ratio equals the likelihood ratio for \mathbf{t} :

$$\ell(\mathbf{y}) = \frac{f_{\theta_1}(\mathbf{y})}{f_{\theta_0}(\mathbf{y})} = \frac{q_{\theta_1}(\mathbf{t})}{q_{\theta_0}(\mathbf{t})} = \ell'(\mathbf{t})$$

We may thus rewrite the NP Lemma in terms of the sufficient statistic:

$$\phi(\mathbf{t}) = \begin{cases} 1, & \ell'(\mathbf{t}) > \eta \\ \gamma, & \ell'(\mathbf{t}) = \eta \\ 0, & \ell'(\mathbf{t}) < \eta \end{cases}$$

where (η, γ) are chosen to meet the P_F constraint.

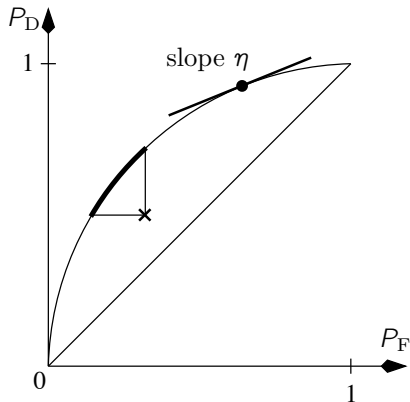
Minimal statistic

A sufficient statistic is **minimal**, meaning it is most memory efficient, if it is a function of every other sufficient statistic.

Invariant statistic

A sufficient statistic is an **invariant statistic** with respect to the transformation group G if $\phi(g(\mathbf{t})) = \phi(\mathbf{t})$ for all $g \in G$. The composition rule for any two transformations within G is $g_1 \circ g_2(\mathbf{t}) = g_1(g_2(\mathbf{t}))$.

Receiver operating characteristics (ROC)



For $t = \ell(\mathbf{y})$, the pdfs under the two hypotheses are connected as

$$f_{\theta_1}(\ell) = \ell f_{\theta_0}(\ell)$$

The probability of detection and probability of false alarm may be written

$$1 - P_D = \int_0^\eta f_{\theta_1}(\ell) d\ell = \int_0^\eta \ell f_{\theta_0}(\ell) d\ell$$

$$1 - P_F = \int_0^\eta f_{\theta_0}(\ell) d\ell$$

Differentiate each of these formulas with respect to η to find

$$\frac{\partial}{\partial \eta} P_D = -\eta f_{\theta_0}(\eta) \quad \text{and} \quad \frac{\partial}{\partial \eta} P_F = -f_{\theta_0}(\eta)$$

and therefore $\frac{dP_D}{dP_F} = \eta$.

6.2 Simple Gaussian hypothesis testing

Uncommon means and common covariance

- Test the alternative H_1 that a Gaussian measurement \mathbf{y} has mean value $\boldsymbol{\mu}_1$ vs. the hypothesis H_0 that it has mean value $\boldsymbol{\mu}_0$.
- Under both hypotheses \mathbf{y} has covariance matrix $\mathbf{R} = E_{\theta_0}[(\mathbf{y} - \boldsymbol{\mu}_0)(\mathbf{y} - \boldsymbol{\mu}_0)^H] = E_{\theta_1}[(\mathbf{y} - \boldsymbol{\mu}_1)(\mathbf{y} - \boldsymbol{\mu}_1)^H]$.
- The pdf of \mathbf{y} under hypothesis H_i is

$$f_{\theta_i}(\mathbf{y}) = \frac{1}{\pi^n \det \mathbf{R}} \exp \{ -(\mathbf{y} - \boldsymbol{\mu}_i)^H \mathbf{R}^{-1} (\mathbf{y} - \boldsymbol{\mu}_i) \}$$

- After some algebra, the log-likelihood ratio may be expressed as a function of \mathbf{y} :

$$\begin{aligned} L = \log \frac{f_{\theta_1}(\mathbf{y})}{f_{\theta_0}(\mathbf{y})} &= -(\mathbf{y} - \boldsymbol{\mu}_1)^H \mathbf{R}^{-1} (\mathbf{y} - \boldsymbol{\mu}_1) + (\mathbf{y} - \boldsymbol{\mu}_0)^H \mathbf{R}^{-1} (\mathbf{y} - \boldsymbol{\mu}_0) \\ &= 2 \operatorname{Re} \{ (\boldsymbol{\mu}_1 - \boldsymbol{\mu}_0)^H \mathbf{R}^{-1} (\mathbf{y} - \mathbf{y}_0) \} \end{aligned}$$

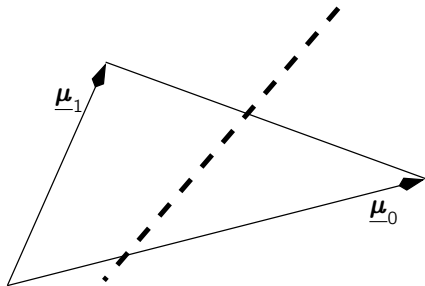
with $\mathbf{y}_0 = \frac{1}{2} (\boldsymbol{\mu}_1 + \boldsymbol{\mu}_0)$.

Uncommon means and common covariance

The log-likelihood ratio may be written as the inner product

$$L = 2\text{Re} \left\{ [\mathbf{R}^{-1}(\boldsymbol{\mu}_1 - \boldsymbol{\mu}_0)]^H (\mathbf{y} - \mathbf{y}_0) \right\} = 2\text{Re} \{ \mathbf{w}^H (\mathbf{y} - \mathbf{y}_0) \},$$

with $\mathbf{w} = \mathbf{R}^{-1}(\boldsymbol{\mu}_1 - \boldsymbol{\mu}_0)$. This inner product can be interpreted as **matched filtering**.



The centered measurement $\mathbf{y} - \mathbf{y}_0$ is resolved onto the line $\langle \mathbf{R}^{-1}(\boldsymbol{\mu}_1 - \boldsymbol{\mu}_0) \rangle$ to produce the **real** log-likelihood ratio L , which is compared to a threshold.

In the figure, we choose lines parallel to the thick dashed line to get the desired probability of false alarm P_F .

Uncommon means and common covariance

But how do we determine the threshold to get the desired P_F ? We will see that the deflection, or output signal-to-noise ratio, plays a key role.

The **deflection** for a likelihood ratio test with log-likelihood ratio L is

$$d = \frac{[E_{\theta_1}(L) - E_{\theta_0}(L)]^2}{\text{var}_{\theta_0}(L)},$$

where $\text{var}_{\theta_0}(L)$ denotes the variance of L under H_0 .

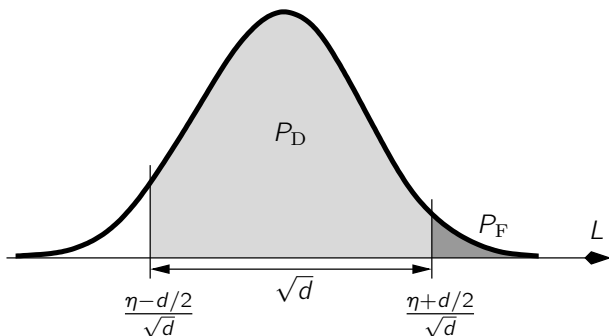
The likelihood ratio L derived on the previous slide results in

$$d = 2(\boldsymbol{\mu}_1 - \boldsymbol{\mu}_0)^H \mathbf{R}^{-1}(\boldsymbol{\mu}_1 - \boldsymbol{\mu}_0).$$

Proof: The mean of L is $d/2$ under H_1 and $-d/2$ under H_0 , and its variance is d under both hypotheses.

Thus, the log-likelihood ratio statistic L is distributed as a real Gaussian random variable with mean value $\pm d/2$ and variance d .

Uncommon means and common covariance



Now P_F and P_D for the detector ϕ that compares L to a threshold η are

$$P_F = 1 - \int_{-\infty}^{\eta} \frac{1}{\sqrt{2\pi d}} \exp \left\{ -\frac{1}{2d} (L + d/2)^2 \right\} dL = 1 - \Phi \left(\frac{\eta + d/2}{\sqrt{d}} \right)$$

$$P_D = 1 - \int_{-\infty}^{\eta} \frac{1}{\sqrt{2\pi d}} \exp \left\{ -\frac{1}{2d} (L - d/2)^2 \right\} dL = 1 - \Phi \left(\frac{\eta - d/2}{\sqrt{d}} \right)$$

where Φ is the cumulative distribution function of a zero-mean, variance one, real Gaussian random variable.

Common mean and uncommon covariances

- Assume w.l.o.g. that the mean is zero. Then the likelihood for the measurement \mathbf{y} under hypothesis H_i is

$$f_{\theta_i}(\mathbf{y}) = \frac{1}{\pi^n \det \mathbf{R}_i} \exp \{ -\mathbf{y}^H \mathbf{R}_i^{-1} \mathbf{y} \}$$

where \mathbf{R}_i is the covariance matrix under hypothesis H_i .

- The log-likelihood ratio for comparing H_1 to H_0 is

$$L = \mathbf{y}^H (\mathbf{R}_0^{-1} - \mathbf{R}_1^{-1}) \mathbf{y} = \mathbf{y}^H \mathbf{R}_0^{-H/2} (\mathbf{I} - \mathbf{S}^{-1}) \mathbf{R}_0^{-1/2} \mathbf{y}$$

where $\mathbf{S} = \mathbf{R}_0^{-1/2} \mathbf{R}_1 \mathbf{R}_0^{-H/2}$ is the **signal-to-noise ratio matrix**.

- The transformed measurement $\mathbf{R}_0^{-1/2} \mathbf{y}$ has covariance matrix \mathbf{I} under H_0 and covariance matrix \mathbf{S} under H_1 .
- Thus L is the log-likelihood ratio for testing that the linearly transformed measurement $\mathbf{R}_0^{-1/2} \mathbf{y}$ is **white** vs. the alternative that it has covariance \mathbf{S} .