

# 6. Detection

**Statistical Signal Processing**

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## **6.1 Neyman-Pearson detectors**

# Binary hypothesis testing

- A hypothesis is a statement about the distribution of a measurement  $\mathbf{y} \in \mathcal{Y}$ , coded by a parameter  $\theta \in \Theta$  that indexes the pdf  $f_\theta(\mathbf{y})$ . The value of  $\theta$  **modulates** the distribution of the measurement (e.g., through the mean or covariance matrix).
- In **binary hypothesis testing** there are two competing hypotheses,  $H_0$  (the **null hypothesis**) and  $H_1$  (the **alternative**).
- Each of the hypotheses may be
  - **simple**, in which case the pdf of the measurement is  $f_{\theta_i}(\mathbf{y})$  under hypothesis  $H_i$
  - **composite**, in which case the distribution of the measurement is  $f_\theta(\mathbf{y}), \theta \in \Theta_i$ , under hypothesis  $H_i$
- There are two main lines of development for detection theory:
  - **Neyman-Pearson**: frequentist theory that assigns no prior probabilities to competing models (we will study only Neyman-Pearson detectors)
  - **Bayes**: assigns prior probabilities to competing models; assigns costs to incorrect decisions, and then minimizes average cost

# Test statistic

A binary test of  $H_1$  vs.  $H_0$  is a **test statistic**, or **threshold detector**  $\phi : \mathcal{Y} \rightarrow \{0, 1\}$  of the form

$$\phi(\mathbf{y}) = \begin{cases} 1, & \mathbf{y} \in \mathcal{Y}_1 \\ 0, & \mathbf{y} \in \mathcal{Y}_0 \end{cases}$$

Two types of errors:

- **Missed detection:** Classify a measurement drawn from the pdf  $f_{\theta}(\mathbf{y}), \theta \in \Theta_1$ , as a measurement drawn from the pdf  $f_{\theta}(\mathbf{y}), \theta \in \Theta_0$
- **False alarm:** Classify a measurement drawn from the pdf  $f_{\theta}(\mathbf{y}), \theta \in \Theta_0$ , as a measurement drawn from the pdf  $f_{\theta}(\mathbf{y}), \theta \in \Theta_1$

For simple hypothesis and alternative the **detection probability** (power)  $P_D$  and the **false alarm probability** (size)  $P_F$  of a test are defined as

$$P_D = P_{\theta_1}(\phi = 1) = E_{\theta_1}[\phi]$$

$$P_F = P_{\theta_0}(\phi = 1) = E_{\theta_0}[\phi]$$

The subscripts  $\theta_i$  denote probability and expectation under pdf  $f_{\theta_i}(\mathbf{y})$ .

# Neyman-Pearson lemma

## Neyman-Pearson (NP) detector

Among all competing binary tests  $\phi'$  of a simple alternative vs. a simple hypothesis, with probability of false alarm less than or equal to  $\alpha$ , none has larger detection probability than the **likelihood ratio test**

$$\phi(\mathbf{y}) = \begin{cases} 1, & \ell(\mathbf{y}) > \eta \\ \gamma, & \ell(\mathbf{y}) = \eta \\ 0, & \ell(\mathbf{y}) < \eta. \end{cases}$$

In this equation,  $0 \leq \ell(\mathbf{y}) < \infty$  is the *likelihood ratio*

$$\ell(\mathbf{y}) = \frac{f_{\theta_1}(\mathbf{y})}{f_{\theta_0}(\mathbf{y})}$$

and the threshold parameters  $(\eta, \gamma)$  are chosen to meet the constraint on false alarm probability  $P_{\theta_0}[\ell(\mathbf{y}) > \eta] + \gamma P_{\theta_0}[\ell(\mathbf{y}) = \eta] = \alpha$ . When  $\phi(\mathbf{y}) = \gamma$ , then select  $H_1$  with probability  $\gamma$ , and  $H_0$  with probability  $1 - \gamma$ .

# Sufficient statistics

The test function  $\phi$ , given its likelihood ratio  $\ell$ , is 0 if  $\ell < \eta$ ,  $\gamma$  if  $\ell = \eta$ , and 1 if  $\ell > \eta$ , independently of  $\theta$ . Thus, the likelihood ratio statistic is a **sufficient statistic** for testing  $H_1$  vs.  $H_0$ .

## Fisher-Neyman factorization theorem

We call a statistic  $\mathbf{t}(\mathbf{y})$  **sufficient** if the pdf  $f_\theta(\mathbf{y})$  may be factored as  $f_\theta(\mathbf{y}) = a(\mathbf{y})q_\theta(\mathbf{t})$ .

In this case the likelihood ratio equals the likelihood ratio for  $\mathbf{t}$ :

$$\ell(\mathbf{y}) = \frac{f_{\theta_1}(\mathbf{y})}{f_{\theta_0}(\mathbf{y})} = \frac{q_{\theta_1}(\mathbf{t})}{q_{\theta_0}(\mathbf{t})} = \ell'(\mathbf{t})$$

We may thus rewrite the NP Lemma in terms of the sufficient statistic:

$$\phi(\mathbf{t}) = \begin{cases} 1, & \ell'(\mathbf{t}) > \eta \\ \gamma, & \ell'(\mathbf{t}) = \eta \\ 0, & \ell'(\mathbf{t}) < \eta \end{cases}$$

where  $(\eta, \gamma)$  are chosen to meet the  $P_F$  constraint.

# Minimal and invariant statistics

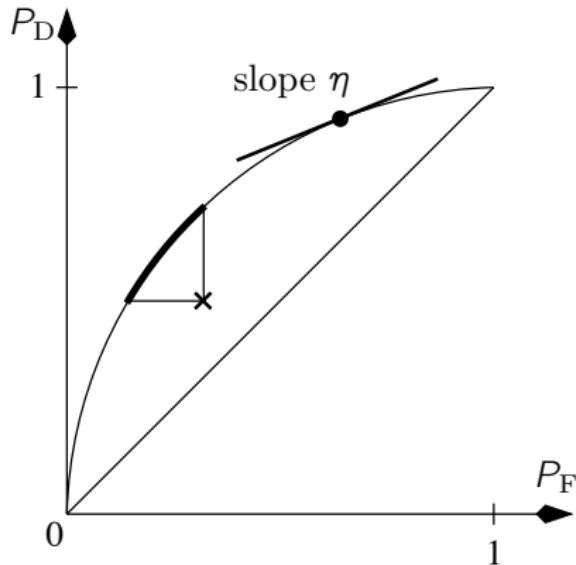
## Minimal statistic

A sufficient statistic is **minimal**, meaning it is most memory efficient, if it is a function of every other sufficient statistic.

## Invariant statistic

A sufficient statistic is an **invariant statistic** with respect to the transformation group  $G$  if  $\phi(g(\mathbf{t})) = \phi(\mathbf{t})$  for all  $g \in G$ . The composition rule for any two transformations within  $G$  is  $g_1 \circ g_2(\mathbf{t}) = g_1(g_2(\mathbf{t}))$ .

# Receiver operating characteristics (ROC)



For  $t = \ell(\mathbf{y})$ , the pdfs under the two hypotheses are connected as

$$f_{\theta_1}(\ell) = \ell f_{\theta_0}(\ell)$$

The probability of detection and probability of false alarm may be written

$$1 - P_D = \int_0^\eta f_{\theta_1}(\ell) d\ell = \int_0^\eta \ell f_{\theta_0}(\ell) d\ell$$

$$1 - P_F = \int_0^\eta f_{\theta_0}(\ell) d\ell$$

Differentiate each of these formulas with respect to  $\eta$  to find

$$\frac{\partial}{\partial \eta} P_D = -\eta f_{\theta_0}(\eta) \quad \text{and} \quad \frac{\partial}{\partial \eta} P_F = -f_{\theta_0}(\eta)$$

and therefore  $\frac{dP_D}{dP_F} = \eta$ .

## **6.2 Simple Gaussian hypothesis testing**

# Uncommon means and common covariance

- Test the alternative  $H_1$  that a Gaussian measurement  $\mathbf{y}$  has mean value  $\boldsymbol{\mu}_1$  vs. the hypothesis  $H_0$  that it has mean value  $\boldsymbol{\mu}_0$ .
- Under both hypotheses  $\mathbf{y}$  has covariance matrix  
$$\mathbf{R} = E_{\theta_0}[(\mathbf{y} - \boldsymbol{\mu}_0)(\mathbf{y} - \boldsymbol{\mu}_0)^H] = E_{\theta_1}[(\mathbf{y} - \boldsymbol{\mu}_1)(\mathbf{y} - \boldsymbol{\mu}_1)^H].$$
- The pdf of  $\mathbf{y}$  under hypothesis  $H_i$  is

$$f_{\theta_i}(\mathbf{y}) = \frac{1}{\pi^n \det \mathbf{R}} \exp \left\{ -(\mathbf{y} - \boldsymbol{\mu}_i)^H \mathbf{R}^{-1} (\mathbf{y} - \boldsymbol{\mu}_i) \right\}$$

- After some algebra, the log-likelihood ratio may be expressed as a function of  $\mathbf{y}$ :

$$\begin{aligned} L = \log \frac{f_{\theta_1}(\mathbf{y})}{f_{\theta_0}(\mathbf{y})} &= -(\mathbf{y} - \boldsymbol{\mu}_1)^H \mathbf{R}^{-1} (\mathbf{y} - \boldsymbol{\mu}_1) + (\mathbf{y} - \boldsymbol{\mu}_0)^H \mathbf{R}^{-1} (\mathbf{y} - \boldsymbol{\mu}_0) \\ &= 2 \operatorname{Re} \{(\boldsymbol{\mu}_1 - \boldsymbol{\mu}_0)^H \mathbf{R}^{-1} (\mathbf{y} - \mathbf{y}_0)\} \end{aligned}$$

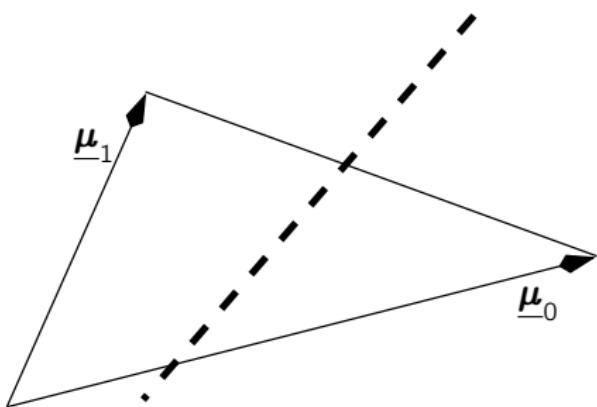
with  $\mathbf{y}_0 = \frac{1}{2} (\boldsymbol{\mu}_1 + \boldsymbol{\mu}_0)$ .

# Uncommon means and common covariance

The log-likelihood ratio may be written as the inner product

$$L = 2\operatorname{Re} \left\{ [\mathbf{R}^{-1}(\boldsymbol{\mu}_1 - \boldsymbol{\mu}_0)]^H (\mathbf{y} - \mathbf{y}_0) \right\} = 2\operatorname{Re} \{ \mathbf{w}^H (\mathbf{y} - \mathbf{y}_0) \},$$

with  $\mathbf{w} = \mathbf{R}^{-1}(\boldsymbol{\mu}_1 - \boldsymbol{\mu}_0)$ . This inner product can be interpreted as **matched filtering**.



The centered measurement  $\mathbf{y} - \mathbf{y}_0$  is resolved onto the line  $\langle \mathbf{R}^{-1}(\boldsymbol{\mu}_1 - \boldsymbol{\mu}_0) \rangle$  to produce the **real** log-likelihood ratio  $L$ , which is compared to a threshold.

In the figure, we choose lines parallel to the thick dashed line to get the desired probability of false alarm  $P_F$ .

# Uncommon means and common covariance

But how do we determine the threshold to get the desired  $P_F$ ? We will see that the deflection, or output signal-to-noise ratio, plays a key role.

The **deflection** for a likelihood ratio test with log-likelihood ratio  $L$  is

$$d = \frac{[E_{\theta_1}(L) - E_{\theta_0}(L)]^2}{\text{var}_{\theta_0}(L)},$$

where  $\text{var}_{\theta_0}(L)$  denotes the variance of  $L$  under  $H_0$ .

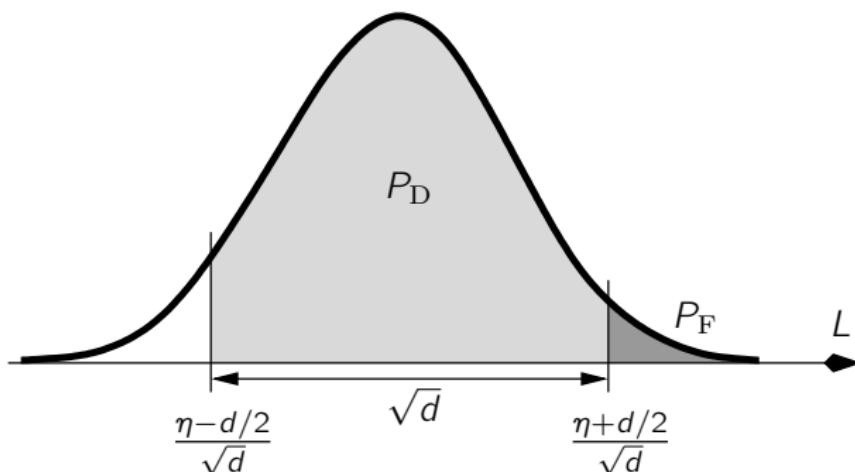
The likelihood ratio  $L$  derived on the previous slide results in

$$d = 2(\boldsymbol{\mu}_1 - \boldsymbol{\mu}_0)^H \mathbf{R}^{-1} (\boldsymbol{\mu}_1 - \boldsymbol{\mu}_0).$$

**Proof:** The mean of  $L$  is  $d/2$  under  $H_1$  and  $-d/2$  under  $H_0$ , and its variance is  $d$  under both hypotheses.

Thus, the log-likelihood ratio statistic  $L$  is distributed as a real Gaussian random variable with mean value  $\pm d/2$  and variance  $d$ .

# Uncommon means and common covariance



Now  $P_F$  and  $P_D$  for the detector  $\phi$  that compares  $L$  to a threshold  $\eta$  are

$$P_F = 1 - \int_{-\infty}^{\eta} \frac{1}{\sqrt{2\pi d}} \exp \left\{ -\frac{1}{2d}(L + d/2)^2 \right\} dL = 1 - \Phi \left( \frac{\eta + d/2}{\sqrt{d}} \right)$$

$$P_D = 1 - \int_{-\infty}^{\eta} \frac{1}{\sqrt{2\pi d}} \exp \left\{ -\frac{1}{2d}(L - d/2)^2 \right\} dL = 1 - \Phi \left( \frac{\eta - d/2}{\sqrt{d}} \right)$$

where  $\Phi$  is the cumulative distribution function of a zero-mean, variance one, real Gaussian random variable.

# Common mean and uncommon covariances

- Assume w.l.o.g. that the mean is zero. Then the likelihood for the measurement  $\mathbf{y}$  under hypothesis  $H_i$  is

$$f_{\theta_i}(\mathbf{y}) = \frac{1}{\pi^n \det \mathbf{R}_i} \exp \left\{ -\mathbf{y}^H \mathbf{R}_i^{-1} \mathbf{y} \right\}$$

where  $\mathbf{R}_i$  is the covariance matrix under hypothesis  $H_i$ .

- The log-likelihood ratio for comparing  $H_1$  to  $H_0$  is

$$L = \mathbf{y}^H (\mathbf{R}_0^{-1} - \mathbf{R}_1^{-1}) \mathbf{y} = \mathbf{y}^H \mathbf{R}_0^{-H/2} (\mathbf{I} - \mathbf{S}^{-1}) \mathbf{R}_0^{-1/2} \mathbf{y}$$

where  $\mathbf{S} = \mathbf{R}_0^{-1/2} \mathbf{R}_1 \mathbf{R}_0^{-H/2}$  is the **signal-to-noise ratio matrix**.

- The transformed measurement  $\mathbf{R}_0^{-1/2} \mathbf{y}$  has covariance matrix  $\mathbf{I}$  under  $H_0$  and covariance matrix  $\mathbf{S}$  under  $H_1$ .
- Thus  $L$  is the log-likelihood ratio for testing that the linearly transformed measurement  $\mathbf{R}_0^{-1/2} \mathbf{y}$  is **white** vs. the alternative that it has covariance  $\mathbf{S}$ .